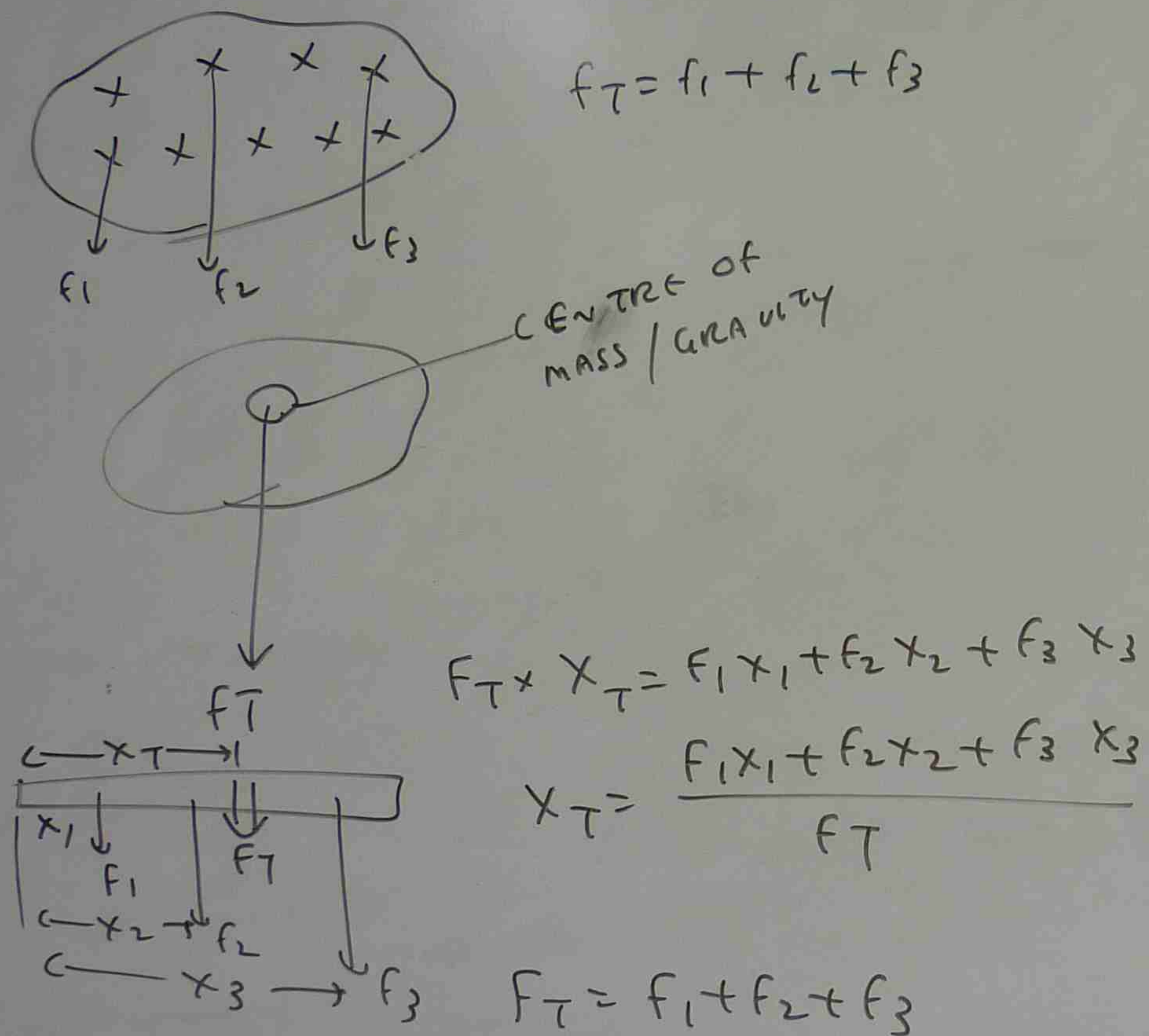


CENTRE OF MASS AND LINEAR MOMENTUM



$$X_T = \frac{F_1 X_1 + F_2 X_2 + F_3 X_3}{F_1 + F_2 + F_3}$$

$F = \text{force}$

$$F = m g$$

$m = \text{MASS}$

$g = \text{GRAVITY}$

$$X_T = \frac{m_1 g X_1 + m_2 g X_2 + m_3 g X_3}{m_1 g + m_2 g + m_3 g}$$

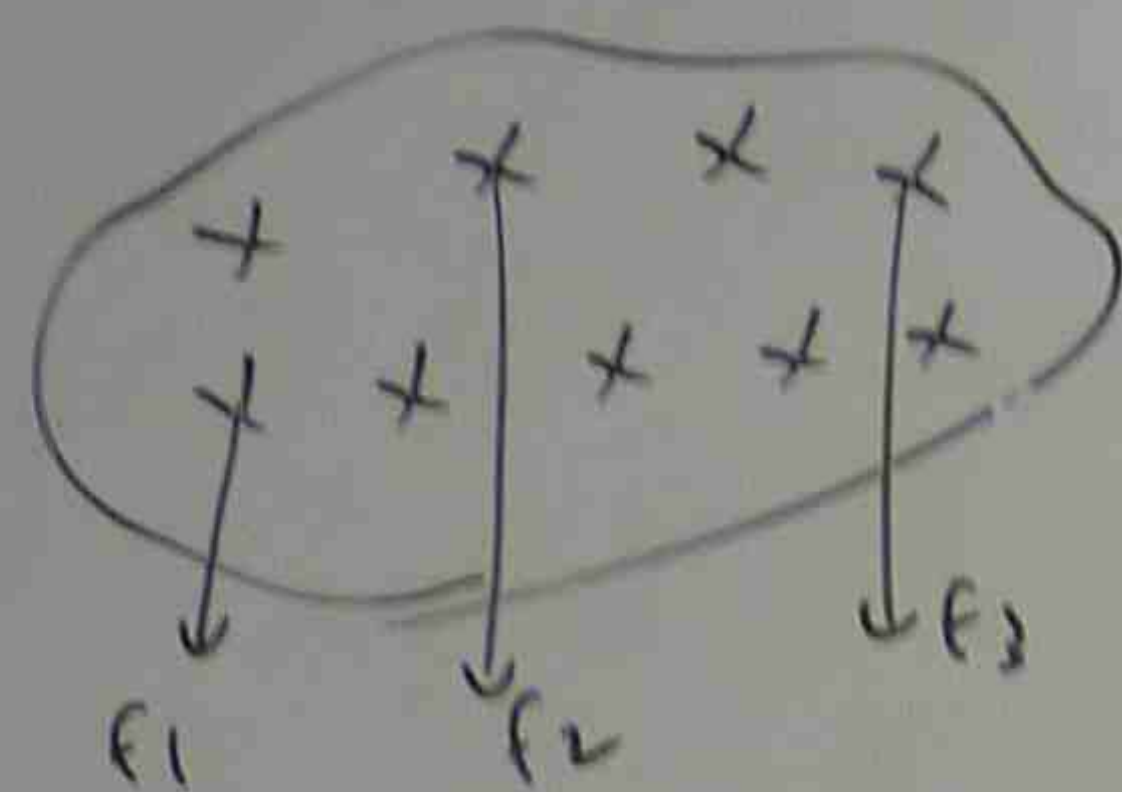
$$X_T = \frac{m_1 X_1 + m_2 X_2 + m_3 X_3}{m_1 + m_2 + m_3}$$

