

I006 - PROCESS CONTROL

TRANSDUCERS, FLOW, PRESSURE, TEMPERATURE MEASUREMENT

SIGNAL CONDITIONING (ANALOG + DIGITAL)

SENSORS, PROCESS CONTROL SYSTEM, ELECTRONICS SIGNAL

AND SYSTEM, PROCESS CONTROLLERS,

PLC SYSTEM.

www.power semester 4. zoom share.com

Analog Digital Signal Conditioning

H085_I006 Note 1 Sensor 1

_____ 2 Sensor 2

_____ 3 Sensor 3

H085_I006 Note 4 Control concept 1

_____ Note 5 _____ 2

H085_I006 Note 6 Electronic signal

_____ Note 8 Process control 1

_____ 9 Process control 2

PLC

PLC Textbook 1

PLC Textbook 2

PLC Textbook 3

PLC 6487 E. ZIP

PLC REFERENCE

TRILOGIC PLC

USER MANUAL

SETUP TL6 EDU

INSTALLATION INSTRUCTION

I001 - INSTALL SETUP TRANSDUCERS AND SENSING DEVICES

I002 - SOLVE THE PROBLEMS IN PRESSURE MEASUREMENT

I004 - SOLVE THE PROBLEMS IN FLOW MEASUREMENT

I005 - SOLVE THE PROBLEMS IN TEMPERATURE
MEASUREMENT.

I002 + I004

I002 I004 PRESSURE FLOW PNEUMATIC REFERENCE. ZIP

I005

I005 TEMPERATURE MEASUREMENT. ZIP

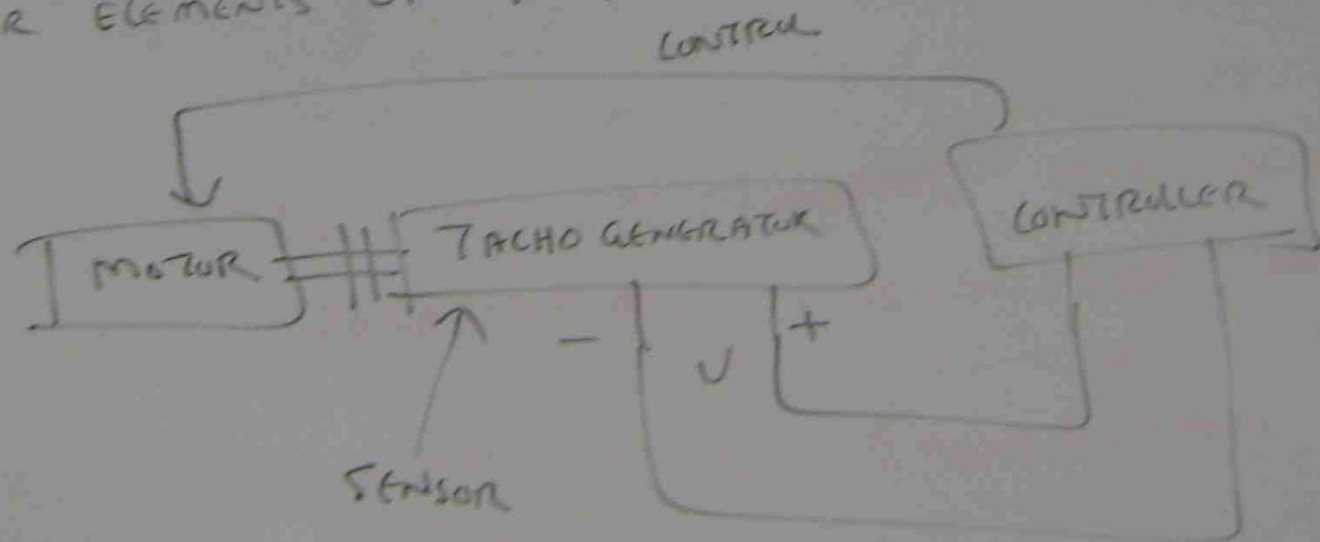
FIRST PART - TEMPERATURE
LIGHT

LATER PART - FLOW

PRINCIPLE OF ANALOG SIGNAL CONDITIONING

A SENSOR MEASURES A VARIABLE SIGNAL BY CONVERTING THE INFORMATION ABOUT THAT VARIABLE INTO A DEPENDENT SIGNAL OF EITHER ELECTRICAL (OR) PNEUMATIC NATURE.

ANALOG SIGNAL CONDITIONING PROVIDES THE OPERATION NECESSARY TO TRANSFORM A SENSOR OUTPUT INTO A FORM NECESSARY TO INTERFACE WITH OTHER ELEMENTS OF THE PROCESS CONTROL LOOP.



