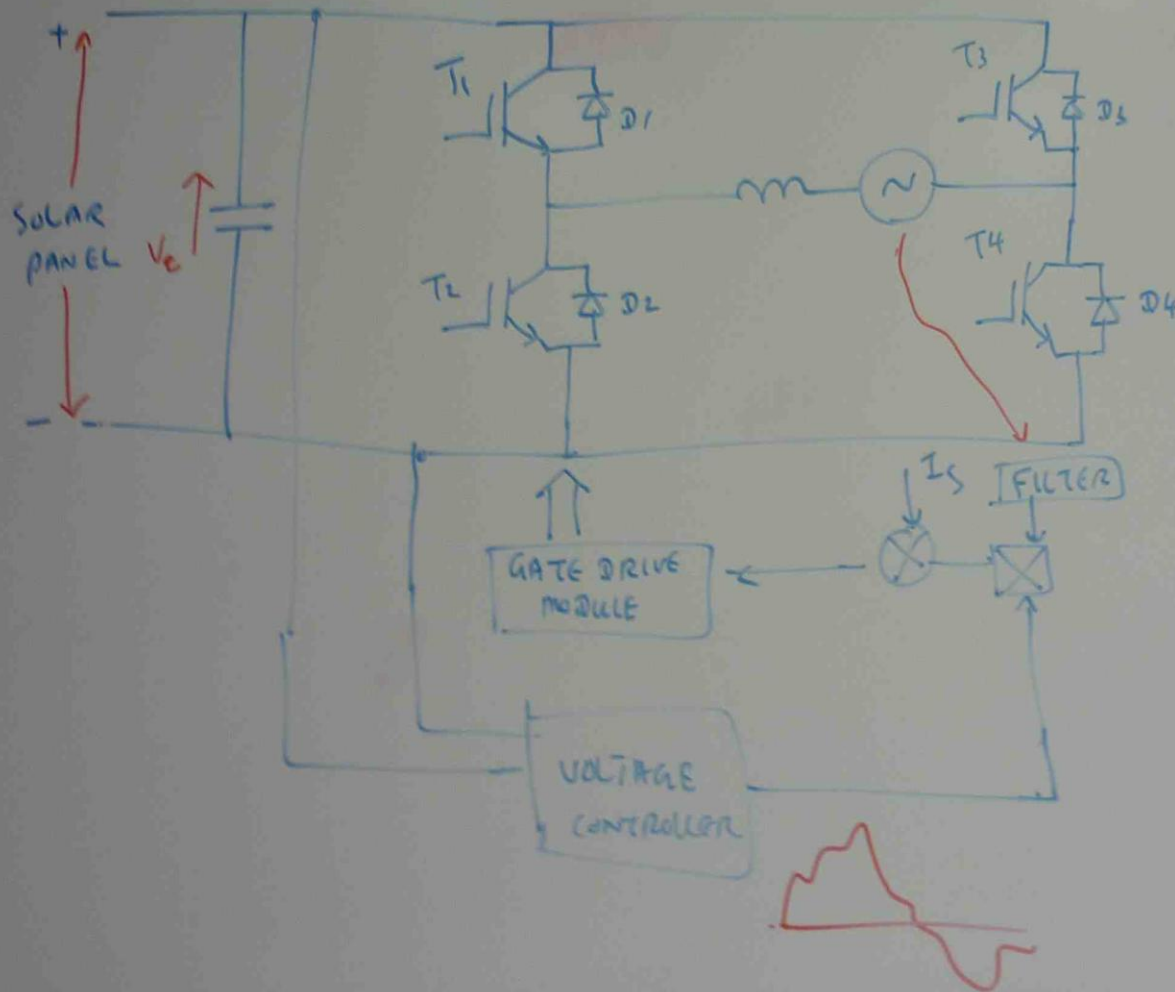


PV INVERTER SYSTEM



GRID CONNECTED SINGLE PHASE
PHOTOVOLTATIC SYSTEM MAY BE
UNIPOLAR SWITCHED (OR)
BIPOLAR SWITCHED.

THEY CAN BE CURRENT
CONTROLLED (OR) VOLTAGE
CONTROLLED.