CENTRE OF MASS

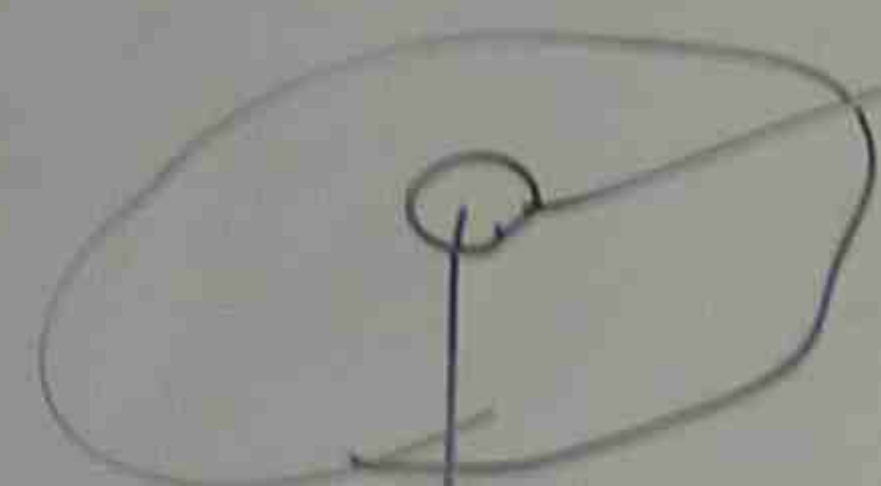
$$X_T = \frac{\sum Fx}{\sum F} \quad (\text{or}) \quad \frac{\sum mx}{\sum m}$$

PD THREE PARTICLES OF MASSES $m_1 = 1.2 \text{ kg}$, $m_2 = 2.5 \text{ kg}$ AND $m_3 = 3.4 \text{ kg}$ FORM AN EQUILATERAL TRIANGLE OF EDGE LENGTH $a = 140 \text{ cm}$. WHERE IS THE CENTRE OF MASS OF THIS SYSTEM?

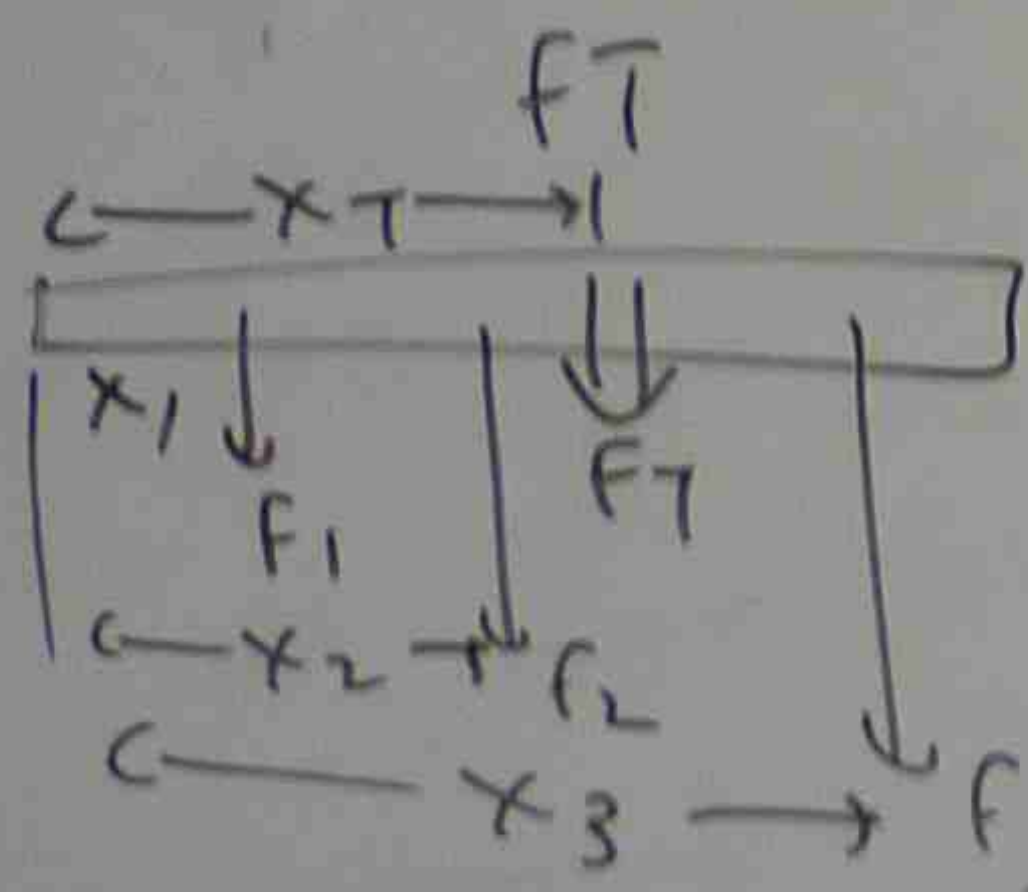
CENTRE OF MASS AND LINEAR MOMENTUM



$$F_T = F_1 + F_2 + F_3$$



CENTRE OF
MASS / GRAVITY



$$F_T \times X_T = F_1 x_1 + F_2 x_2 + F_3 x_3$$

$$X_T = \frac{F_1 x_1 + F_2 x_2 + F_3 x_3}{F_T}$$

$$F_T = F_1 + F_2 + F_3$$

$$X_T = \frac{F_1 x_1 + F_2 x_2 + F_3 x_3}{F_1 + F_2 + F_3}$$

$F = \text{force}$

$$F = m g$$

$m = \text{MASS}$

$g = \text{GRAVITY}$

$$X_T = \frac{m_1 g x_1 + m_2 g x_2 + m_3 g x_3}{m_1 g + m_2 g + m_3 g}$$

$$X_T = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3}{m_1 + m_2 + m_3}$$

↑
CENTRE OF MASS

$$X_T = \frac{\sum Fx}{\sum F} \quad (\text{or}) \quad \frac{\sum mx}{\sum m}$$

PD THREE PARTICLES OF MASSES $m_1 = 1.2 \text{ kg}$, $m_2 = 2.5 \text{ kg}$ AND $m_3 = 3.4 \text{ kg}$ FORM AN EQUILATERAL TRIANGLE OF EDGE LENGTH $a = 140 \text{ cm}$. WHERE IS THE CENTRE OF MASS OF THIS SYSTEM?

momentum

+ f₃

$$X_T = \frac{m_1 g x_1 + m_2 g x_2 + m_3 g x_3}{m_1 g + m_2 g + m_3 g}$$

$$X_T = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3}{m_1 + m_2 + m_3}$$

