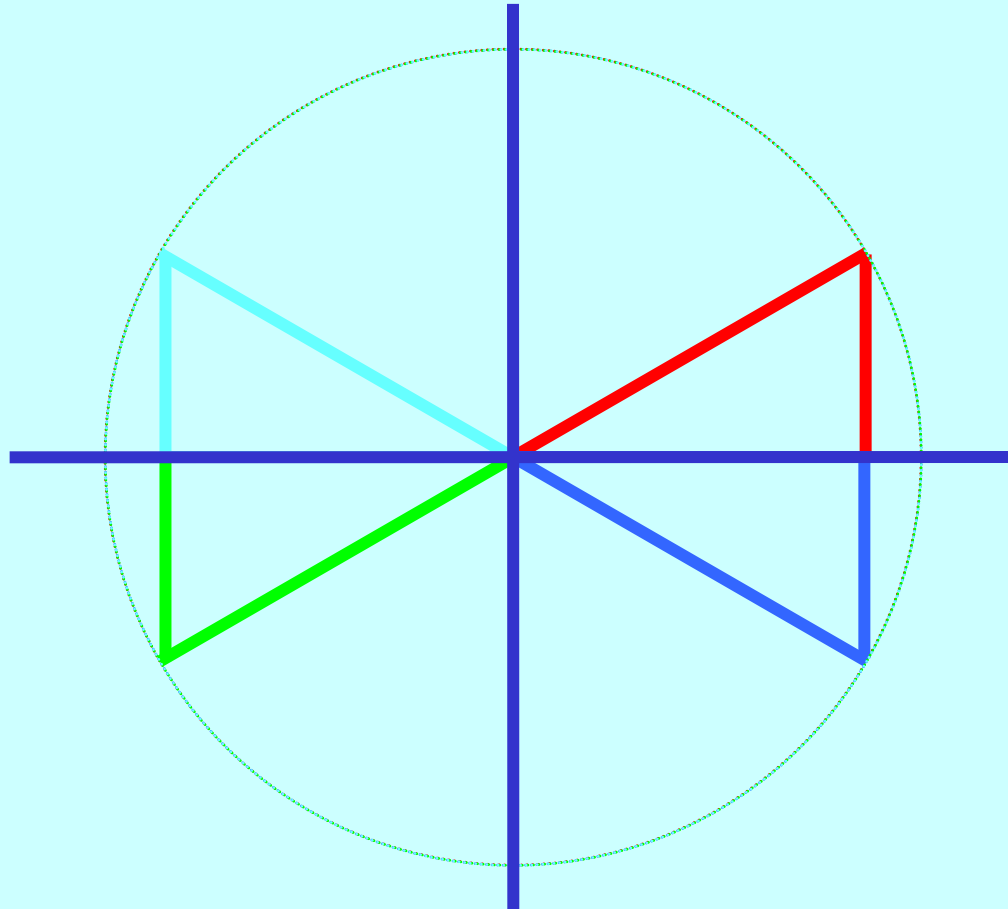


**UEENEEEG102A**

**Solve problems in  
low voltage a.c. circuits**

**Trigonometry**

# Trigonometry

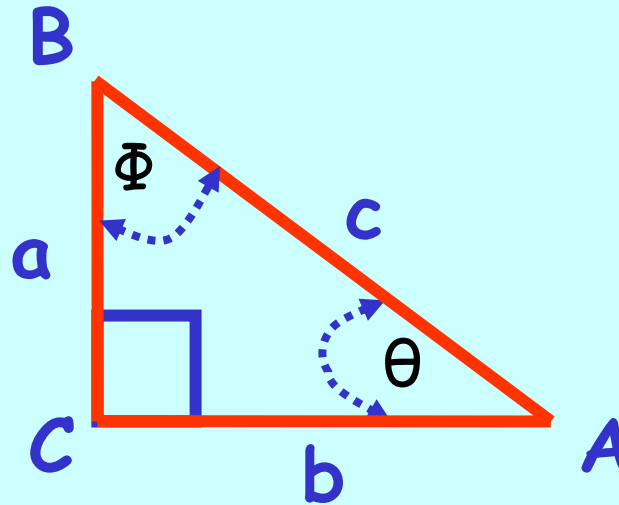


# Objectives:

At the end of this lesson students should be able to:

1. State and apply the Sine, Cosine and Tangent ratios of a right-angle triangle.
2. Use a calculator to find the Sine, Cosine and Tangent of any angle.
3. Apply Pythagoras' Theorem to a right-angle triangle.

# The Right Angle Triangle



$$\angle A = \angle CAB = \theta$$

$$\text{Side } BC = a$$

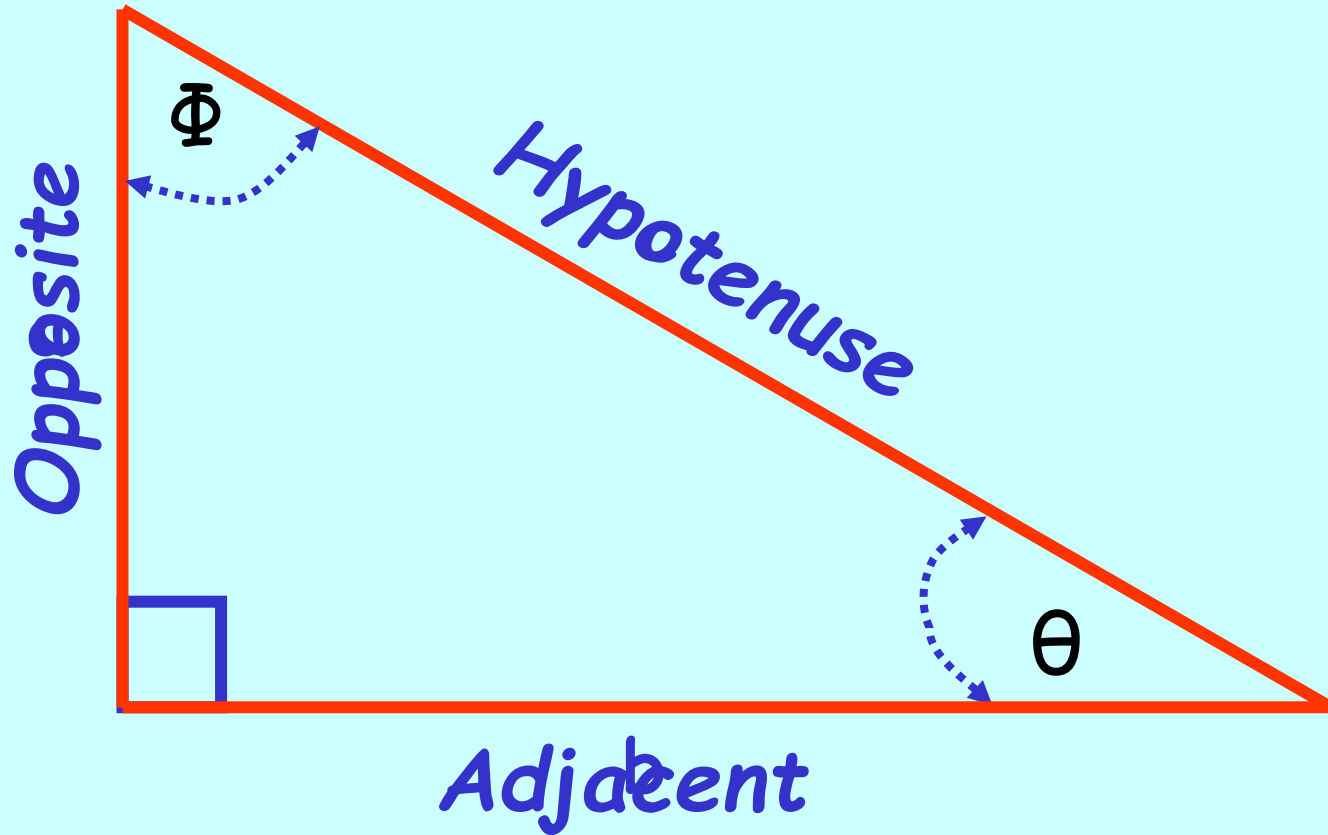
$$\angle B = \angle ABC = \Phi$$

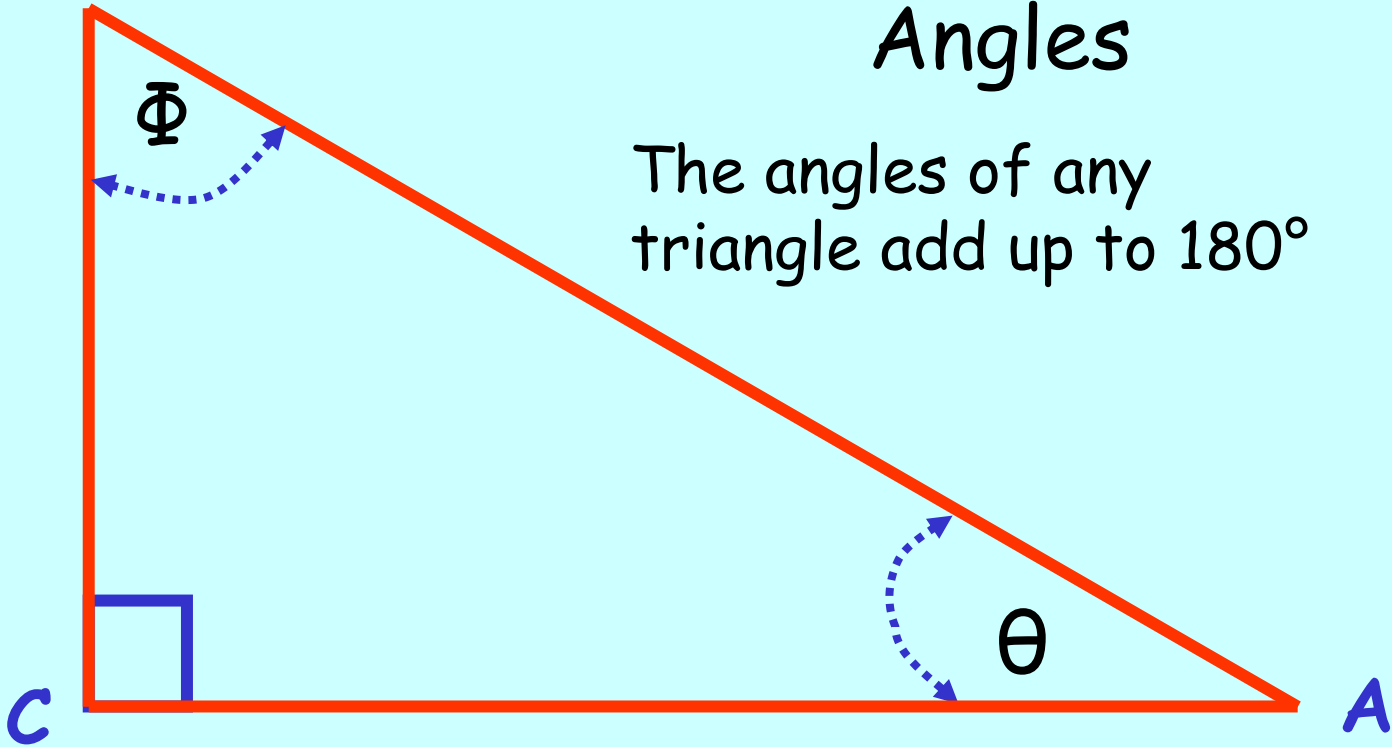
$$\text{Side } CA = b$$

$$\angle C = \angle BCA = 90^\circ$$

$$\text{Side } AB = c$$

# Names of Sides



**B**

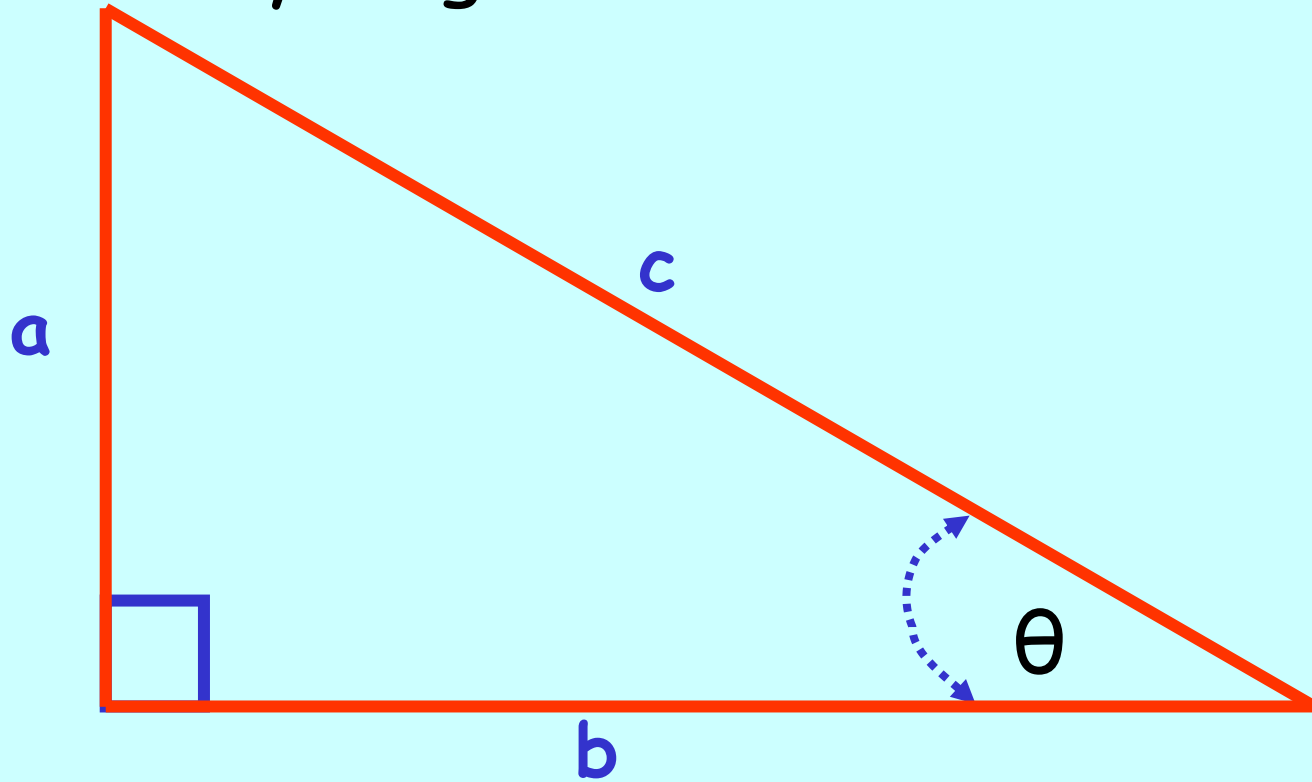
# Angles

The angles of any triangle add up to  $180^\circ$

$$\angle A + \angle B + \angle C = 180$$

$$\theta + \Phi = 90^\circ$$

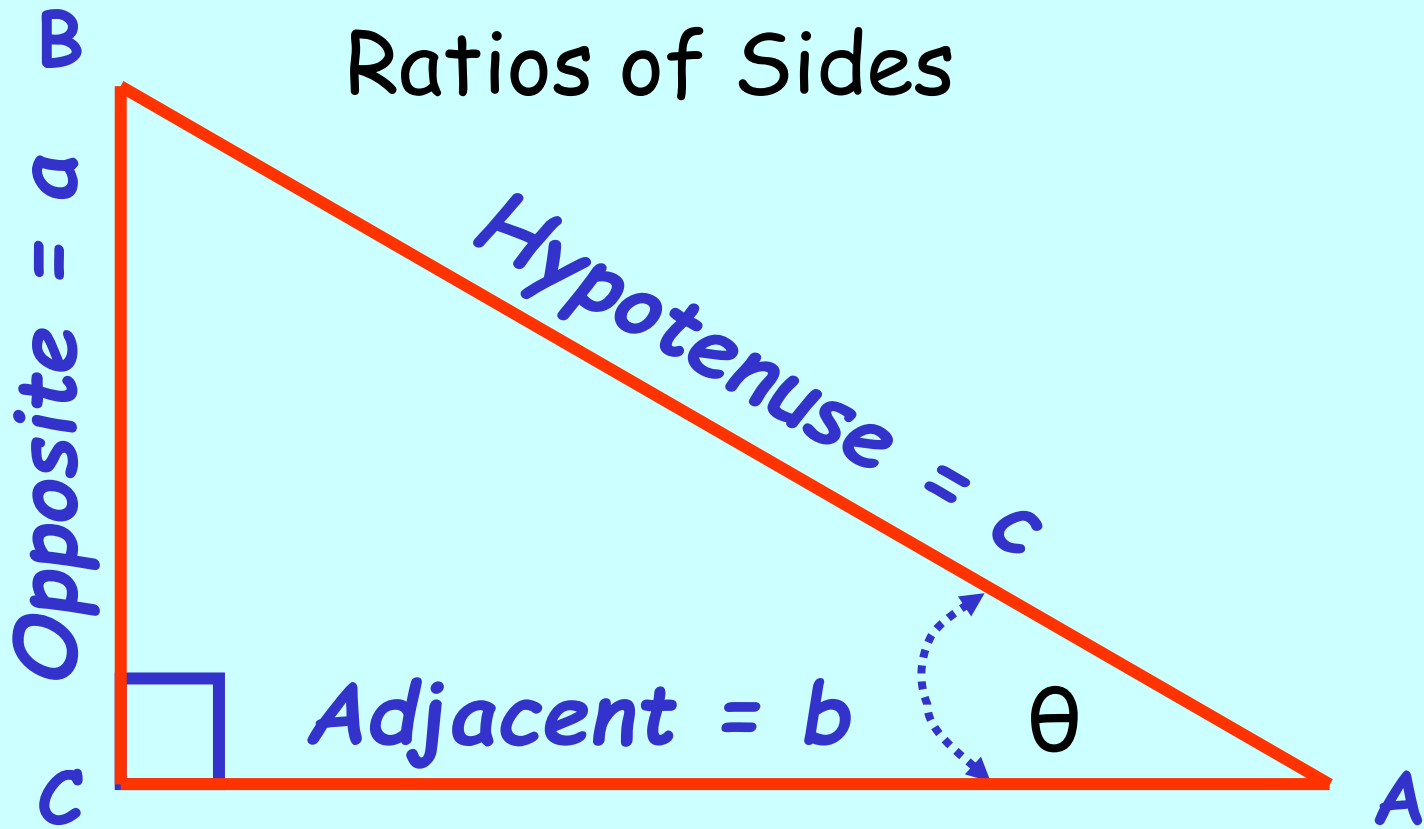
# Pythagoras' Theorem



The square on the Hypotenuse is equal to the sum of the squares on the other two sides ....

$$c^2 = a^2 + b^2$$

# Ratios of Sides



$$\sin \theta = \frac{\text{Opp}}{\text{Hyp}}$$

$$\sin \theta = \frac{a}{c}$$

$$\cos \theta = \frac{\text{Adj}}{\text{Hyp}}$$

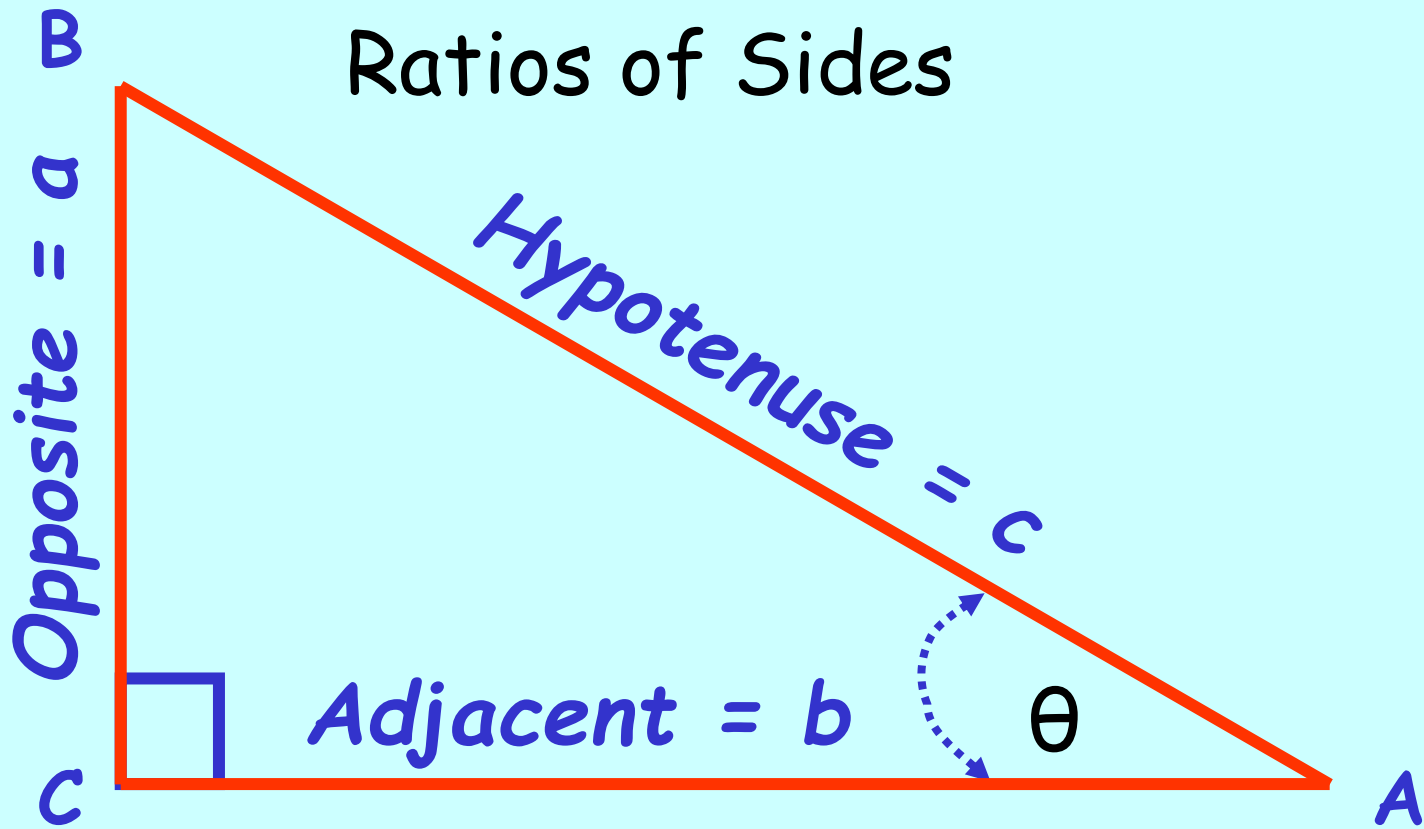
$$\cos \theta = \frac{b}{c}$$

$$\tan \theta = \frac{\text{Opp}}{\text{Adj}}$$

$$\tan \theta = \frac{a}{b}$$



# Ratios of Sides



$$\sin \theta = \frac{\text{Opp}}{\text{Hyp}}$$

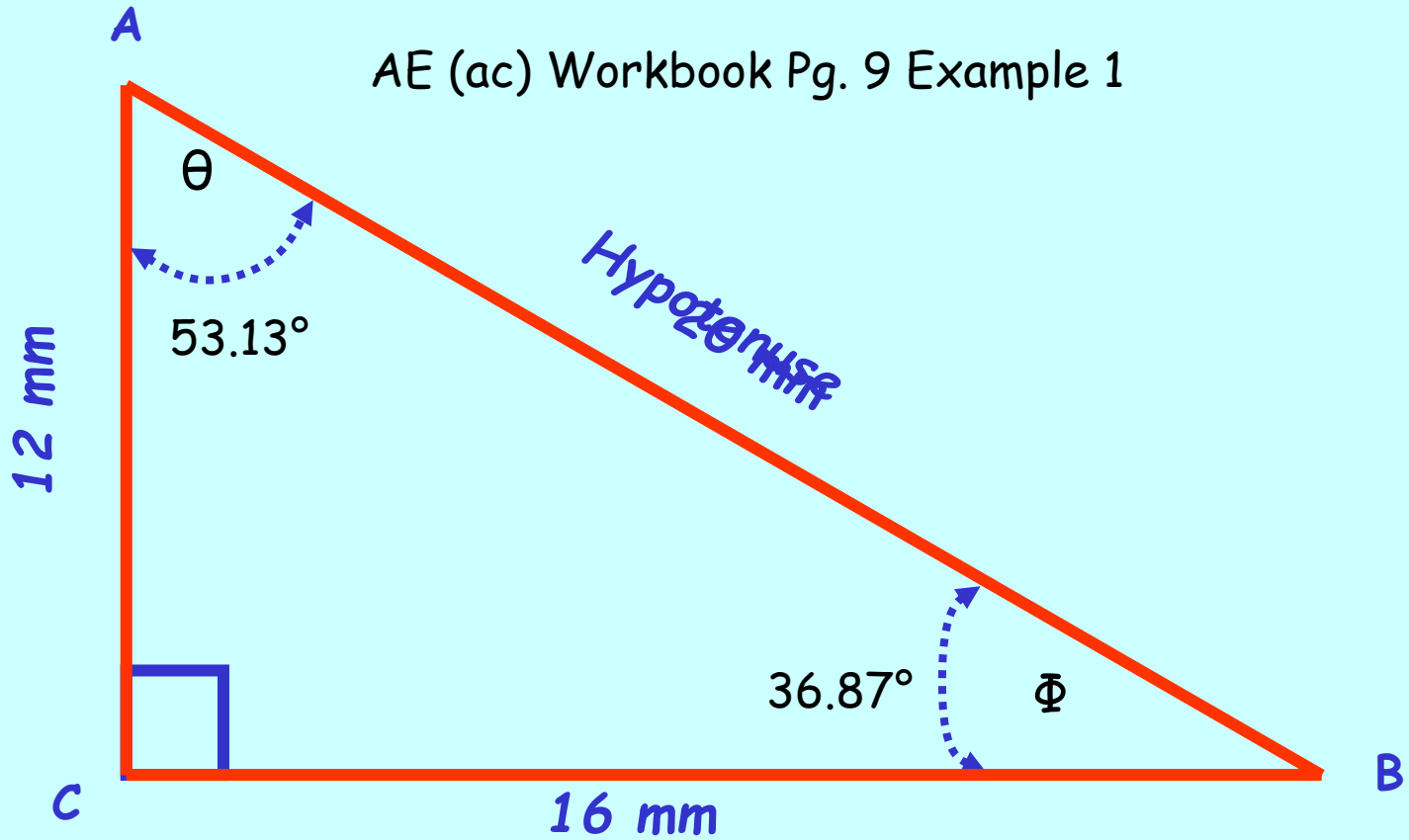
$$\cos \theta = \frac{\text{Adj}}{\text{Hyp}}$$