CONTROL SIGNAL

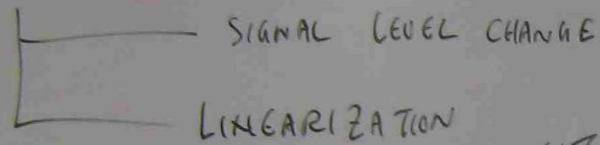


PHOTO CELL

LIGHT \rightarrow VOLTAGE

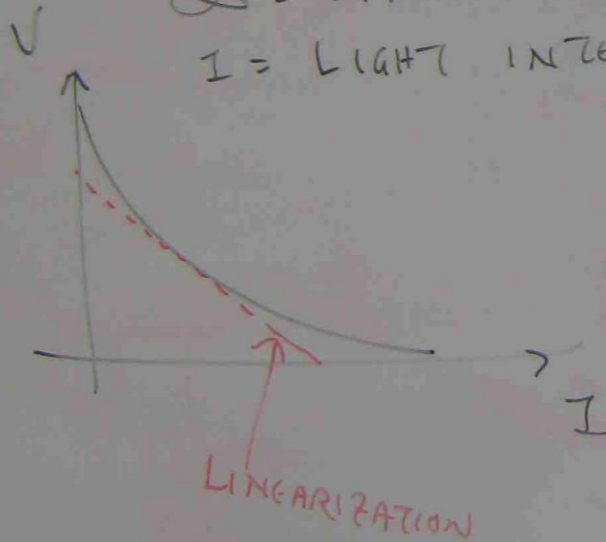
$$V_i = V_0 e^{-\lambda I}$$

V_i = OUTPUT VOLTAGE AT INTENSITY I

V_0 = ZERO INTENSITY VOLTAGE

λ = EXPONENTIAL CONSTANT

I = LIGHT INTENSITY



SIGNAL CONVERSION

LIGHT \rightarrow PHOTO CELL \rightarrow VOLTAGE

GAS \rightarrow COMPRESSOR \rightarrow PRESSURE FORCE

MOTION \rightarrow TACHO GENERATOR \rightarrow VOLTAGE
ROTATIONAL FORCE

HEAT \rightarrow THERMOCOUPLE \rightarrow MECHANICAL MOVEMENT
TEMPERATURE

SIGNAL TRANSMISSION

THE SIGNAL IS TRANSMITTED OVER ELECTRICAL WIRE, DATA BUSES AND FED TO CONTROLLER.

SIGNAL CONVERSION

LIGHT \rightarrow PHOTO CELL \rightarrow VOLTAGE

GAS \rightarrow COMPRESSOR \rightarrow PRESSURE
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MOTION \rightarrow TACHO GENERATOR \rightarrow VOLTAGE
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TEMPERATURE MOVEMENT

SIGNAL TRANSMISSION

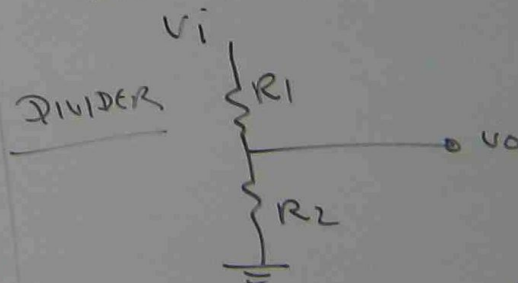
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ELECTRICAL WIRE, DATA BUSES
AND FED TO CONTROLLER.

DIGITAL INTERFACE

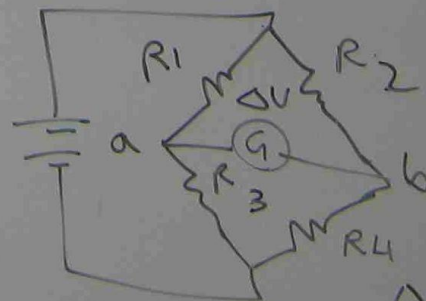
THE USE OF COMPUTER IN PROCESS CONTROL
REQUIRES CONVERSION OF ANALOG SIGNAL
IN TO DIGITAL FORMAT BY INTEGRATED
DEVICES CALLED ANALOG TO DIGITAL CONVERTER

PASSIVE CIRCUIT

BRIDGE AND DIVIDERS.



$$V_o = V_i \times \frac{R_2}{R_1 + R_2}$$



$$V_a = \frac{V R_3}{R_1 + R_3}$$

$$V_b = \frac{V R_4}{R_2 + R_4}$$

$$\Delta V = V_a - V_b$$

CONTROL SIGNAL

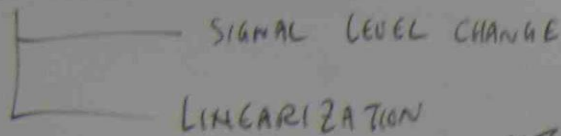


PHOTO CELL

LIGHT \rightarrow VOLTAGE

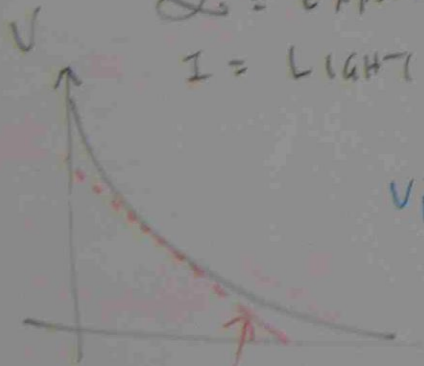
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I = LIGHT INTENSITY



LINEARIZATION

$$V_i = V_0 \log_e e^{-\alpha I}$$

$$V_i = V_0 (-\alpha I)$$

$$dB = 20 \log \frac{V_i}{V_0}$$

SIGNAL CONVERSION

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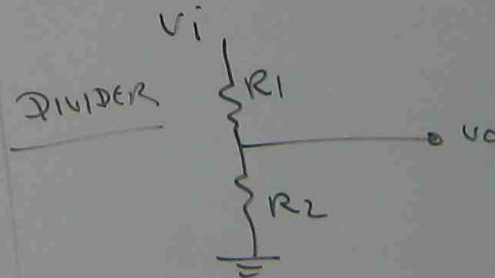
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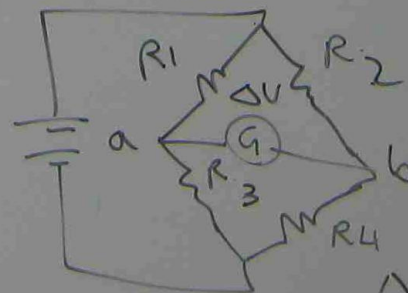
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BRIDGE AND DIVIDERS.