↑ CENTRE OF MASS

$$X_T = \frac{\sum Fx}{\sum F} \quad (\text{or}) \quad \frac{\sum mx}{\sum m}$$

f₂x₂ + f₃x₃

f₂x₂ + f₃x₃

f_T

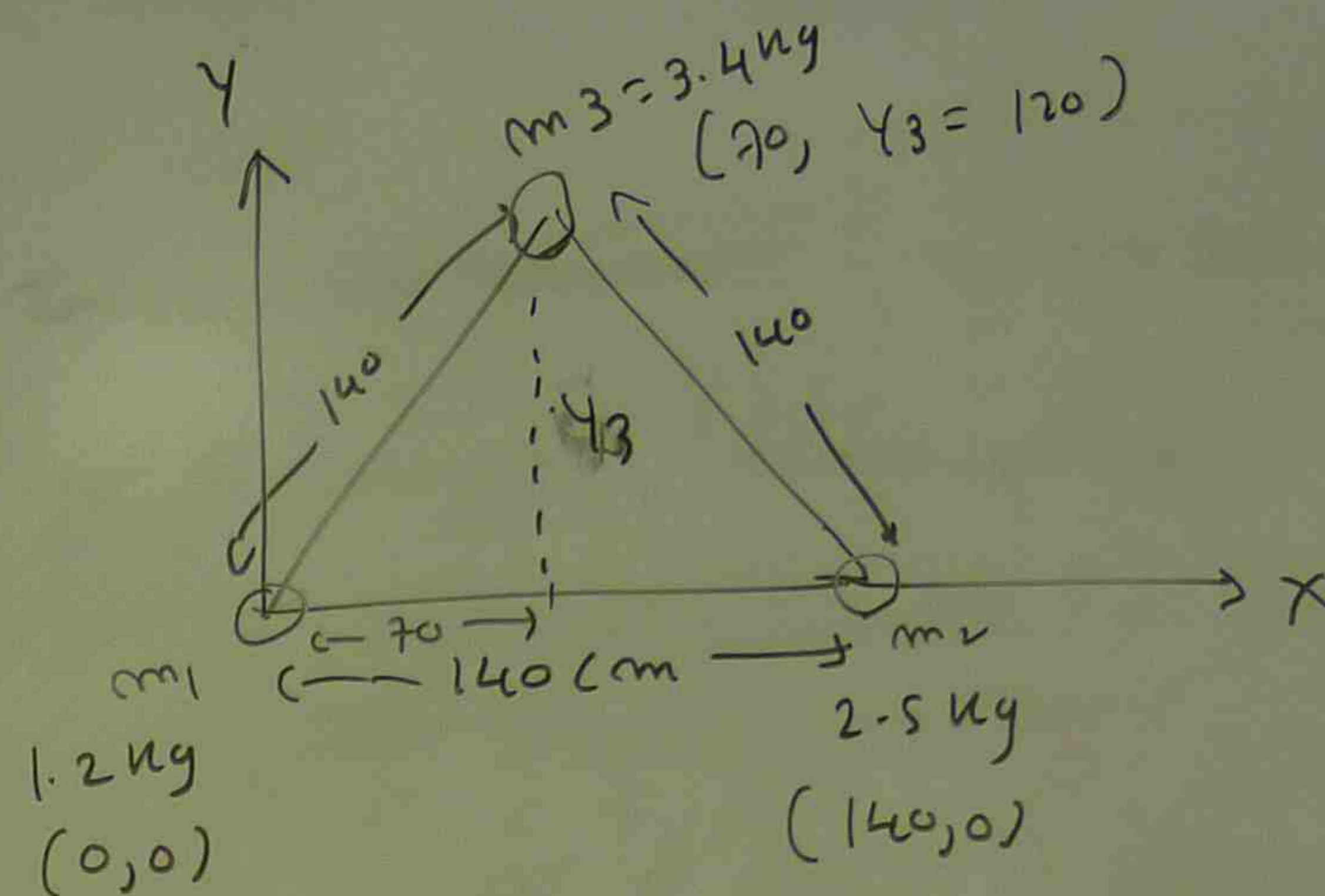
+ f₃

2 + f₃x₃

+ f₃

1y

PD THREE PARTICLES OF MASSES $m_1 = 1.2 \text{ kg}$, $m_2 = 2.5 \text{ kg}$ AND $m_3 = 3.4 \text{ kg}$ FORM AN EQUILATERAL TRIANGLE OF EDGE LENGTH $a = 140 \text{ cm}$. WHERE IS THE CENTRE OF MASS OF THIS SYSTEM?



$$y_3 = \sqrt{140^2 - 70^2} = 120$$

$$X_T = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3}{m_1 + m_2 + m_3}$$