$$\tan \theta = \frac{\text{Opp}}{\text{Adj}}$$

SOH

SOH CAH TOA

TOA

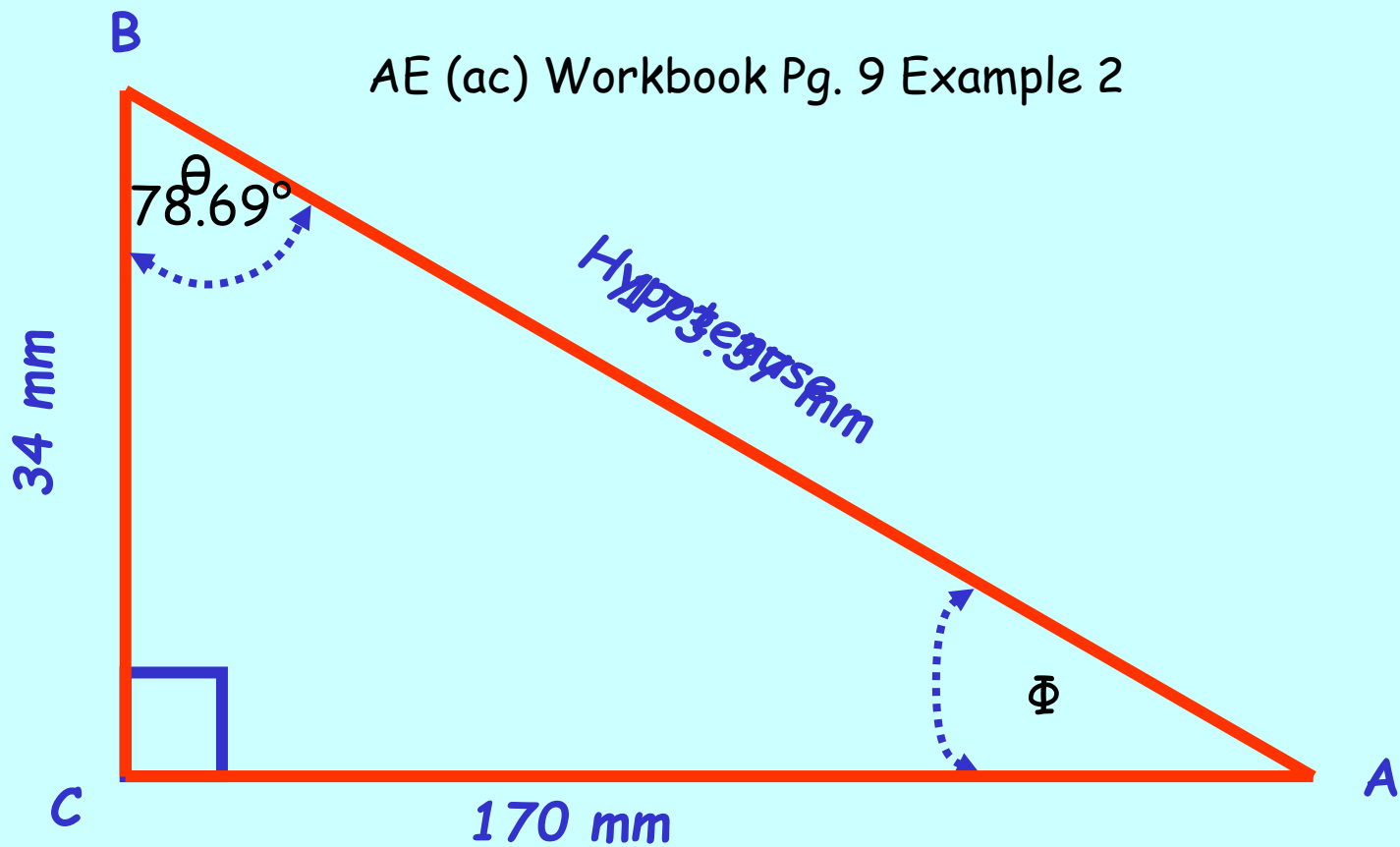


$$\theta = \cos^{-1} \frac{12}{20} = 53.13^\circ$$

$$\Phi = \sin^{-1} \frac{12}{20} = 36.87^\circ$$

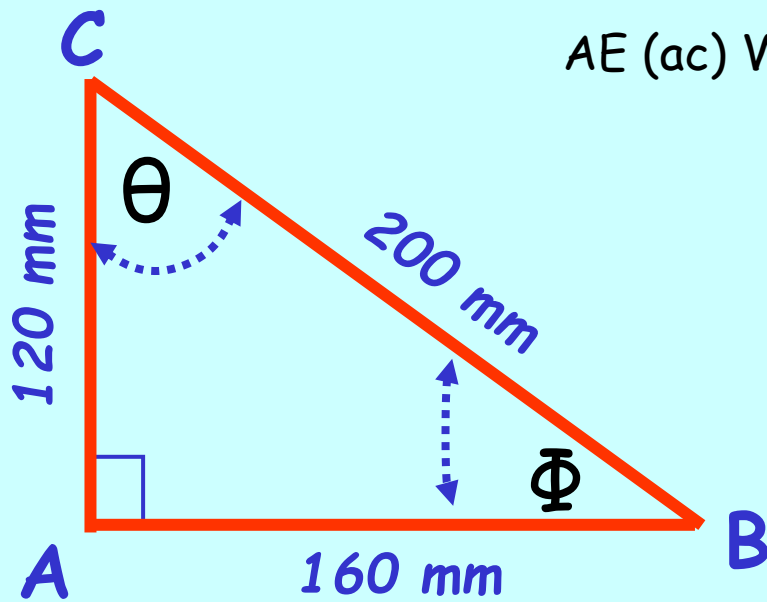
$$\Phi = 90 - 53.13 = 36.87^\circ$$

$$BC = \sqrt{20^2 - 12^2} = 16 \text{ mm}$$



$$\theta = \tan^{-1} \frac{170}{34} = 78.69^\circ$$

$$AB = \sqrt{170^2 + 34^2} = 173.37 \text{ mm}$$



$$AC = \sqrt{200^2 - 160^2} = 120 \text{ mm}$$

$$(a) \quad \sin B = \frac{120}{200} = 0.6$$

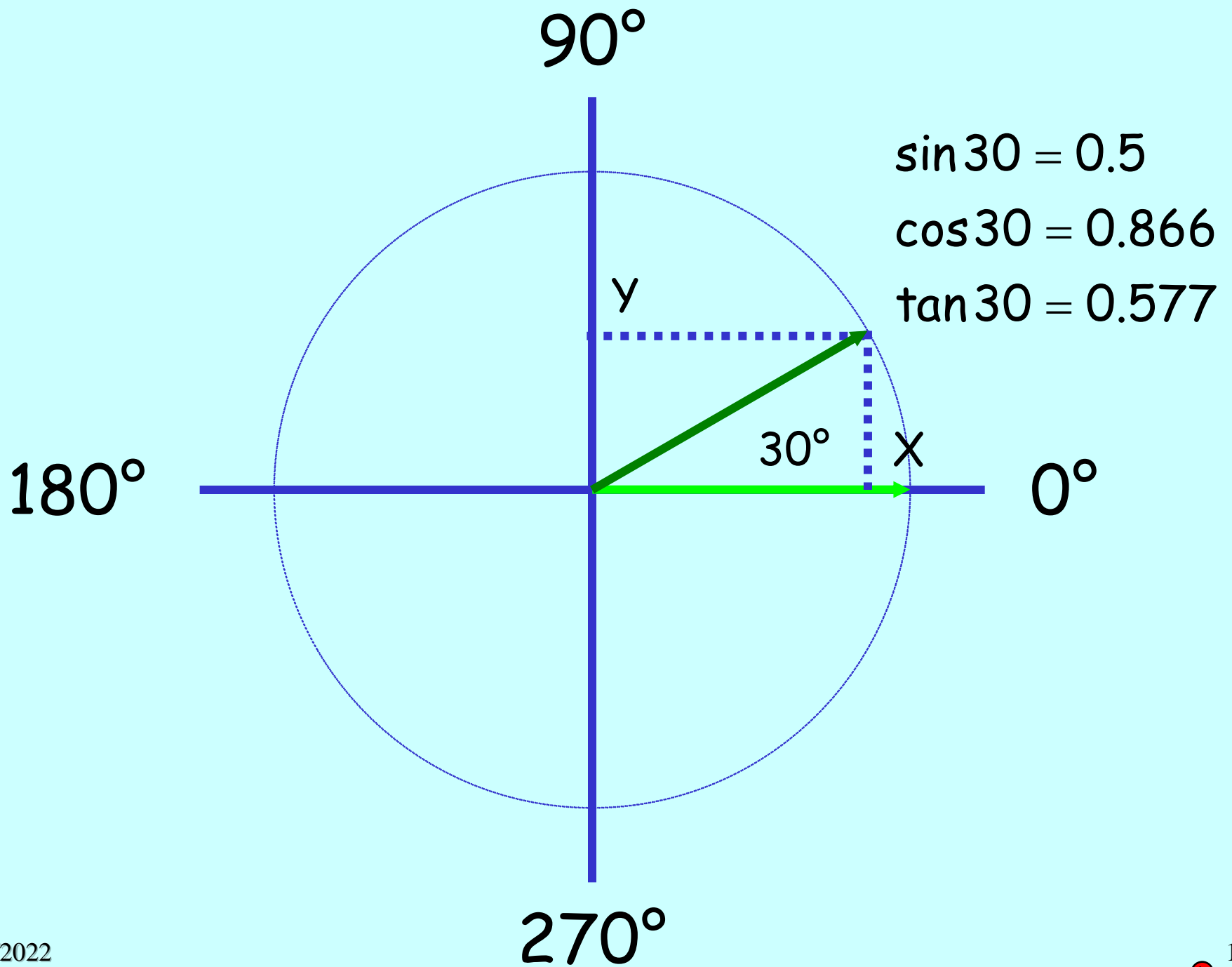
$$\cos B = \frac{160}{200} = 0.8$$

$$\tan B = \frac{120}{160} = 0.75$$

$$(b) \quad \sin C = \frac{160}{200} = 0.8$$

$$\cos C = \frac{120}{200} = 0.6$$

$$\tan C = \frac{160}{120} = 1.33$$

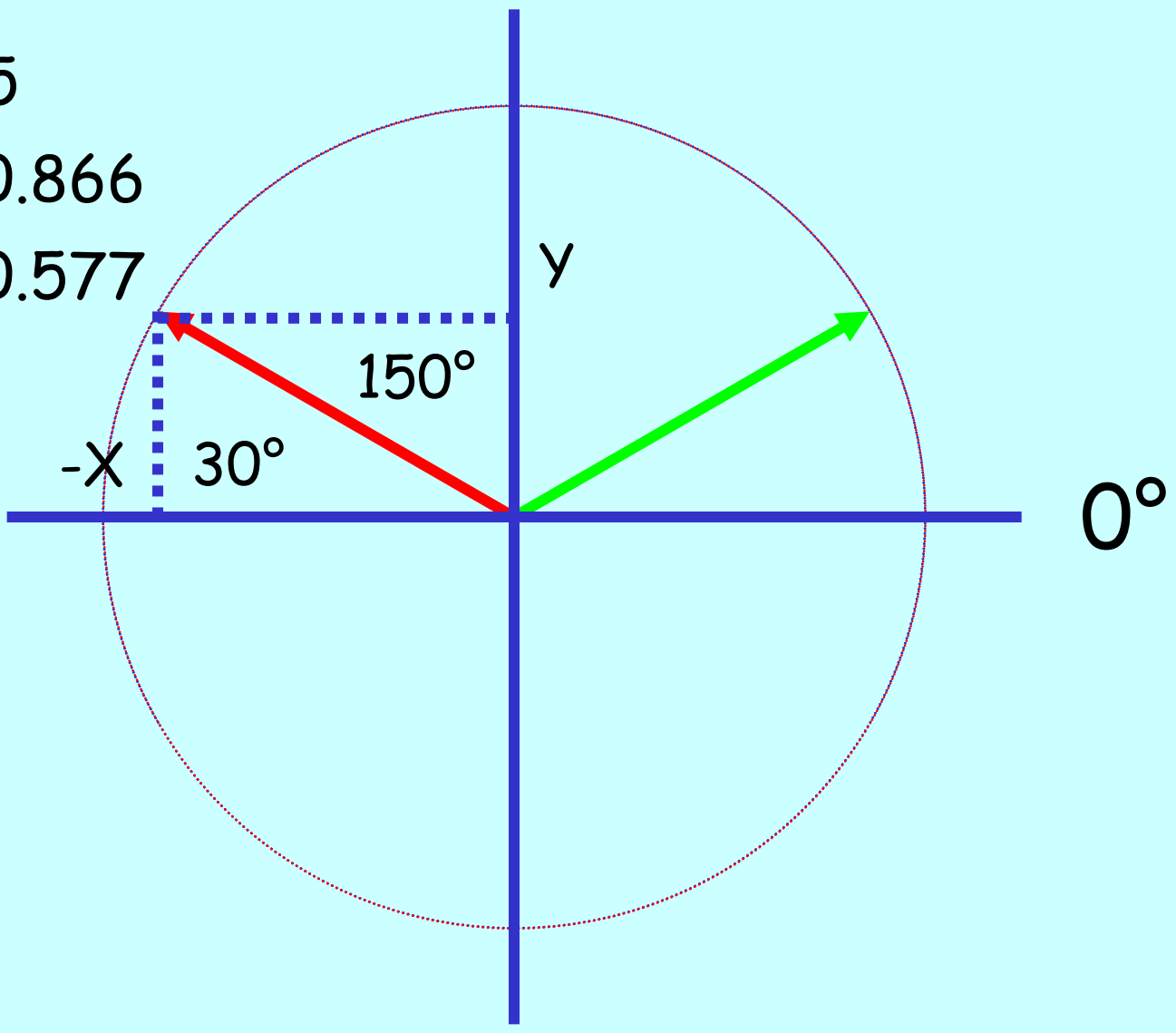


90°

$\sin 150 = 0.5$

$\cos 150 = -0.866$

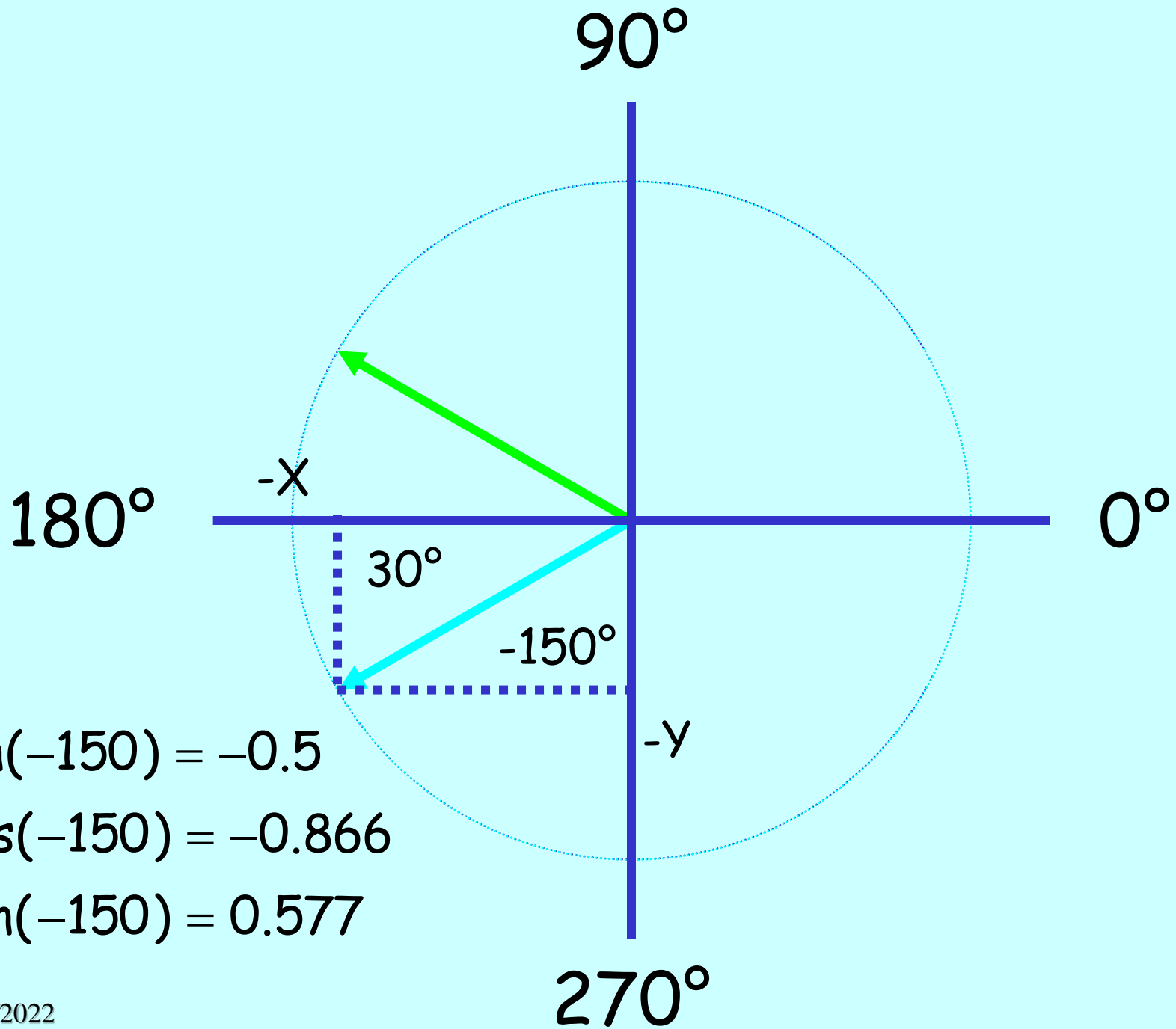
$\tan 150 = -0.577$

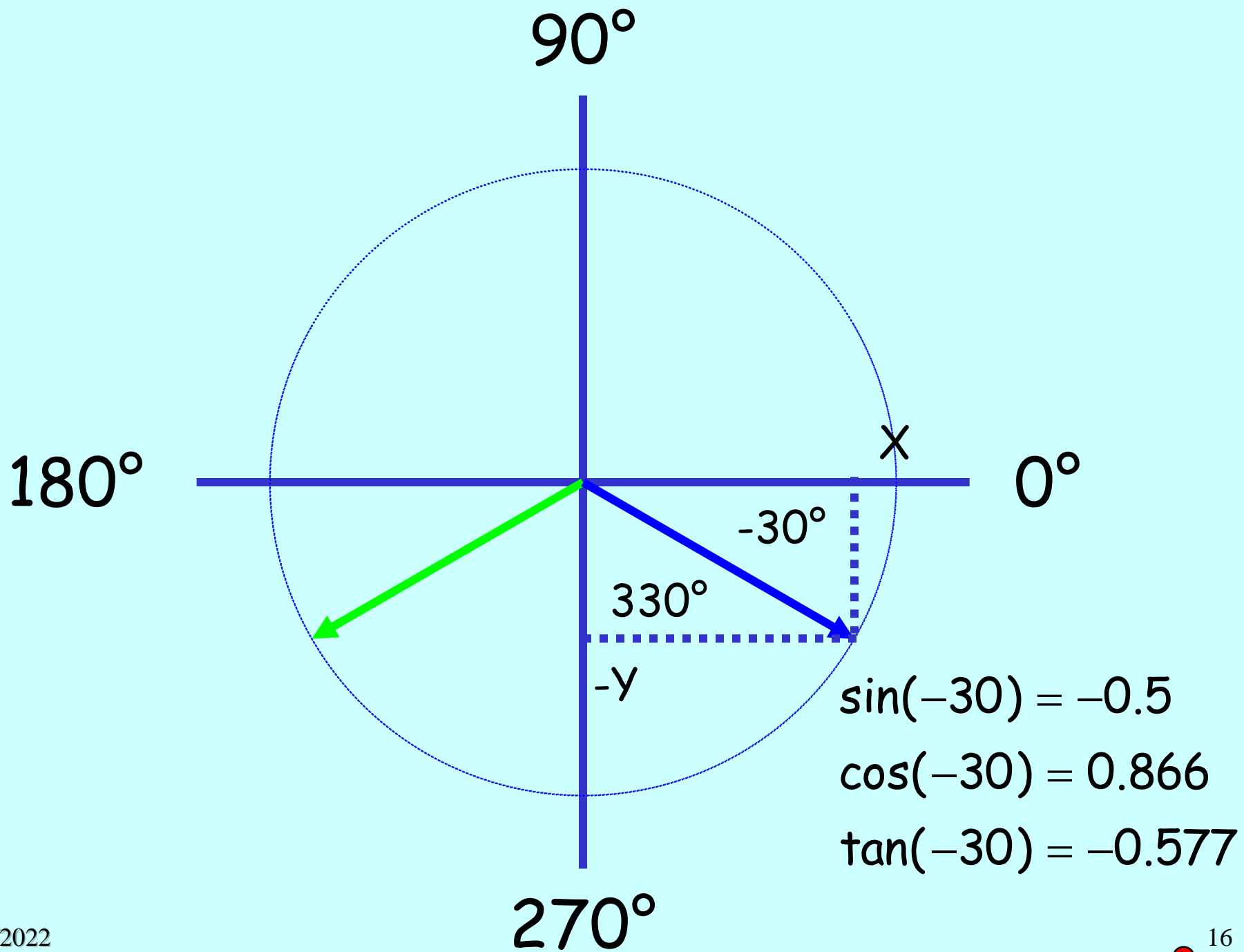


180°

0°

270°







90°

sin 30 = 0.5  
cos 30 = 0.866  
tan 30 = 0.577

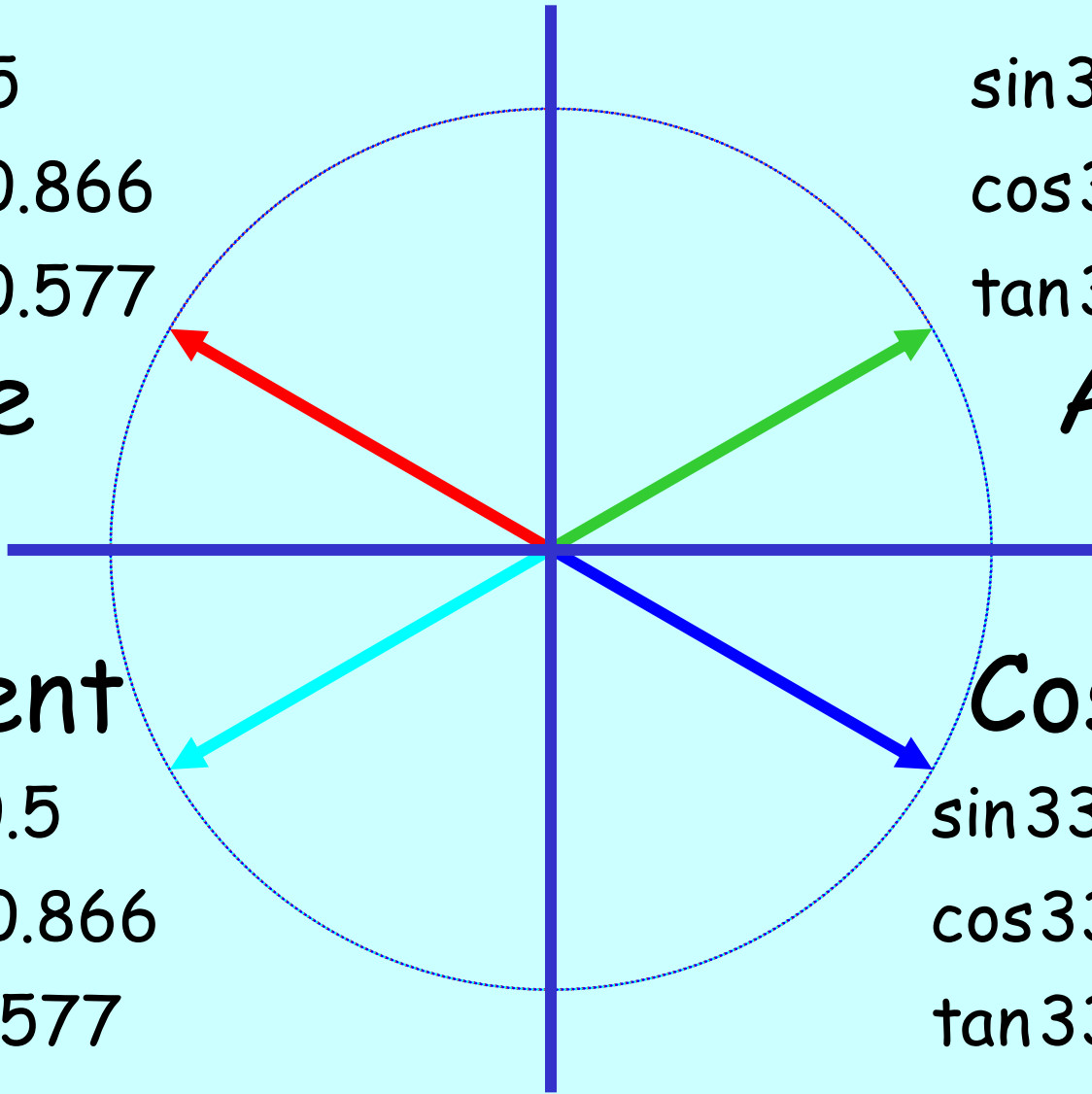
All

0°

Cosine

sin 330 = -0.5  
cos 330 = 0.866  
tan 330 = -0.577

270°



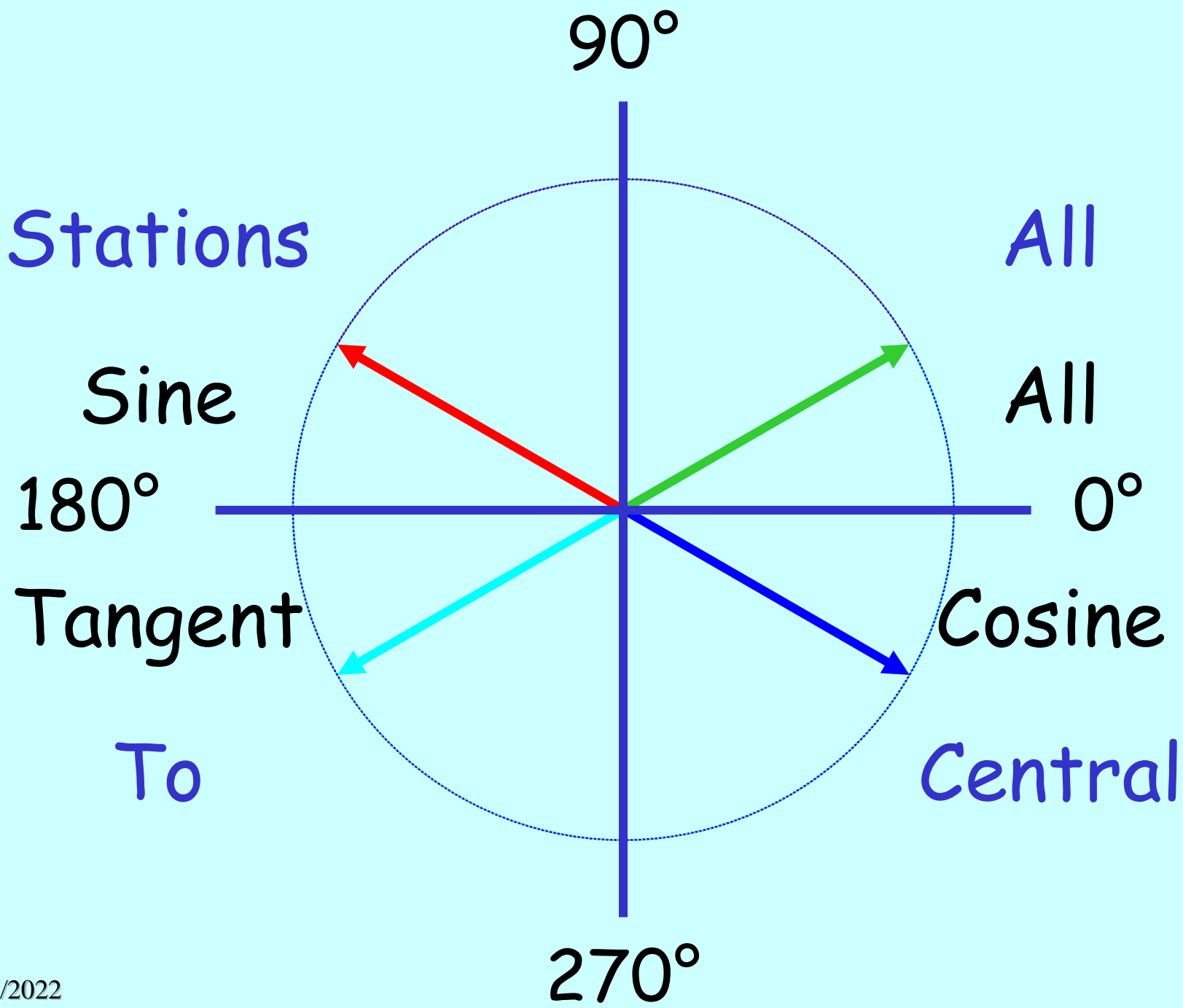
sin 150 = 0.5  
cos 150 = -0.866  
tan 150 = -0.577

Sine

180°

Tangent

sin 210 = -0.5  
cos 210 = -0.866  
tan 210 = 0.577



AE (ac) Workbook Pg. 10 Example 4

Angle $\theta$	Sine $\theta$	Cosine $\theta$	Tangent $\theta$
10°	0.1736	0.9848	0.1763
27°	0.4540	0.8910	0.5095
22.5°	0.3827	0.9239	0.4142
32°	0.5299	0.8480	0.6249
47°	0.7314	0.6820	1.0724
57°	0.8387	0.5446	1.5399
63°	0.8910	0.4540	1.9626
69°	0.9336	0.3584	2.6051
101°	0.9816	- 0.1908	- 5.1446
146°	0.5592	- 0.8290	- 0.6745
154°	0.4384	- 0.8988	- 0.4877
163.7°	0.2807	- 0.9598	- 0.2924

# Problems and Exercises

**UEENEEEG102A**  
**Solve problems in**  
**low voltage a.c. circuits**

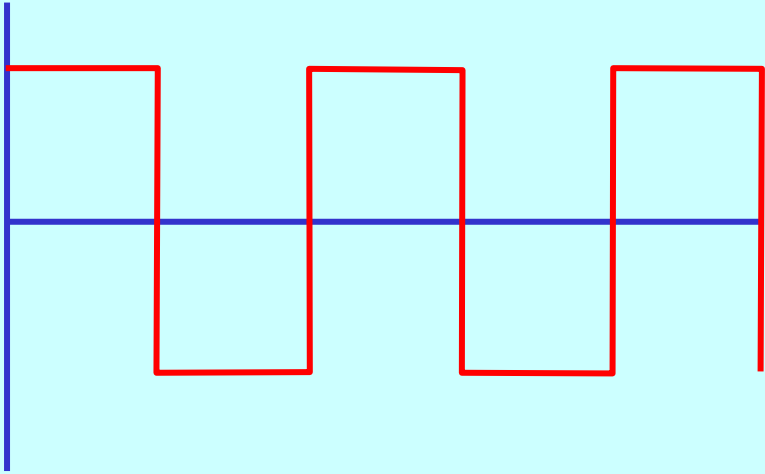
**Alternating**  
**Quantities**

# Objectives:

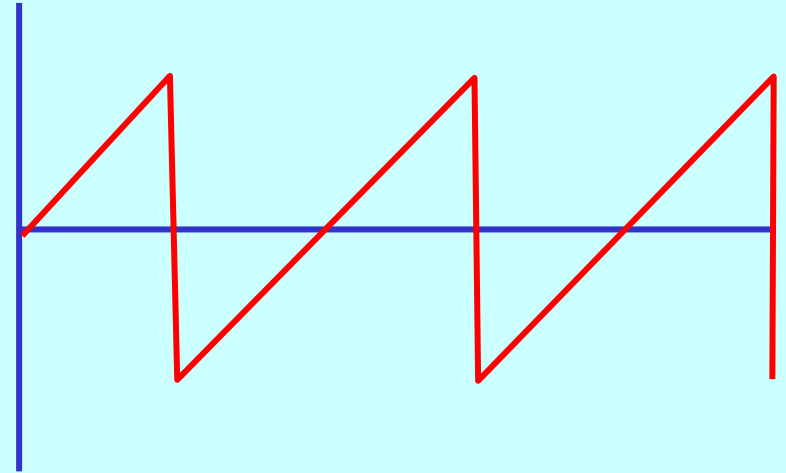
At the end of this lesson students should be able to:

1. Define the term *Alternating Current* and list advantages.
2. Identify basic waveshapes and list uses for each.
3. Sketch a simple SINE Wave and show Peak to Peak, Peak, and RMS values as well as the Period of the wave.
4. Calculate values associated with AC Waveforms.
5. Define Crest and Form Factors for an AC Waveform.

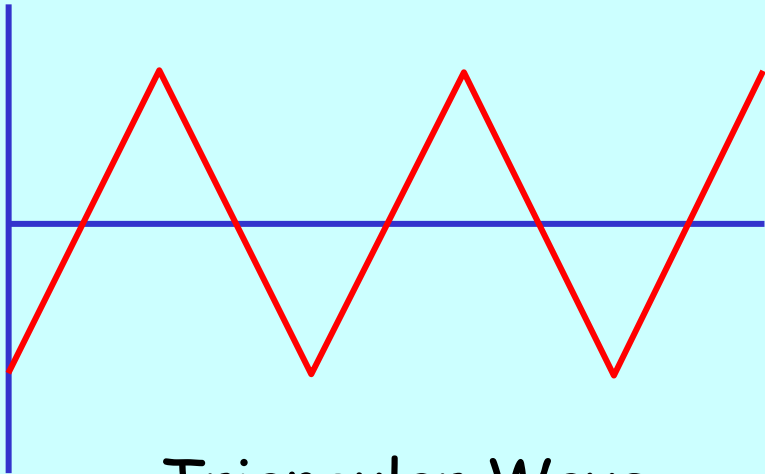
# Common Wave Forms



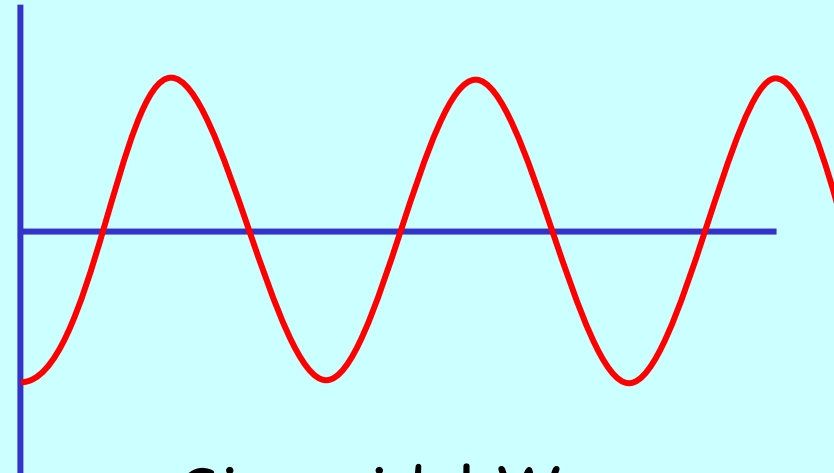
Square Wave



Sawtooth Wave

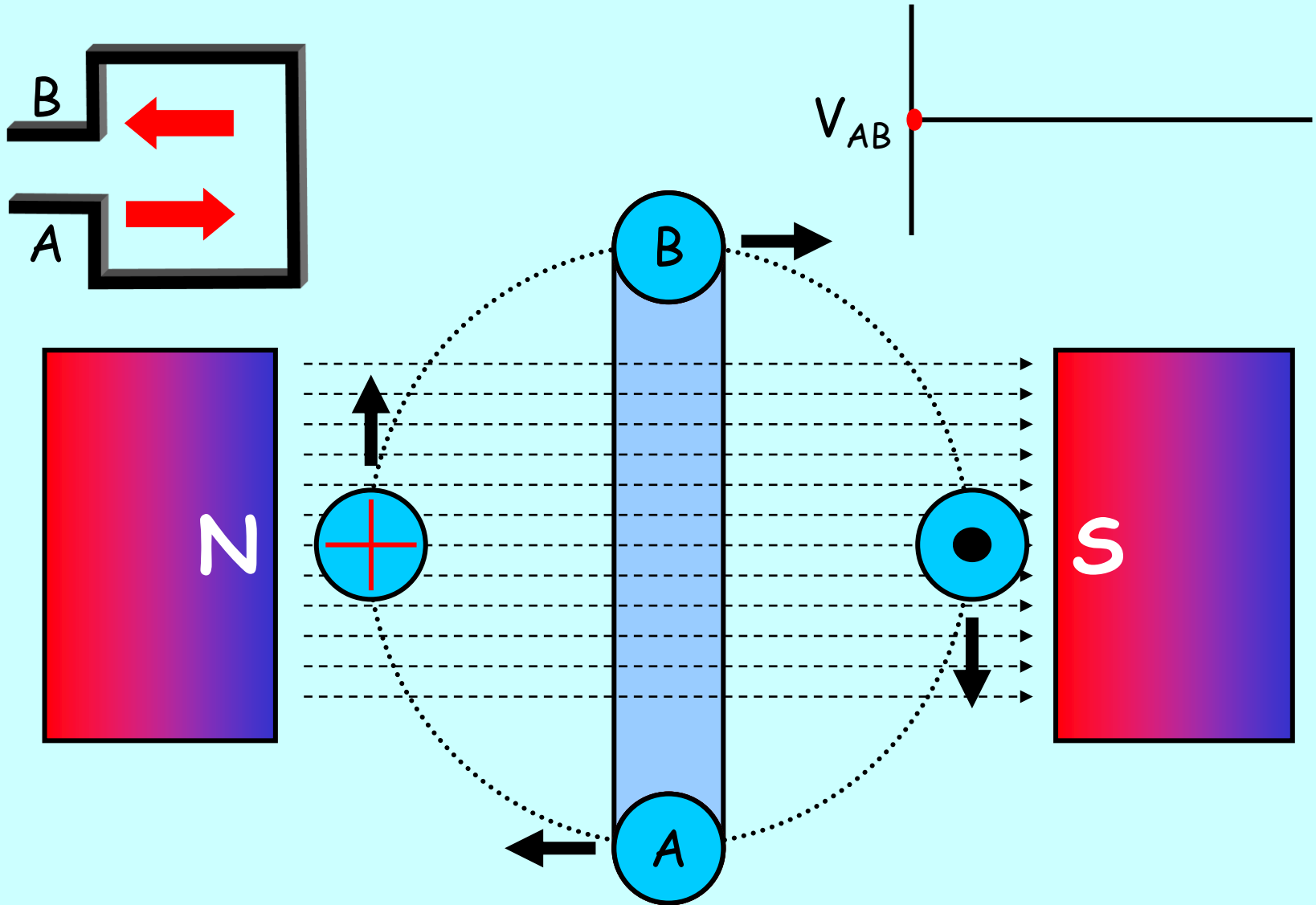


Triangular Wave



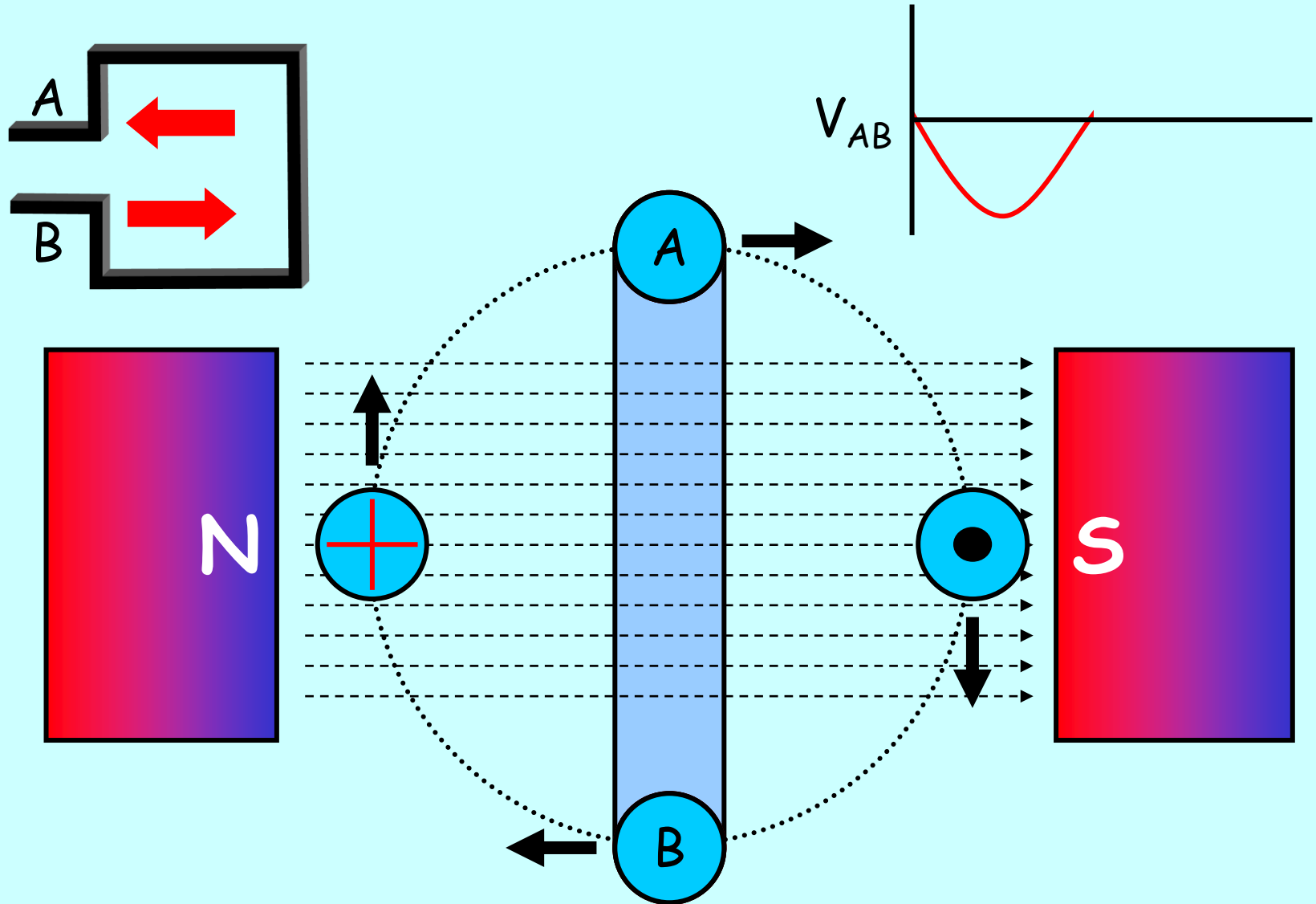
Sinusoidal Wave

# Generator Operation

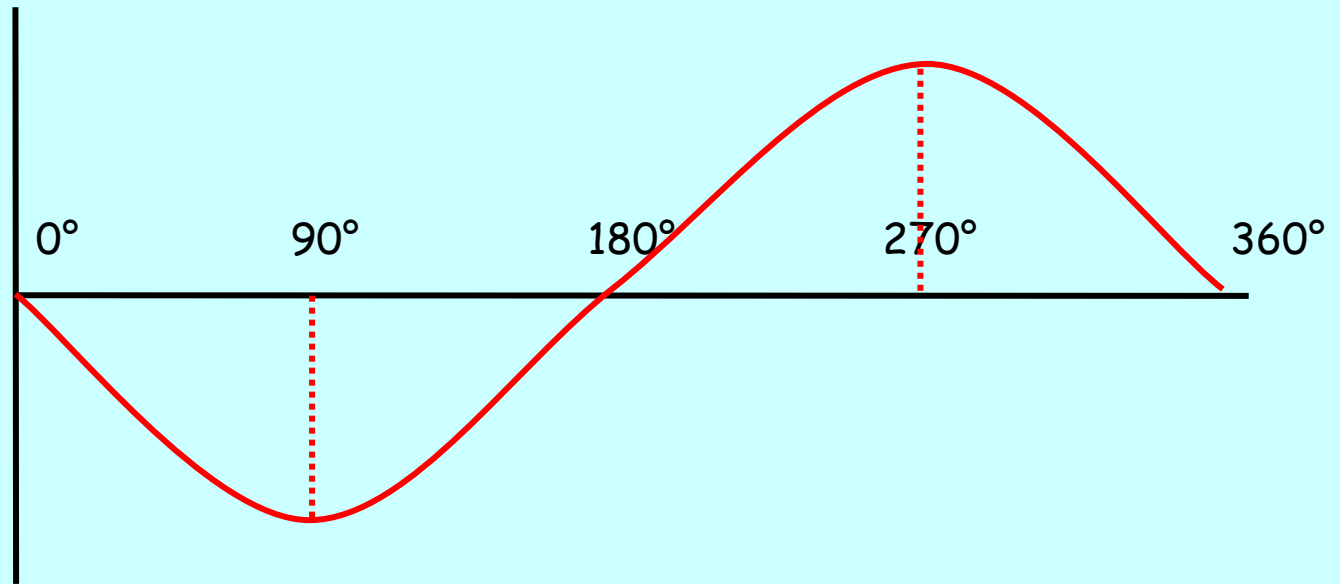




# Generator Operation

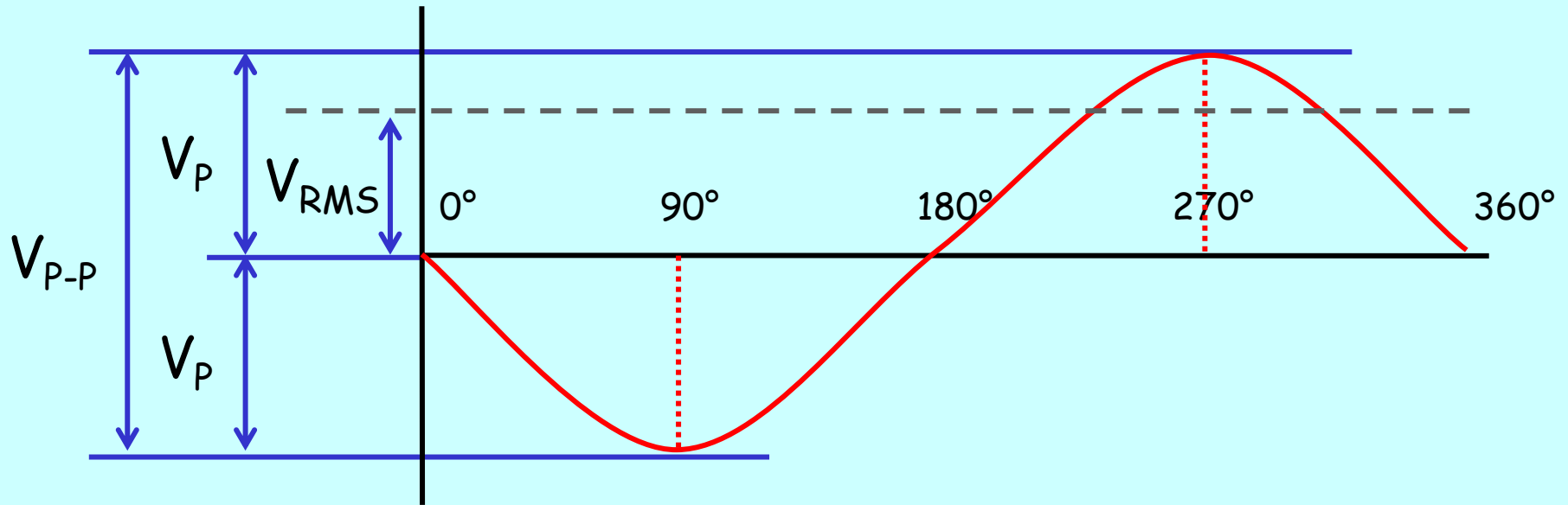


# Alternating Quantities



The Output of a generator is **ALTERNATING**  
The *Average* value of an AC Quantity is **ZERO**.

The Amplitude between the peaks of an AC Quantity is known as the Peak to Peak Value.