$$V_o = V_i \times \frac{R_2}{R_1 + R_2}$$

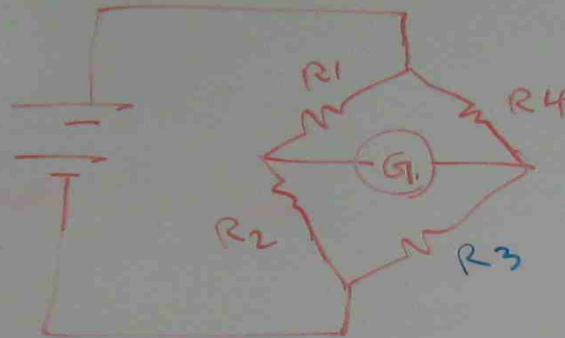


$$V_a = \frac{V R_3}{R_1 + R_3}$$

$$V_b = \frac{V R_4}{R_2 + R_4}$$

$$\Delta V = V_a - V_b$$

pb



IN GIVEN WHEATSTONE BRIDGE, IF $R_1 = 1000\Omega$
 $R_2 = 842\Omega$, $R_3 = 500\Omega$, FIND R_4 .

BALANCE

$$R_1 \times R_3 = R_2 \times R_4$$

$$1000 \times 500 = 842 \times R_4$$

$$R_4 = \frac{1000 \times 500}{842} =$$

WALVANO MOTOR DETECTOR

$$V_{th} = V \frac{R_3 R_2 - R_1 R_4}{(R_1 + R_3)(R_2 + R_4)}$$

$$R_{th} = \frac{R_1 R_3}{R_1 + R_3} + \frac{R_2 R_4}{R_2 + R_4}$$

$$I_g = \frac{V_{th}}{R_{th} + R_g}$$

↑
OFFSET CURRENT

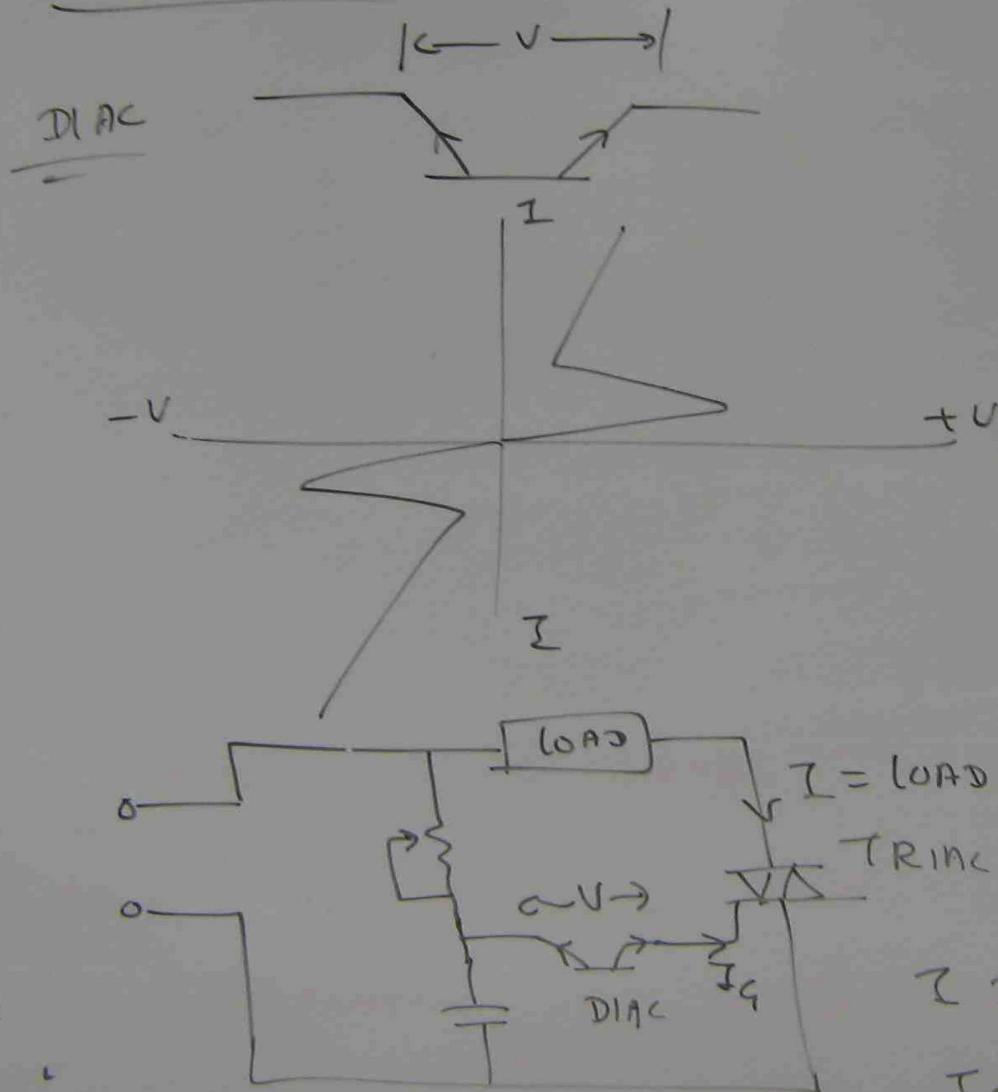
pb
 A BRIDGE CIRCUIT HAS $R_1 = R_2 = R_3 = 2 \text{ k}\Omega$ RESISTANCES, $R_4 = 2.05 \text{ k}\Omega$
 5V SUPPLY. THE BRIDGE IS NULLED. IF A GALVANOMETER WITH 500 Ω
 INTERNAL RESISTANCE IS USED FIND THE OFFSET CURRENT.