$$= \frac{1.2 \times 0 + 2.5 \times 140 + 3.4 \times 70}{1.2 + 2.5 + 3.4}$$

$$= 83 \text{ cm}$$

$$Y_T = \frac{m_1 y_1 + m_2 y_2 + m_3 y_3}{m_1 + m_2 + m_3}$$

$$= \frac{1.2 \times 0 + 2.5 \times 0 + 3.4 \times 120}{1.2 + 2.5 + 3.4}$$

$$= 58 \text{ cm}$$

PD

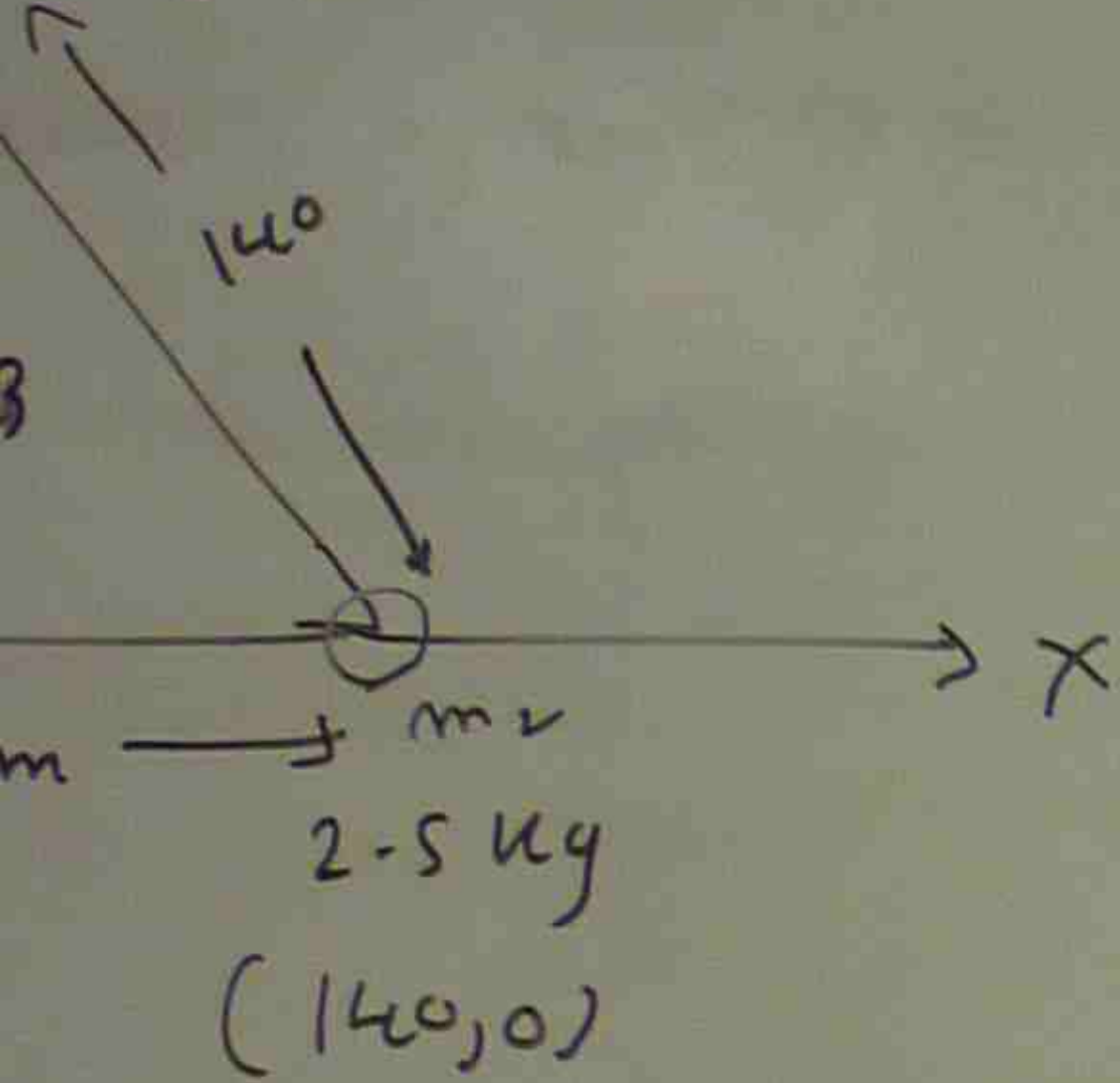
THE F
A DIS
CO+OR



$\bar{X}_T =$

$$m_3 = 3.4 \text{ kg}$$

$$(x_3, y_3 = 120)$$



$$m_2 x_2 + m_3 x_3$$

$$m_2 + m_3$$

$$2.5 \times 140 + 3.4 \times 70$$

$$.5 + 3.4$$

$$m_2 y_2 + m_3 y_3$$

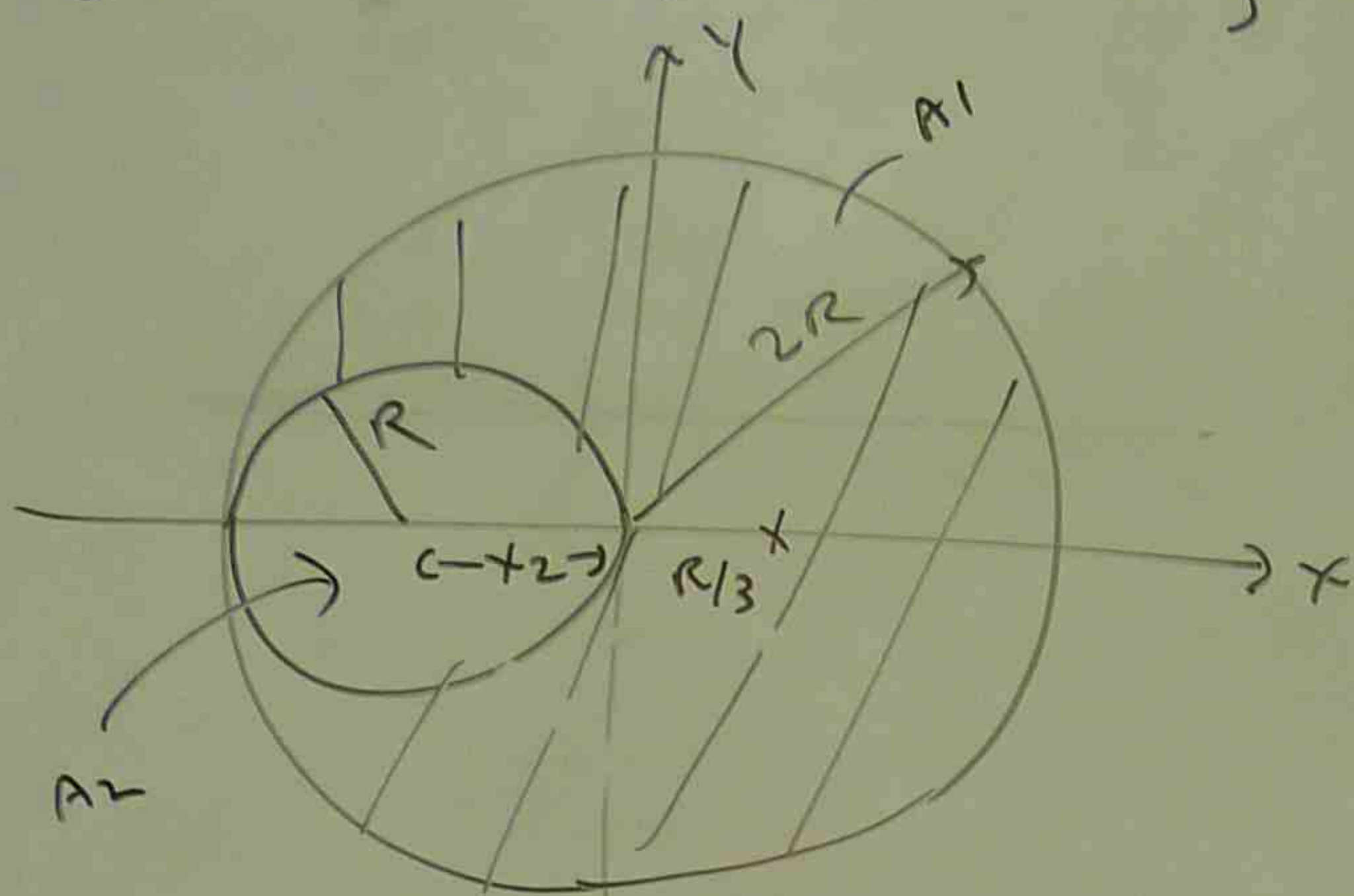
$$m_2 + m_3$$

$$2.5 \times 0 + 3.4 \times 120$$

$$2.5 + 3.4$$

pb

THE FIGURE SHOWS A UNIFORM METAL PLATE "P" OF RADIUS $(2R)$ FROM WHICH A DISK OF RADIUS R HAS BEEN STAMPED OUT. USING THE $x-y$ COORDINATE SYSTEM SHOWN, LOCATE THE CENTRE OF MASS OF THE PLATE.