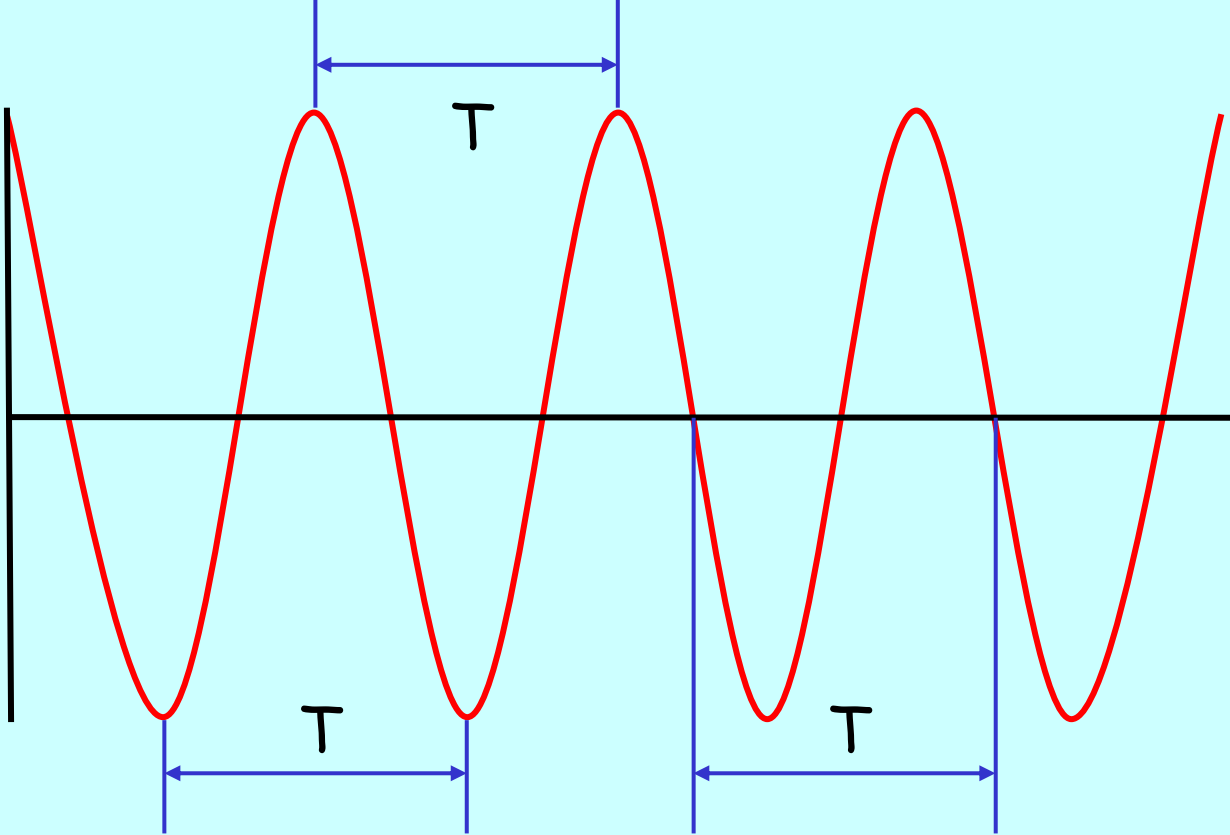


Half of the Peak to Peak Value is known as the Peak (or Maximum) Value.

$$V_{P-P} = 2V_P$$

The *Root Mean Square (RMS)* value of an AC Quantity is the equivalent DC Value that would do the same work.

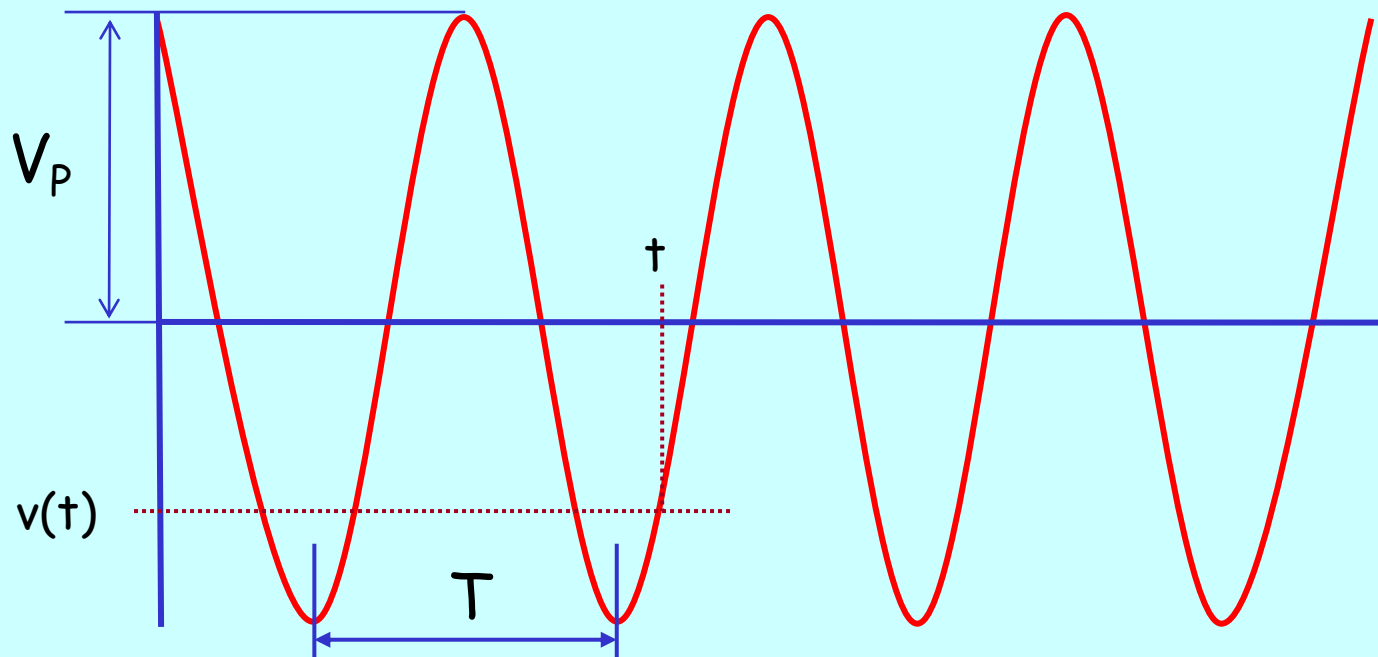
$$V_P = \sqrt{2}V_{RMS}$$



The time taken to complete one cycle ( $360^\circ$ ) of a waveform is known as the Period ( $T$ ).

The Frequency (Hertz) of a waveform is the number of cycles per second (cps).

$$f = \frac{1}{T} \quad T = \frac{1}{f}$$



Any Sinusoidal Waveform can be described mathematically by:

$$v(t) = V_p \sin(360ft) = V_p \sin\left(\frac{360t}{T}\right)$$

where:  $v(t)$  = The instantaneous value of the wave.

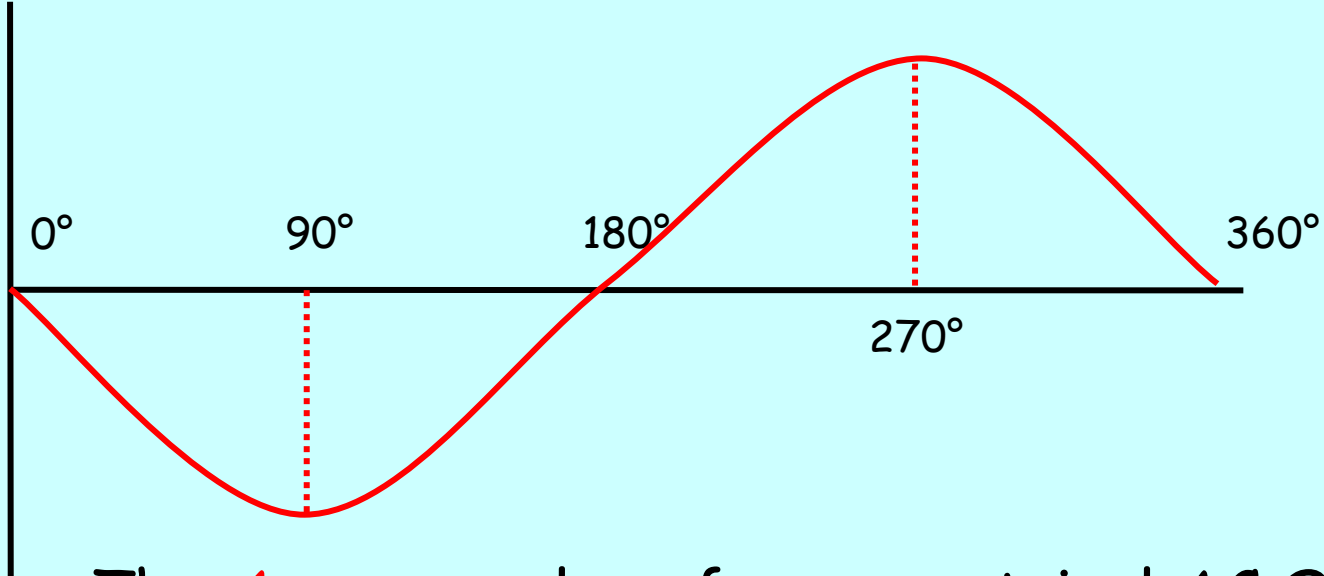
$t$  = The instantaneous time.

$V_p$  = The Peak value of the wave.

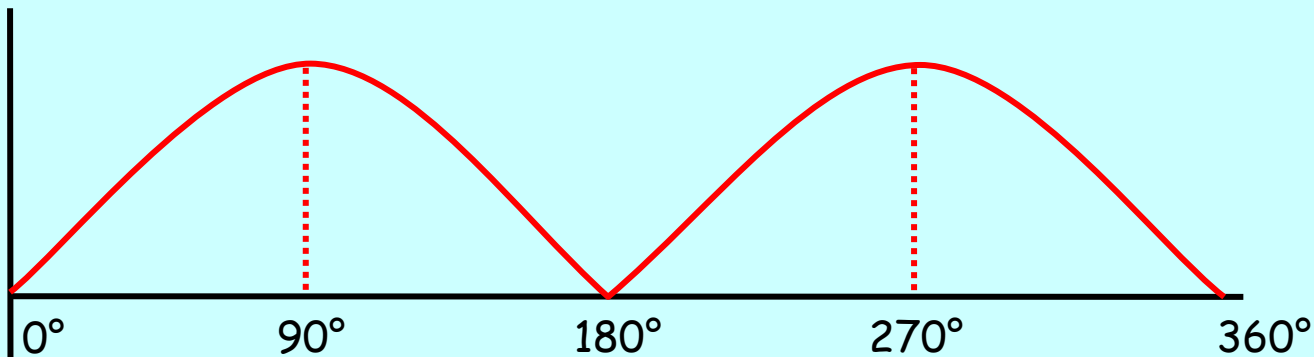
$f$  = The frequency of the wave.

$$f = \frac{1}{T}$$

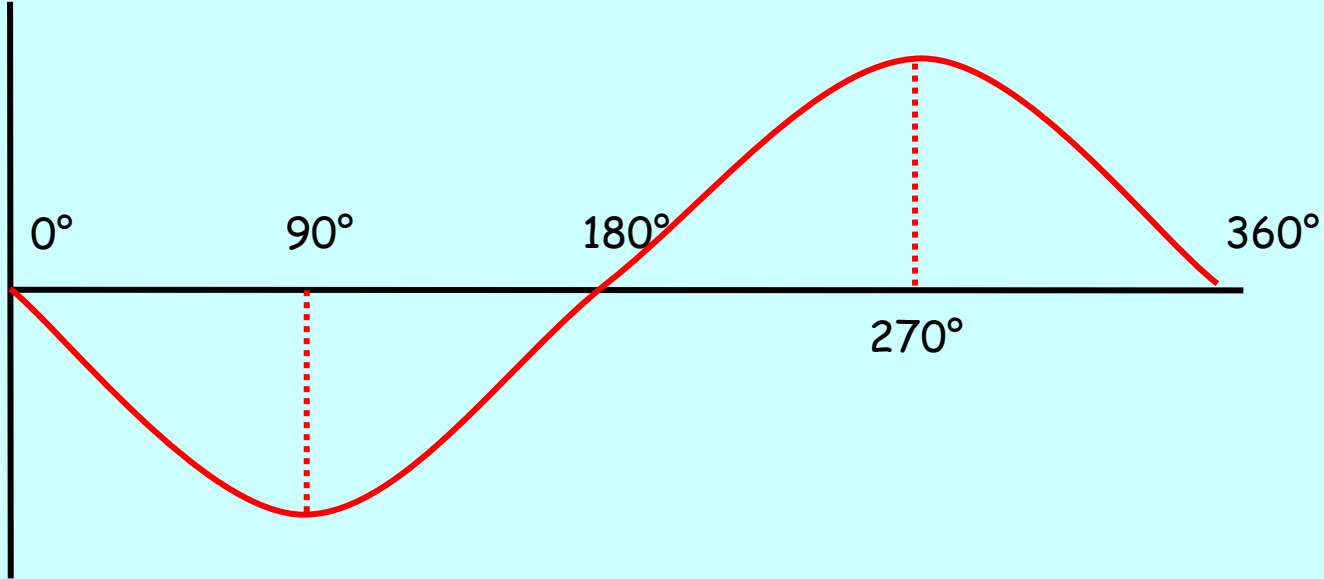
*$(360ft)$  = The angle at the instantaneous time  $t$ .*



The *Average* value of a symmetrical AC Quantity is ZERO.



The *Average* value of a Rectified AC Quantity is  $\frac{2}{\pi} = 0.637$



The *form factor* of an AC Waveform is:

$$\text{form factor} = \frac{V_{\text{RMS}}}{V_{\text{Avg}}} = \frac{\pi}{2\sqrt{2}} = \frac{0.707}{0.637} = 1.11$$

The *crest factor* of an AC Waveform is:

$$\text{crest factor} = \frac{V_{\text{Max}}}{V_{\text{RMS}}} = \sqrt{2} = 1.414$$

# Problems and Exercises





# End of Lesson

## Practical Exercises

Sinusoidal Waveforms

Pp. 53 - 57

Pg. 50 Ex. 1

$$v(t) = V_p \sin(360ft)$$

$$V_p = 340 \text{ V}$$

A.  $(360ft) = 45^\circ$

$$v(t) = 340 \sin(45)$$

$$v(t) = 240.42 \text{ V}$$

B.  $(360ft) = 120^\circ$

$$v(t) = 340 \sin(120)$$

$$v(t) = 294.45 \text{ V}$$

C.  $(360ft) = 270^\circ$

$$v(t) = 340 \sin(270)$$

$$v(t) = -340 \text{ V}$$

Pg. 51 Ex. 2

$$i(t) = I_p \sin(360ft)$$

$$I_p = 20 \text{ A}$$

$$f = 50 \text{ Hz}$$

A.  $(360ft) = 360 \times 50 \times 0.006 = 108^\circ$

$$i(t) = 20 \sin(108)$$

$$i(t) = 19.02 \text{ A}$$

B.  $(360ft) = 360 \times 50 \times 0.009 = 162^\circ$

$$i(t) = 20 \sin(162)$$

$$i(t) = 6.18 \text{ A}$$

C.  $(360ft) = 360 \times 50 \times 0.015 = 270^\circ$

$$i(t) = 20 \sin(270)$$

$$i(t) = -20 \text{ A}$$

Pg. 52 Ex. 3

A.  $V_{PP} = 400 \text{ V}$

B.  $T = 0.010 \text{ S} = 10 \text{ mS}$

C.  $f = 1/0.010 = 100 \text{ Hz}$

Pg. 51 Ex. 4

$$V_{RMS} = \frac{V_P}{\sqrt{2}} = \frac{340}{\sqrt{2}}$$

$$V_{RMS} = 240 \text{ V}$$

Pg. 51 Ex. 5

$$I_P = \sqrt{2}I_{RMS} = 10\sqrt{2}$$

$$I_P = 14.14 \text{ A}$$

**UEENEEEG102A**

**Solve problems in  
low voltage a.c. circuits**

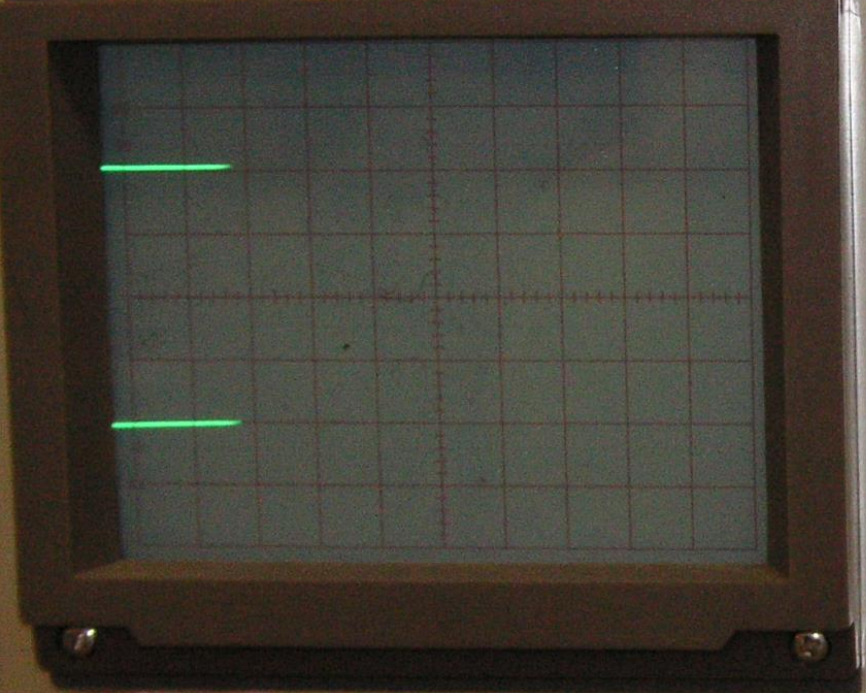
**The CRO**

# Objectives:

At the end of this lesson students should be able to:

1. Correctly adjust the controls of a basic CRO.
2. Check the calibration of a basic CRO.
3. Measure DC and AC Voltages on a basic CRO.
4. Use a CRO to determine the phase difference between two sinewaves.

HC HUNG CHANG MODEL OS-620 OSCILLOSCOPE



**VARIABLE SWEEP TIME/DIV**

ms: 2, 1, .5, .2, .1, .05, .02, .01  
 μs: 5, 10, 20, 50, 100, 200, 500, 1000  
 SEC: 1, .5, .2, .1, .05, .02, .01

**TRIGGERING**

LEVEL PULL AUTO  
 SLOPE: +, -  
 SYNC: AC, HF REJ, TV  
 SOURCE: INT, CH B, LINE, EXT

POSITION PULL 5X MAG

**CH A**

POSITION  
 VARIABLE VOLTS/DIV  
 V: 1, .5, .2, .1, .05, .02, .01  
 mV: 5, 10, 20, 50, 100, 200, 500, 1000

**CH B**

POSITION PULL INVERT  
 VARIABLE VOLTS/DIV  
 V: 1, .5, .2, .1, .05, .02, .01  
 mV: 5, 10, 20, 50, 100, 200, 500, 1000

**MODE**

CHA  
 CHB  
 DUAL  
 ADD

**INPUT Y** AC GND DC

**INPUT X** AC GND DC

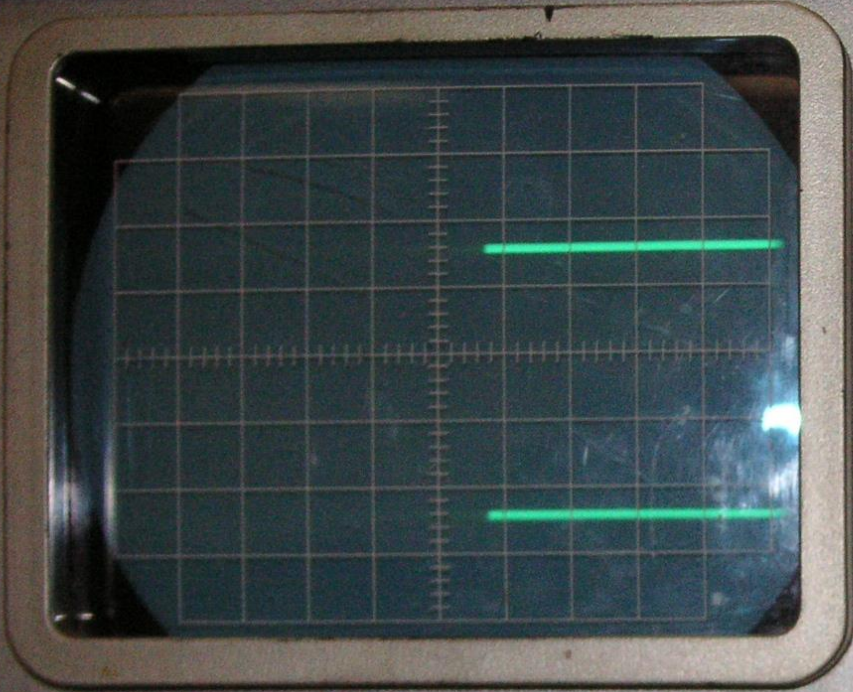
INTENSITY  
 FOCUS  
 ON  
 OFF POWER  
 TRACE ROTATOR

EXT. TRIG  
 CAL 1.5V.P.P.

COMP TEST

← COMP. TEST IN N.S.W. DEPT. OF TAFE 0115522AN

**TRIO 15MHz OSCILLOSCOPE CS-1560A**



**VARIABLE SWEEP TIME/DIV**

POWER ILLUM **OFF**

INTENSITY

ASTIG

FOCUS

**TRIGGERING**

LEVEL PULL AUTO

SYNC NOR TV

SOURCE CH1 CH2 EXT

POSITION PULL X5 MAG

EXT. TRIG

CAL 1VP-P

SEC 10 20 50 .1 .2 .5

mS 2 1.5 2

TVV TVH

μS 20 10 5 2

X-Y

**VARIABLE VOLTS/DIV**

POSITION **x1**

**CH1 or Y**

INPUT 1MΩ = 22pF

AC GND

**VARIABLE VOLTS/DIV**

MODE CH1 CH2 DUAL ADD SUB

**VARIABLE VOLTS/DIV**

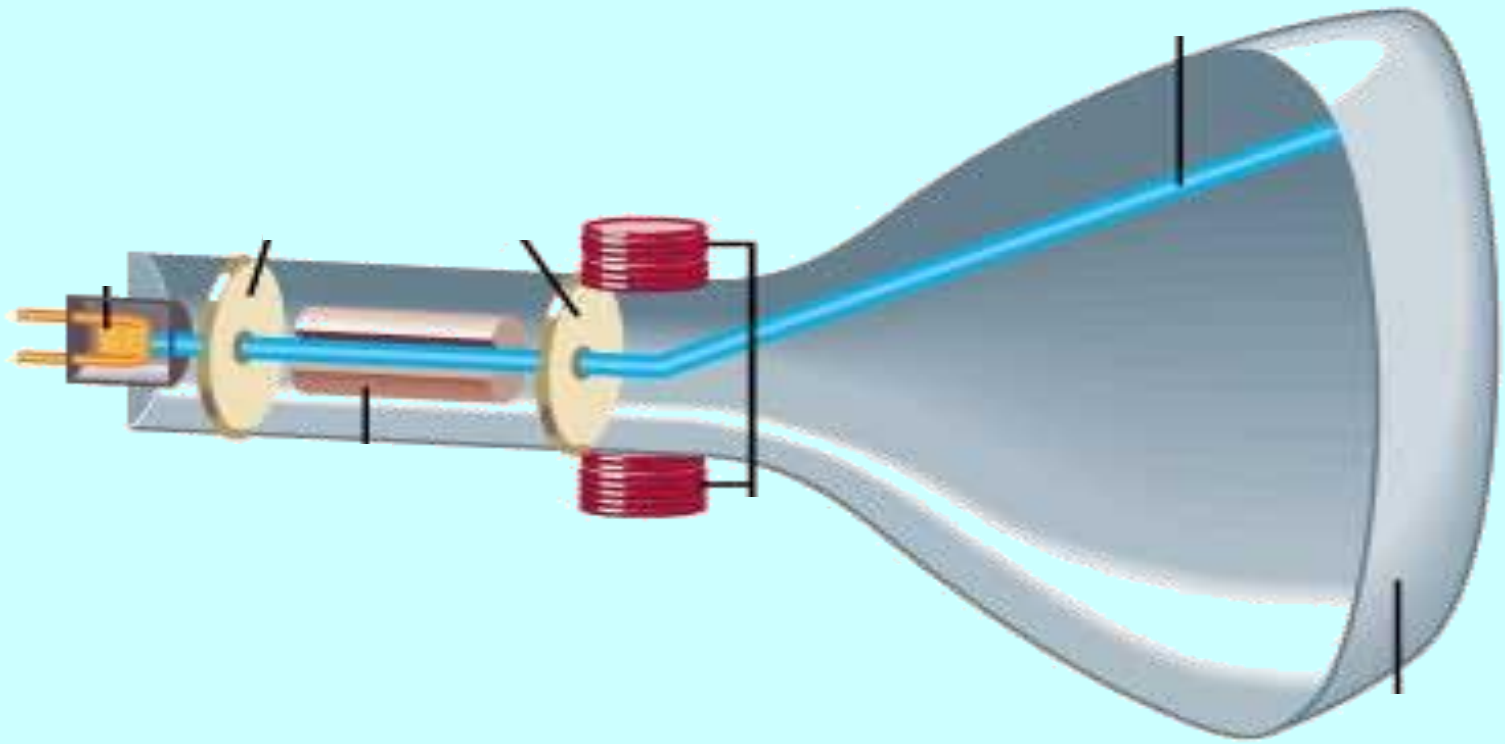
**CH2 or X**

INPUT 1MΩ = 22pF

AC GND

POSITION **x1**

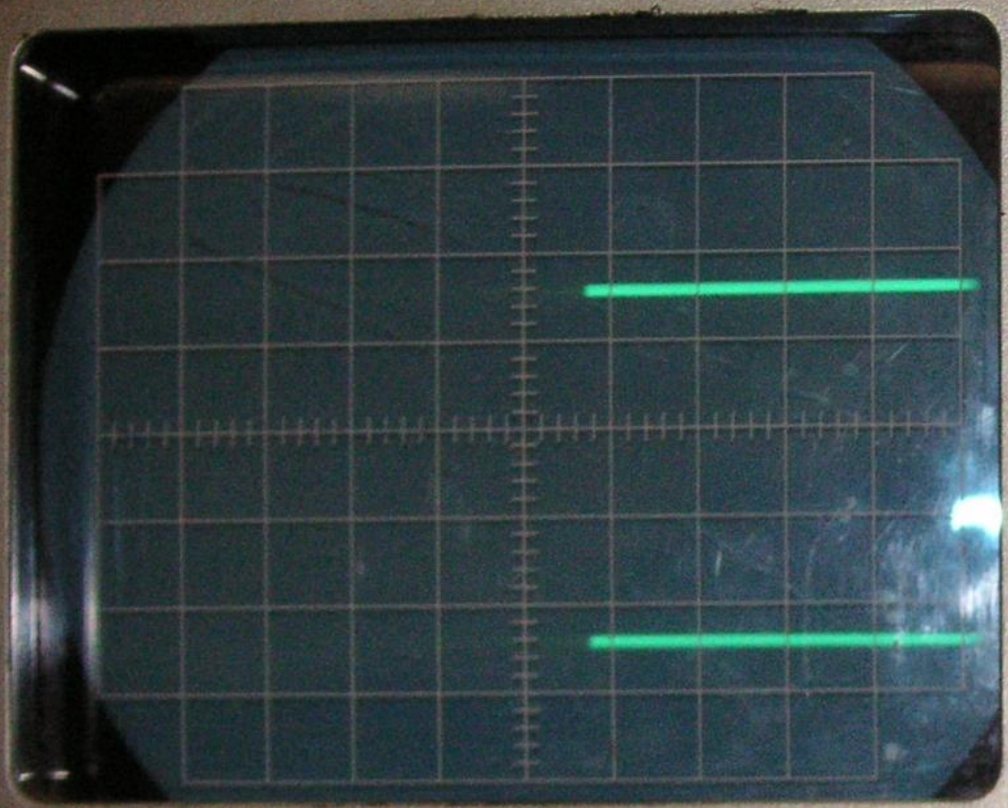
DC BAL **x10**



Precision Graphics



TRIO 15MHz OSCILLOSCOPE CS-1560A



POWER ILLUM



OFF

INTENSITY



FOCUS



DN  
AG

G

G

G

G

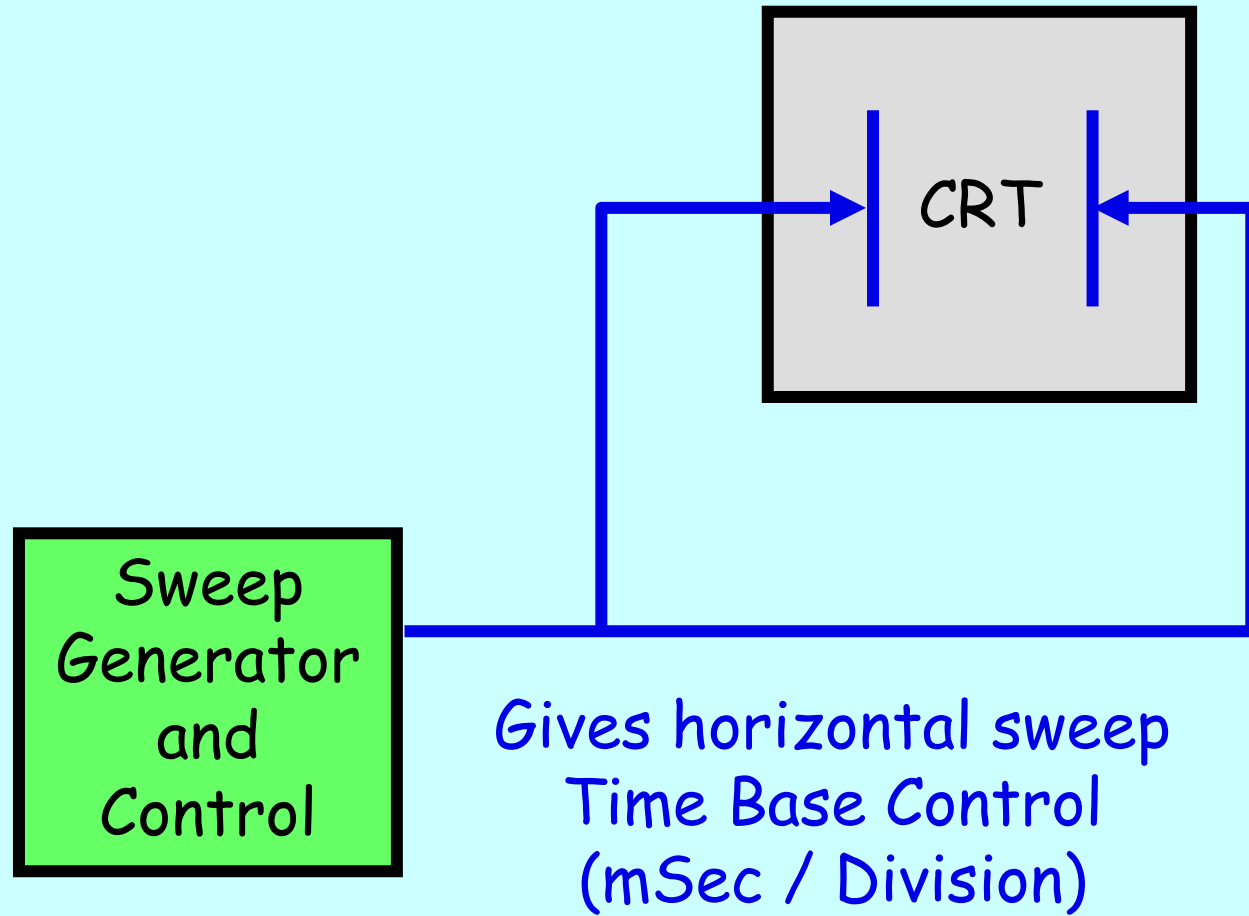
G

G

G

G

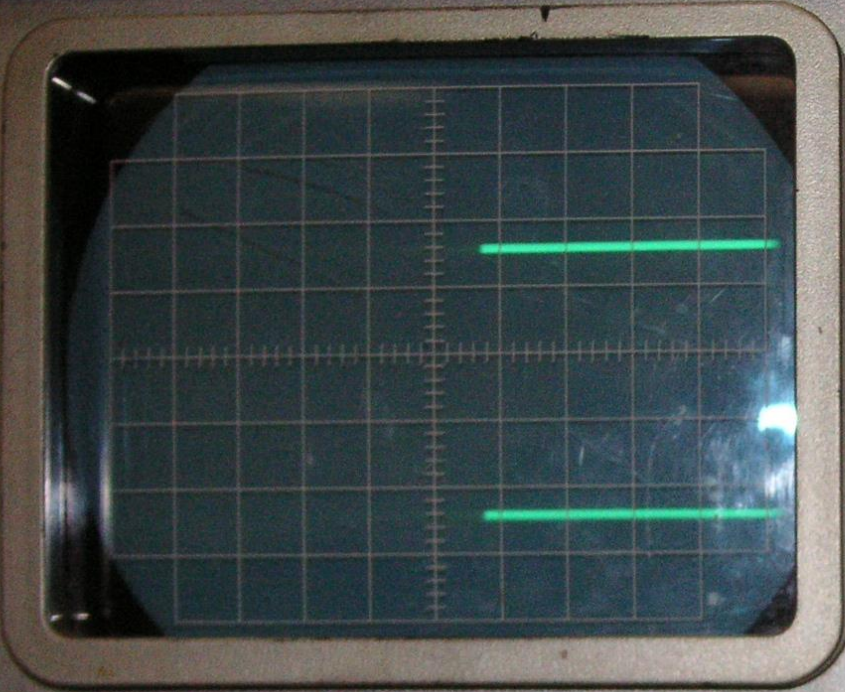




Typical Block Diagram of a Oscilloscope



TRIO 15MHz OSCILLOSCOPE CS-1560A



X-Y

### TRIGGERING

LEVEL  
PULL AUTO



SYNC

NOR TV



SOURCE

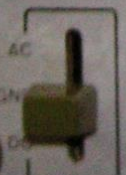
CH1 CH2 EXT



POSITION

CH1  
or Y

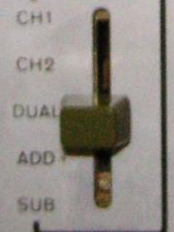
INPUT  
1MΩ - 220pF



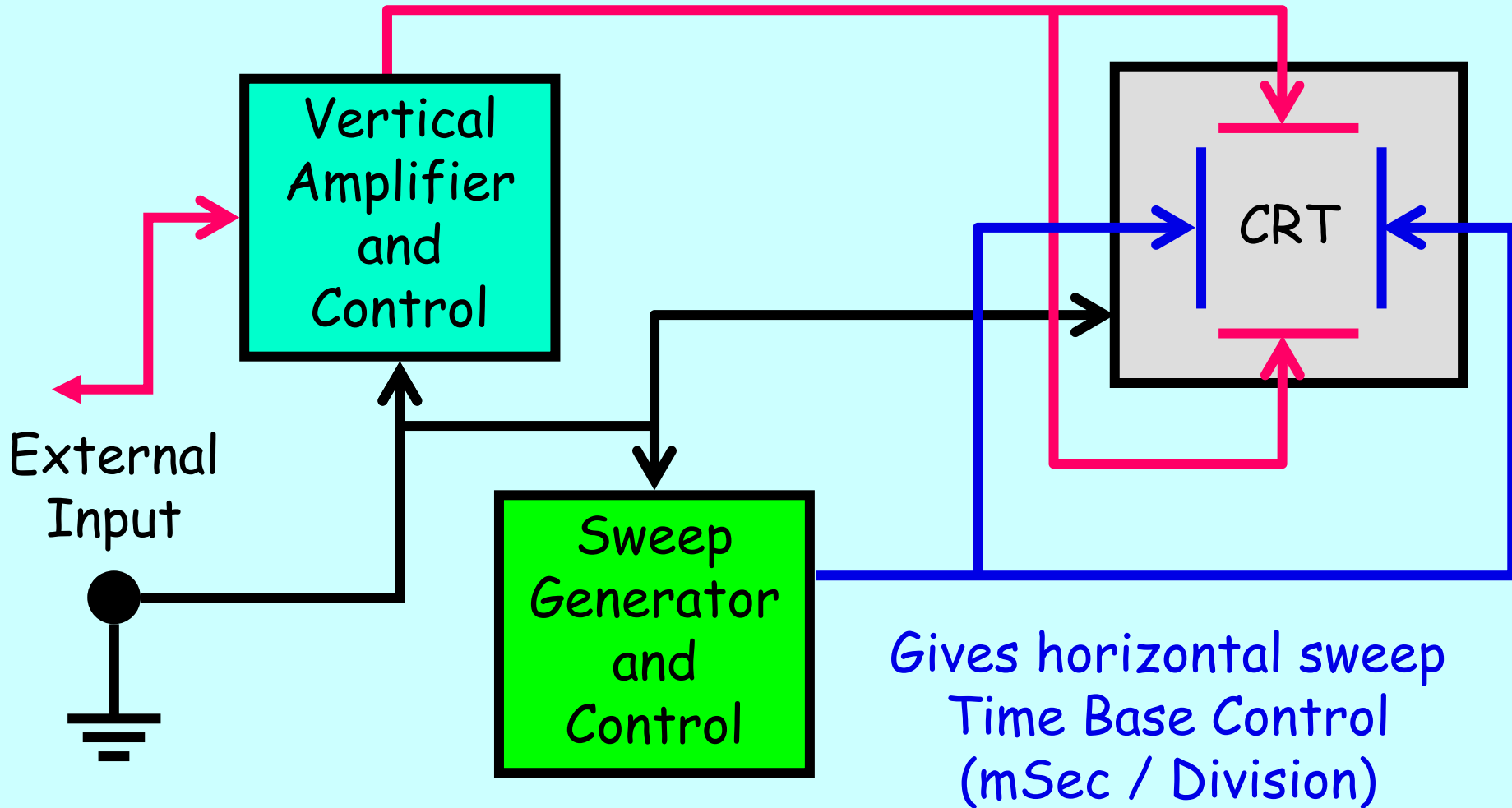
VARIABLE  
VOLTS/DIV



MODE



Gives vertical displacement  
Amplitude Control  
(Volts / Division)