$$\begin{aligned}
 V_{th} &= V \frac{R_3 R_2 - R_1 R_4}{(R_1 + R_3)(R_2 + R_4)} \\
 &= 5 \frac{(2 \times 2) - (2 \times 2.05)}{(2 + 2)(2 + 2.05)} \\
 &= -30.9 \text{ mV}
 \end{aligned}$$

$$\begin{aligned}
 R_{th} &= \frac{R_1 R_3}{R_1 + R_3} + \frac{R_2 R_4}{R_2 + R_4} \\
 &= \frac{2 \times 2}{2 + 2} + \frac{2 \times 2.05}{2 + 2.05} \\
 &= 2.01 \text{ k}\Omega
 \end{aligned}$$

$$\begin{aligned}
 I_G &= \frac{V_{th}}{R_{th} + R_g} \\
 &= \frac{-30.9 \text{ mV}}{2.01 \text{ k}\Omega + 0.05 \text{ k}\Omega} \\
 &= -15 \mu\text{A}
 \end{aligned}$$

TRIGGER CONTROL



PLC TL31 V3
INSTRUCTION

SELF STUDY

WEEK

1, 2, 3

4, 5,

6, 7, 8

9, 10

9, 10

I DEPENDS ON I_G

I_G DEPENDS ON V

PLC TL31 V3
INSTRUCTION



SELF STUDY

+U

WEEK	PERIOD		TOPIC
	1 1→3	2 3→4:30	
1, 2, 3	✓	✓	ANALOG SIGNAL CONDITIONING + TEMPERATURE PRESSURE MEASUREMENT
4, 5,	✓	✓	DIGITAL (2)
6, 7, 8	✓	✓	DIGITAL SIGNAL PROCESSING
9, 10	✓		ELECTRONICS SIGNAL
9, 10		✓	PROCESS CONTROL

= LOAD CURRENT

TRIAL

I DEPENDS ON I_g

I_g DEPENDS ON V

EM

E

GUIDELINES FOR ANALOG SIGNAL CONDITIONING DESIGN

(1) DEFINE THE MEASUREMENT OBJECTIVES

(a) PARAMETER

WHAT IS THE NATURE OF MEASURED VARIABLE:

PRESSURE, TEMPERATURE, FLOW, LEVEL, VOLTAGE,
CURRENT, RESISTANCE ETC?

(b) RANGE

WHAT IS THE RANGE OF THE MEASUREMENT?

(c) ACCURACY

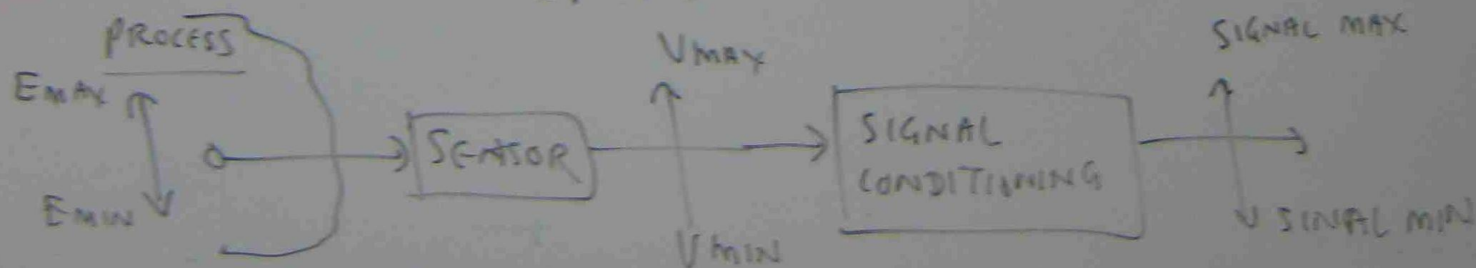
WHAT IS THE REQUIRED ACCURACY?

(d) LINEARITY

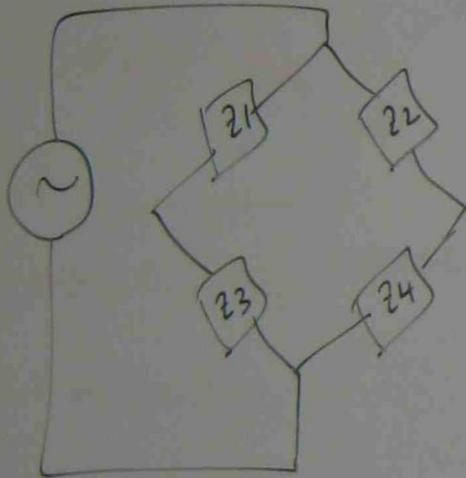
MUST THE MEASUREMENT OUTPUT BE LINEAR?

(e) NOISE

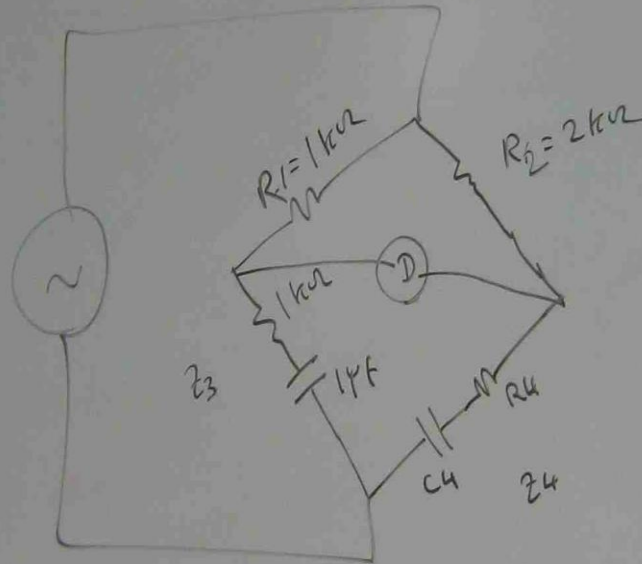
WHAT IS THE NOISE LEVEL AND FREQUENCY SPECTRUM
OF THE MEASUREMENT ENVIRONMENT?