$$A_1 = \pi (\text{RADIUS})^2$$

$$m_1 = A_1 \times \rho \leftarrow \text{DENSITY}$$

$$= \pi (2R)^2 \times \rho = \pi \times 4R^2 \times \rho$$

$$x_1 = 0, y_1 = 0$$

$$A_2 = \pi (\text{RADIUS})^2 = \pi (R)^2 = \pi R^2$$

$$m_2 = A_2 \times \rho = \pi R^2 \rho$$

$$x_2 = -R, y_2 = 0$$

$$\bar{x}_T = \frac{m_1 x_1 - m_2 x_2}{m_1 - m_2} = \frac{\pi 4R^2 \rho \times 0 - \pi R^2 \rho (-R)}{\pi \times 4R^2 \rho - \pi R^2 \rho}$$

$$= \frac{+ \pi R^3 \rho}{3\pi R^2 \rho} = \frac{R}{3}$$

$$\bar{y}_T = \frac{m_1 y_1 - m_2 y_2}{m_1 - m_2}$$

$$= \frac{\pi \times 4R^2 \times 0 - \pi R^2 \times 0}{\pi 4R^2 - \pi R^2}$$

$$= \frac{0}{3\pi R^2}$$

$$= 0$$

CENTRE OF MASS = $R/3, 0$

pb

THREE PARTICLES ARE INITIALLY AT REST. THEY EXPERIENCE A FORCE DUE TO BO. THREE PARTICLES

THE DIRECT AND THE M

$$F_2 = 12 \text{ N}$$

WHAT IS THE

FROM WHICH
X-Y
OF THE PLATE

$$\begin{aligned}\bar{y}_T &= \frac{m_1 y_1 - m_2 y_2}{m_1 - m_2} \\ &= \frac{\pi \times 4 R^2 \rho \times 0 - \pi R^2 \rho \times 0}{\pi 4 R^2 \rho - \pi R^2 \rho} \\ &= \frac{0}{3 \pi R^2 \rho} \\ &= 0\end{aligned}$$

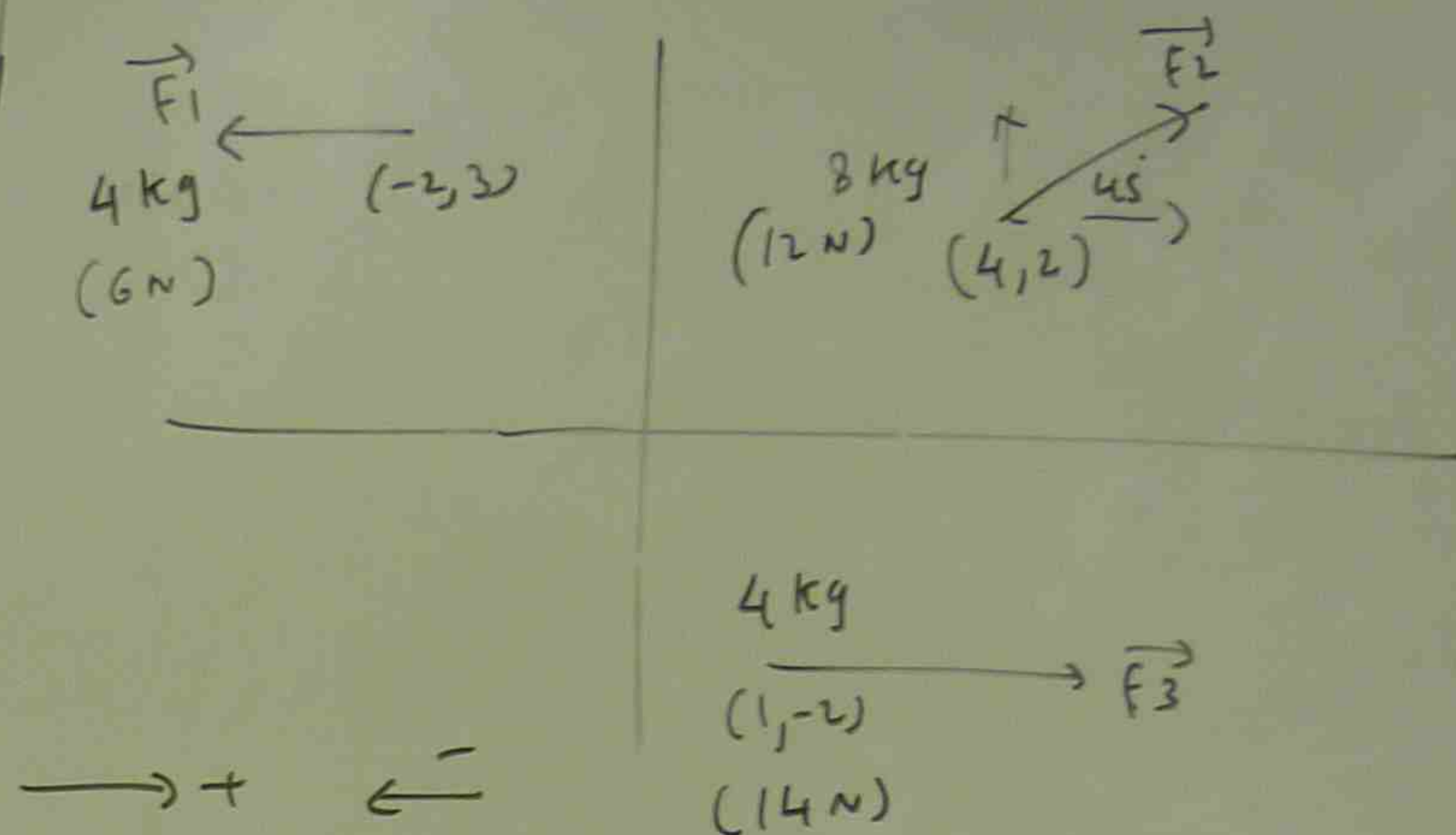
CENTRE OF MASS = $R/3, 0$

PD THREE PARTICLES IN FIGURE ARE INITIALLY AT REST. EACH EXPERIENCE THE EXTERNAL FORCE DUE TO BODIES OUTSIDE THE THREE PARTICLE SYSTEM.

THE DIRECTIONS ARE INDICATED. AND THE MAGNITUDES ARE $F_1 = 6\text{N}$, $F_2 = 12\text{N}$ AND $F_3 = 14\text{N}$.

WHAT IS THE ACCELERATION OF THE CENTRE

OF MASS OF THE SYSTEM AND IN WHAT DIRECTION DOES IT MOVE?



$$\begin{aligned}F_x &= \sum F_x = F_{1x} + F_{2x} + F_{3x} \\ &= (-6) + (F_2 \cos 45) + (F_3) \\ &= -6 + 12 \cos 45 + 14 \\ &= -6 + 12 \times 0.707 + 14 \\ &= 16.48 \text{ N}\end{aligned}$$