THE GRID CONNECTED
INVERTERS HAVE TO
OPERATE WITH IN DISTORTION
LIMIT SPECIFIED
AUSTRALIAN STANDARD
AS 4777.2

UNI POLAR MODE

T_3 - off
 T_4 - ON

(POSITIVE HALF CYCLE)

TRANSISTOR T_1 IS SWITCHED ON
WHEN THE INVERTER CURRENT
GOES BELOW BOTTOM LIMIT

I_s RISES WHILE IT FLOWS
THROUGH T_1 AND T_4

(NEGATIVE HALF CYCLE)

T_4 IS OFF

T_3 IS ON

TRANSISTOR T_2 IS SWITCHED
ON

BIPOLAR MODE

TWO SWITCHES CAN BE SWITCHED ON
AND SWITCHED OFF.

POSITIVE HALF CYCLE

T_1 AND T_4 ARE SWITCHED

NEGATIVE HALF CYCLE

T_2 AND T_3 ARE SWITCHED ON

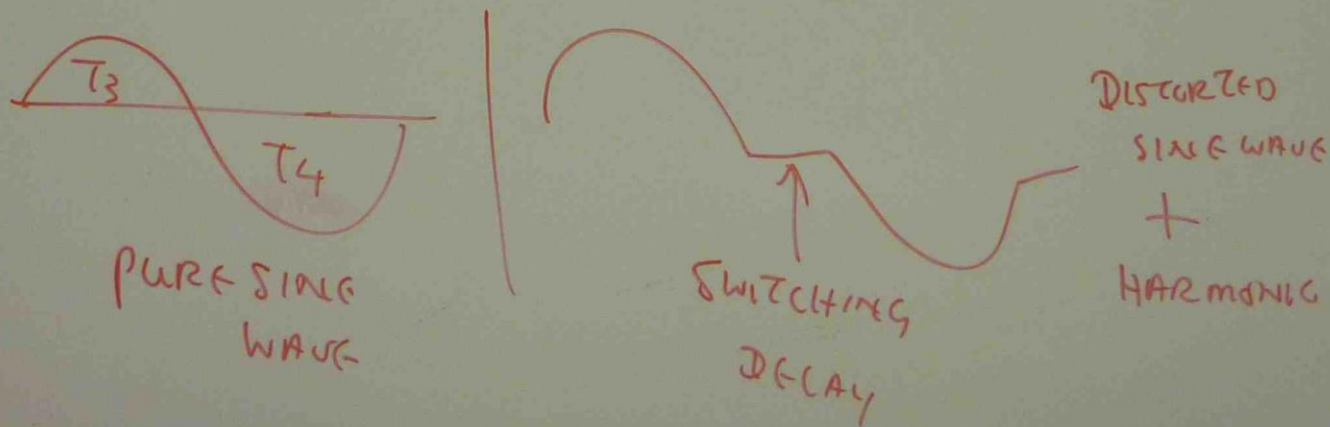
IF THE CURRENT RISES THROUGH T_1 AND T_4 ,

T_1 AND T_4 ARE SWITCHED OFF

AS THE SWITCHING RATE DETERMINES THE OUT PUT AC VOLTAGE AND CURRENT, IT CAN CAUSE HIGHER FREQUENCIES (HARMONIC FREQUENCIES AND HARMONIC DISTORTION).

THE FOLLOWINGS CAUSE LOW FREQUENCY DISTORTION

- (a) HARMONIC CONTENTS IN SIGNAL VOLTAGE V_{ref}
- (b) HARMONIC CONTENT IN THE VOLTAGE CONTROLLER OUT PUT
- (c) SWITCHING DELAY
- (d) INDUCTOR NON LINEARITY



MULTIPLIER INPUT SIGNAL VOLTAGE

WITHOUT ANY SIGNAL CONDITIONING, MULTIPLIER SIGNAL V_{REF} IS MERELY AN ATTENUATED VERSION OF AC MAIN VOLTAGE.

THE HARMONIC DISTORTION IN V_{REF} EQUAL TO TOTAL HARMONIC DISTORTION OF SUPPLY VOLTAGE

3.4 %.