AC BRIDGES



$$Z_1 Z_4 = Z_3 Z_2$$



CALCULATE R_4 & C_4

$$Z_1 Z_4 = Z_3 Z_2$$

$$R_1 \left(R_4 - j \frac{1}{\omega C_4} \right) = R_2 \left(R_3 - j \frac{1}{\omega C_3} \right)$$

$$R_1 R_4 - j \frac{R_1}{\omega C_4} = R_2 R_3 - j \frac{R_2}{\omega C_3}$$

$$R_1 R_4 = R_2 R_3$$

$$(1 \text{ k}\Omega) (R_4) = (2 \text{ k}\Omega) (1 \text{ k}\Omega)$$

$$R_4 = \frac{2 \times 1}{1} = 2 \text{ k}\Omega$$

$$-\int \frac{R_1}{\omega C_4} = -\int \frac{R_2}{\omega C_3}$$

$$\frac{R_1}{\omega C_4} = \frac{R_2}{\omega C_3}$$

$$\frac{R_1}{C_4} = \frac{R_2}{C_3}$$

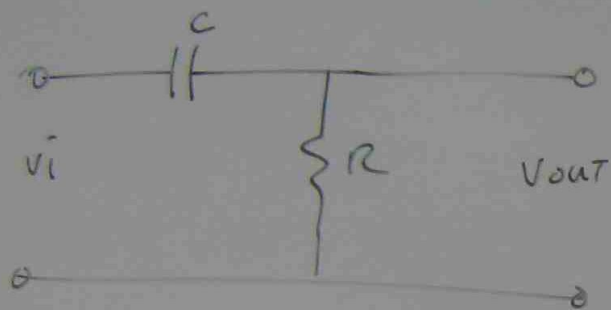
$$\frac{1 \text{ k}\Omega}{C_4} = \frac{2 \text{ k}\Omega}{1 \mu\text{F}}$$

$$C_4 = \frac{1 \text{ k}\Omega \times 1 \mu\text{F}}{2 \text{ k}\Omega}$$

$$= \frac{1 \mu\text{F}}{2}$$

$$= 0.5 \mu\text{F}$$

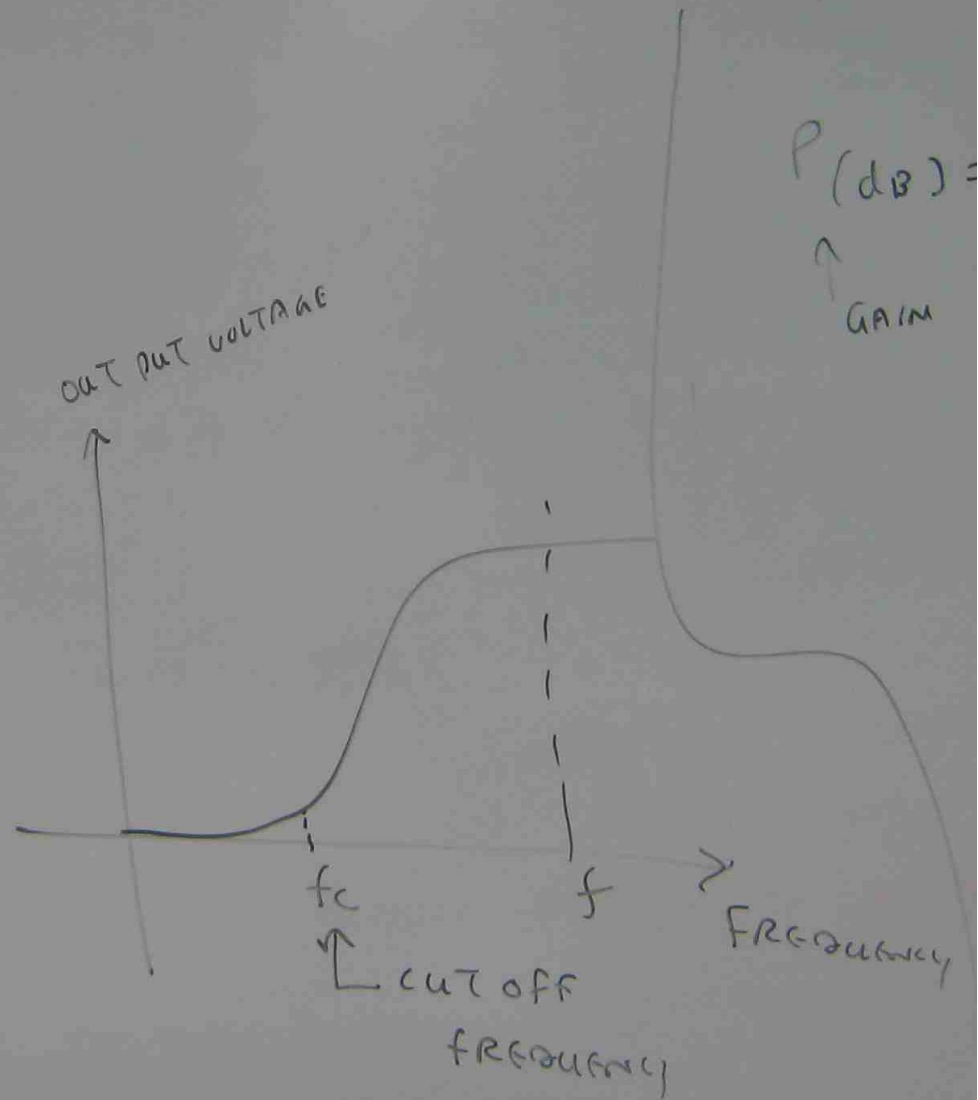
HIGH PASS RC FILTER



$$\frac{V_{out}}{V_{in}} = \frac{f/f_c}{\sqrt{1 + \left(\frac{f}{f_c}\right)^2}}$$