↑ + ↓ -

$$\begin{aligned}F_y &= \sum F_y \\ &= F_{1y} + F_{2y} + F_{3y} \\ &= 0 + F_2 \sin 45 + 0 \\ &= 12 \sin 45 = 8.48 \text{ N}\end{aligned}$$

$$\begin{aligned}F_T &= \sqrt{F_x^2 + F_y^2} \\ &= \sqrt{16.48^2 + 8.48^2} \\ &= 18.53 \text{ N}\end{aligned}$$

$$F_T = m_T \times a_T$$

$$18.53 = (m_1 + m_2 + m_3) a_T$$

$$18.53 = (4 + 8 + 4) a_T$$

$$18.53 = 16 a_T$$

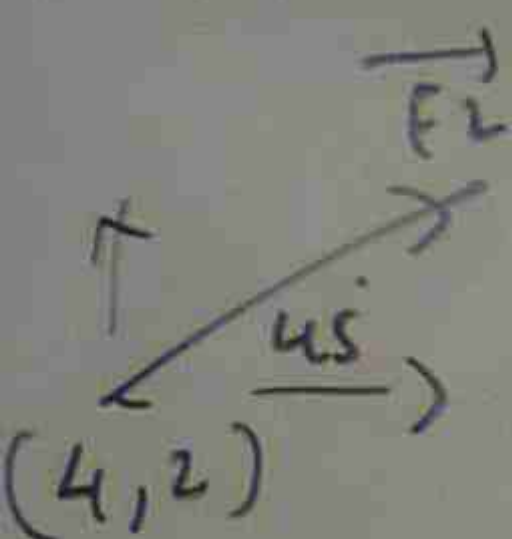
$$a_T = \frac{18.53}{16} = 1.15$$

$$x_T = \frac{F_{1x} x_1 + F_{2x} x_2}{F_{1x} + F_{2x} + F_{3x}}$$

$$= \frac{(-6) \times (-2) + 12 \times 4}{-6 + 12 + 14}$$

$$= \frac{12 + 48}{20} = 3$$

IN WHAT DIRECTION DOES IT MOVE?



$$F_T = \sqrt{F_x^2 + F_y^2}$$

$$= \sqrt{16.48^2 + 8.48^2}$$

$$= 18.53 \text{ N}$$

$$F_T = m_T \times a_T$$

$$18.53 = (m_1 + m_2 + m_3) a_T$$

$$18.53 = (4 + 8 + 4) a_T$$

$$18.53 = 16 a_T$$

$$a_T = \frac{18.53}{16} = 1.158 \text{ m/s}^2$$

$$x_T = \frac{F_{1x}x_1 + F_{2x}x_2 + F_{3x}x_3}{F_{1x} + F_{2x} + F_{3x}}$$

$$= \frac{(-6) \times (-2) + 12 \cos 45^\circ \times 4 + 14(1)}{-6 + 12 \cos 45^\circ + 14}$$

$$= \frac{12 + 8.48 + 14}{-6 + 8.48 + 14} = \frac{34.48}{16.48} = 2.09$$

$$y_T = \frac{F_{1y}y_1 + F_{2y}y_2 + F_{3y}y_3}{F_{1y} + F_{2y} + F_{3y}}$$

$$= \frac{0 \times 3 + 12 \sin 45^\circ \times 2 + 0 \times (-2)}{0 + 12 \sin 45^\circ + 0}$$

$$= \frac{12 \sin 45^\circ \times 2}{12 \sin 45^\circ}$$

$$= 2$$

DIRECTION $\begin{cases} x = 2.09 \\ y = 2 \end{cases}$

$$\theta = \tan^{-1} \frac{y}{x}$$

$$= \tan^{-1} \frac{2}{2.09}$$

$$= \tan^{-1} 0.956$$

$$= 43.7^\circ$$

$$F_1 + F_2 + F_3$$

$$F_1 + F_2 + F_3$$

$$3 + 12 \sin 45 \times 2 + 0 \times (-2)$$

$$0 + 12 \sin 45 + 0$$

$$12 \sin 45 \times 2$$

$$12 \sin 45$$

$$2$$

$$\text{DIRECTION } (x = 2.09)$$

$$y = 2$$

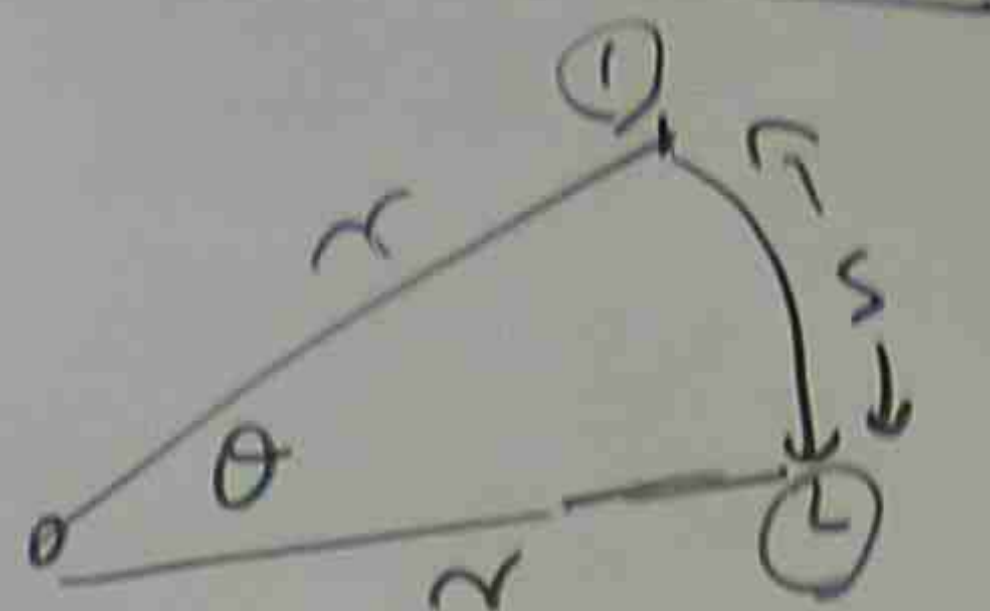
$$\theta = \tan^{-1} \frac{y}{x}$$

$$= \tan^{-1} \frac{2}{2.09}$$

$$= \tan^{-1} 0.956$$

$$= 43.7^\circ$$

ROTATION



$r = \text{RADIUS}$

$s = \text{ANGULAR PATH}$

$$1 \text{ REVOLUTION} = 360^\circ = 2\pi \text{ RADIANS}$$

$$1 \text{ RADIANS} = \frac{1}{2\pi} = 0.159 \text{ REVOLUTION}$$

$$\text{ANGULAR VELOCITY} = \omega = \frac{\Delta \theta}{\Delta t} = \frac{\theta_2 - \theta_1}{t_2 - t_1}$$