Typical Block Diagram of a Oscilloscope

TRIO 15MHz OSCILLOSCOPE CS-1560A

POWER ILLUM

VARIABLE SWEEP TIME/DIV

TVV TVR  
mS 2 1.5 2 20 10 5 2  
10 20 50 .1 .2 .5  
SEC .5  
CAL X-Y

CAL  $\square$  1VP-P

POSITION PULL X5 MAG

VARIABLE VOLTS/DIV

1 .5 .2  
2 .1  
5 .05  
10 .02  
20 .01  
CAL

DENSITY

TRIGGERING

LEVEL PULL AUTO

ASTIG

SYNC

EXT. TRIG

CH2 or X

POSITION X-Y

x1

AC

INPUT 1M $\Omega$   $\approx$  22pF

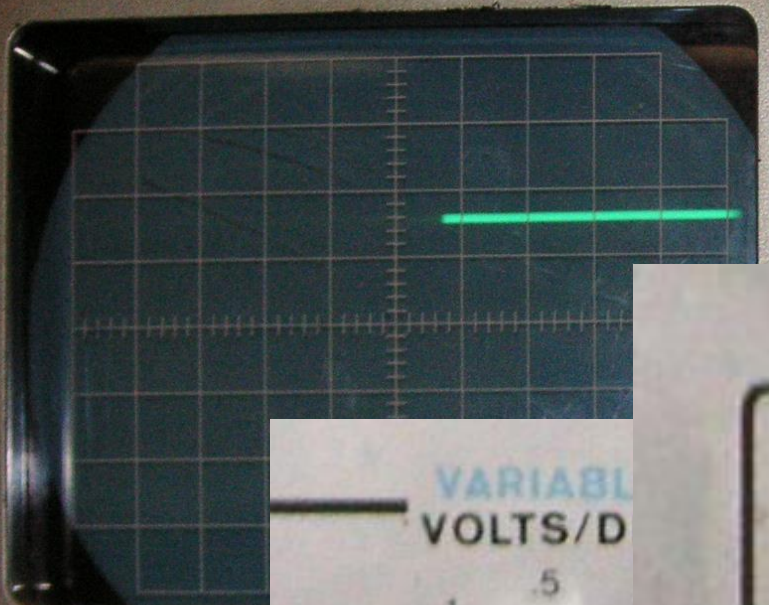
GND

DC

DC BAL

x10

TRIO 15MHz OSCILLOSCOPE CS-1560A



VARIABLE SWEEP TIME/DIV



CAL 1VP-P



POSITION PULL X5 MAG



TRIGGERING



VARIABLE VOLTS/DIV



AC

GND

DC

POSITION X-Y

x1

2pF

DC BAL

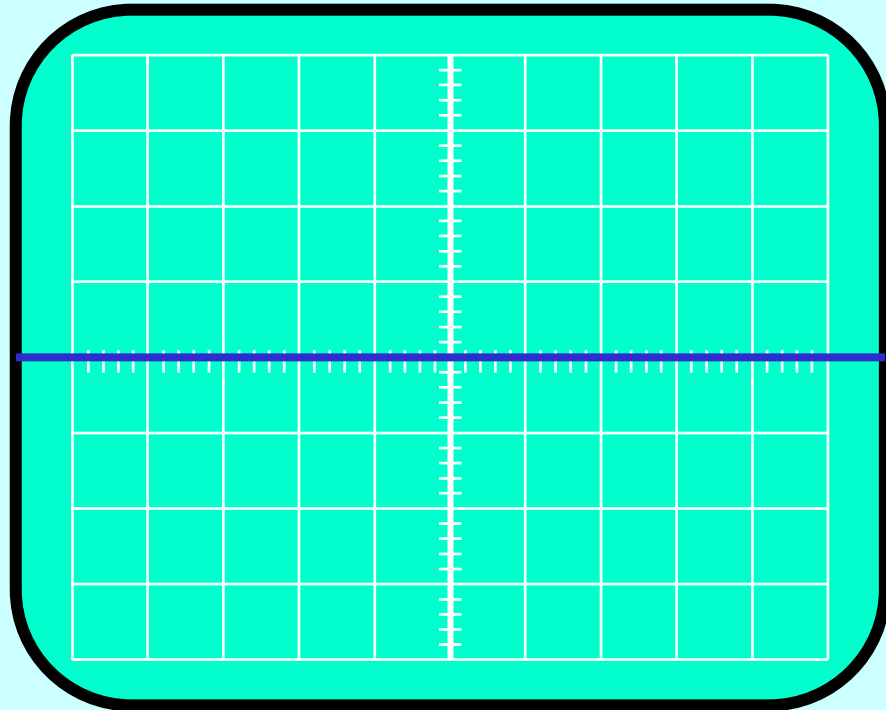
x10







## Exercise 1 Pg. 24



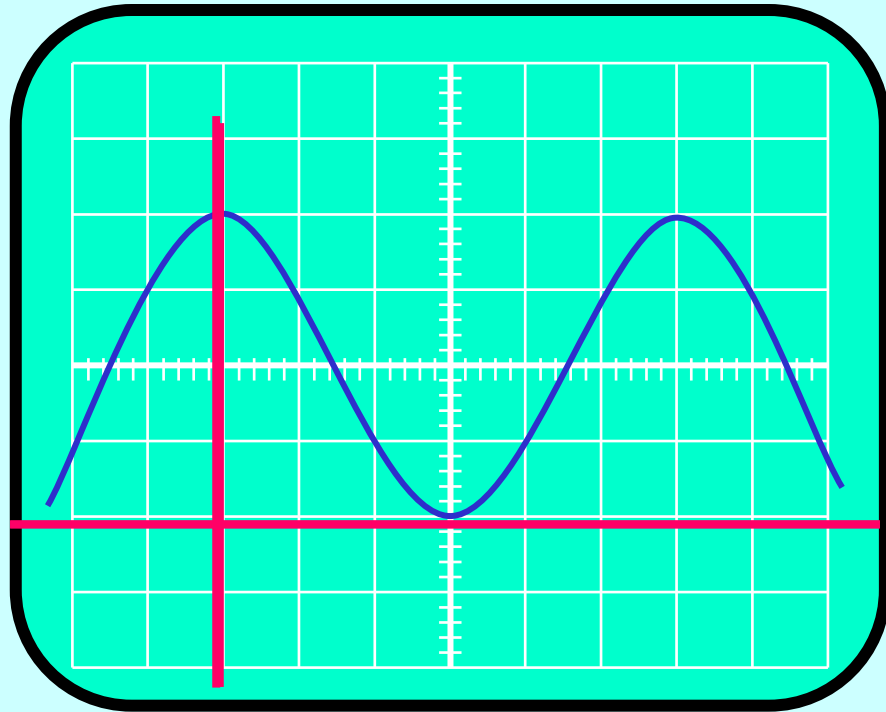
Vertical Scale  
10 V/div

Horizontal Scale  
2 mS/div

Trace centred at  
ZERO when Earthed.

- A. The signal is DC
- B. Change the Vertical Scale to 20 V/div and leave the Time Base at 2 mS/div.
- C. Change the Vertical Scale back to 10 V/div and change the Time Base to 0.5 mS/div.

## Exercise 2 Pg. 25



Vertical Scale  
1 V/div

Horizontal Scale  
0.1 mS/div

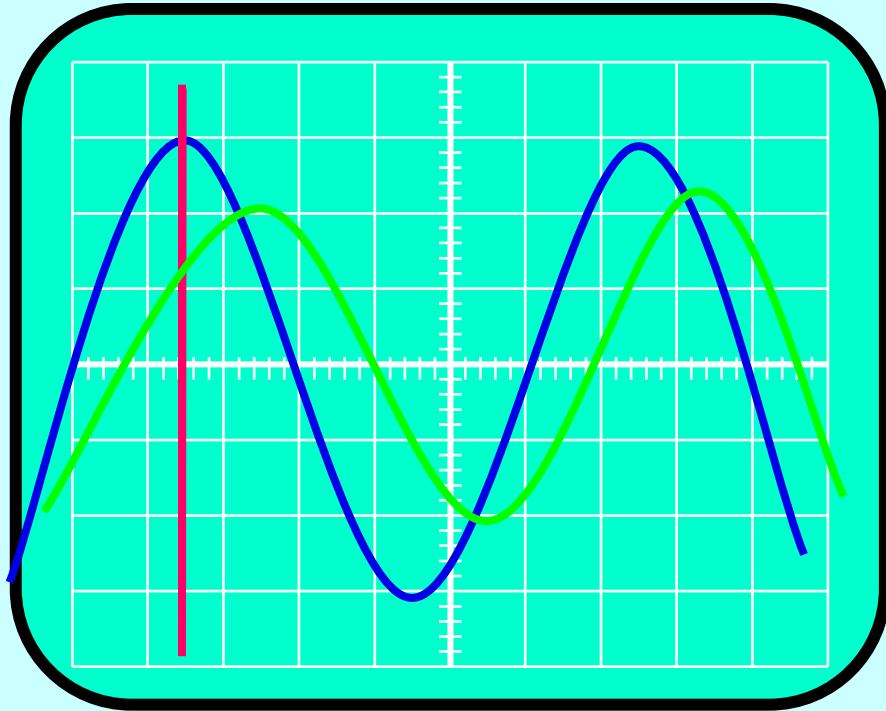
A.  $V_{\text{Peak to Peak}} = \underline{4 \times 1 = 4 \text{ V}}$

B.  $V_{\text{Peak}} = \underline{4/2 = 2 \text{ V}}$

C.  $T = \underline{6 \times 0.1 = 0.6 \text{ mS}}$

D.  $f = 1 / T = \underline{1 / 0.6 \text{ mS} = 1,666 \text{ Hz}}$

## Exercise 3 Pg. 26



Vertical Scale

Ch A = 1 V/div

Ch B = 0.5 V/div

Horizontal Scale

0.1 mS/div

A.  $V_{A(\text{Peak})} = \frac{(6.2 \times 1)}{2} = 3.1 \text{ V}$

B.  $V_{B(\text{Peak})} = \frac{(4.2 \times 0.5)}{2} = 1.05 \text{ V}$

C.  $T = \frac{6 \times 0.1}{1} = 0.6 \text{ mS}$

D.  $f = 1 / T = \frac{1}{0.6 \text{ mS}} = 1,666 \text{ Hz}$

E.  $\Phi_T = \frac{1 \times 0.1 \text{ mS}}{0.6} = 0.1 \text{ mS}$

F.  $\Phi^\circ = \frac{360 \times (0.1/0.6)}{1} = 60^\circ$

# End of Lesson

## Practical Exercises

Pp. 27 - 37

2.1, 2.2, 2.3 & 2.4

**UEENEEEG102A**  
**Solve problems in**  
**low voltage a.c. circuits**

**Vectors and**  
**Phasors**

# Objectives:

At the end of this lesson students should be able to:

1. Define the term *Vector*.
2. Define the term *Phasor*.
3. Draw the phasor representation of *AC Sinusoidal* waveforms.
4. Identify leading and lagging phase angles.
5. Draw and read phasor diagrams.

# What is a *Vector*?

A quantity that has **MAGNITUDE** and **DIRECTION**.

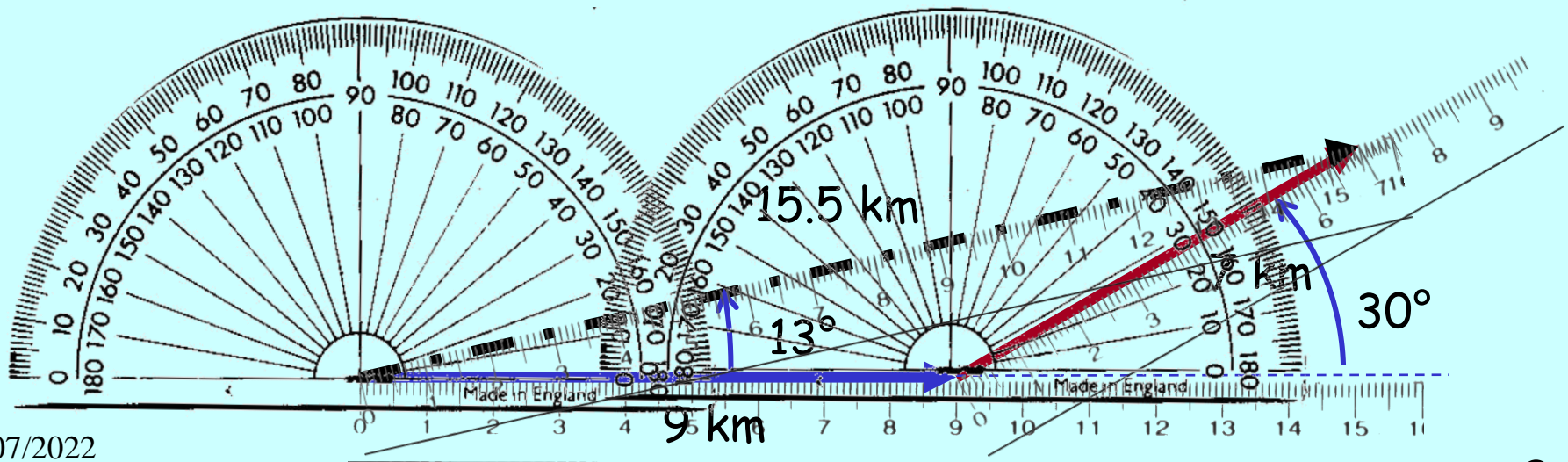
Examples: Displacement, Velocity, Acceleration, Force

A person travels due East for 9 km

and then travels  $30^\circ$  North of East for 7 km

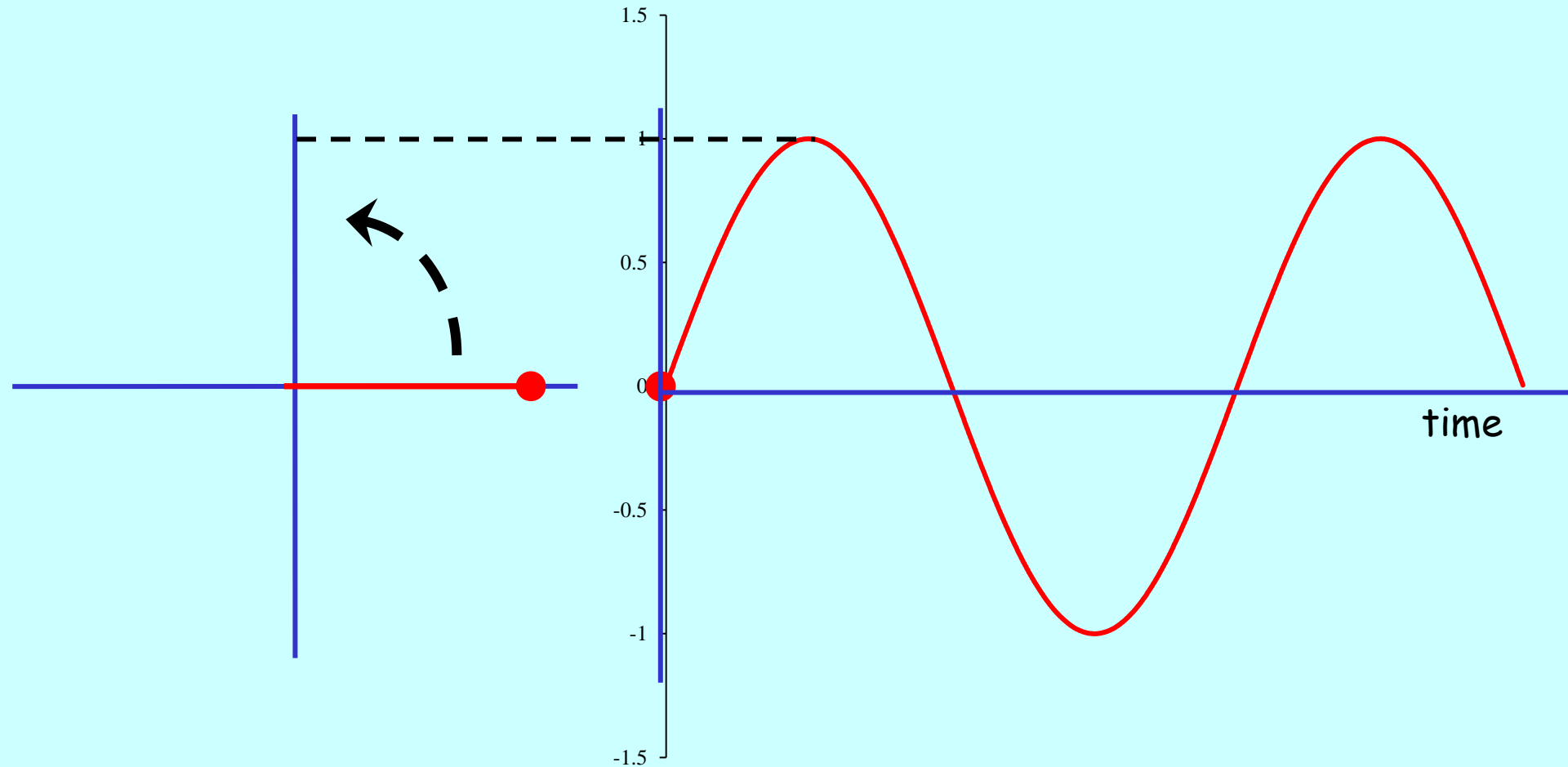
What is their displacement from the original starting position?

**15.5 km  $\angle$   $13^\circ$**



# What is a *Phasor*?

A Vector representation of an electrical quantity.  
Specifically Sinusoidal quantities.

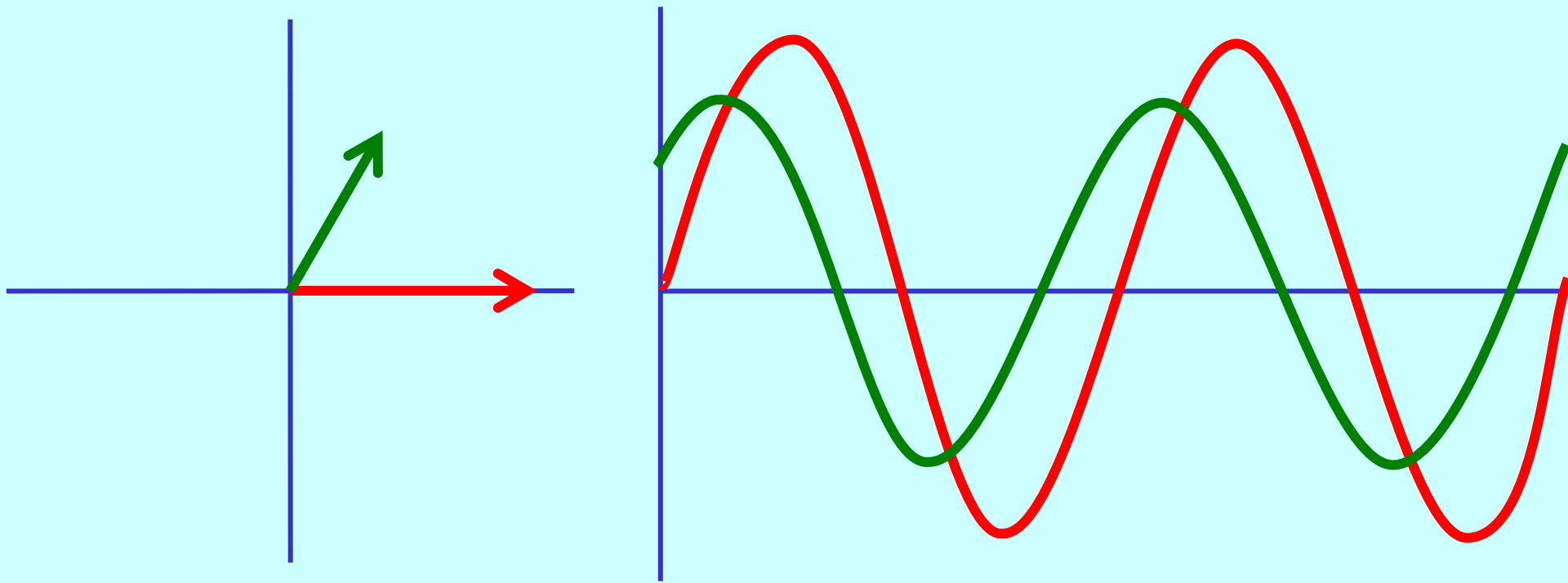




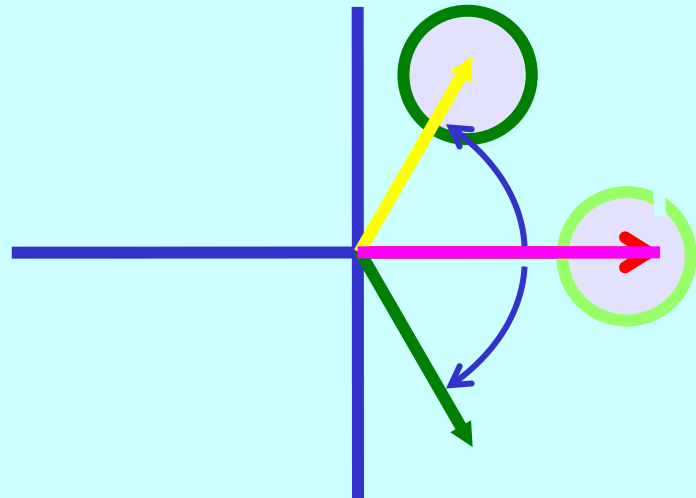
And if we have more than one quantity?

Simply add more Vectors with appropriate phase angles.

The only stipulations are that the quantities **MUST** be the same units (ie. V, A,  $\Omega$ , etc.) and have the same frequency.



# Conventions



The Reference Phasor is always at ZERO degrees.

Voltage Phasors are shown by an open arrow head.

Current Phasors are shown by a closed arrow head.

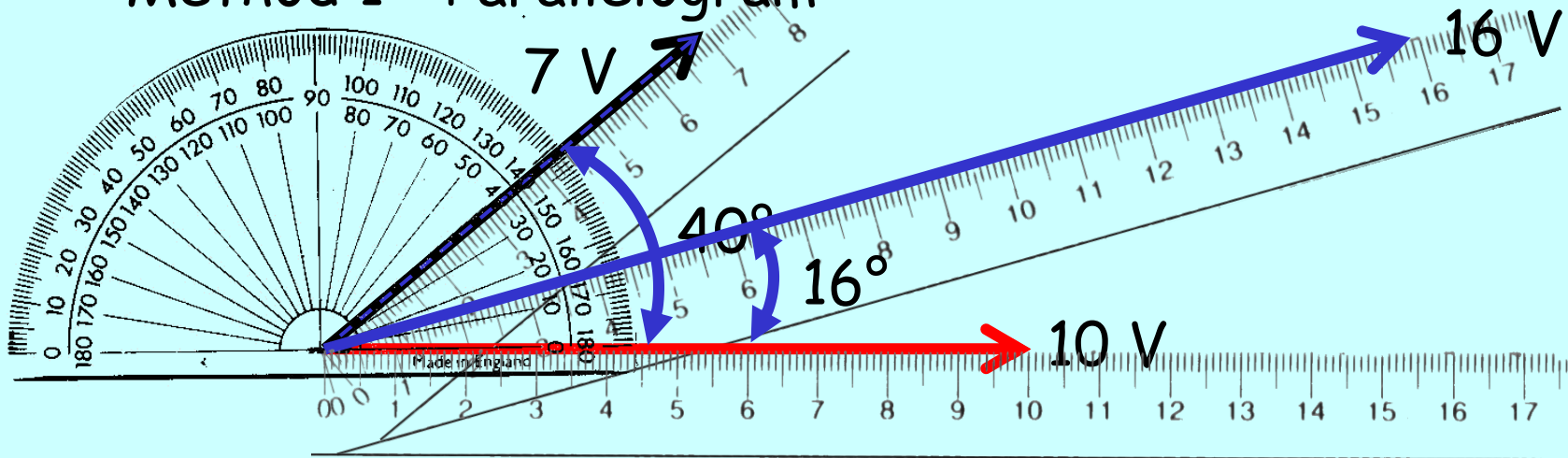
Phasors rotate in an Anti-Clockwise direction.

Phasor Angles are specified as either Leading or Lagging.

Phasor Magnitudes are generally specified in RMS values.

# Phasor Addition

## Method 1 - Parallelogram



Always start by drawing the Reference Phasor which will be at ZERO degrees.

Measure the Phase Angle of the Phasor to be added to the reference.

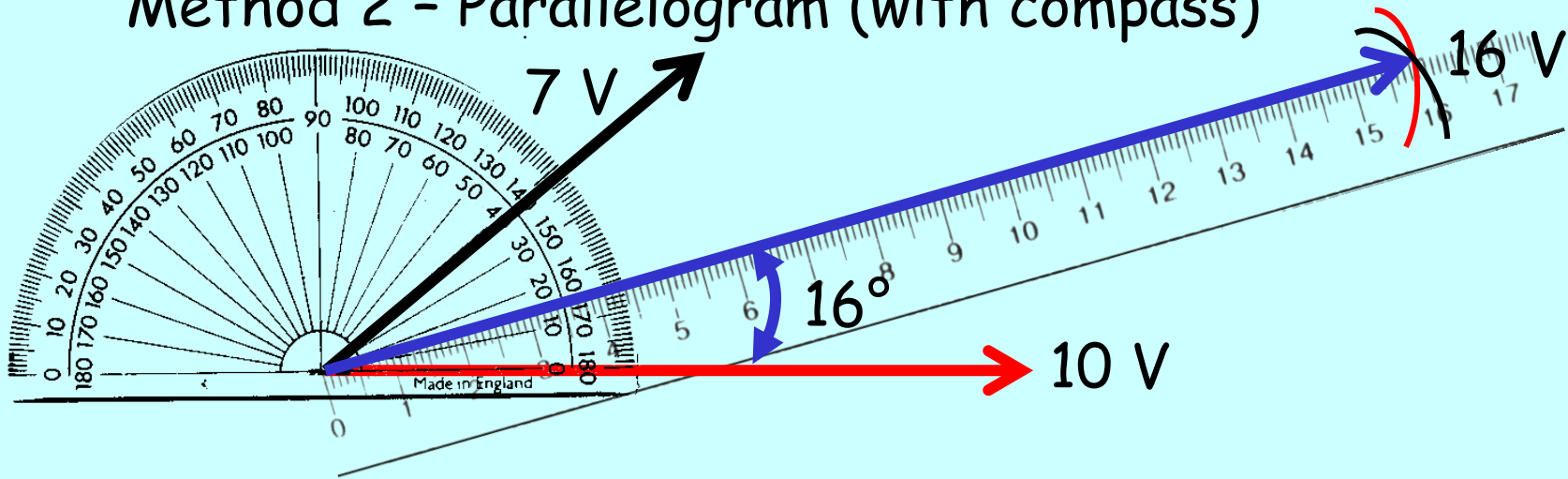
Draw in the second Phasor and complete the parallelogram.

Draw in the diagonal of the parallelogram. This is the resultant Phasor.

Measure the Magnitude and Phase Angle of the Resultant Phasor.

# Phasor Addition

## Method 2 - Parallelogram (with compass)



Always start by drawing the Reference Phasor which will be at ZERO degrees.

Measure the Phase Angle of the Phasor to be added to the reference.

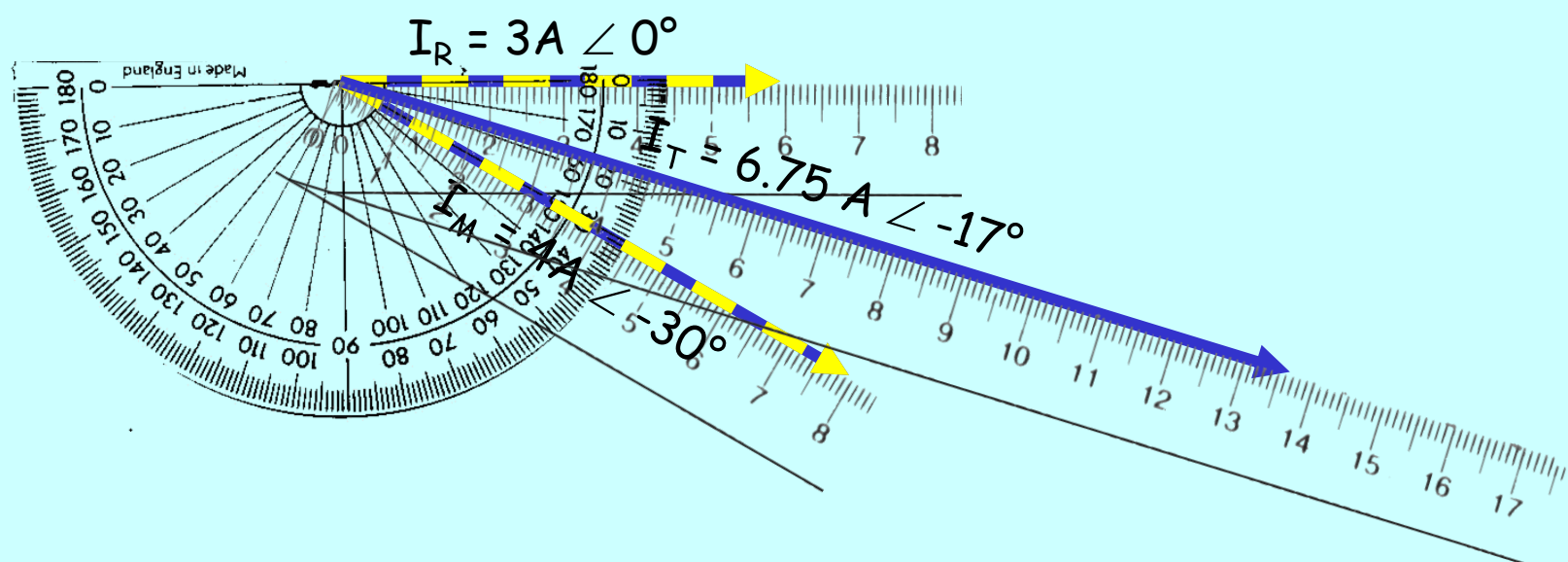
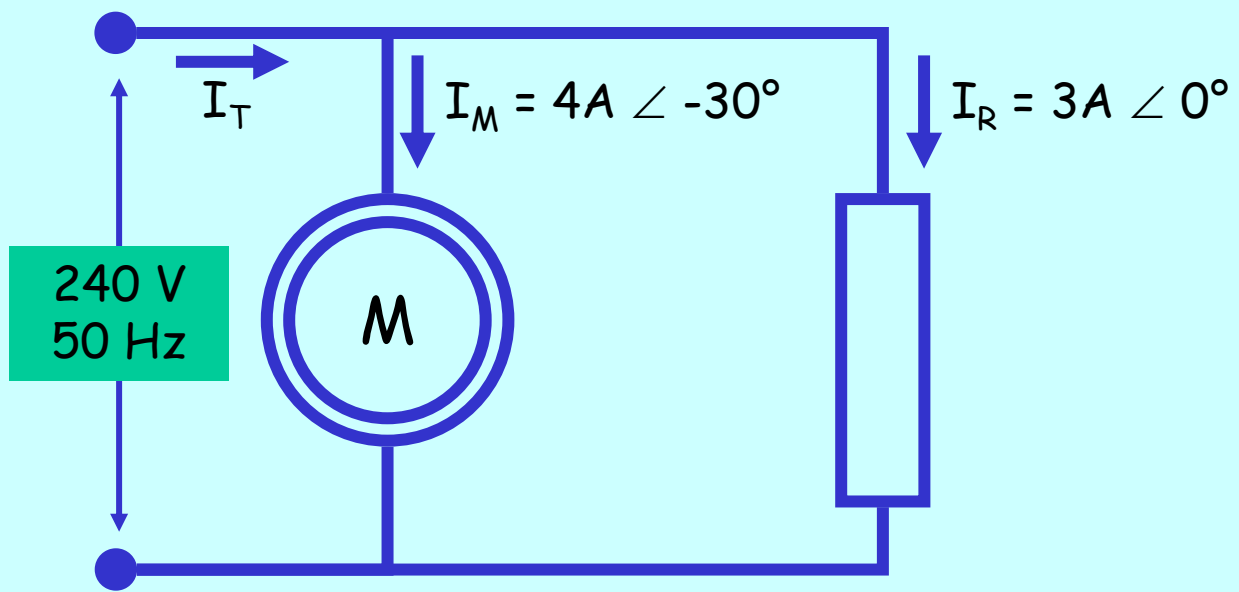
Draw in the second Phasor.

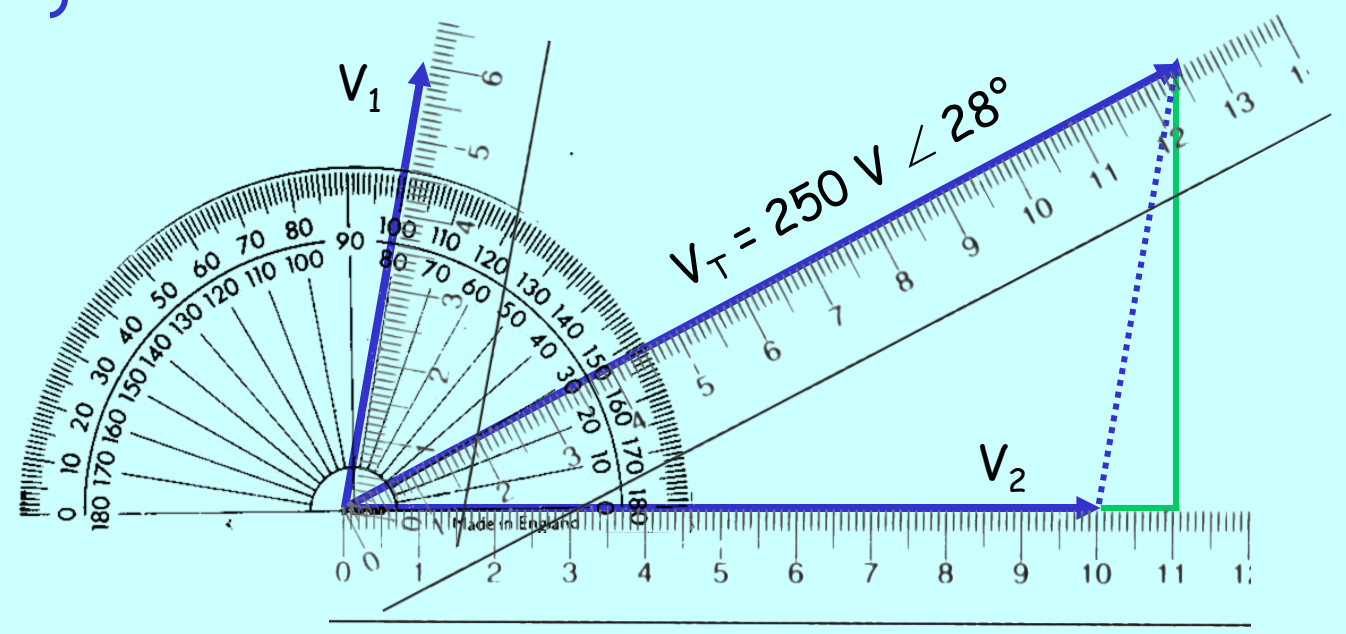
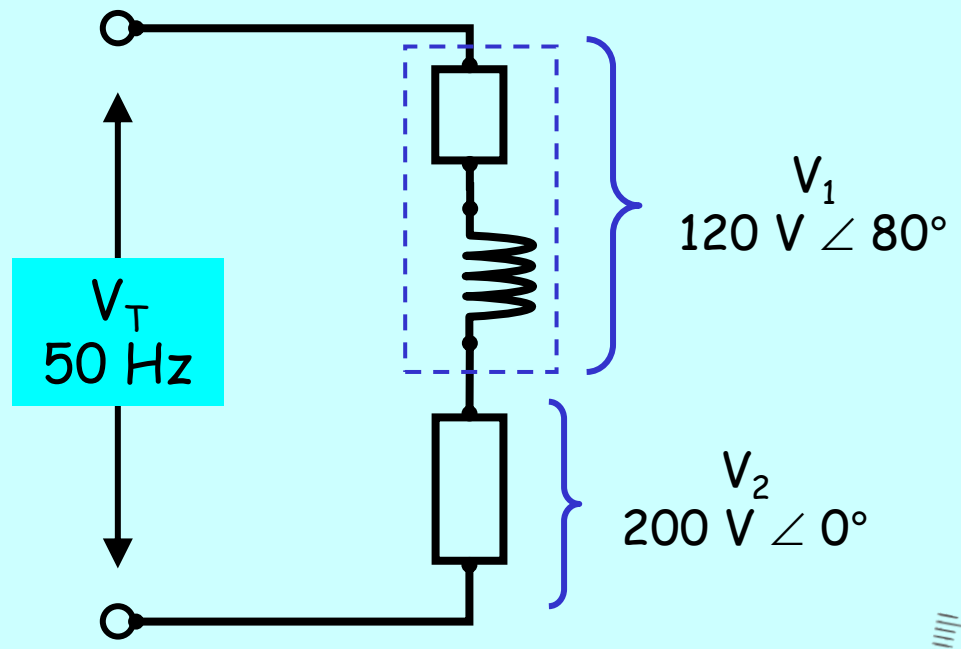
Measure the length of the reference phasor with a compass and draw an arc from the tip of the second phasor.

Measure the length of the second phasor with a compass and draw an arc from the tip of the reference phasor.

Draw in the resultant Phasor.