TO MINIMIZE DISTORTION, TOTAL HARMONIC DISTORTION OF OUTPUT FILTER NEEDS TO BE 1.5%.

HARMONIC CONTENT IN VOLTAGE CONTROLLER OUTPUT SIGNAL

THE FEED BACK SIGNAL TO THE VOLTAGE CONTROLLER CONTAINS THE HARMONIC BECAUSE OF DISTORTION IN DC BUS VOLTAGE.

THE MAIN CAUSE OF THAT DISTORTION IS THAT DISTORTION IS COMPONENTS AT 100 Hz AND HIGHER MULTIPLES OF 100 Hz WHICH ARE PART OF STORAGE CAPACITOR.

WITH ANALOG PI CONTROLLER, THE HARMONIC PROPAGATE TO CONTROLLER OUTPUT DOMINATED BY THIRD HARMONIC.

BY USING DIGITAL CONTROLLER, 100 Hz HARMONIC FROM PI CONTROLLER OUTPUT CAN BE ELIMINATED.

PI - PROPORTIONAL INTEGRAL CONTROL

SWITCHING DELAY

$$\hat{i}_s - \hat{i}_{ref} = \frac{s_{gn}(V_s) t_d V_c}{2L} - \frac{t_d V_s}{L}$$

\hat{i}_s = SUPPLY CURRENT

\hat{i}_{ref} = REFERENCE CURRENT

$s_{gn}(V_s)$ = SIGNIFICANT PORTION OF SUPPLY
VOLTAGE

t_d = SWITCHING TIME DELAY

V_c = CAPACITOR VOLTAGE

L = INDUCTANCE

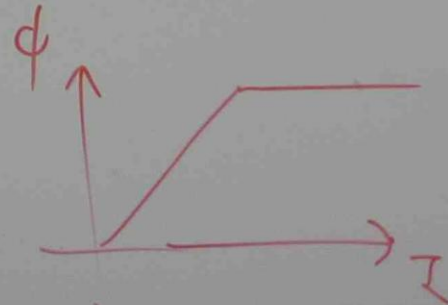
$$i_s - i_{ref} = -\frac{t_d v_s}{L}$$

INDUCTOR SATURATION

$$t_d = \frac{(i_s - i_{ref}) \times (-L)}{v_s}$$

FOR LOW FREQUENCY, THE VALUE OF
INDUCTANCE IS MAIN FUNCTION OF
SWITCHING DELAY.

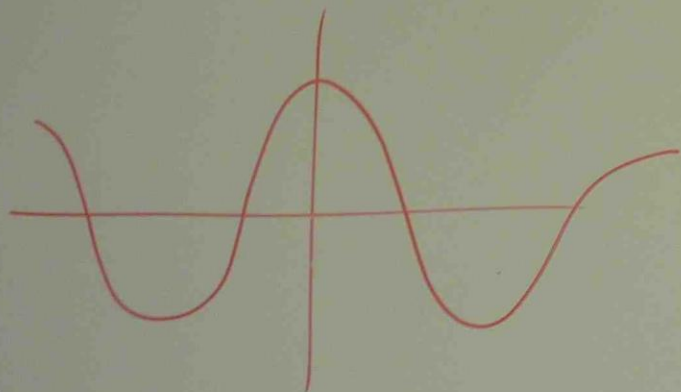
INDUCTOR IS TO BE USED WITHIN
LINEAR RANGE.



INVERTER OUTPUT CURRENT

DIGITAL OSCILLOSCOPE

TETRONIK TDS 720
TDS 720



BIPOLAR SWITCHING

$$i_{ref} = 2 \text{ A}$$



$$i_{ref} = 0.5 \text{ A}$$

BIPOLAR SWITCHING



UNIPOLAR SWITCHING

$$i_{ref} = 2 \text{ A}$$



UNIPOLAR
SWITCHING

$$i_{ref} = 0.5 \text{ A}$$

TOTAL HARMONIC DISTORTION

REFERENCE CURRENT AMP (RMS)	% THD UNIPOLAR SWITCHING	% THD BIPOLAR SWITCHING
0.5	11.25%	8.37%
0.75	8.18%	5.02%
1.0	6.34%	3.8%
2.0	3.42%	2.06%