$$\omega_2 = \omega_1 + \alpha \Delta t$$

$\alpha = \text{ANGULAR ACCELERATION (RAD S}^{-2}\text{)}$

$$\omega = \text{ANGULAR VELOCITY} \frac{1}{\text{RAD} \times \text{S}}$$

$$\alpha = \frac{\omega_2 - \omega_1}{\Delta t}$$

$$\text{ANGULAR DISPLACEMENT } s = \omega_1 t + \frac{1}{2} \alpha t^2$$

pb

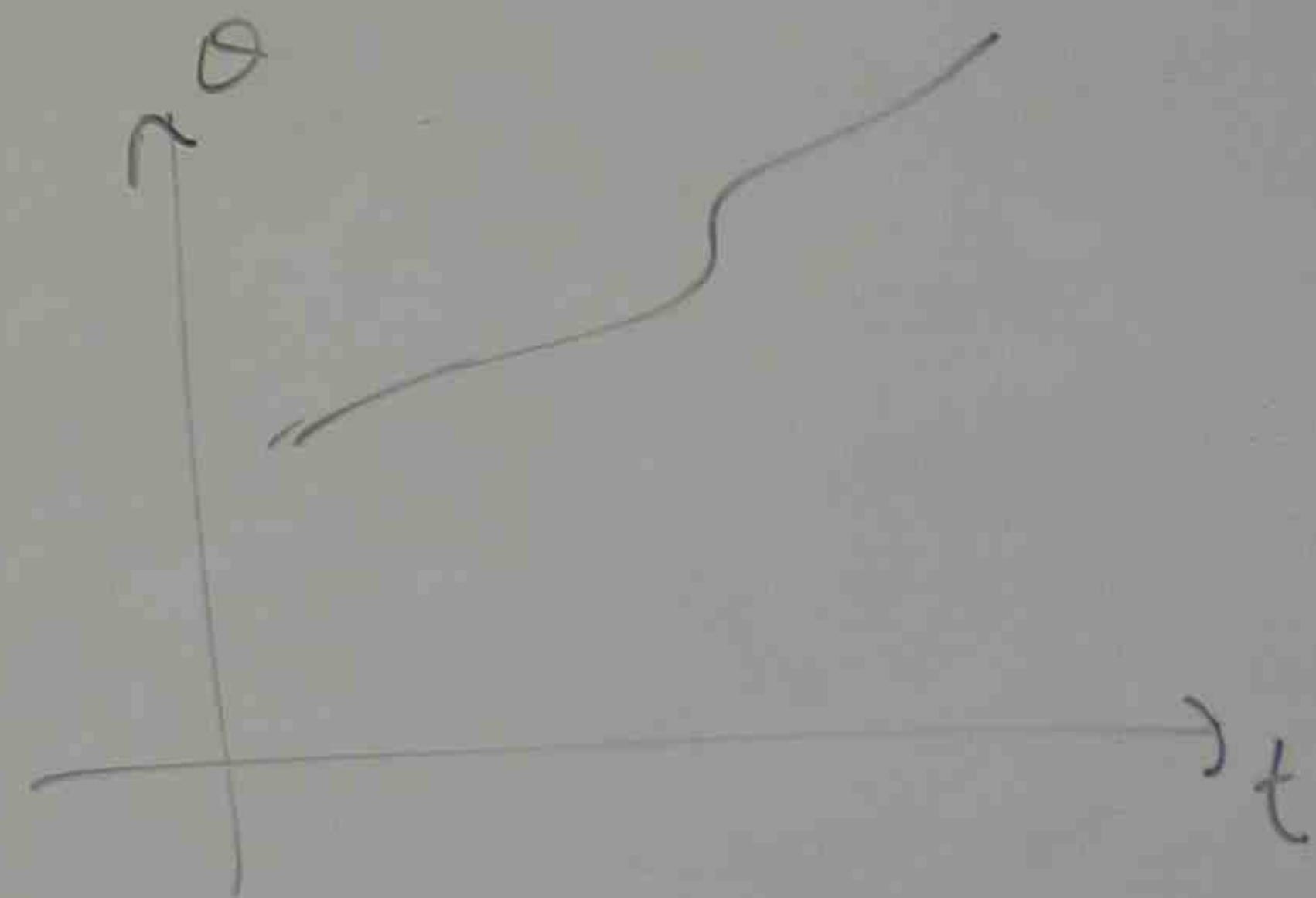
THE ANGULAR POSITION $\theta(t)$ OF A REFERENCE LINE ON THE DISK IS GIVEN BY

$$\theta = -1 - 0.6t + 0.250t^2$$

(a) GRAPH THE ANGULAR POSITION OF THE DISK VERSUS TIME (-3 TO 5.4 SEC)

(b) AT WHAT TIME DOES $\theta(t)$ REACH MINIMUM VALUE?
WHAT IS THE MINIMUM VALUE?

$$\begin{aligned} \text{(a)} \quad \theta(-3) &= -1 - 0.6(-3) + 0.25(-3)^2 \\ \theta(-2) &= -1 - 0.6(-2) + 0.25(-2)^2 \\ \theta(-1) &= -1 - 0.6(-1) + 0.25(-1)^2 \\ \theta(0) &= -1 - 0.6(0) + 0.25(0)^2 \\ &\quad \downarrow \\ &\quad (5.4) \end{aligned}$$



$$\text{(b)} \quad \text{minimum} \quad \frac{d\theta}{dt} = 0 \rightarrow t = ?$$

$$\theta = -1 - 0.6t + 0.25t^2$$

$$\frac{d\theta}{dt} = \frac{d}{dt}(-1) - \frac{d}{dt}(0.6t) + \frac{d}{dt}(0.25t^2)$$

REFERENCE LINE ON THE

of THE DISK VERSUS TIME (-3 TO 5.4 SEC)

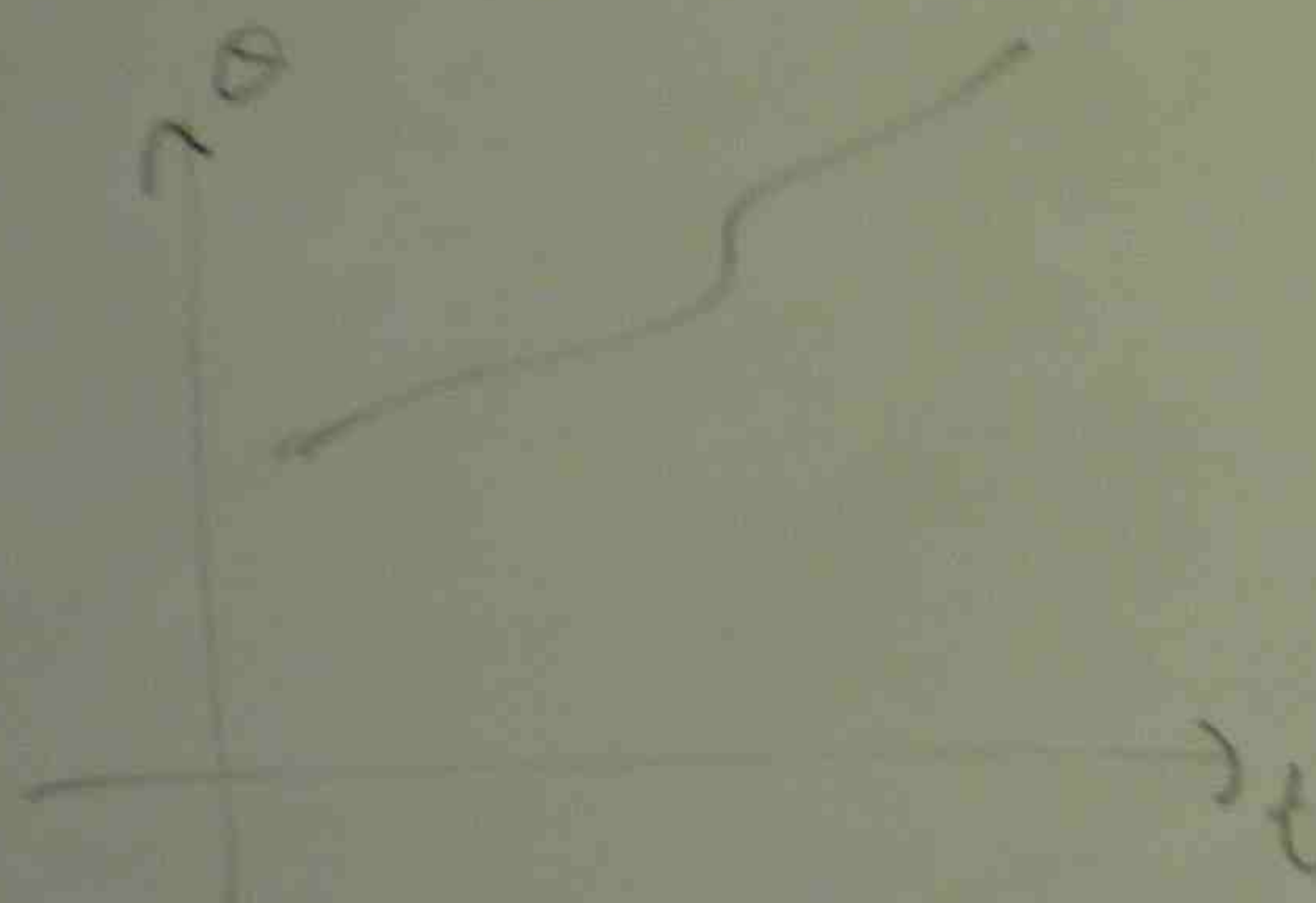
REACH MINIMUM VALUE?
LINE?