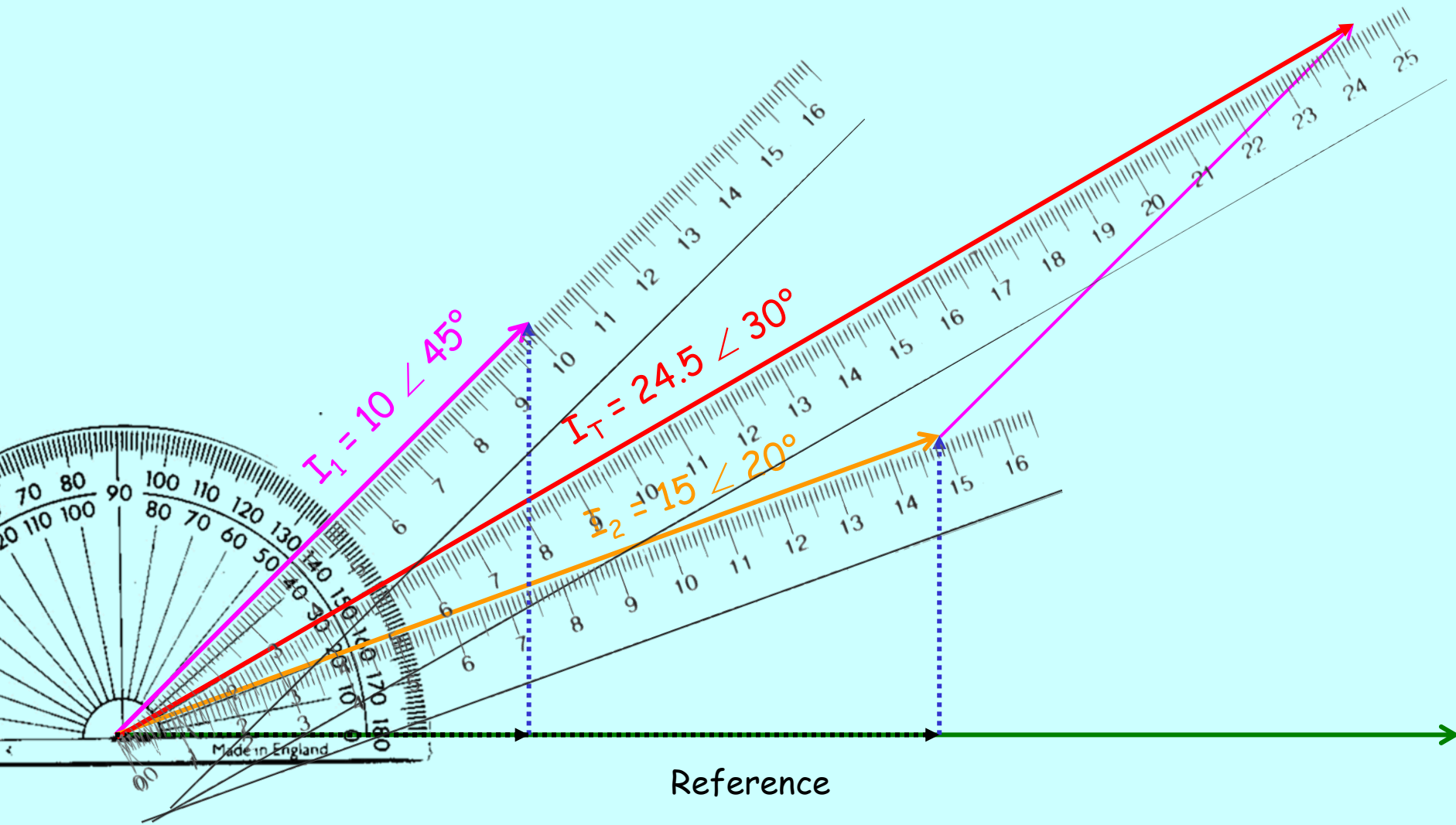
18/07/2022 Measure the Magnitude and Phase Angle of the Resultant Phasor.

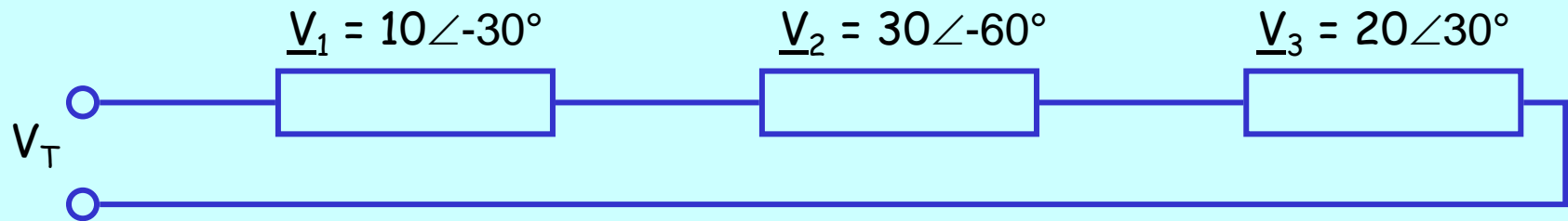




$$I_1 = 10 \angle 45^\circ$$

$$I_2 = 15 \angle 20^\circ$$



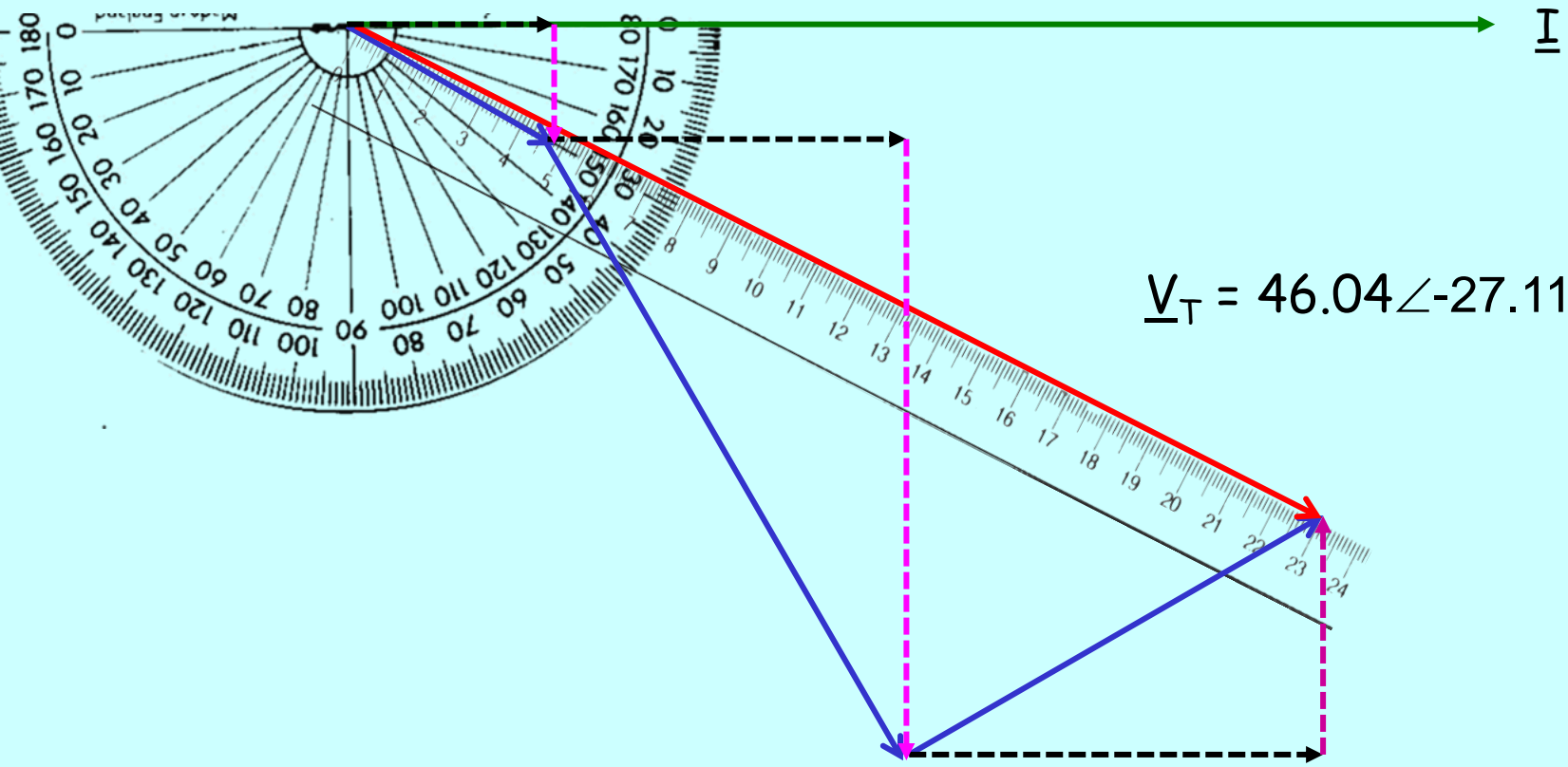


Series Circuit

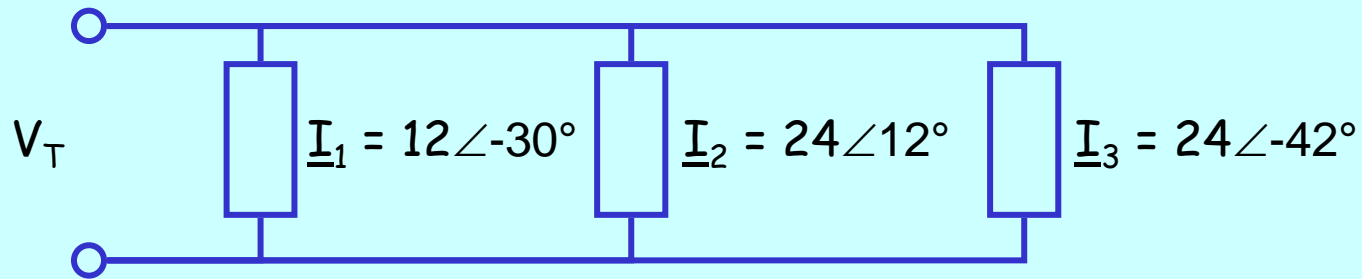
$\therefore$  the Reference is Current

AND

$$\underline{V}_T = \underline{V}_1 + \underline{V}_2 + \underline{V}_3$$





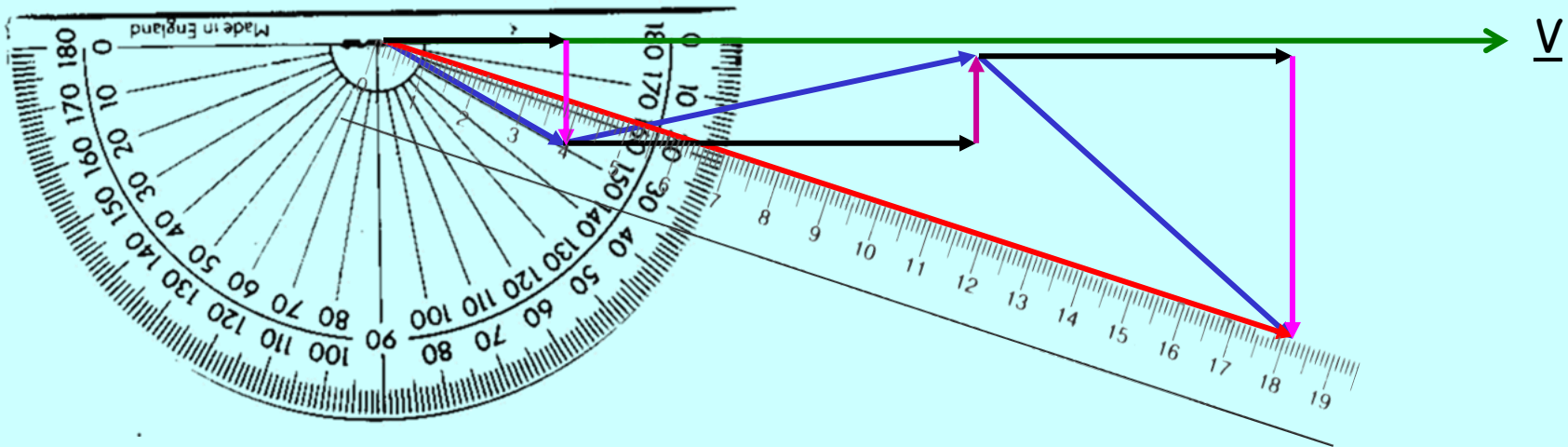


Parallel Circuit

$\therefore$  the Reference is Voltage

AND

$$\underline{I}_T = \underline{I}_1 + \underline{I}_2 + \underline{I}_3$$

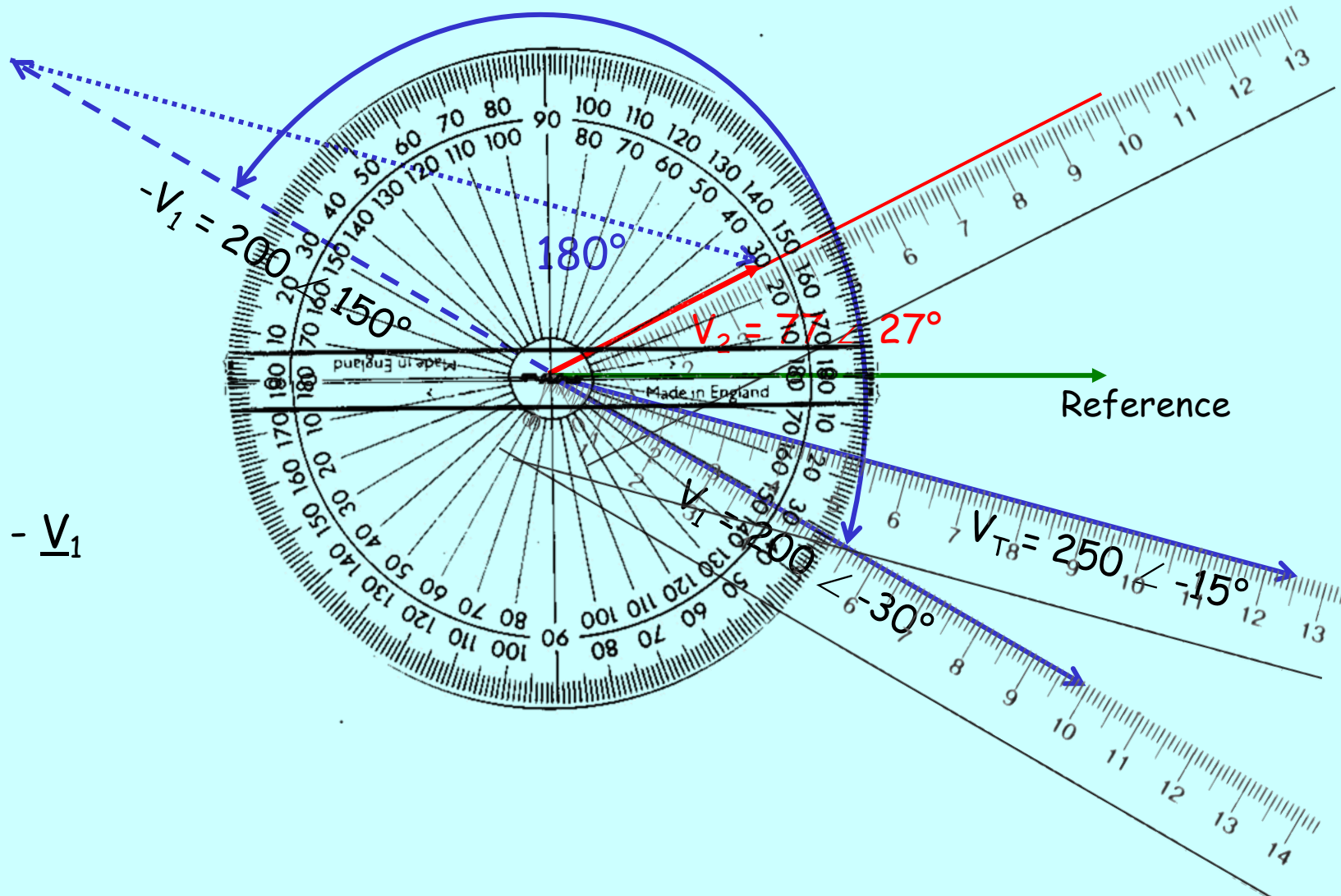


$$\underline{I}_T = 54.45 \angle -18.27^\circ$$

$$\underline{V}_1 = 200 \angle -30^\circ$$

$$\underline{V}_T = 250 \angle -15^\circ$$

$$\underline{V}_2 = \underline{V}_T - \underline{V}_1$$



# End of Lesson

## Practical Exercises

Phasor Addition

Pp. 75 - 80



**UEENEEG102A**

**Solve problems in  
low voltage a.c. circuits**

**Resistive  
AC Circuits**

# Objectives:

At the end of this lesson students should be able to:

1. Apply Ohm's Law in a Resistive ac circuit.
2. State the phase relationship between Voltage and Current in a Resistive ac circuit.
3. Draw the phasor diagram for a Resistive ac circuit.
4. Calculate the Power consumed by a Resistive ac circuit.

# Terminology and Relationships

In an ac circuit opposition to current flow is called:

Impedance (Z).  $Z = \frac{V}{I}$

Ohm's Law for  
ac circuits

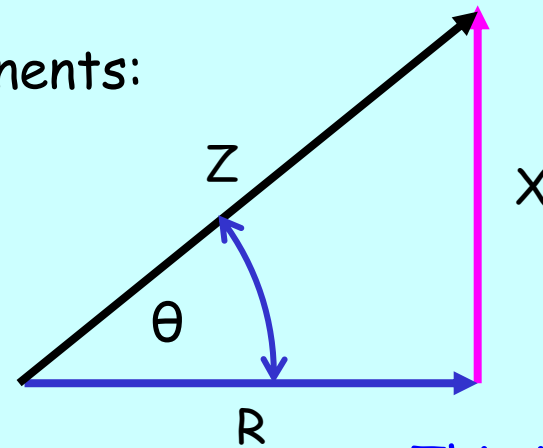
Impedance (Z) has three (3) components:

R Resistance

X Reactance

$X_L$  Inductive Reactance

$X_C$  Capacitive Reactance

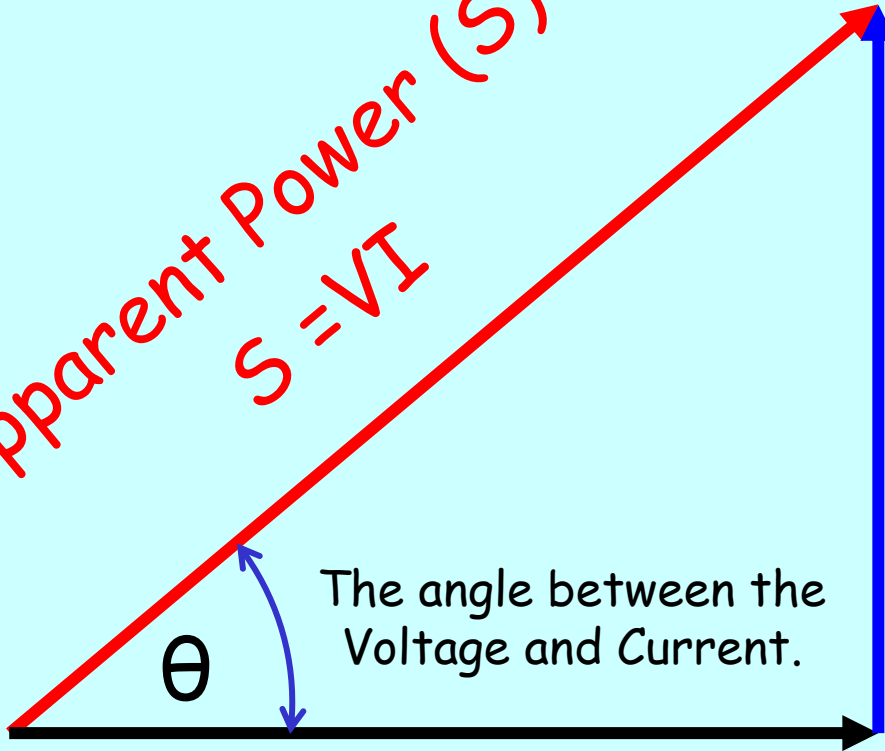


This is called the  
Impedance Triangle

θ The angle between the Voltage and Current.

# Power Triangle

Apparent Power (S)  
 $S = VI$



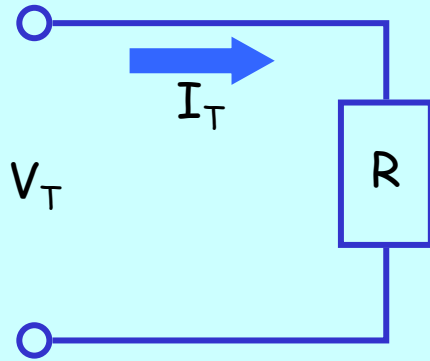
$Q = VI \sin \theta$   
Reactive  
Power (Q)

$$P = VI \cos \theta$$

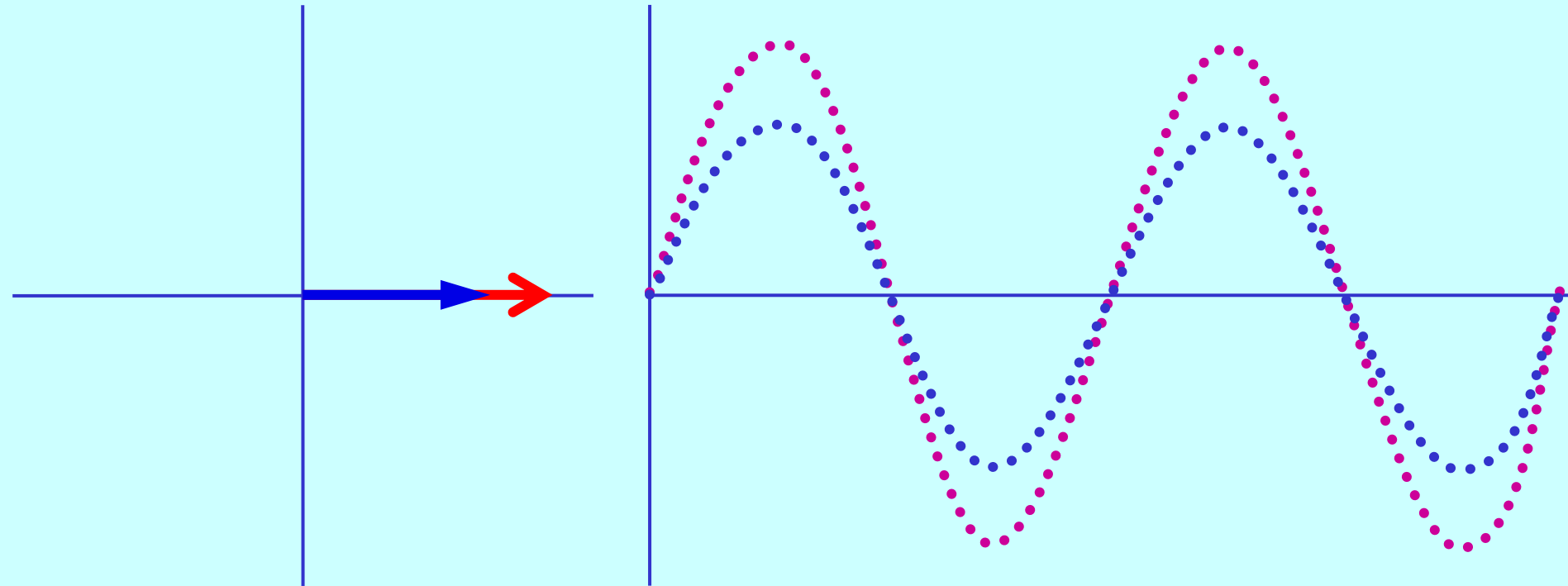
Real Power (P)

$\cos \theta$  is called the Power Factor ( $\lambda$ )  
of the circuit because it relates the  
Real Power to the Apparent Power.



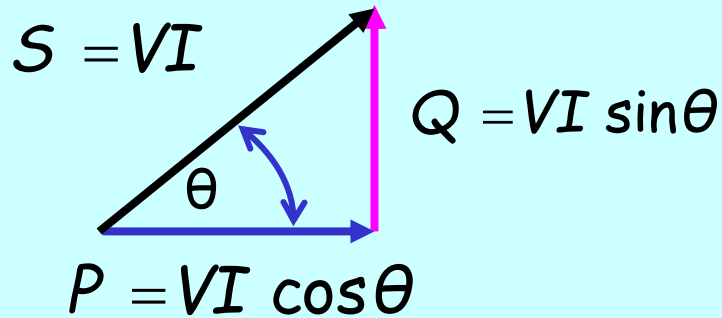


In a purely **RESISTIVE** ac circuit  
the **Current** is **IN PHASE**  
with the **Voltage**.



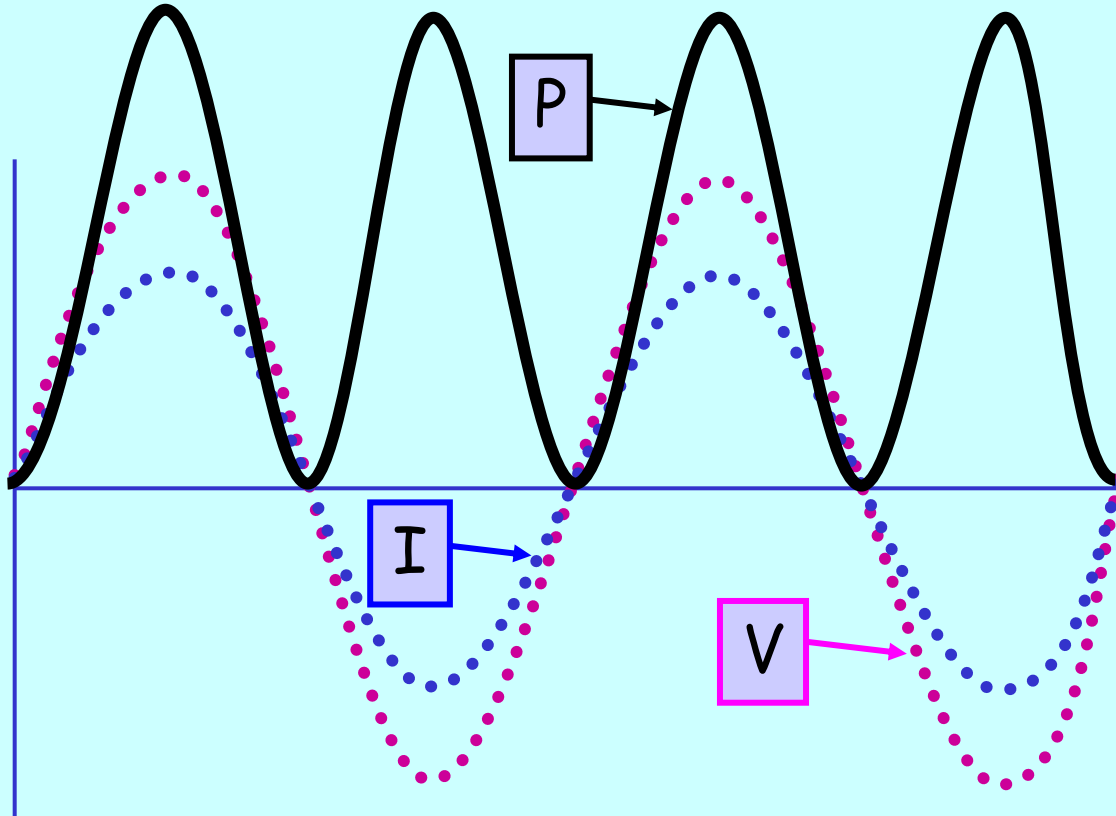
# From the Power Triangle:

In a purely resistive circuit Current is  
In Phase with Voltage  $\therefore \theta = 0^\circ$   
( $\cos 0 = 1$  &  $\sin 0 = 0$ )



$$P = VI$$

$$Q = 0$$



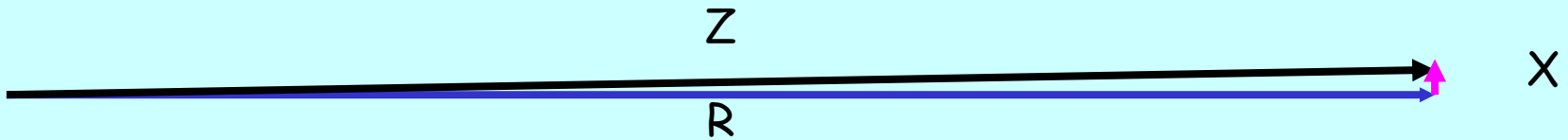
All practical components have some resistance and therefore use some Real Power.

Resistance is that property of a circuit that opposes current flow.

In any circuit:  $Z = \frac{V}{I}$

So in a purely Resistive circuit:  $Z \approx R$

In an ac circuit the Voltage is continually changing,  
but the Resistance is constant.



With a phase angle of  $-\theta$  ( $\approx 0^\circ$ ).

# Example Calculations

$$Z = \frac{V}{I}$$

$$Z \approx R$$

$$S = VI$$

$$P = VI \cos \theta$$

$$Q = VI \sin \theta$$

Ex. 1

The element of a toaster has a resistance of  $60 \Omega$ . Determine the circuit current if the toaster is connected to a  $240 \text{ V } 50 \text{ Hz}$  supply.

What do we know?

$$R = 60 \Omega$$

$$V = 240 \text{ V}$$

What do we want to know?

$$I = \frac{V}{Z}$$

$$I = \frac{240}{60}$$

$$I = 4 \text{ A}$$

## Ex. 2

A purely resistive lamp is connected to a 24 V 50 Hz supply. If the lamp draws 1.25 A determine the circuit resistance, circuit impedance and the power consumption.

What do we know?

$$V = 24 \text{ V}$$

$$I = 1.25 \text{ A}$$

What do we want to know?

$$Z = R$$

$$Z = \frac{V}{I}$$

$$Z = \frac{24}{1.25}$$

$$Z = 19.2 \Omega$$

$$P = VI \cos \theta$$

$$P = 24 \times 1.25 \times 1$$

$$P = 30 \text{ W}$$

### Ex. 3

A 2k2  $\Omega$  resistor is connected to a sinewave generator. If the frequency of the signal is set to 2 kHz and the circuit draws 4  $\mu$ A determine the output voltage of the generator.

What do we know?

$$Z = R = 2\text{k}2 \Omega$$

$$f = 2 \text{ kHz}$$

$$I = 4 \mu\text{A}$$

What do we want to know?

$$V = IZ$$

$$V = 2200 \times 4\mu$$

$$V = 8.8\text{mV}$$

## Ex. 4

A circuit has a resistance of  $20 \Omega$  and draws a current of  $16 \text{ A}$ . Determine:

- The applied voltage,
- The circuit impedance, and
- The power drawn by the circuit.

What do we know?

$$R = 20 \Omega$$

$$I = 16 \text{ A}$$

What do we want to know?

$$(a) \quad V = ZI$$

$$V = 20 \times 16$$

$$V = 320 \text{ V}$$

$$(b) \quad Z = R = 20 \Omega$$

$$(c) \quad P = VI$$

$$P = 320 \times 16$$

$$P = 5.12 \text{ kW}$$



**UEENEEEG102A**

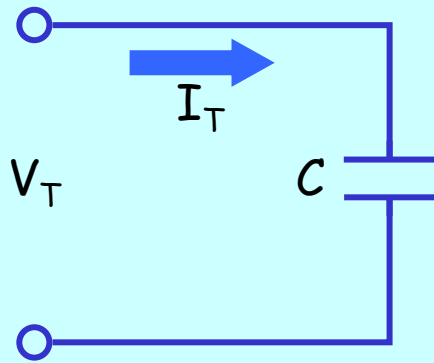
**Solve problems in  
low voltage a.c. circuits**

**Capacitive  
AC Circuits**

# Objectives:

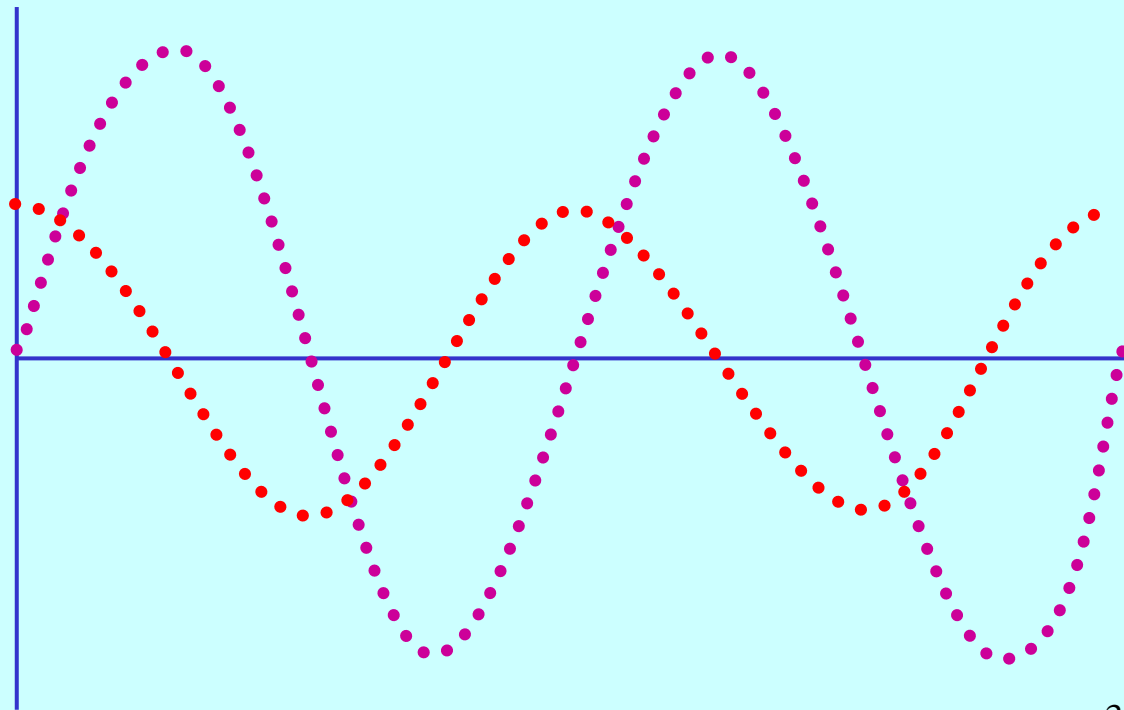
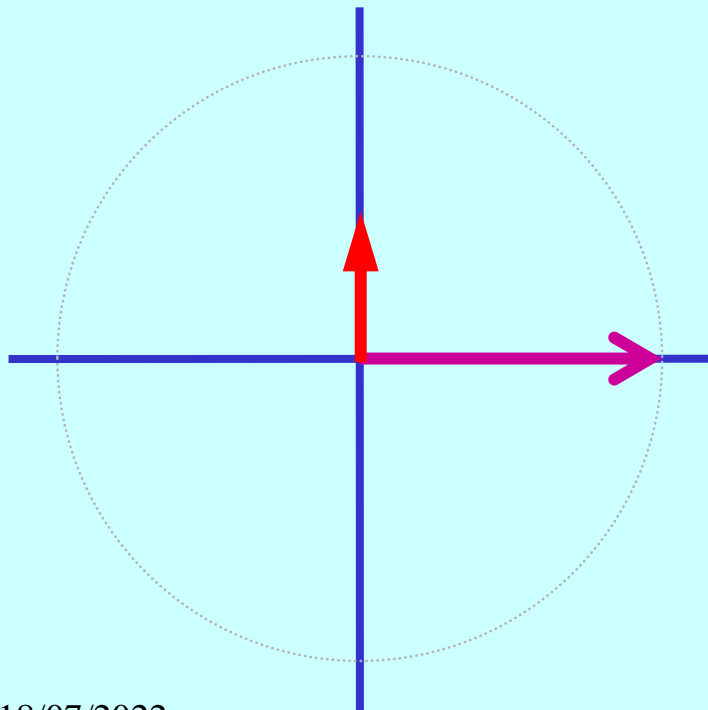
At the end of this lesson students should be able to:

1. List the effects and applications of Capacitance in an ac circuit.
2. Define the term Capacitive Reactance.
3. Draw Impedance, Current and Voltage phasors in an Ideal Capacitive circuit.
4. Calculate Impedance, Currents and Voltages in an Ideal Capacitive circuit given certain characteristics.
5. Calculate the Power consumed by a Capacitive ac circuit.

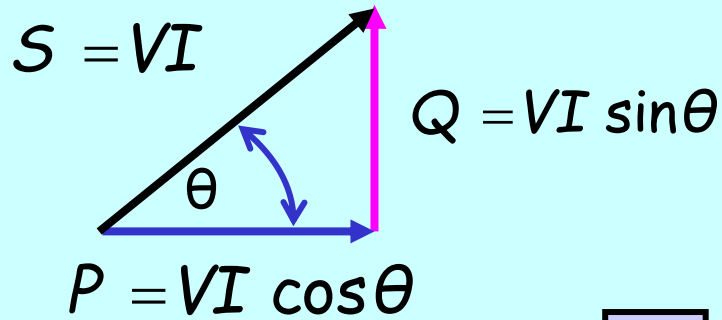


Capacitance is that property of a circuit that opposes changes in voltage.

In a purely **CAPACITIVE** ac circuit the **Current Leads** the **Voltage** by  $90^\circ$ .



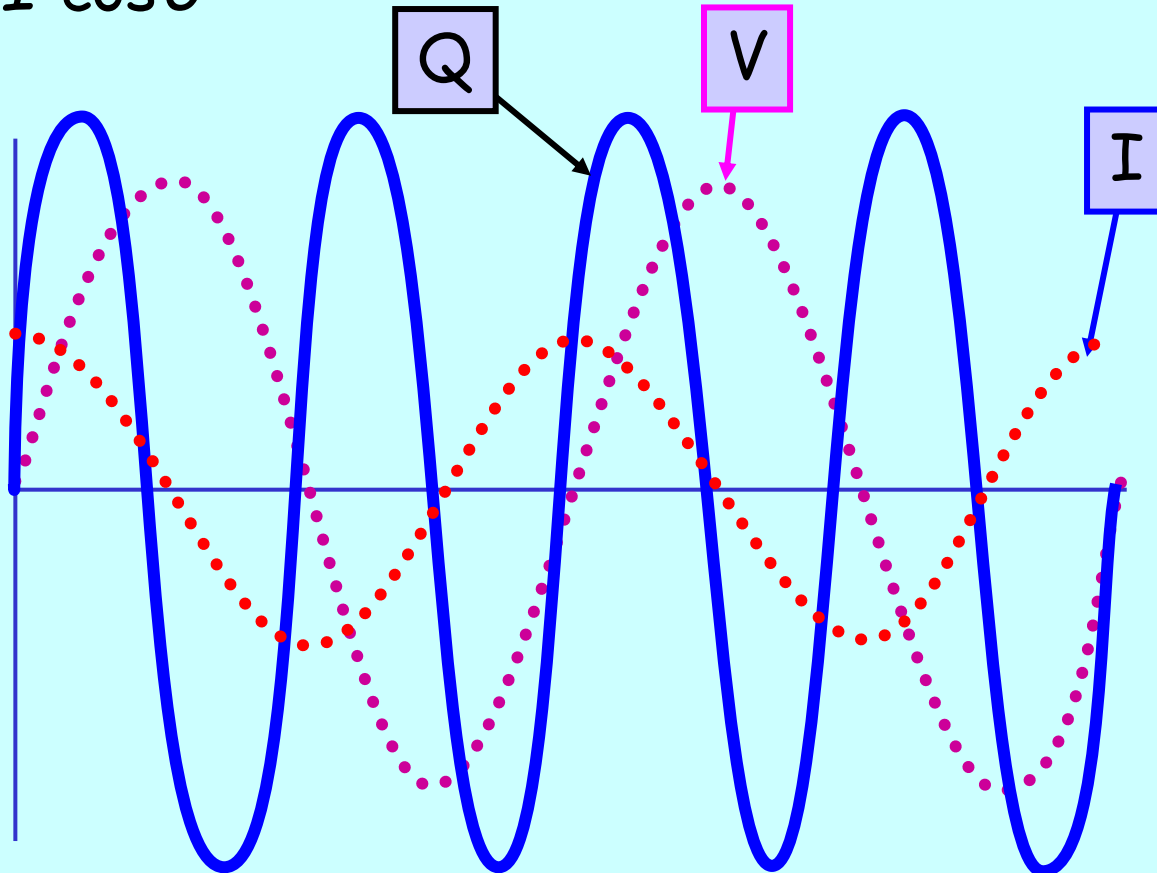
# From the Power Triangle:



In a purely Capacitive circuit Current Leads Voltage  $\therefore \theta = 90^\circ$   
( $\cos 90 = 0$  &  $\sin 90 = 1$ )

$$P = 0$$

$$Q = VI$$

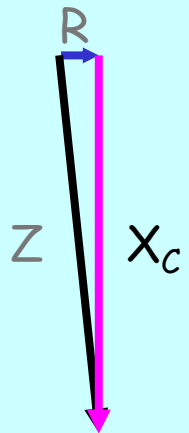


Capacitance is that property of a circuit that opposes changes in voltage.