f = ANY FREQUENCY

f_c = CUT OFF FREQUENCY



$$P(\text{dB}) = 20 \log \frac{V_{\text{out}}}{V_{\text{in}}}$$

↑
GAIN IN DECIBEL UNIT (dB)

pb PULSES FOR STEPPING MOTOR
ARE BEING TRANSMITTED AT 2000 Hz
DESIGN A FILTER TO REDUCE 50 Hz
NOISE, BUT REDUCE THE PULSES BY
NO MORE THAN 3 dB

$$P(\text{dB}) = 20 \log \frac{V_{\text{out}}}{V_{\text{in}}}$$

$$-3 \text{ dB} = 20 \log_{10} \frac{V_{\text{out}}}{V_{\text{in}}}$$

$$-\frac{3}{20} = \log_{10} \frac{V_{\text{out}}}{V_{\text{in}}}$$

$$-0.15 = \log_{10} \frac{V_{\text{out}}}{V_{\text{in}}}$$

$$\frac{V_{\text{out}}}{V_{\text{in}}} = 10^{-0.15}$$

$$\frac{V_{\text{out}}}{V_{\text{in}}} = 0.707$$

Frequency

$$\frac{V_{out}}{V_{in}} = \frac{f/f_c}{\sqrt{1 + \left(\frac{f}{f_c}\right)^2}}$$

$$\frac{V_{out}}{V_{in}} = \frac{60/2000}{\sqrt{1 + \left(\frac{60}{2000}\right)^2}}$$

$$= 0.03$$

ONLY 3% OF 60Hz NOISE REMAIN

IF INPUT VOLTAGE IS REDUCED TO 70.7%, NOISE WILL BE 3dB

IF INPUT VOLTAGE IS REDUCED TO 3%, NOISE CAN BE ELIMINATED.

OPERATION PROCEDURE FOR PLC

TL 31 V3 SOFTWARE

PLC 6487E - ZIP

DOWN LOAD ZIP FILE & EXTRACT THE FILES.

DIRECTORY

(ENTER)