$$0.25(-3)^2$$

$$0.25(-2)^2$$

$$0.25(-1)^2$$

$$0.25(0)^2$$



→ t = ?

$$0.25t^2$$

$$t(0.5t) + \frac{d}{dt}(0.25t^2)$$

$$\frac{d\theta}{dt} = 0 - 0.6 + 0.25 \times 2t^{2-1}$$

$$\frac{d\theta}{dt} = -0.6 + 0.5t$$

$$0 = -0.6 + 0.5t$$

$$0.5t = 0.6$$

$$t = \frac{0.6}{0.5} = 1.2 \text{ sec}$$

$$\theta = -1 - 0.6t + 0.25t^2$$

$$= -1 - 0.6(1.2) + 0.25 \times (1.2)^2$$

$$= -1.36 \text{ RAD}$$

$$180^\circ = \pi \text{ Radian}$$

$$\pi = 3.14 \text{ RAD} \rightarrow 180^\circ$$

$$\frac{-1.36}{3.14} = 180^\circ \times \frac{(-1.36)}{3.14}$$

$$= -77.9^\circ$$

ph

A GRIND

$$\alpha = 0.3$$

$$\omega_0 = -4$$

AT THE M

(a) AT

AT

(n) 3

(c) R

$$(a) \theta_0 =$$

ce

$$10\pi$$

$$31.4$$

$$0.175t^2$$

$$Ax^2$$

$$x =$$

ph

A GRIND STONE ROTATES AT A CONSTANT ANGULAR ACCELERATION
 $\alpha = 0.35 \text{ RAD/S}^2$ AT TIME $t = 0$, IT HAS ANGULAR VELOCITY
 $\omega_0 = -4.6 \text{ RAD/S}$ AND A REFERENCE LINE ON IT IS HORIZONTAL
 AT THE ANGULAR POSITION $\theta_0 = 0$.

- (a) AT WHAT TIME AFTER $t = 0$, IS THE REFERENCE LINE
 AT AN ANGULAR POSITION $\theta = 5 \text{ REV}$
 (b) DESCRIBE THE ROTATION BETWEEN $t = 0$ & $t = 32 \text{ SEC}$
 (c) AT WHAT TIME t , DOES THE GRIND STONE MOMENTARILY
 STOP?

(a) $\theta_0 = 0$, $\theta = 5 \text{ REV} = 5 \times 2\pi \text{ RAD} = 10\pi$
 $\theta = \omega_0 t + \frac{1}{2} \alpha t^2$

$10\pi = (-4.6)t + \frac{1}{2} \times 0.35 \times t^2$

$31.4 = -4.6t + 0.175t^2$

$0.175t^2 - 4.6t - 31.4 = 0$

$Ax^2 + Bx + C = 0$

$x = \frac{-B \pm \sqrt{B^2 - 4AC}}{2A}$

$t = \frac{-(-4.6) \pm \sqrt{(-4.6)^2 - 4 \times 0.175 \times (-31.4)}}{2 \times 0.175}$

$= 32 \text{ SEC}$

(b) $t = 0 \rightarrow$

$\alpha =$

DECE

(c) $\omega_0 = -$

$\omega =$

$t = ?$

$t = \frac{\omega - \omega_0}{\alpha}$

$2t^{2-1}$

$(1.2)^2$

180

$= \frac{180 \times (-1.36)}{3.14}$

$= -77.9$

STONE ROTATES AT A CONSTANT ANGULAR ACCELERATION
 RAD/S^2 AT TIME $t=0$, IT HAS ANGULAR VELOCITY
 RAD/S AND A REFERENCE LINE ON IT IS HORIZONTAL
 ANGULAR POSITION $\theta_0 = 0$.

WHAT TIME AFTER $t=0$, IS THE REFERENCE LINE
 ANGULAR POSITION $\theta = 5 \text{ REV}$
 DESCRIBE THE ROTATION BETWEEN $t=0$ & $t=32 \text{ SEC}$
 WHAT TIME t , DOES THE GRIND STONE MOMENTARILY
 STOP?

$$\theta = 5 \text{ REV} = 5 \times 2\pi \text{ RAD} = 10\pi$$

$$\omega_0 t + \frac{1}{2} \alpha t^2$$

$$(-4.6)t + \frac{1}{2} \times 0.35 \times t^2$$

$$= -4.6t + 0.175t^2$$

$$-4.6t - 31.4 = 0$$

$$Bx + C = 0$$

$$\frac{-B \pm \sqrt{B^2 - 4AC}}{2A}$$

$$2A$$

$$t = \frac{-(-4.6) \pm \sqrt{(-4.6)^2 - 4 \times 0.175 \times (-31.4)}}{2 \times 0.175}$$

$$= 32 \text{ SEC}$$

$$(b) t=0 \rightarrow t=32$$

$$\alpha = -4.6 \text{ RAD/S}^2$$

DECELERATION

$$(c) \omega_0 = -4.6$$

$$\omega = 0$$

$$t = ?$$

$$t = \frac{\omega - \omega_0}{\alpha} = \frac{0 - (-4.6)}{0.35}$$

$$= \frac{4.6}{0.35}$$

$$= 13 \text{ SEC}$$

OF MASS OF THE SYS

$$\vec{F}_1 \leftarrow (-2, 3)$$

4 kg
(6N)

$$\rightarrow + \leftarrow -$$

$$F_x = \sum F_x$$

$$= (-6)$$

$$= -6$$

$$= -6$$

$$= 16$$

$$\uparrow + \downarrow -$$

$$F_y = \sum$$

$$=$$

$$=$$

$$=$$