In any circuit:  $Z = \frac{V}{I}$

So in a purely Capacitive circuit  $Z \approx X_C$  ( $X_C = \text{Capacitive Reactance}$ )

In an ac circuit the Voltage is continually changing, and the Capacitive Reactance is frequency dependant.


$$|X_C| = \frac{1}{2\pi f C}$$

With a phase angle of  $-\theta$  ( $\approx -90$ ).

# Example Calculations

CIVIL

$$Z = \frac{V}{I}$$

$$Z \approx X_C$$

$$S = VI$$

$$|X_C| = \frac{1}{2\pi fC}$$

$$P = VI \cos\theta$$

$$|X_L| = 2\pi fL$$

$$Q = VI \sin\theta$$

Ex. 1

Determine the impedance of a purely capacitive circuit which draws 4.7 A from a 240 V, 50 Hz supply.

What do we know?

$$I = 4.7 \text{ A}$$

$$V = 240 \text{ V}$$

What do we want to know?

$$Z = ?$$

$$Z \approx X_C$$

$$X_C = \frac{V}{I}$$

$$X_C = \frac{240}{4.7}$$

$$X_C = 51 \Omega$$

## Ex. 2

Determine the reactance and circuit current drawn by an 8  $\mu$ F Capacitor connected to a 240 V, 50 Hz supply. Draw the Phasor diagram for this component.

What do we know?

$$C = 8 \mu F$$

$$V = 240 V$$

$$f = 50 \text{ Hz}$$

What do we want to know?

$$X_c = \frac{1}{2\pi f C}$$

C I V I L

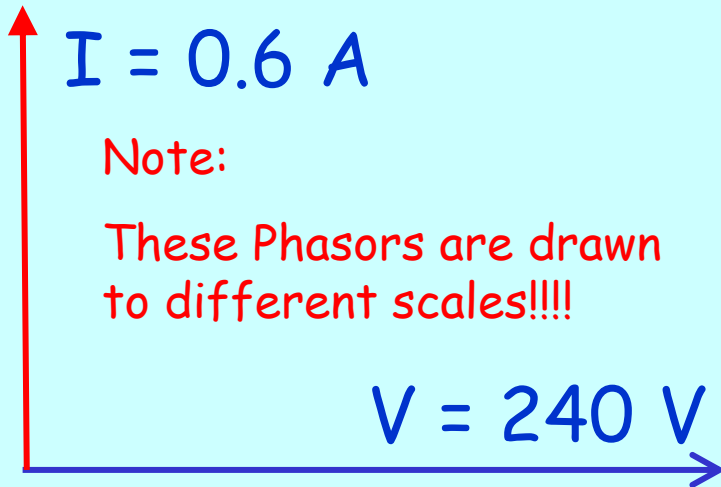
$$X_c = \frac{1}{2\pi \times 50 \times 8\mu}$$

$$X_c = 397.89 \Omega$$

$$I = \frac{V}{Z}$$

$$I = \frac{240}{397.89}$$

$$I = 0.603 A$$





## Ex. 2

A single phase synchronous motor draws 40 A with a leading power factor of 0.22 from a 240 V, 50 Hz supply. Determine the Apparent and True Powers.

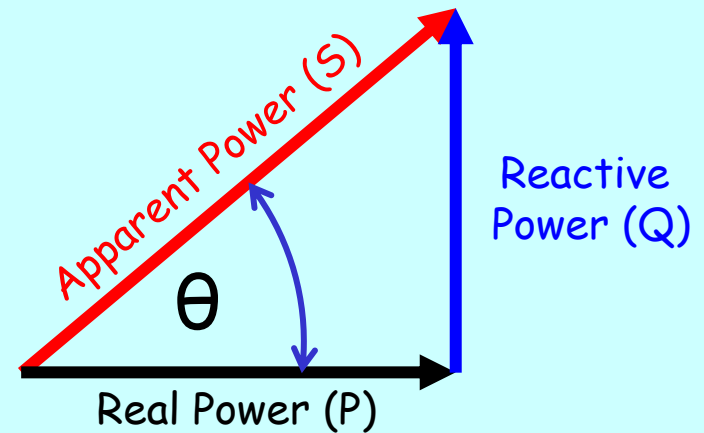
What do we know?

$$I = 40 \text{ A}$$

$$\lambda = 0.22 \text{ lead}$$

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$



What do we want to know?

$$S = VI$$

$$S = 240 \times 40$$

$$S = 9.6 \text{ kVA}$$

$$P = VI \cos \theta$$

$$\lambda = \cos \theta$$

$$P = 9.6 \text{ k} \times 0.22$$

$$P = 2.1 \text{ kW}$$

Ex. 3

Calculate the phase angle for a circuit which has a Power Factor ( $\lambda$ ) of:

- a. 0.1 lead, and
- b. 0.33 lead.

What do we know?

$$\lambda_a = 0.10 \text{ lead}$$

$$\lambda_b = 0.33 \text{ lead}$$

What do we want to know?

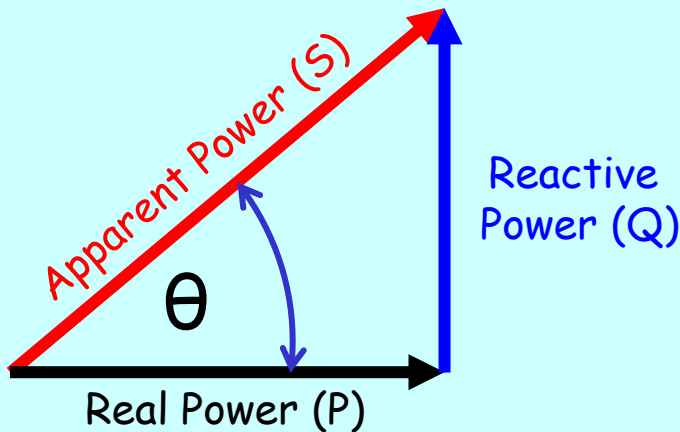
$$\theta_a = \cos^{-1}(0.10)$$

$$\theta_b = \cos^{-1}(0.33)$$

$$\theta_a = 84.26^\circ$$

$$\theta_b = 70.73^\circ$$

Circuits are Capacitive.



Ex. 3

Calculate the phase angle for a circuit which has a Power Factor ( $\lambda$ ) of:

- a. 0.1 lead, and
- b. 0.33 lead.

What do we know?

$$\lambda_a = 0.10 \text{ lead}$$

$$\lambda_b = 0.33 \text{ lead}$$

What do we want to know?

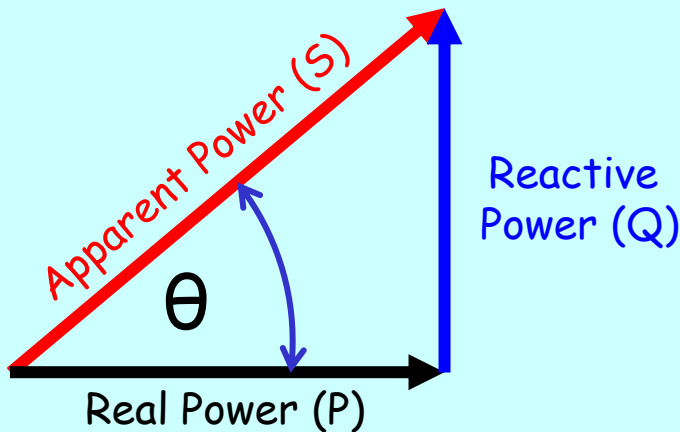
$$\theta_a = \cos^{-1}(0.10)$$

$$\theta_b = \cos^{-1}(0.33)$$

$$\theta_a = 84.26^\circ$$

$$\theta_b = 70.73^\circ$$

Circuits are Capacitive.



Ex. 3

Calculate the capacitance of a capacitor if its capacitive reactance is 100  $\Omega$  at a frequency of 50 Hz.

What do we know?

$$X_c = 100 \Omega$$

$$f = 50 \text{ Hz}$$

$$X_c = \frac{1}{2\pi fC}$$

What do we want to know?

$$C = ?$$

$$C = \frac{1}{2\pi fX_c}$$

$$C = \frac{1}{100\pi \times 100} = 31.8 \mu\text{F}$$

Ex. 4

Determine the current taken by a 100  $\mu$ F capacitor which is connected to a 230 V 50 Hz supply.

What do we know?

$$C = 100 \mu\text{F}$$

$$V = 230 \text{ V}$$

$$f = 50 \text{ Hz}$$

What do we want to know?

$$I = ?$$

$$X_c = \frac{1}{2\pi fC}$$

$$X_c = \frac{1}{100\pi \times 100\mu} = 31.8 \Omega$$

$$I = \frac{V}{Z} = \frac{230}{31.8} = 7.23 \text{ A}$$

# End of Lesson

## Practical Exercises

Ohm's Law in ac & dc Circuits

Inductive Reactance

Capacitive Reactance

**UEENEEEG102A**

**Solve problems in  
low voltage a.c. circuits**

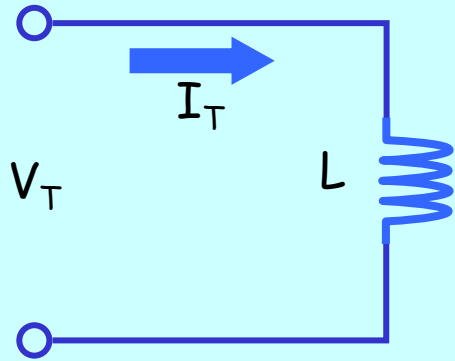
**Inductive  
AC Circuits**

# Objectives:

At the end of this lesson students should be able to:

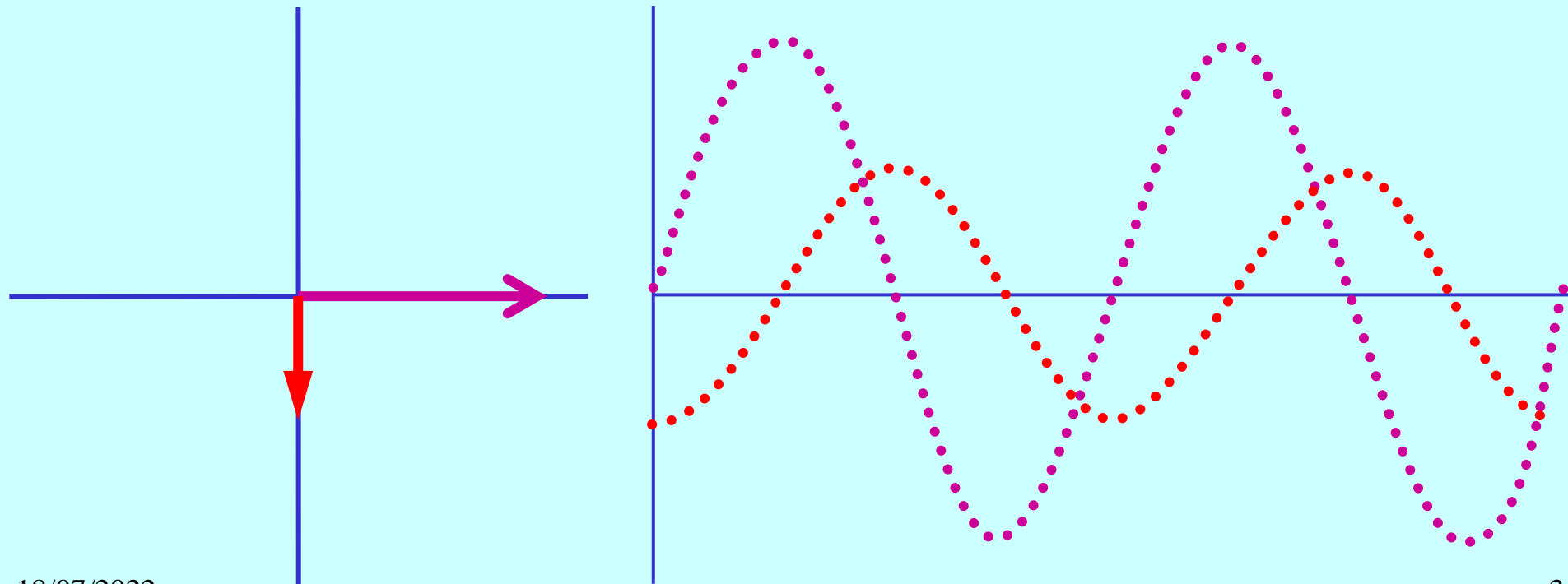
1. List the effects and applications of Inductance in an ac circuit.
2. Define the term Inductive Reactance.
3. Draw Impedance, Current and Voltage phasors in an Ideal Inductive circuit.
4. Calculate Impedance, Currents and Voltages in an Ideal Inductive circuit given certain characteristics.
5. Calculate the Power consumed by an Inductive ac circuit.





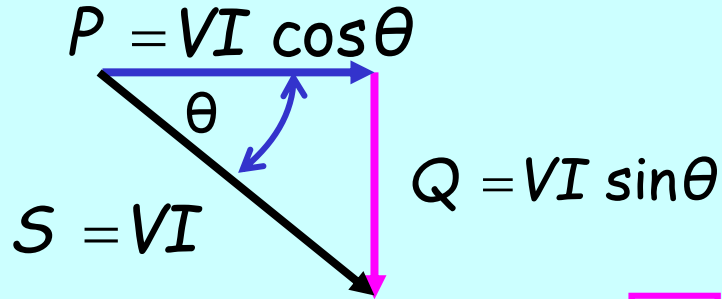
Inductance is that property of a circuit that opposes changes in current.

In a purely **INDUCTIVE** ac circuit the **Current Lags** the **Voltage** by  $90^\circ$ .



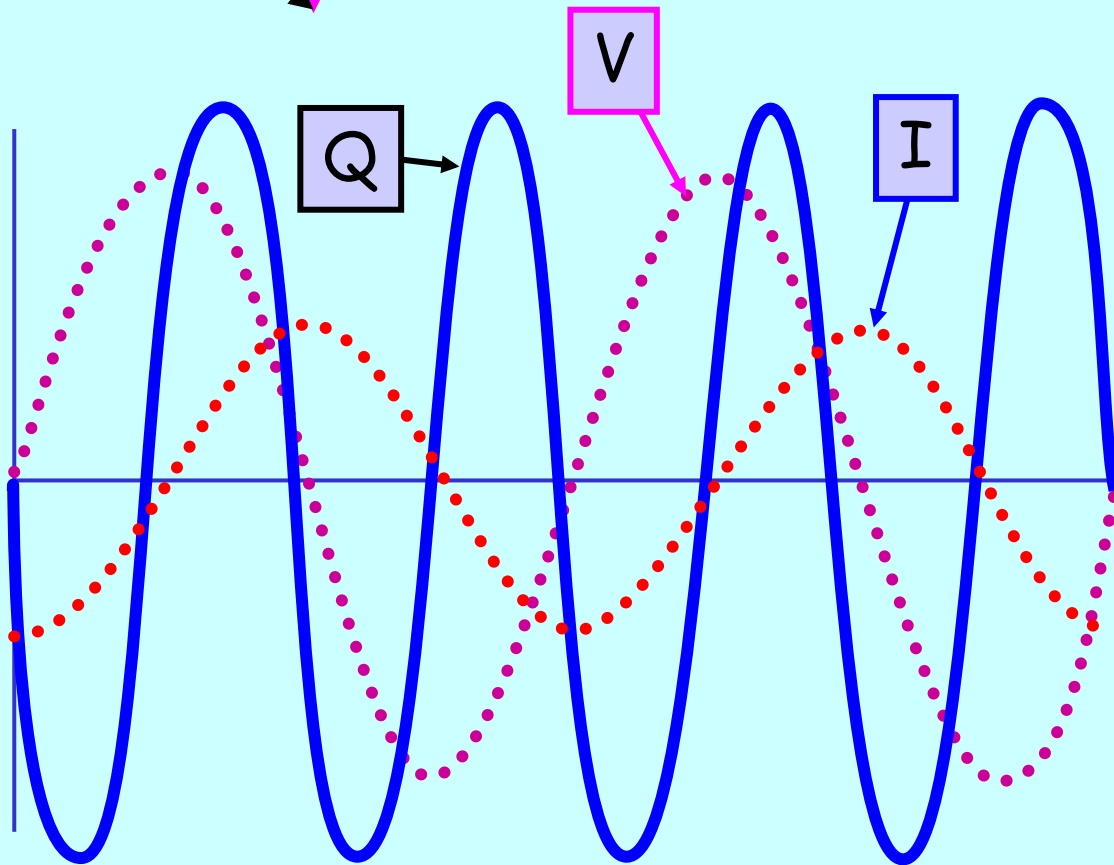
# From the Power Triangle:

In a purely Inductive circuit Current Lags Voltage  $\therefore \theta = -90^\circ$   
( $\cos -90 = 0$  &  $\sin -90 = -1$ )



$$P = 0$$

$$Q = -VI$$



Practical Inductors have some resistance and therefore use some Real Power ( $I^2R$ ).

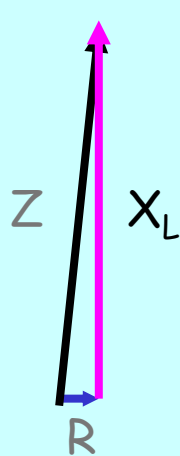
Inductors are used in AC Circuits because they use very little Real Power.

Inductance is that property of a circuit that opposes changes in current.

In any circuit:  $Z = \frac{V}{I}$

So in a purely Inductive circuit  $Z \approx X_L$  ( $X_L = \text{Inductive Reactance}$ )

In an ac circuit the Voltage is continually changing, and the Inductive Reactance is frequency dependant.



$$|X_L| = 2\pi fL$$

With a phase angle of  $-\theta$  ( $\approx 90^\circ$ ).

# Example Calculations

$$Z = \frac{V}{I}$$

$$Z \approx X_L$$

$$S = VI$$

$$|X_L| = 2\pi fL$$

$$P = VI \cos\theta$$

$$Q = VI \sin\theta$$

Ex. 1

Determine the impedance of an inductor if it draws 1.8 A from a 230 V 50 Hz supply.

What do we know?

$$I = 1.8 \text{ A}$$

$$V = 240 \text{ V}$$

What do we want to know?

$$Z = ?$$

$$Z \approx X_L = \frac{V}{I}$$

$$Z \approx X_L = \frac{V}{I} = \frac{240}{1.8} = 133.3 \text{ } \Omega$$

## Ex. 2

Determine the impedance and inductance of a coil with negligible resistance which draws 0.2 A when connected to a 240 V, 50 Hz supply.  
Draw the Phasor diagram for this component.

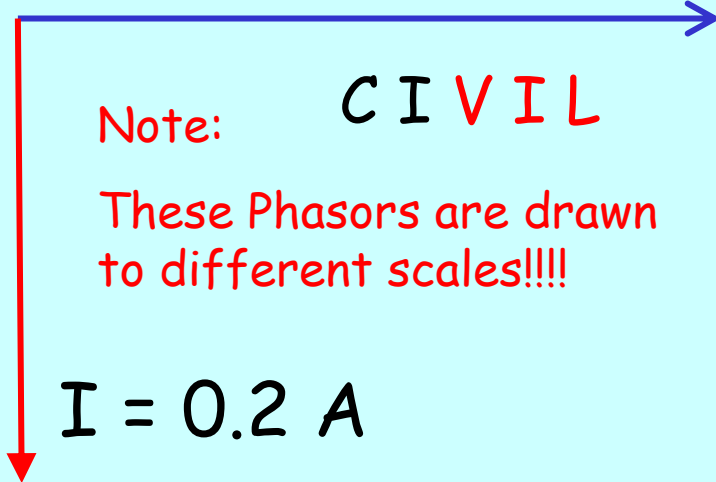
What do we know?

$$I = 0.2 \text{ A}$$

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$V = 240 \text{ V}$$



What do we want to know?

$$Z \approx X_L = \frac{V}{I}$$

$$X_L = \frac{240}{0.2}$$

$$X_L = 1200 \Omega$$

$$L = \frac{X_L}{2\pi f}$$

$$L = \frac{1200}{2\pi \times 50}$$

$$L = 3.82 \text{ H}$$

$$X_L = 2\pi fL$$

### Ex. 3

Draw the V-I Phasor diagram (with values) for a 0.2 H coil with negligible resistance when it is connected to a 240 V, 50 Hz supply.

What do we know?

$$L = 0.2 \text{ H}$$

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

What do we want to know?

C I V I L

$$Z \approx X_L = 2\pi fL$$

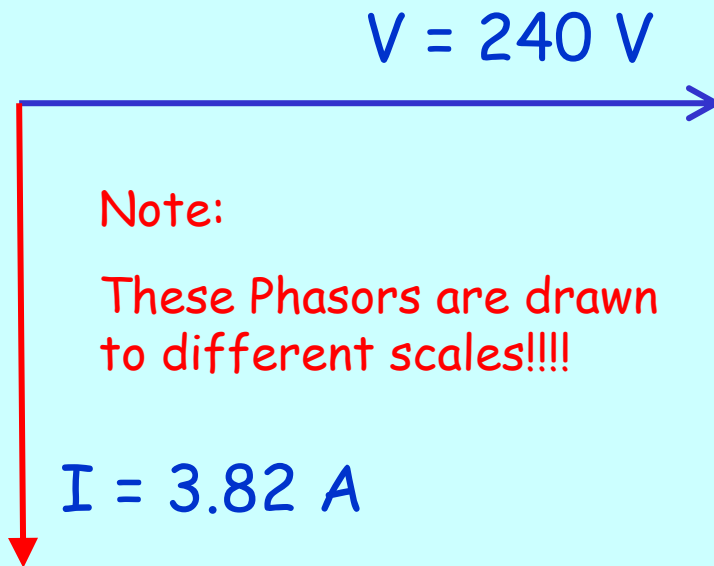
$$X_L = 2\pi \times 50 \times 0.2$$

$$X_L = 62.8 \Omega$$

$$I = \frac{V}{Z}$$

$$I = \frac{240}{62.8}$$

$$I = 3.82 \text{ A}$$



## Ex. 4

A welder draws 40 A with a lagging power factor of 0.22 from a 240 V, 50 Hz supply. Determine the Apparent and True Powers for the welder.

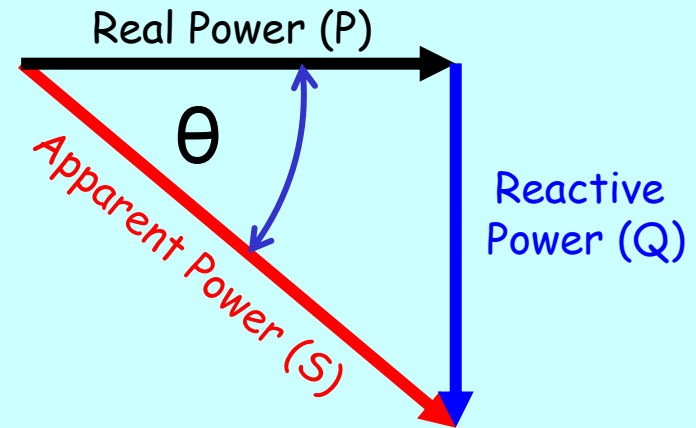
What do we know?

$$I = 40 \text{ A}$$

$$\lambda = 0.22 \text{ lead}$$

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$



What do we want to know?

$$S = VI$$

$$S = 240 \times 40$$

$$S = 9.6 \text{ kVA}$$

$$P = VI \cos \theta$$

$$\lambda = \cos \theta$$

$$P = 9.6 \text{ k} \times 0.22$$

$$P = 2.1 \text{ kW}$$



Ex. 5

Calculate the phase angle for a circuit which has a Power Factor ( $\lambda$ ) of:

- a. 0.76 lag, and
- b. 0.96 lag.

What do we know?

$$\lambda_a = 0.76 \text{ lag}$$

$$\lambda_b = 0.96 \text{ lag}$$

What do we want to know?

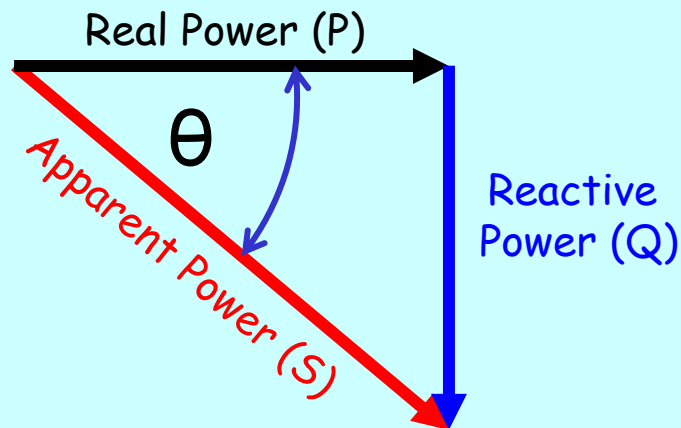
$$\theta_a = \cos^{-1}(0.76)$$

$$\theta_b = \cos^{-1}(0.96)$$

$$\theta_a = -40.5^\circ$$

$$\theta_b = -16.3^\circ$$

Circuits are Inductive.



Ex. 6

An ideal inductor draws 10 A from a 240 V, 50 Hz supply.

How much current would it draw from a 120 V, 100 Hz supply?

What do we know?

$$I_1 = 10 \text{ A}$$

$$V_1 = 240 \text{ V}$$

$$f_1 = 50 \text{ Hz}$$

What do we want to know?

$$I_2 = ?$$

$$V_2 = 120 \text{ V}$$

$$f_2 = 100 \text{ Hz}$$

$$I_2 = \frac{120}{48}$$

$$I_2 = 2.5 \text{ A}$$

$$I = \frac{V}{Z}$$

$$Z = X_L = 2\pi fL$$

$$X_{L1} = \frac{V}{I} = \frac{240}{10} = 24 \Omega$$

$$L = \frac{X_{L1}}{2\pi f} = \frac{24}{2\pi \times 50} = 76.4 \text{ mH}$$

$$X_{L2} = 2\pi fL = 2\pi \times 100 \times 76.4 \text{ m}$$

$$X_{L2} = 48 \Omega$$

$$f_2 = 2f_1$$



$$X_{L2} = 2X_{L1}$$

$$X_{L2} = 48 \Omega$$

**UEENEEG102A**

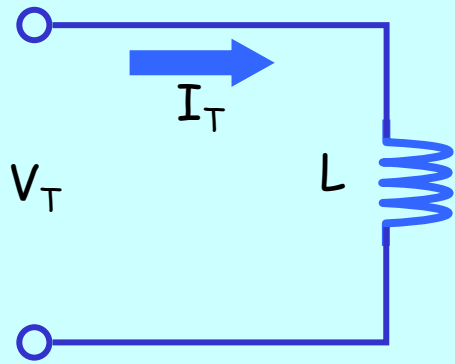
**Solve problems in  
low voltage a.c. circuits**

**Series RL  
AC Circuits**

# Objectives:

At the end of this lesson students should be able to:

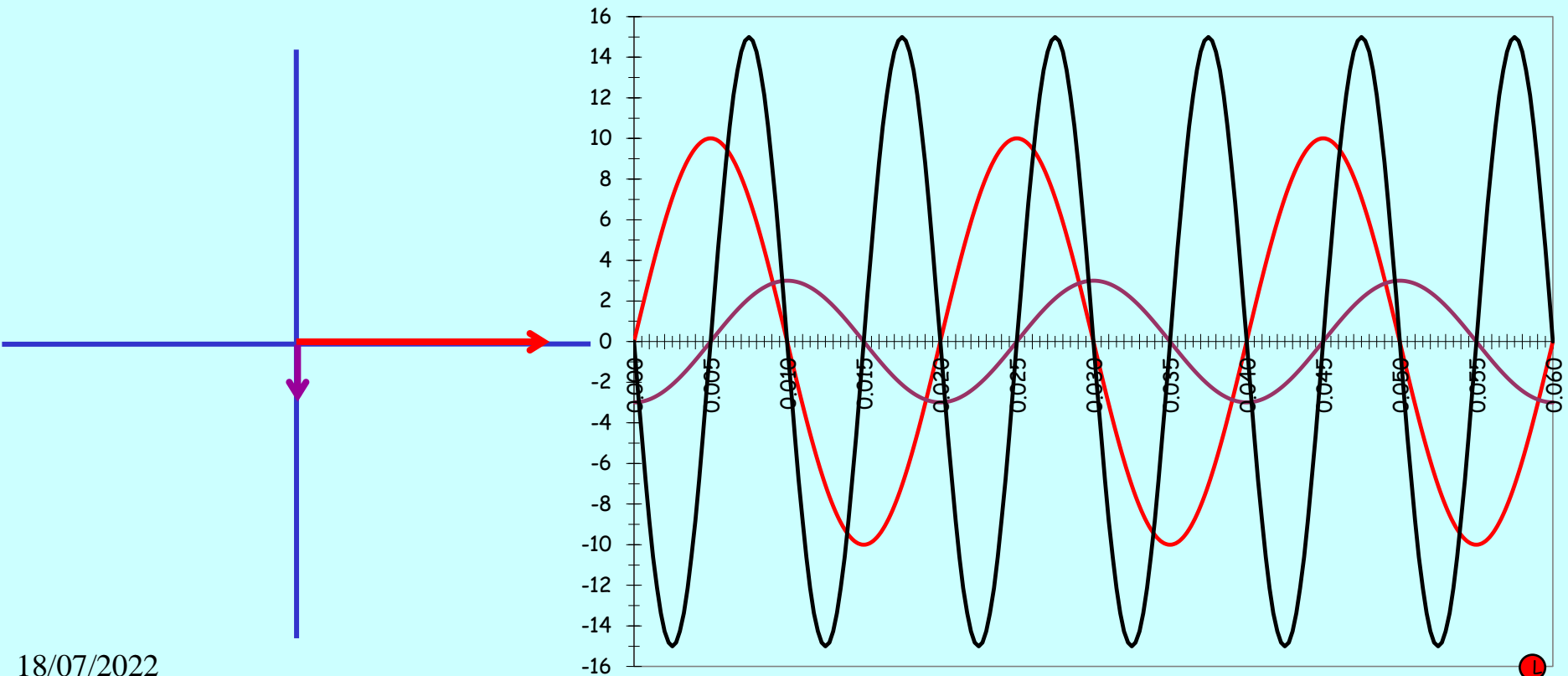
1. Determine circuit quantities and characteristics of Series RL ac circuits.
2. Draw the equivalent circuit for a practical Inductor.
3. Draw and label the Phasor Diagram for Series RL ac circuits.
4. Draw and label Impedance and Power Triangles for Series RL ac circuits.
5. List a number of practical applications for RL circuits.

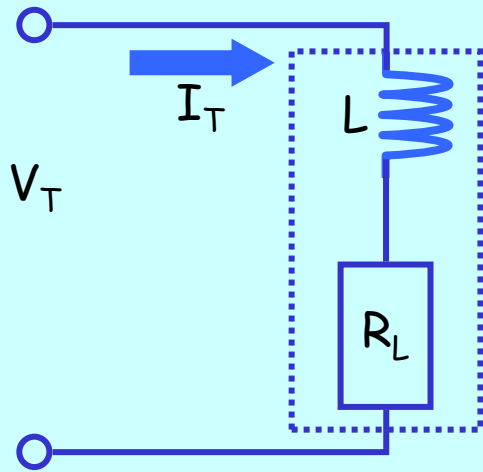


Inductance is that property of a circuit that opposes changes in current.

In a purely **Inductive** ac circuit the **Current Lags** the **Voltage** by  $90^\circ$ .

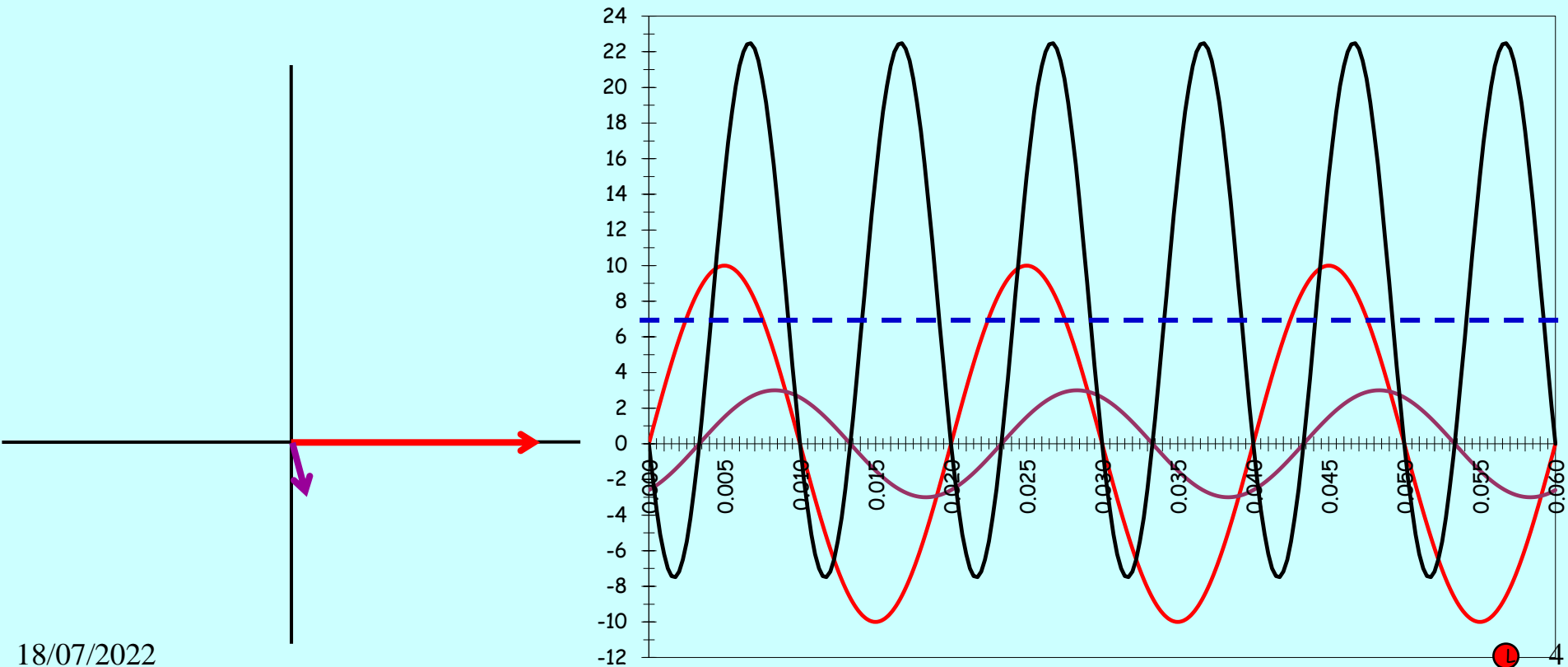
Average Real Power is **ZERO** Watts.





In a practical **Inductive** ac circuit there is some Resistance and therefore the **Current Lags** the **Voltage** by some angle less than  $90^\circ$ .

Average Real Power is **NOT ZERO**.

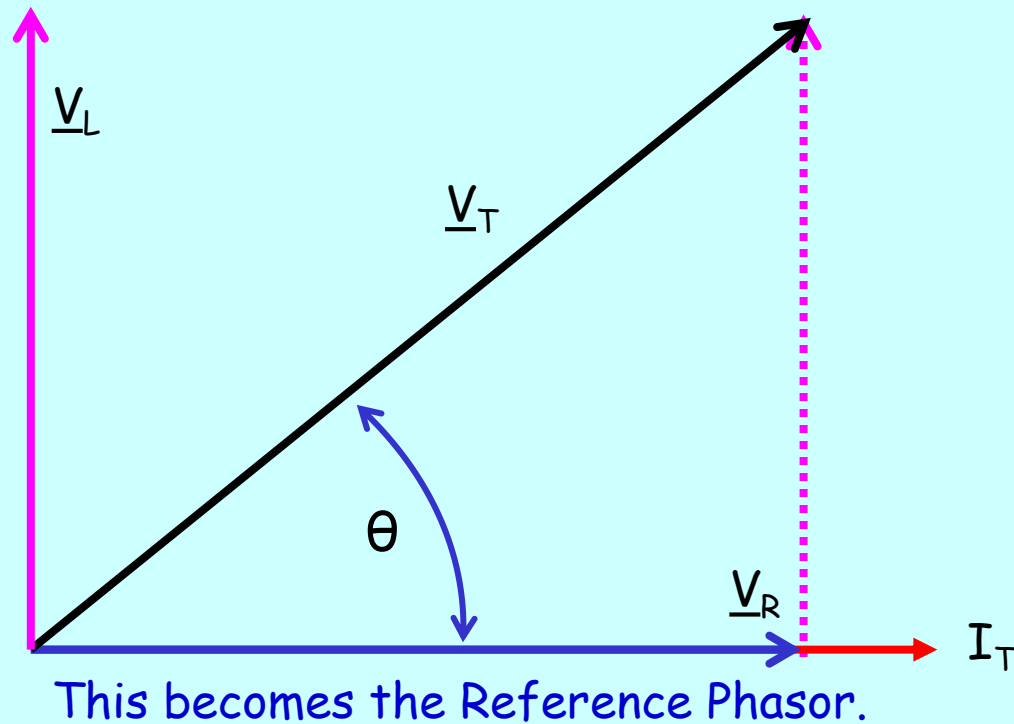


In a SERIES Circuit the common factor is current.