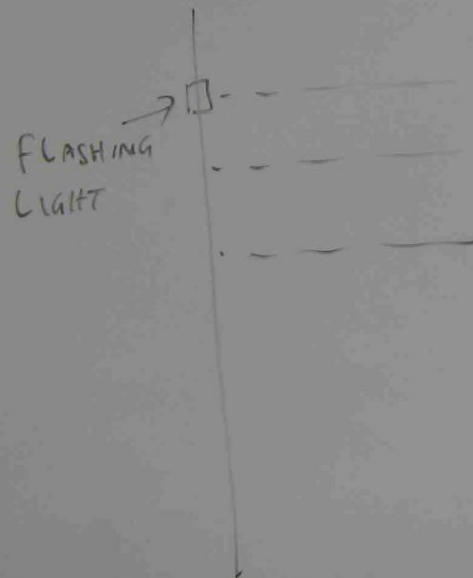
YOU CAN ACCESS THE
PLC PROGRAM
MAIN PAGE

PRESS ANY KEY

TO START THE PROGRAM

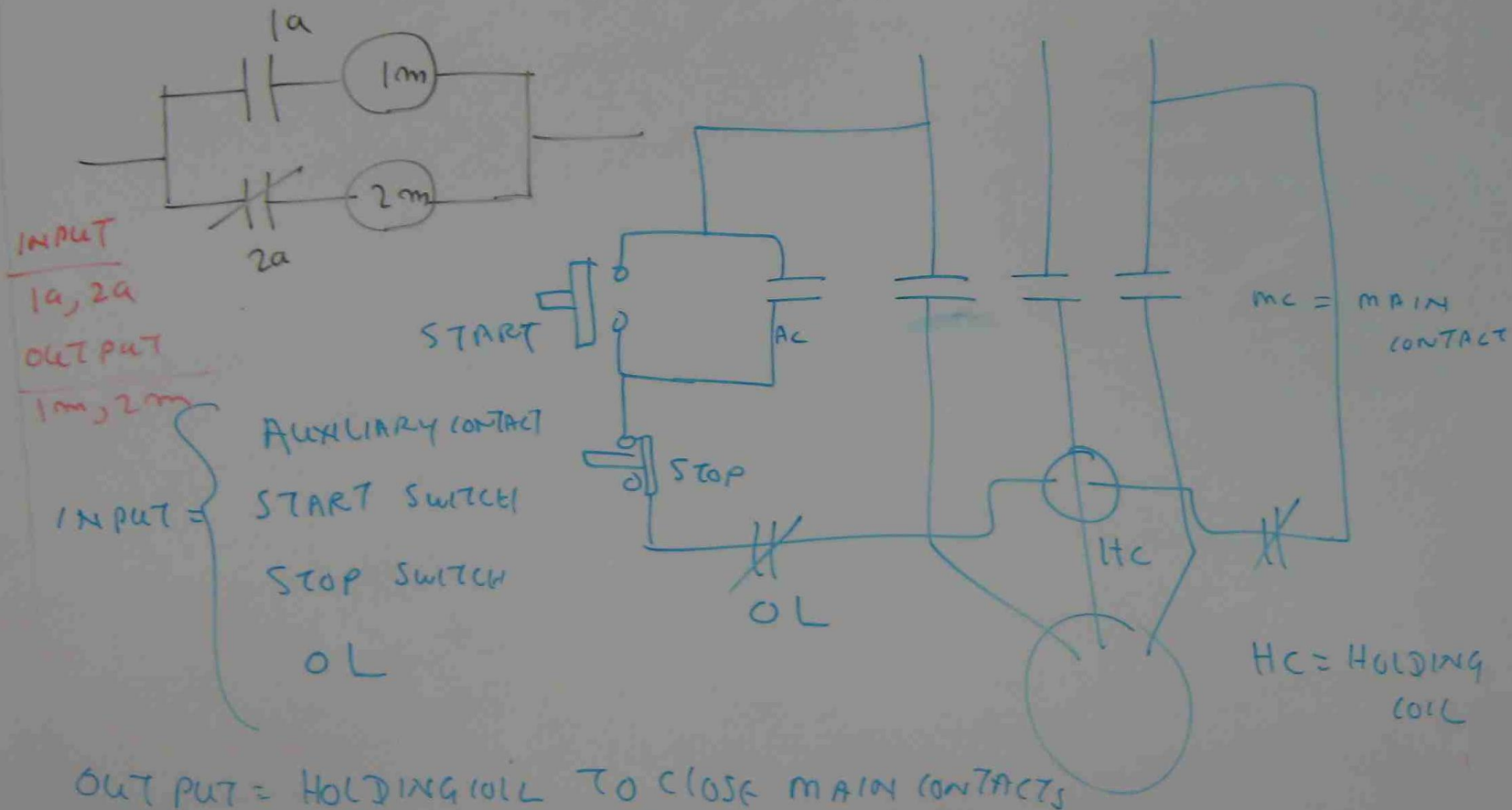
FILE - LOAD - PC3 - SELECT PC3 <ENTER>

YOU CAN REACH MAIN PROGRAM PAGE
TO DRAW LADDER DIAGRAM



TO DRAW PLC CONTROL PROGRAM

IT IS REQUIRED TO ALLOCATE INPUT, OUTPUT, RELAY, TIMER AND COUNTER.



TL 31

INPUT — PRESS F2 →
 OUTPUT — PRESS F3 →
 RELAY — PRESS F4
 TIMER — PRESS F5
 COUNTER — PRESS F6

INPUT NUMBER	LABEL	CH BIT
--------------	-------	--------

OUTPUT NUMBER	LABEL	CH BIT
---------------	-------	--------

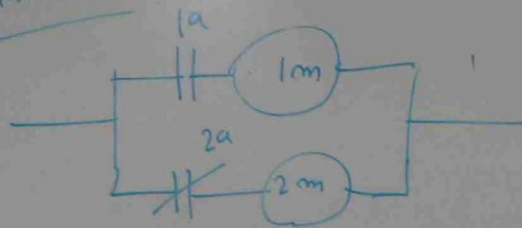
RELAY NUMBER	LABEL	CH. BIT
--------------	-------	---------

TIMER NUMBER	LABEL	CH. BIT
--------------	-------	---------

COUNTER NUMBER	LABEL	CH. BIT
----------------	-------	---------

STEP

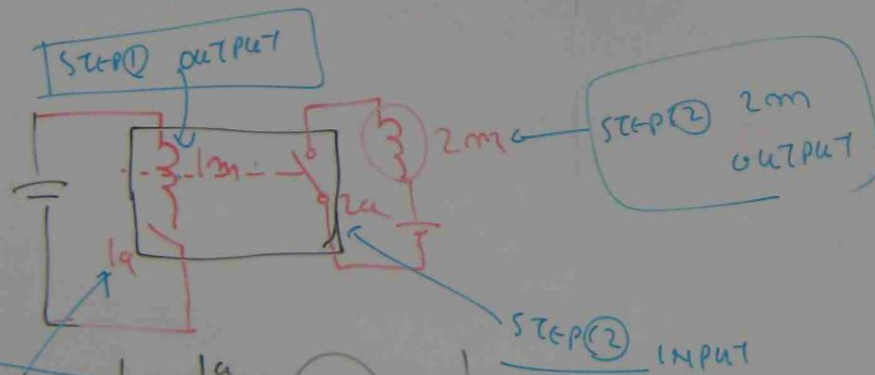
EXAMPLE



CLOSE 1a, 1m ENERGIZED

THEN 1m OPENS 2a

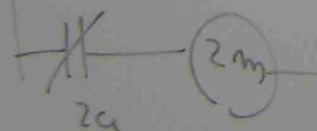
THEN 2m IS DE ENERGIZED



STEP 1 INPUT



STEP (1)



STEP (2)

INPUT

1a, 2a

OUTPUT

1m, 2m

PROGRAM IN

PRESS F2

TYPE 1a

TYPE 2a

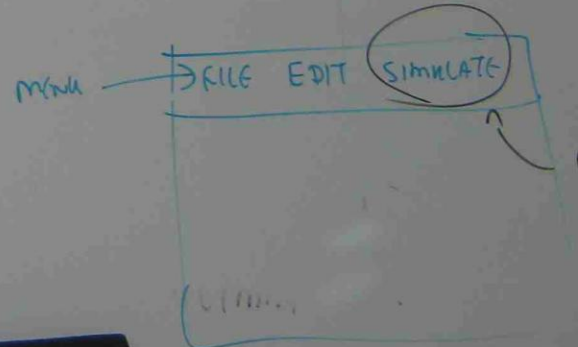
END

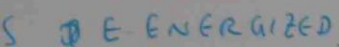
PROGRAM OUT

PRESS F3

TYPE

TYPE





STEP (2) INPUT

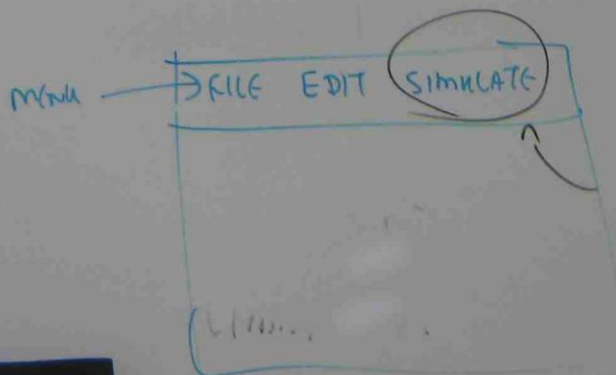
$$ST(A^2)$$

PROGRAM INPUT

PROGRAM OUTPUT

press F3	OUTPUT number	LABEL	CH. BIT
TYPE 1m (ENTER)			
TYPE 2m (ENTER)			