The Voltage across the Resistor ( $\underline{V}_R$ ) is in phase with the current.

The Voltage across the Inductor ( $\underline{V}_L$ ) Leads the current, and therefore  $\underline{V}_R$ , by  $90^\circ$ .

The Algebraic Addition:  $\underline{V}_R + \underline{V}_L$  gives  $\underline{V}_T$ .  
Which then gives us the circuit's phase angle.



In a Series Circuit (where  $I$  is common to ALL elements)  
we can develop the Voltage Triangle.

And then use Ohm's Law to find  
**The Impedance Triangle.**

The Impedance ( $Z_T$ ) can be found from:

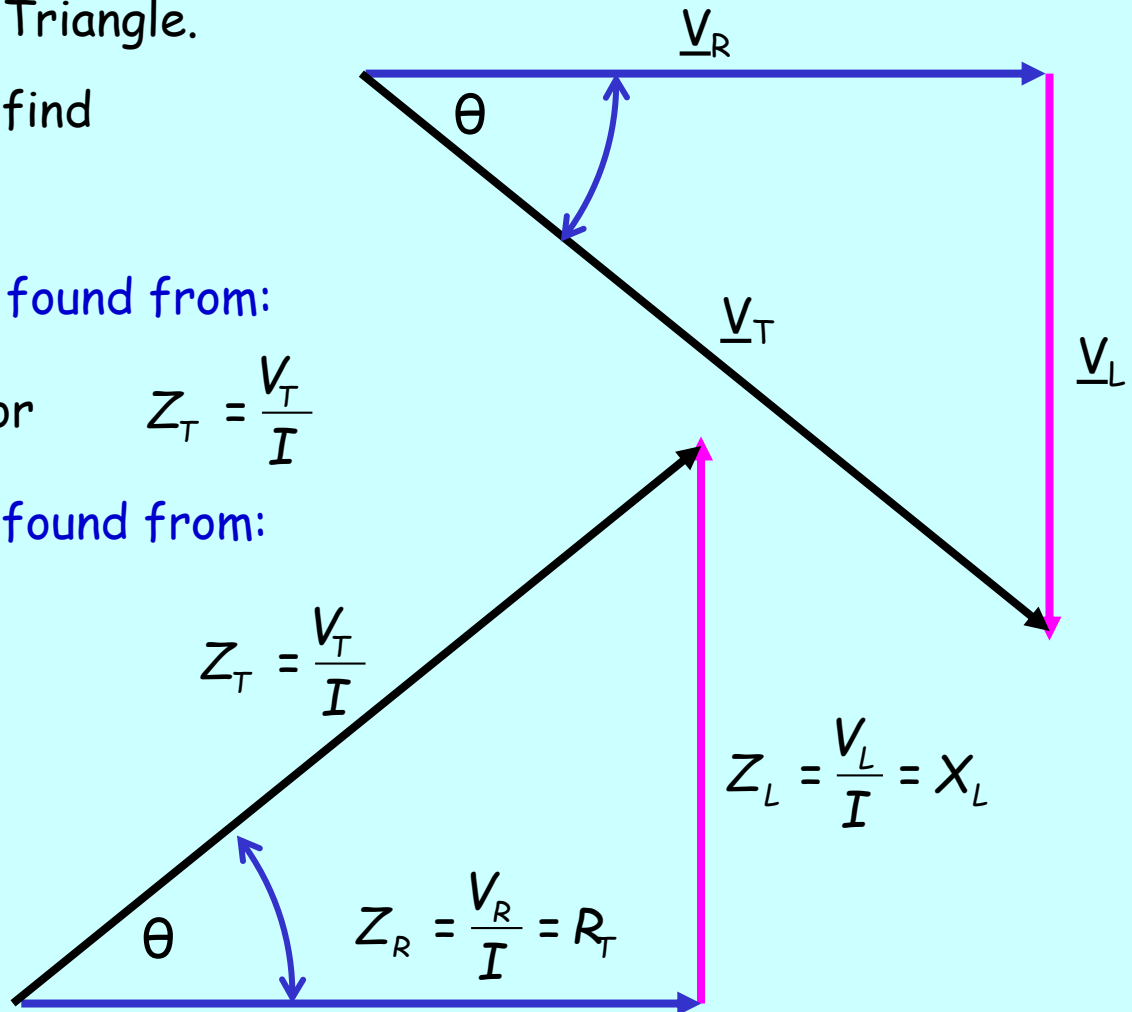
$$Z_T = \sqrt{R_T^2 + X_L^2} \quad \text{or} \quad Z_T = \frac{V_T}{I}$$

The Phase Angle ( $\theta$ ) can be found from:

$$\sin \theta = \frac{X_L}{Z_T} = \frac{V_L}{V_T}$$

or 
$$\cos \theta = \frac{R_T}{Z_T} = \frac{V_R}{V_T}$$

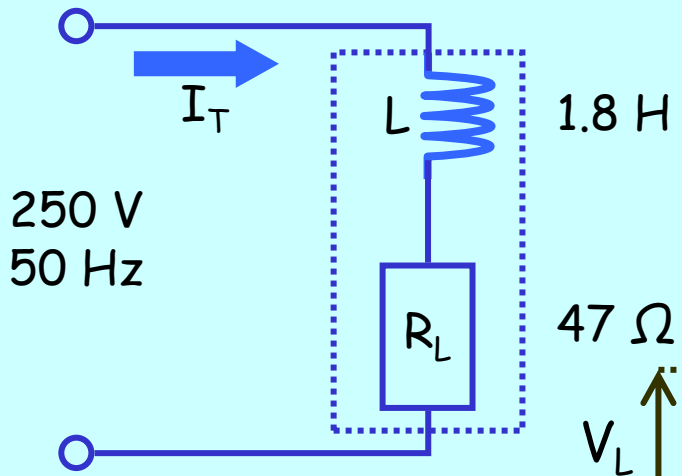
or 
$$\tan \theta = \frac{X_L}{R_T} = \frac{V_L}{V_R}$$



These are Similar Triangles.  
They have the same angles,  
and their sides are proportional.



Example 1



- A. Find Inductive Reactance ( $X_L$ )
- B. Find Circuit Impedance ( $Z$ )
- C. Draw the Phasor Diagram for the circuit.

A.  $X_L = 2\pi fL$   
 $X_L = 2\pi \times 50 \times 1.8$   
 $X_L = 565.48 \Omega$

B.  $Z = \sqrt{R^2 + X_L^2}$   
 $Z = \sqrt{47^2 + 565.48^2}$   
 $Z = 567.44 \Omega$

$I = \frac{V}{Z}$

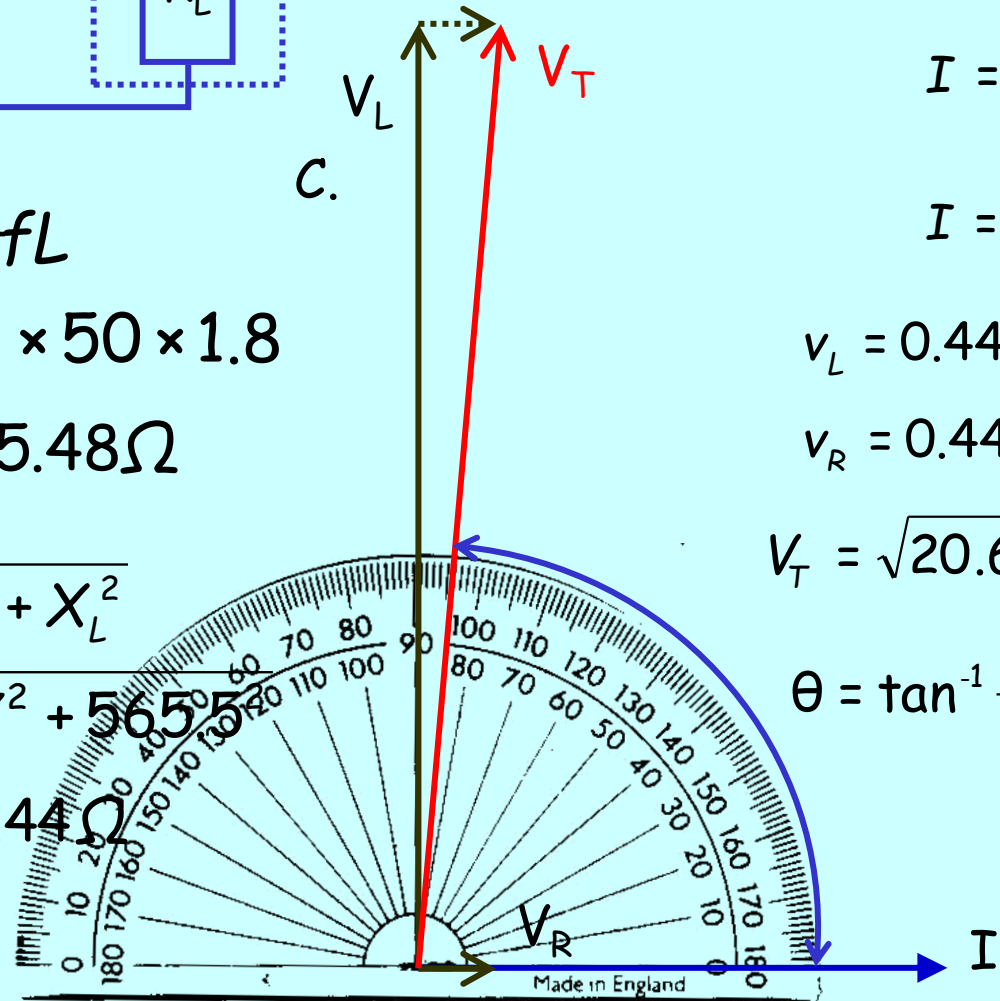
$I = \frac{250}{567.4} = 440 \text{ mA}$

$V_L = 0.44 \times 567 = 249.48 \text{ V}$

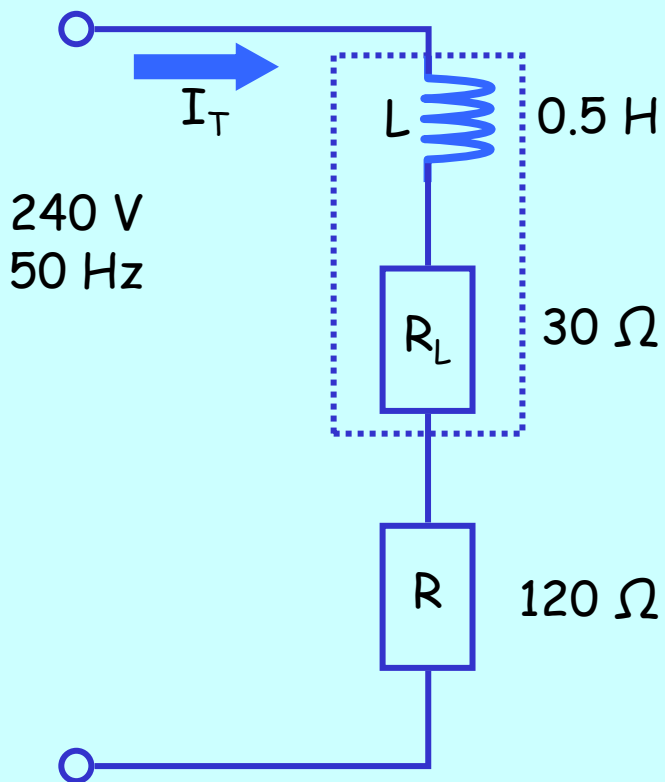
$V_R = 0.44 \times 47 = 20.68 \text{ V}$

$V_T = \sqrt{20.68^2 + 249.48^2} = 250 \text{ V}$

$\theta = \tan^{-1} \frac{249.48}{20.68} = 85.26^\circ$



# Example 2



d.  $I = \frac{V}{Z}$

$$I = \frac{240}{217} = 1.1 \text{ A}$$

a.  $R_T = R + R_L$

$$R_T = 120 + 30 = 150 \Omega$$

b.  $X_L = 2\pi fL$

$$X_L = 2\pi \times 50 \times 0.5$$

$$X_L = 157 \Omega$$

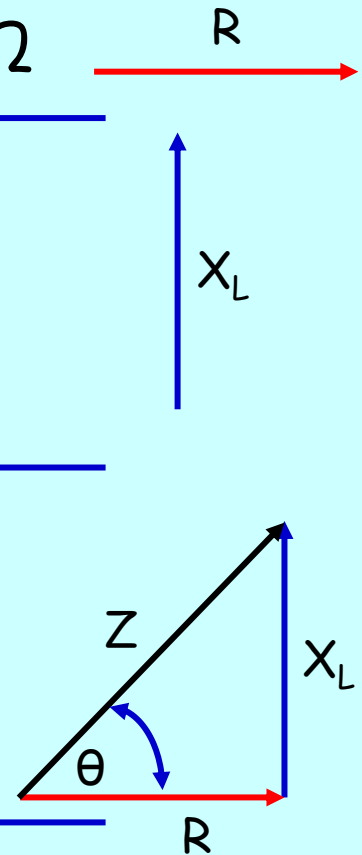
c.  $Z = \sqrt{R_T^2 + X_L^2}$

$$Z = \sqrt{150^2 + 157^2}$$

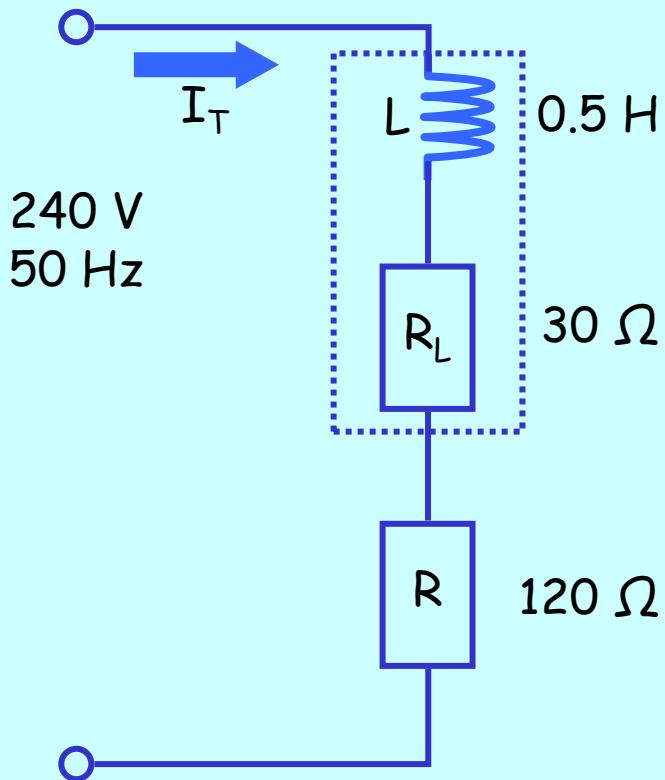
$$Z = 217 \Omega$$

e.  $\theta = \tan^{-1} \frac{X}{R}$

$$\theta = \tan^{-1} \frac{157}{150} = 46.3^\circ$$



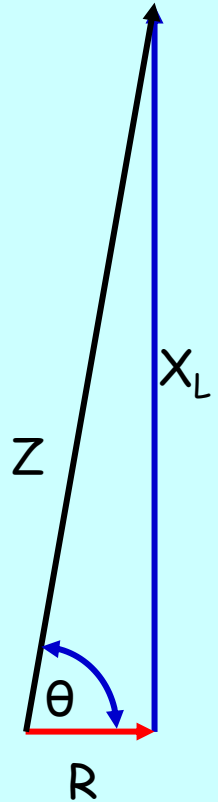
## Example 2 (cont)



f.  $\lambda = \cos \theta \quad \lambda = \frac{P}{S}$   
 $\lambda = \cos 46.3 = 0.691$

g.  $Z_L = \sqrt{R_L^2 + X_L^2}$   
 $Z_L = \sqrt{30^2 + 157^2}$   
 $Z_L = 159.8 \Omega$

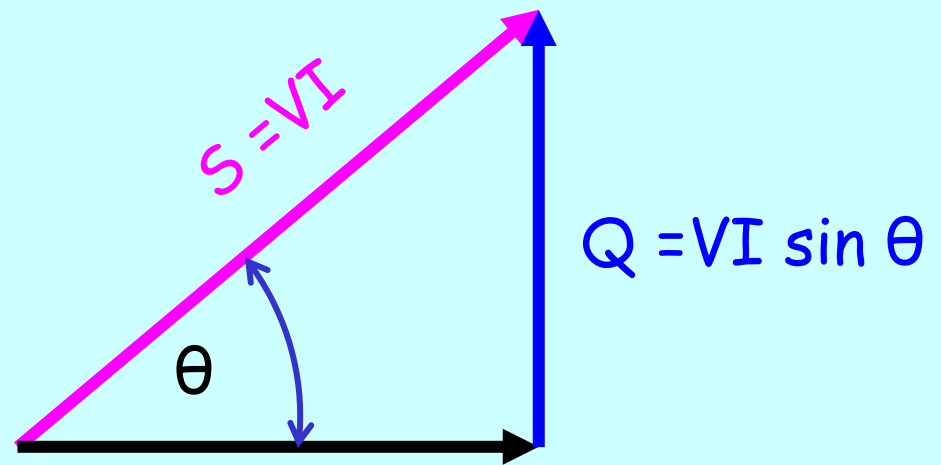
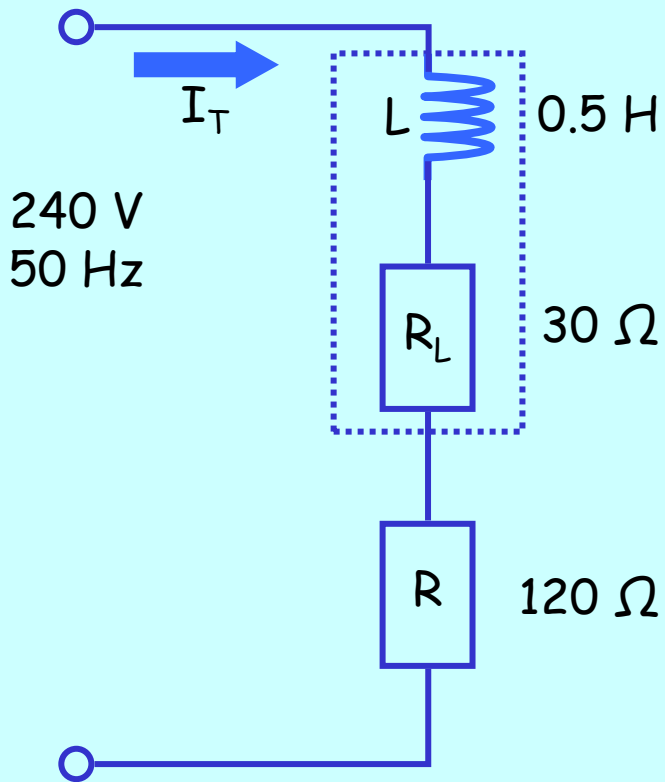
h.  $\theta = \tan^{-1} \frac{X}{R}$   
 $\theta = \tan^{-1} \frac{157}{30} = 79.2^\circ$



i.  $V_R = IR$   
 $V_R = 1.1 \times 120$   
 $V_R = 132 \text{ V}$

j.  $V_L = IZ_L$   
 $V_L = 1.1 \times 159.8$   
 $V_L = 175.8 \text{ V}$

## Example 2 (cont)



$$P = VI \cos \theta$$

k.  $S = VI$

$$S = 240 \times 1.1$$

$$S = 264 \text{ VA}$$

l.  $P = VI \cos \theta$

$$P = 240 \times 1.1 \times \cos 46.3$$

$$P = 182 \text{ W}$$

m.  $Q = VI \sin \theta$

$$Q = 240 \times 1.1 \times \sin 46.3$$

$$Q = 191 \text{ Var}$$

# Example Calculations

## CIVIL

$$Z = \frac{V}{I} \quad Z = \sqrt{R^2 + X^2} \quad |X_C| = \frac{1}{2\pi fC} \quad |X_L| = 2\pi fL$$

$$\sin\theta = \frac{X_L}{Z_T} = \frac{V_L}{V_T} = \frac{Q}{S}$$

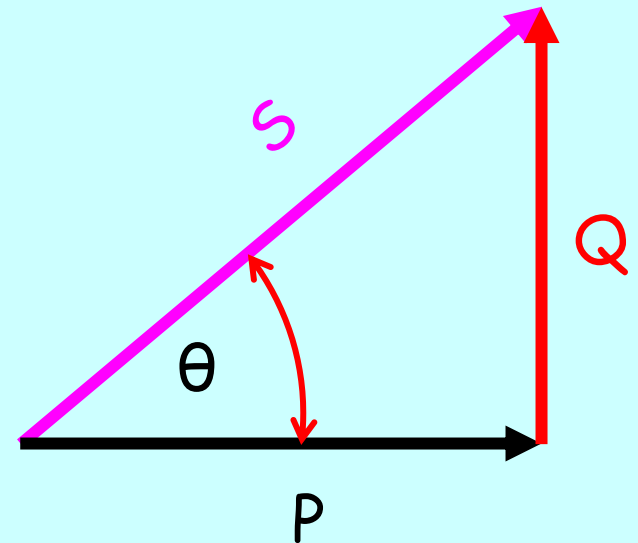
$$S = VI$$

$$P = VI \cos\theta$$

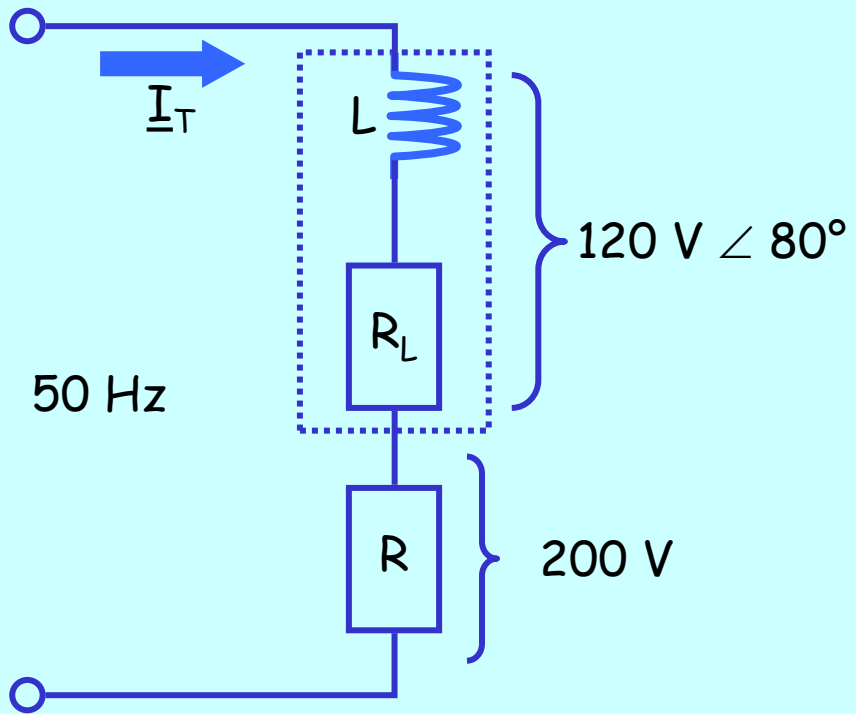
$$Q = VI \sin\theta$$

$$\cos\theta = \frac{R_T}{Z_T} = \frac{V_R}{V_T} = \frac{P}{S}$$

$$\tan\theta = \frac{X_L}{R_T} = \frac{V_L}{V_R} = \frac{Q}{P}$$



Exercise 1



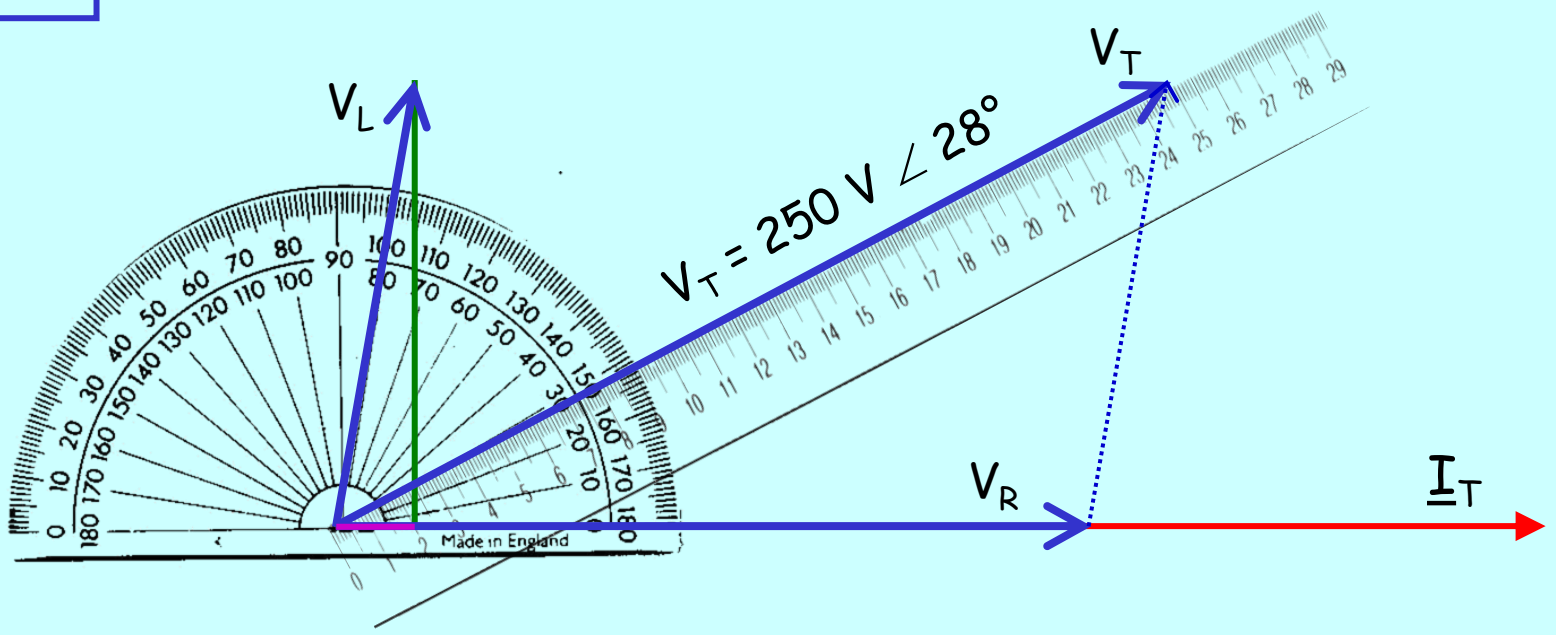
Draw the Phasor diagram for the circuit and find  $V_T$ .

$\underline{V}_R = 200 \angle 0^\circ$

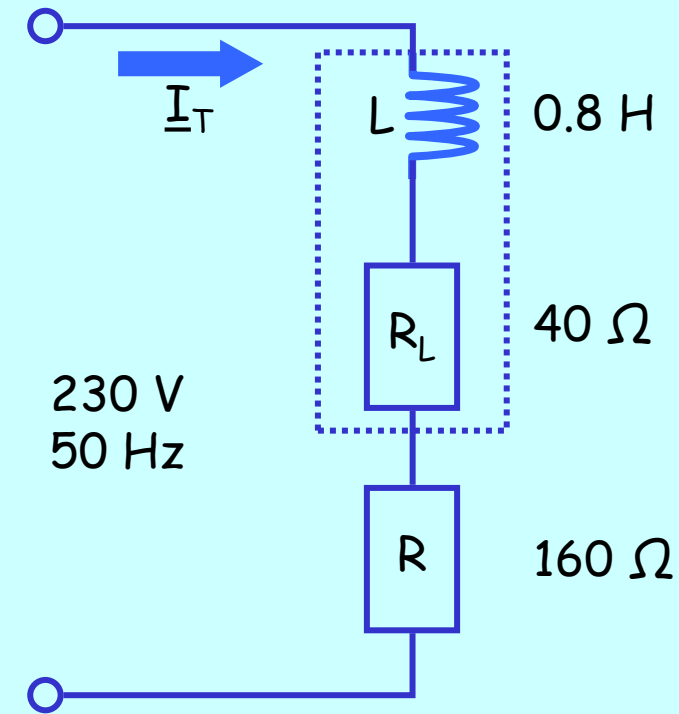
$\underline{V}_L = 120 \angle 80^\circ$

$|\underline{V}_T| = 250.5\text{ V}$

$\underline{\theta} = 28^\circ$



## Exercise 2



a.  $R_T$

b.  $X_L$

c.  $Z_T$

d.  $I_T$

e.  $\Theta_T$

f.  $Z_L$

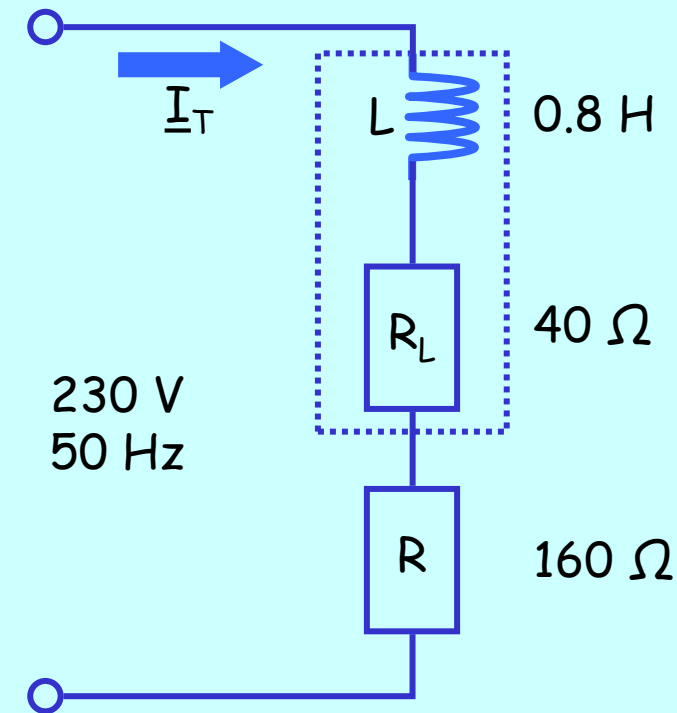
g.  $\Theta_L$

h.  $V_R$

i.  $V_L$

j. *Draw the Phasor diagram for the circuit.*

## Exercise 2



d. 
$$I = \frac{V}{Z}$$

$$I = \frac{230}{321} = 0.717 \text{ A}$$

a.  $R_T = R + R_L$

$$R_T = 160 + 40 = 200 \Omega$$

b.  $X_L = 2\pi fL$

$$X_L = 2\pi \times 50 \times 0.8$$

$$X_L = 251.3 \Omega$$

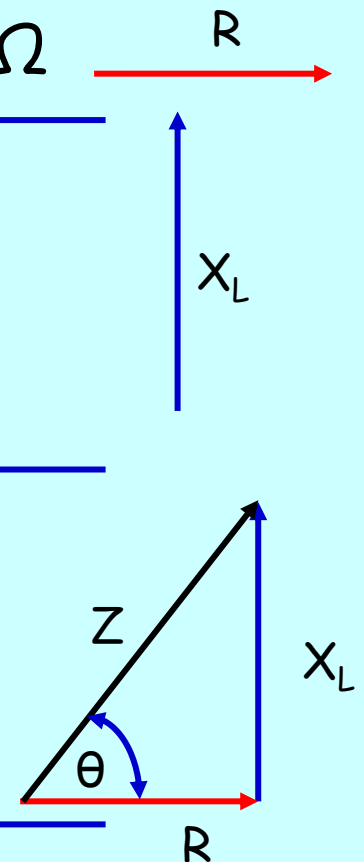
c.  $Z = \sqrt{R_T^2 + X_L^2}$

$$Z = \sqrt{200^2 + 251^2}$$

$$Z = 321 \Omega$$

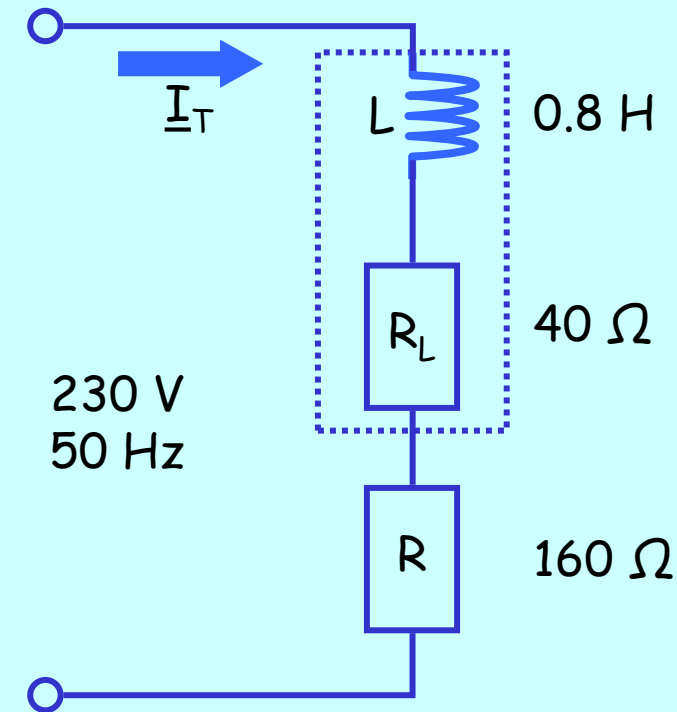
e.  $\theta = \tan^{-1} \frac{X}{R}$

$$\theta = \tan^{-1} \frac{251}{200} = 51.45^\circ$$





## Exercise 2 (cont)



$$R_T = 200 \Omega$$

$$X_L = 251 \Omega$$

$$Z = 321 \Omega$$

$$I = 0.717 \text{ A}$$

$$\theta = 51.45^\circ$$

$$\lambda = \cos 51.45 = 0.623$$

$$f. \quad Z_L = \sqrt{R_L^2 + X_L^2}$$

$$Z_L = \sqrt{40^2 + 251^2}$$

$$Z_L = 254 \Omega$$

$$g. \quad \theta = \tan^{-1} \frac{X}{R}$$

$$\theta_L = \tan^{-1} \frac{251}{40} = 80.9^\circ$$

$$h. \quad V_R = IR$$

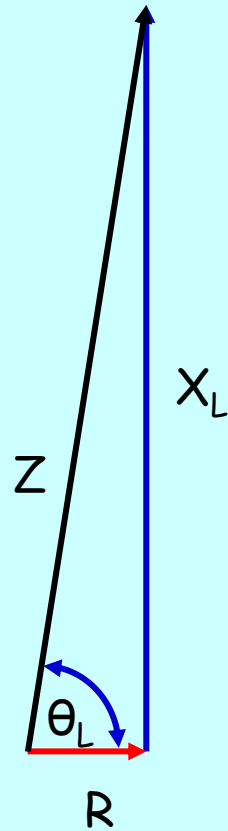
$$V_R = 0.717 \times 160$$

$$V_R = 114.72 \text{ V}$$

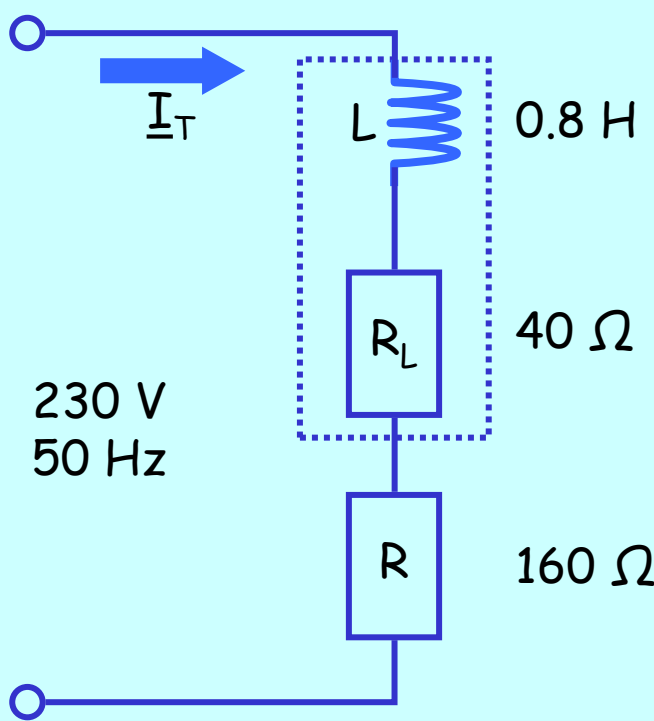
$$i. \quad V_L = IZ_L$$

$$V_L = 0.717 \times 254$$

$$V_L = 182.12 \text{ V}$$



# Exercise 2



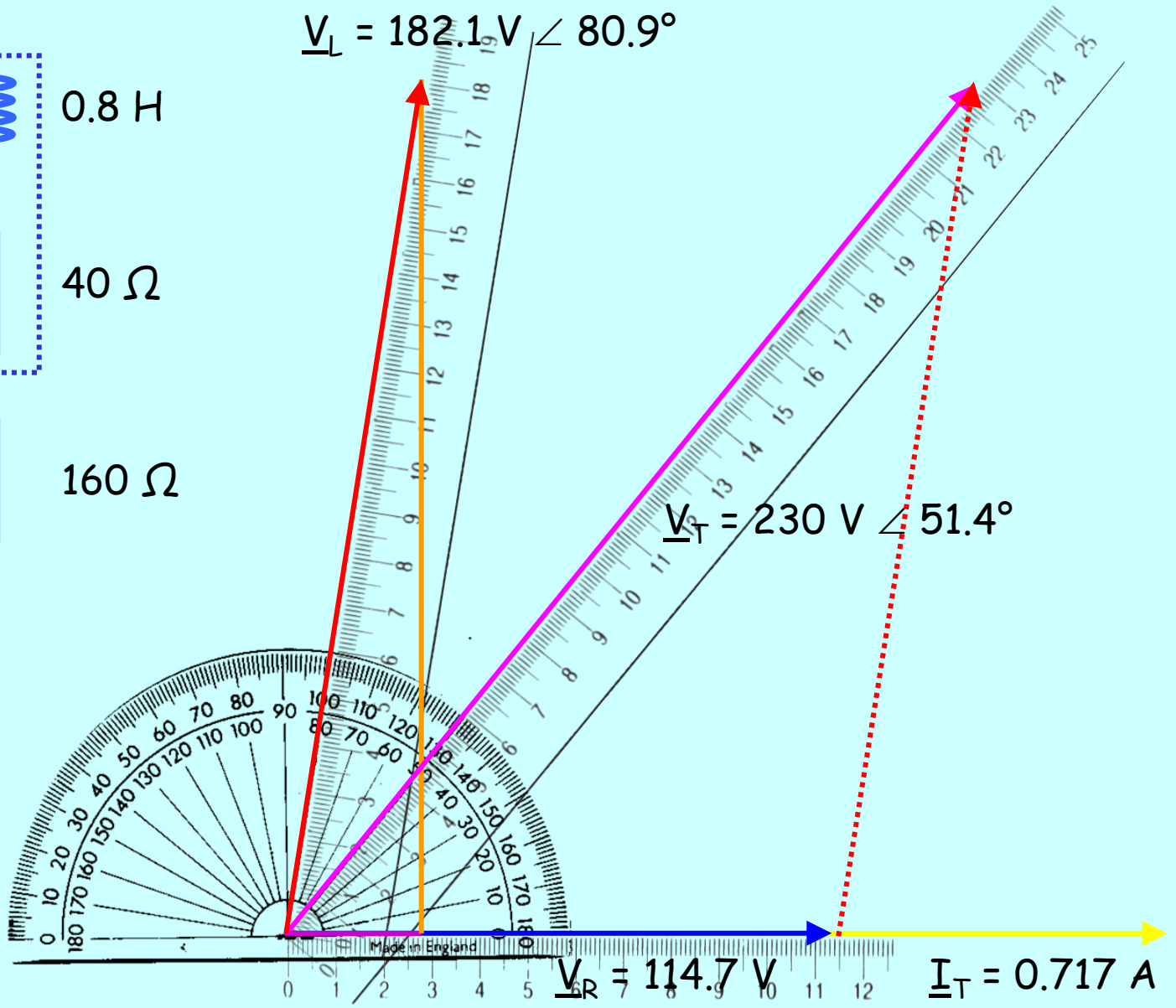
$|V_T| = 230 \text{ V}$   
 $\theta = 51^\circ$