Esc



ENTER \rightarrow YOU WILL SEE
CIRCUIT PERFORMANCES

TL 31

INPUT — PRESS f2 →

OUTPUT — PRESS f3 →

RELAY — PRESS f4

TIMER — PRESS f5

COUNTER — PRESS f6

INPUT NUMBER	LABEL	CH. BIT

OUTPUT NUMBER	LABEL	CH. BIT

RELAY NUMBER	LABEL	CH. BIT

TIMER NUMBER	LABEL	CH. BIT

COUNTER NUMBER	LABEL	CH. BIT

EXAMPLE



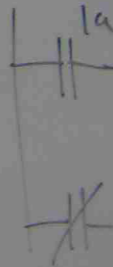
close

THEN

THEN

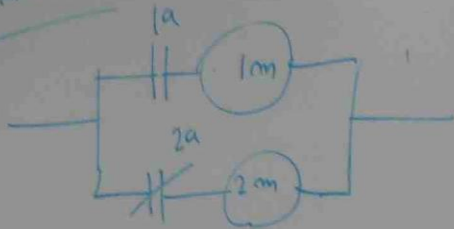


STEP 0 INPUT



2a

EXAMPLE



CLOSE 1a, 1m ENERGIZED

THEN 1m OPENS 2a

THEN 2m IS DE ENERGIZED

INPUT

1a, 2a

OUTPUT

1m, 2m

PROGRAM INPUT

PRESS F2	INPUT NUMBER	LABEL	CH. BIT
	TYPE 1a <ENTER>		
	TYPE 2a <ENTER>		
	ESC		

PROGRAM OUTPUT

PRESS F3	OUTPUT NUMBER	LABEL	CH. BIT
	TYPE 1m <ENTER>		
	TYPE 2m <ENTER>		

ESC

ENTER → YOU WILL SEE
CIRCUIT PERFORMANCES.

STEP 1 OUTPUT

STEP 2 2m
OUTPUT

STEP 2 INPUT

STEP 1

STEP 2

MENU

FILE EDIT

SIMULATE



LADDER DIAGRAM

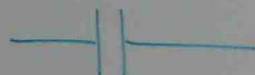
PRESS ESC UNTIL FLASHING OCCURS ON VERTICAL
MARGIN LINE FOR DRAWING

ESC → FLASHING



VERTICAL
LINE

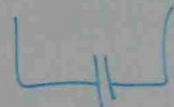
WHEN FLASHING HAPPENS, PRESS SPACE BAR
TO INSERT COMPONENTS FOR DRAWING



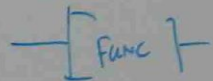
PRESS 1



PRESS 2



PRESS 3



PRESS 4



PRESS 5



PRESS 6



PRESS 7

FLASHING OCCURS ON VERTICAL

DRAWING

WHEN FLASHING HAPPENS, PRESS SPACE BAR

TO INSERT COMPONENTS FOR DRAWING



PRESS 1



PRESS 2



PRESS 3



PRESS 4



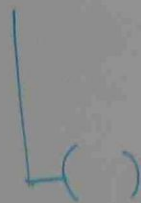
PRESS 5



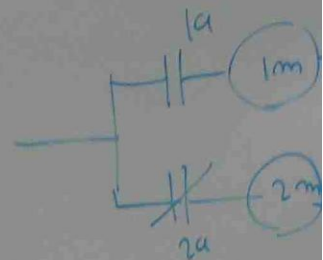
PRESS 6




PRESS 7

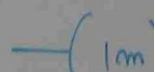



PRESS 8



ESC - FLASHING

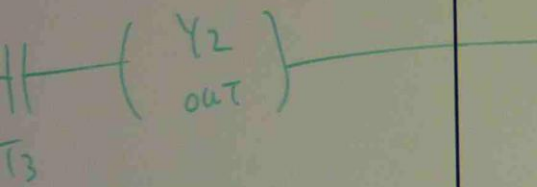
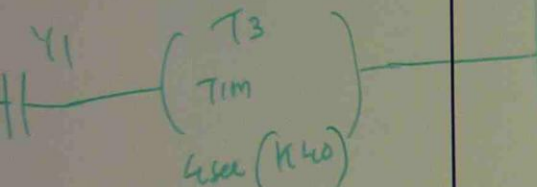
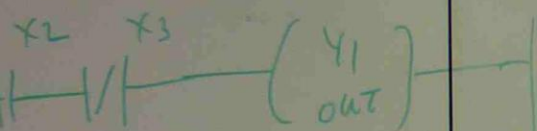
TO INSERT 

TO INSERT 

TO INSERT 

TO SIMULATE - ESC

TO CLOSE THE FILE



Input x_2
 x_3
 y_1
 y_2
 timer T_3 4sec

Simulate

I

$x_2 = 0$	$y_1 = 0$
$x_3 = 0$	$y_2 = 0$

II

$x_2 = 1$	$y_1 = 1$
$x_3 = 0$	Then 4sec $y_2 = 1$

III

$x_2 = 1$	$y_1 = 0$
$x_3 = 1$	$y_2 = 0$