$\underline{V}_L = 182.1 \text{ V} \angle 80.9^\circ$

$\underline{V}_T = 230 \text{ V} \angle 51.4^\circ$

$\underline{V}_R = 114.7 \text{ V}$

$\underline{I}_T = 0.717 \text{ A}$



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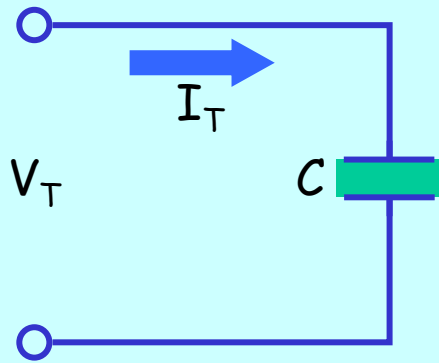
**Solve problems in  
low voltage a.c. circuits**

**Series RC  
AC Circuits**

# Objectives:

At the end of this lesson students should be able to:

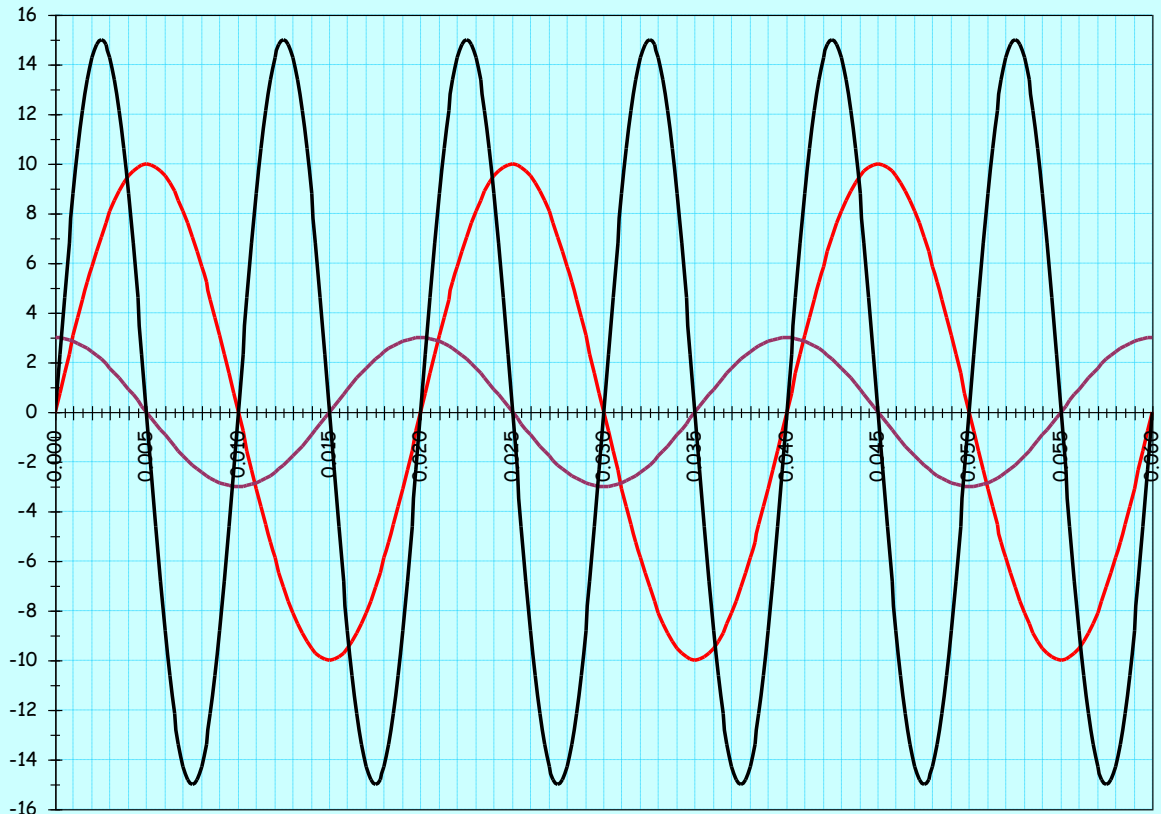
1. Determine circuit quantities and characteristics of Series RC ac circuits.
2. Draw and label Impedance and Power Triangles for Series RC ac circuits.
3. Draw and label the Phasor Diagram for Series RC ac circuits.
4. List a number of practical applications for RC circuits.

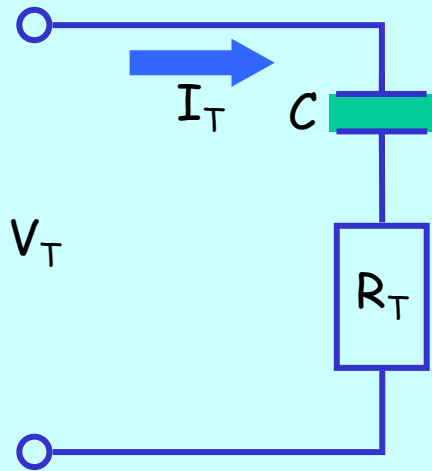


Capacitance is that property of a circuit that opposes changes in voltage.

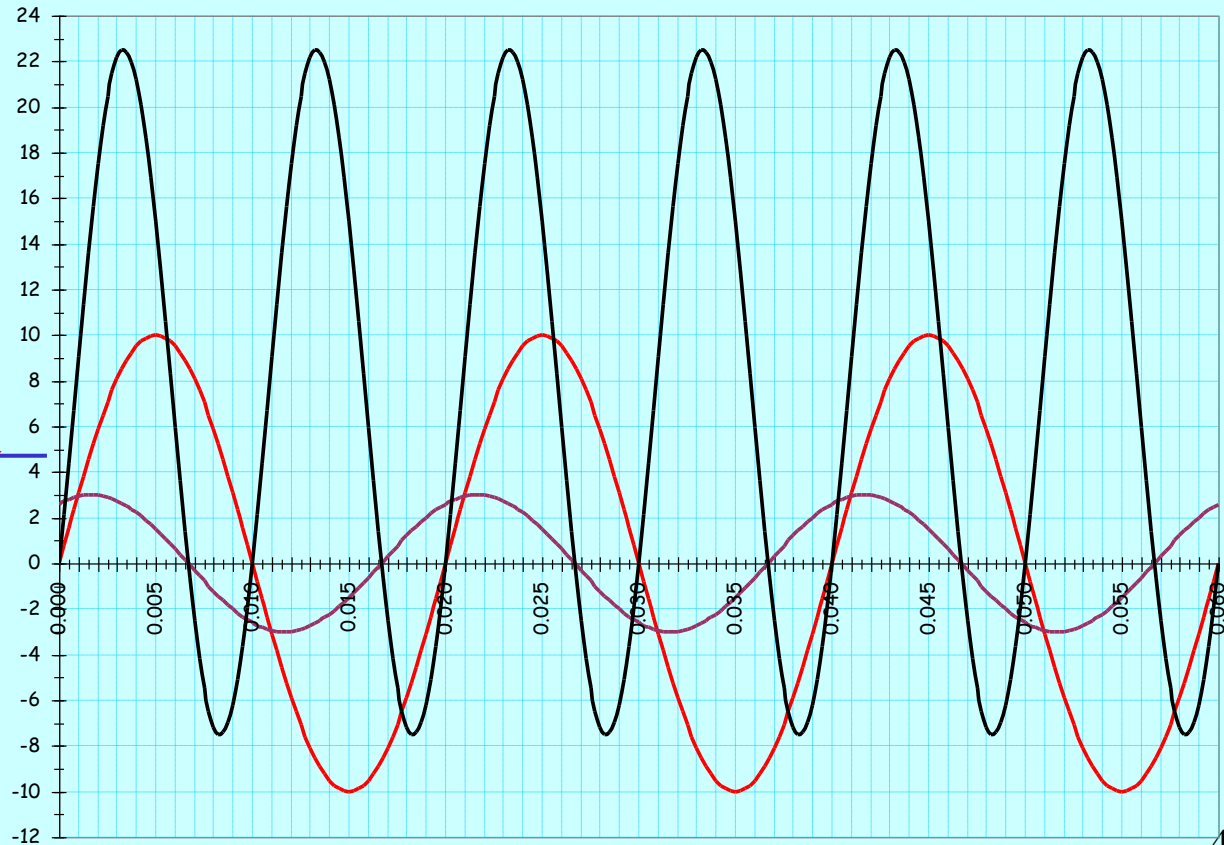
In a purely **CAPACITIVE** ac circuit the **Current Leads** the **Voltage** by  $90^\circ$ .

Average Real Power is **ZERO**.





In a practical **Capacitive** ac circuit there is some Resistance and therefore the **Current Leads** the **Voltage** by some angle less than 90°. Average Real Power is **NOT ZERO**.



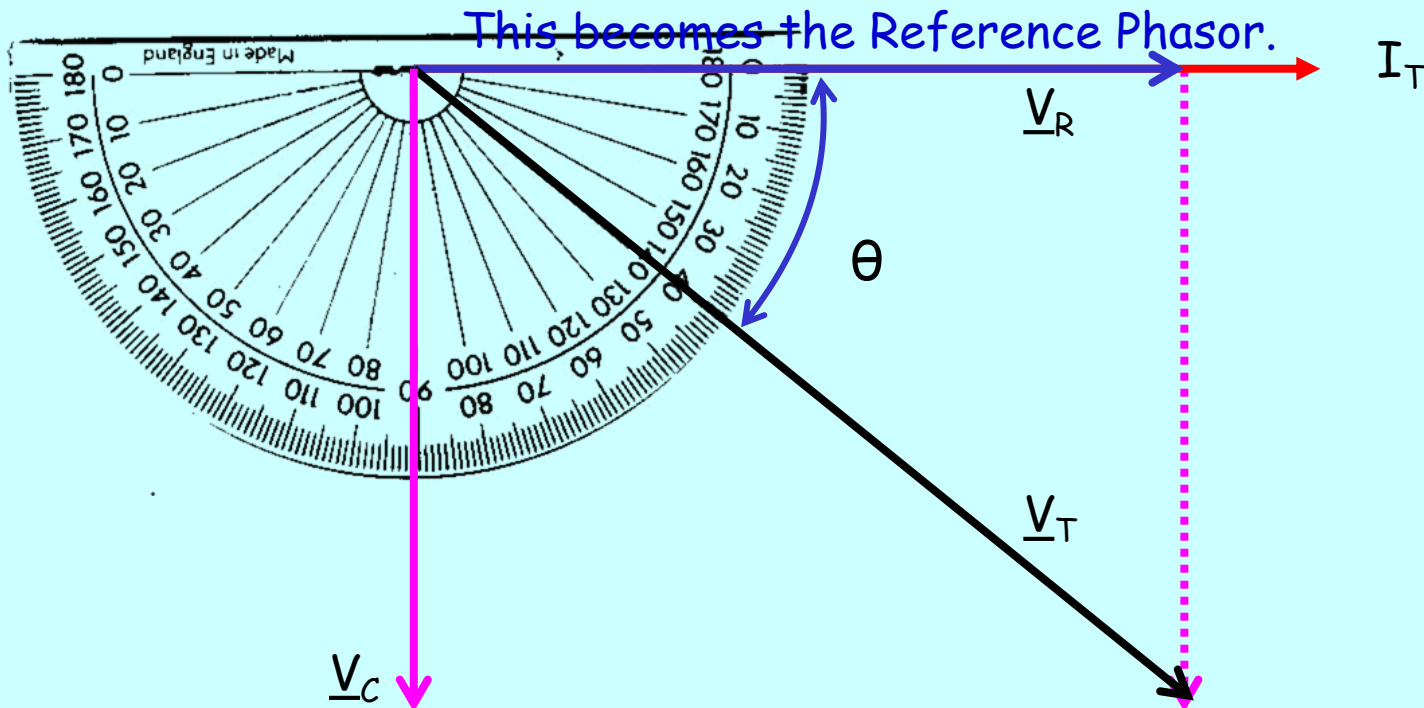
In a SERIES Circuit the common factor is current.

The Voltage across the Resistor ( $\underline{V}_R$ ) is in phase with the current.

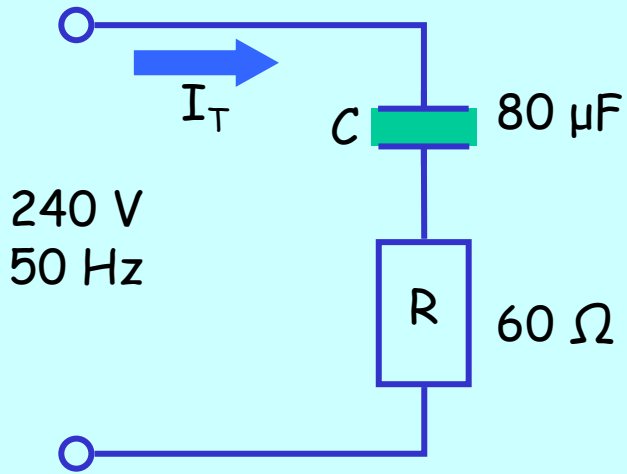
The Voltage across the Capacitor ( $\underline{V}_C$ ) Lags the current, and therefore  $\underline{V}_R$ , by  $90^\circ$ .

The Algebraic Addition:  $\underline{V}_R + \underline{V}_C$  gives  $\underline{V}_T$ .

Which then gives us the circuit's phase angle.



# Example



a. 
$$X_C = \frac{1}{2\pi fC}$$
$$X_C = \frac{1}{2\pi \times 50 \times 80\mu}$$
$$X_C = 39.8\Omega$$

---

b. 
$$Z = \sqrt{R^2 + X_C^2}$$
$$Z = \sqrt{60^2 + 39.8^2}$$
$$Z = 72\Omega$$

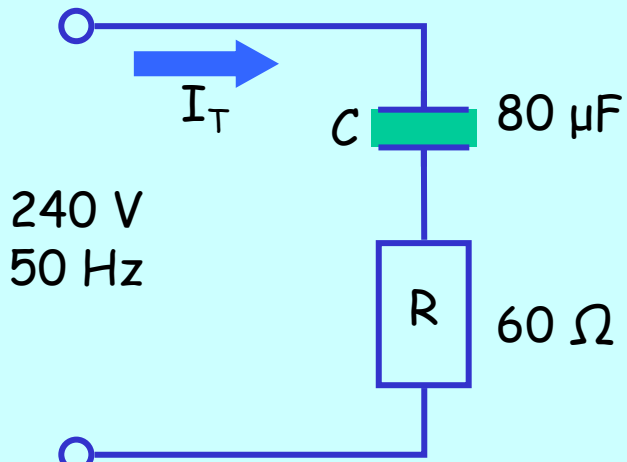
---

c. 
$$I = \frac{V}{Z}$$
$$I = \frac{240}{72} = 3.33 \text{ A}$$

d. 
$$\theta = \tan^{-1} \frac{X}{R}$$
$$\theta = \tan^{-1} \frac{39.8}{60} = 33.56^\circ$$



# Example (cont)



$X_C = 39.8 \Omega$
$Z = 72 \Omega$
$I = 3.33 \text{ A}$
$\theta = 33.56^\circ$

e.  $\lambda \equiv \cos \theta$   $\lambda = \frac{P}{S}$   
 $\lambda = \cos 33.56 = 0.833$

---

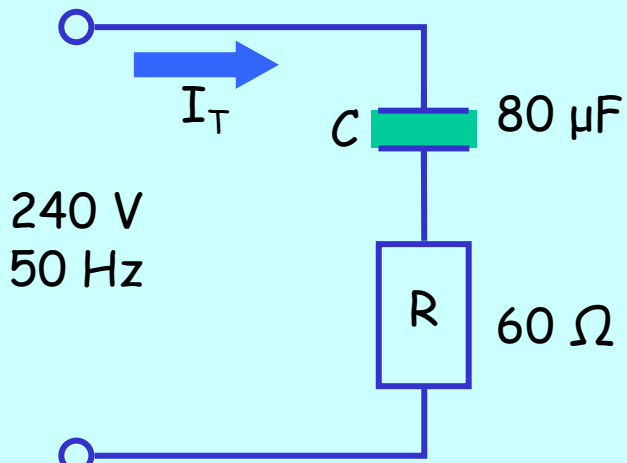
f.  $V_R = IR$   
 $V_R = 3.33 \times 60$   
 $V_R = 199.8 \text{ V}$

---

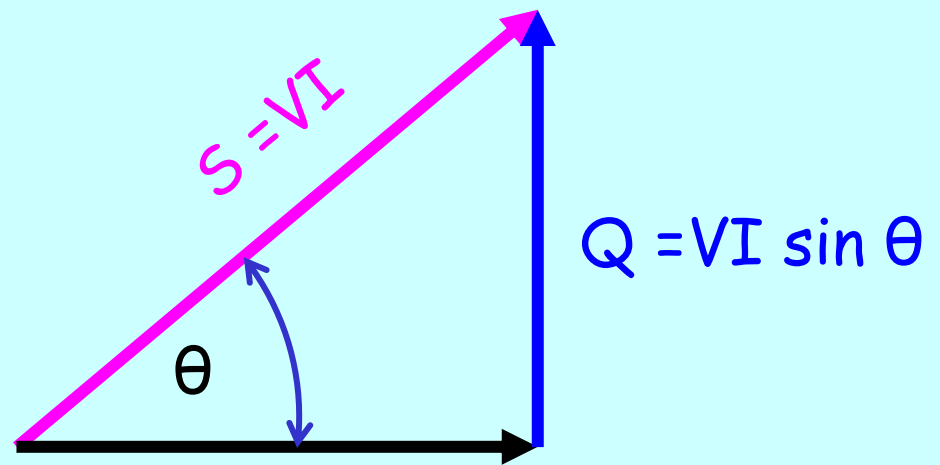
g.  $V_C \equiv IX_C$   
 $V_C = 3.33 \times 39.8$   
 $V_C = 131.87 \text{ V}$

---

# Example (cont)



$$\begin{aligned} X_C &= 39.8 \Omega \\ Z &= 72 \Omega \\ I &= 3.33 \text{ A} \\ \theta &= 33.56^\circ \end{aligned}$$



$$P = VI \cos \theta$$

h.  $S = VI$

$$S = 240 \times 3.33$$

$$S = 799.2 \text{ VA}$$

i.  $P = VI \cos \theta$

$$P = 240 \times 3.33 \times \cos 33.56$$

$$P = 665.98 \text{ W}$$

j.  $Q = VI \sin \theta$

$$Q = 240 \times 3.33 \times \sin 33.56$$

$$Q = 441.81 \text{ Var}$$

# Example Calculations

## CIVIL

$$Z = \frac{V}{I} \quad Z = \sqrt{R^2 + X^2} \quad |X_C| = \frac{1}{2\pi fC} \quad |X_L| = 2\pi fL$$

$$\sin\theta = \frac{X_L}{Z_T} = \frac{V_L}{V_T} = \frac{Q}{S}$$

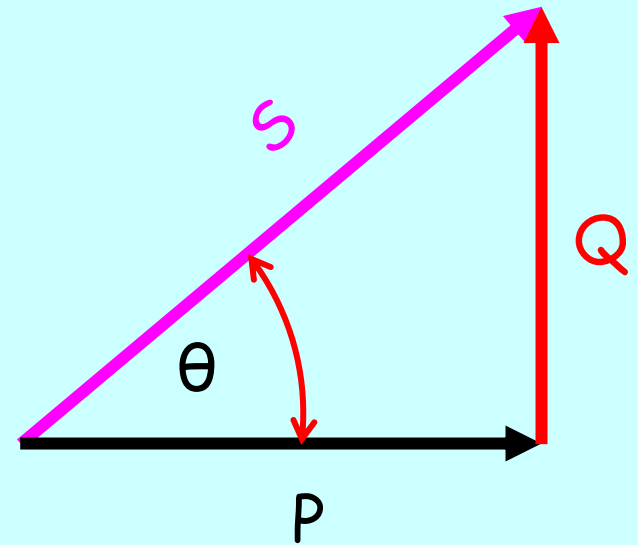
$$S = VI$$

$$\cos\theta = \frac{R_T}{Z_T} = \frac{V_R}{V_T} = \frac{P}{S}$$

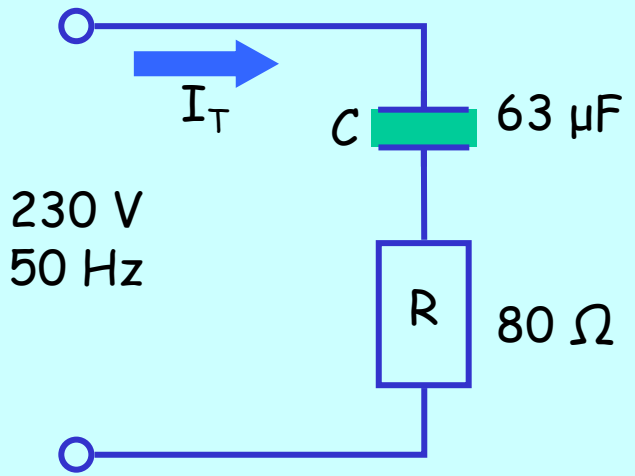
$$P = VI \cos\theta$$

$$\tan\theta = \frac{X_L}{R_T} = \frac{V_L}{V_R} = \frac{Q}{P}$$

$$Q = VI \sin\theta$$



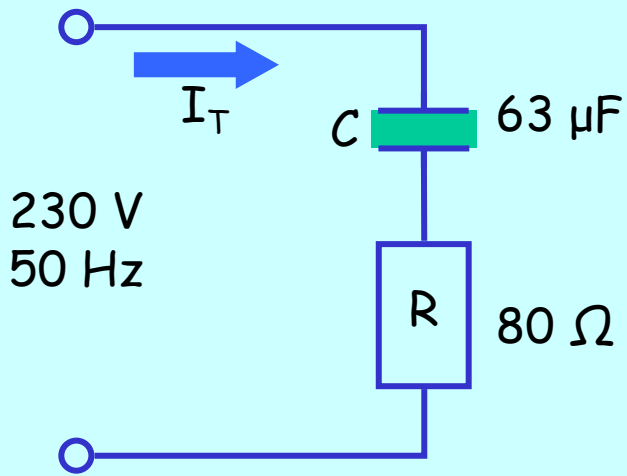
# Example 1



- a.  $R_T$
- b.  $X_C$
- c.  $Z_T$
- d.  $I_T$
- e.  $\Theta_T$
- f.  $V_C$
- g.  $V_R$

h. *Draw the Phasor diagram for the circuit.*

## Example 1



a.  $R_T = 80 \Omega$

---

b.  $X_C = \frac{1}{2\pi f C}$

$$X_C = \frac{1}{2\pi \times 50 \times 63\mu}$$

$$X_C = 50.5 \Omega$$

---

c.  $Z = \sqrt{R_T^2 + X_C^2}$

$$Z = \sqrt{80^2 + 50.5^2}$$

$$Z = 94.6 \Omega$$

---

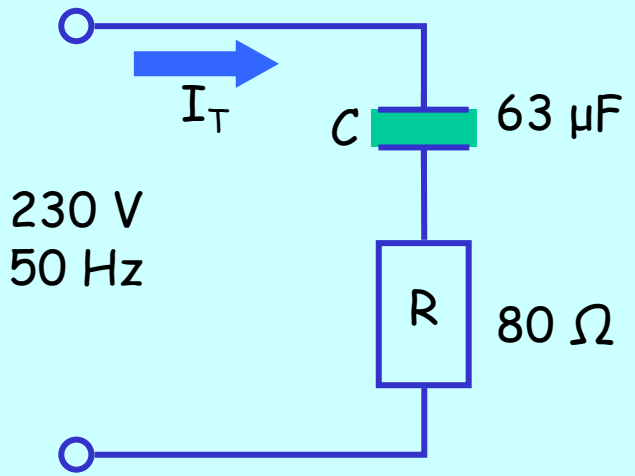
d.  $I = \frac{V}{Z}$

$$I = \frac{230}{94.6} = 2.43 \text{ A}$$

e.  $\theta = \tan^{-1} \frac{X}{R}$

$$\theta = \tan^{-1} \frac{50.5}{80} = 32.26^\circ$$

Example 1 (cont)

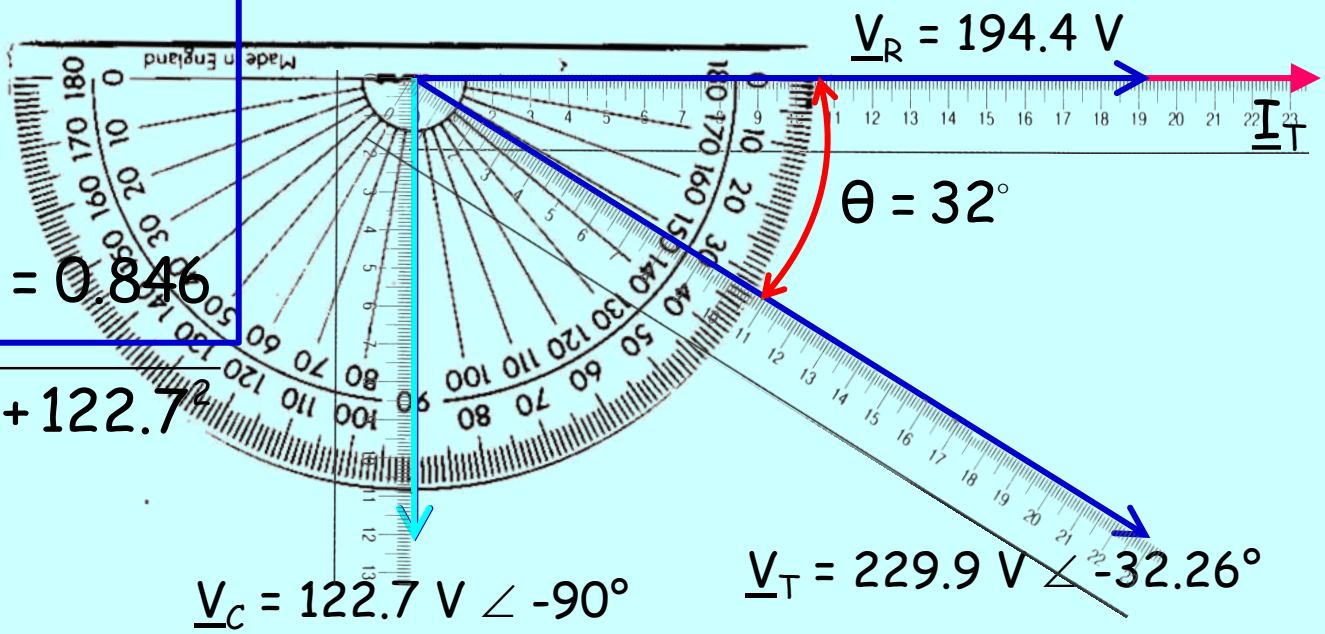


$X_C = 50.5 \Omega$   
 $Z = 94.6 \Omega$   
 $I = 2.43 \text{ A}$   
 $\theta = 32.26^\circ$   
 $\lambda = \cos 32.26 = 0.846$

f.  $V_C = IX_C$   
 $V_C = 2.43 \times 50.5$   
 $V_C = 122.72 \text{ V}$

g.  $V_R = IR$   
 $V_R = 2.43 \times 80$   
 $V_R = 194.4 \text{ V}$

$|V_T| = \sqrt{194.4^2 + 122.7^2}$   
 $|V_T| = 229.9 \text{ V}$



# End of Lesson

## Practical Exercises

Series RL ac circuits

Series RC ac circuits

**UEENEEG102A**

**Solve problems in  
low voltage a.c. circuits**

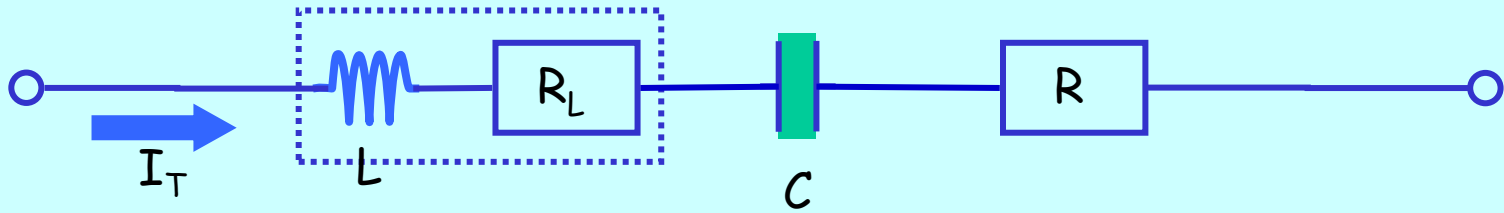
**Series RLC  
AC Circuits**



# Objectives:

At the end of this lesson students should be able to:

1. Determine circuit quantities and characteristics of RLC Series Circuits.
2. Draw and label Impedance and Power Triangles for RLC Series Circuits.
3. Draw and label the Phasor Diagram for RLC Series Circuits.
4. State the effect of, and calculate the frequency of resonance in an RLC Series Circuits.
5. List a number of practical applications for RLC Series Circuits.



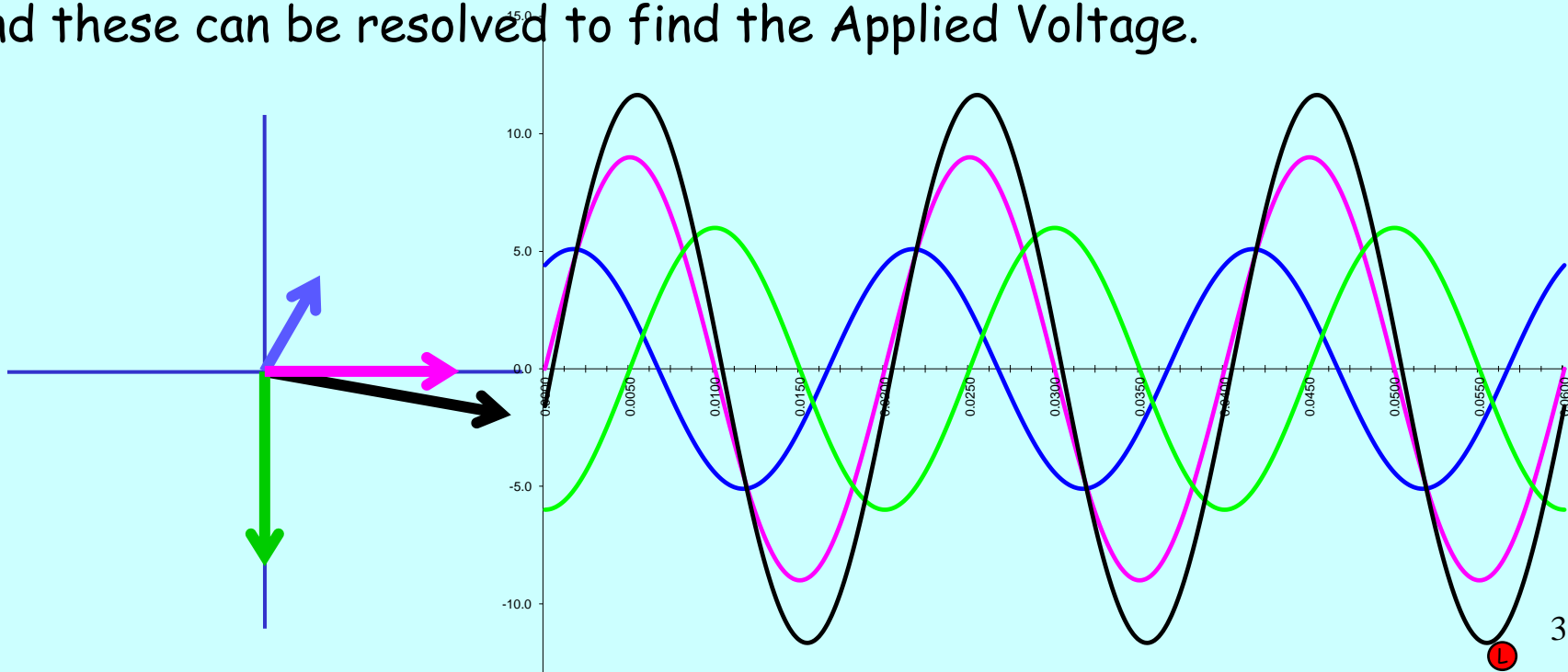
In a practical Series ac Circuit the Current is Common.

The voltage across the Resistor is in phase with the current,

The voltage across the Inductor leads the current by some angle less than  $90^\circ$ ,

The voltage across the Capacitor lags the current by about  $90^\circ$ .

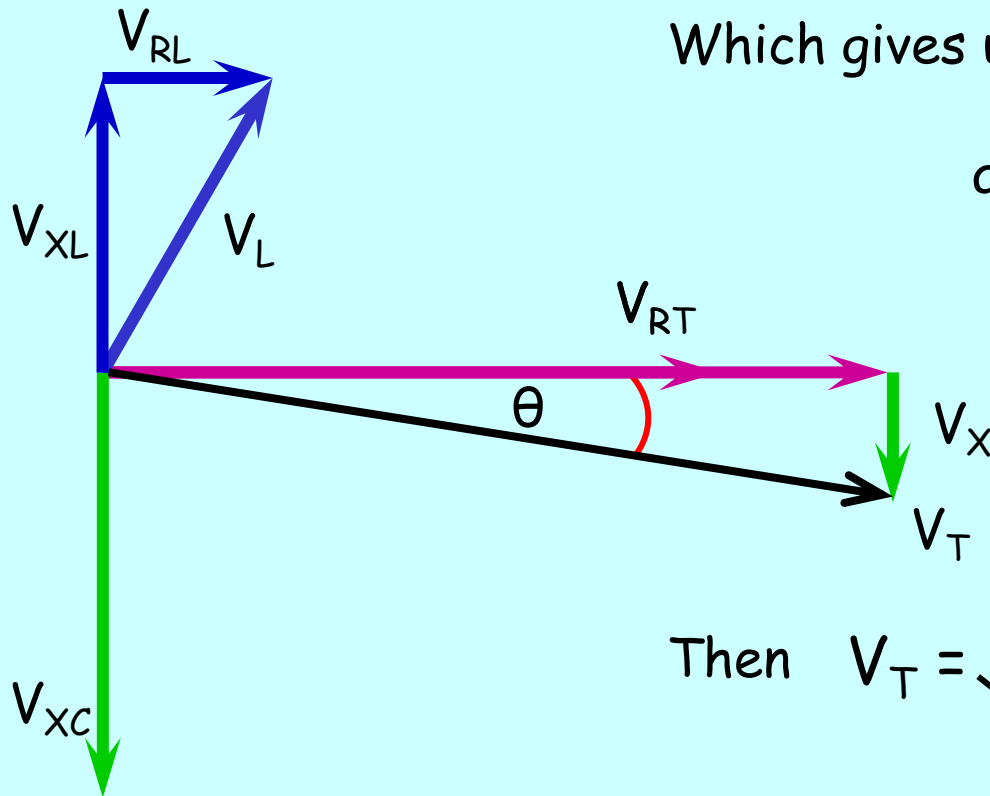
and these can be resolved to find the Applied Voltage.



# The Voltage Phasor diagram

can be resolved thus:

$V_L$  has components  $V_{XL}$  and  $V_{RL}$ .



Which gives us:  $V_{RT} = V_R + V_{RL}$

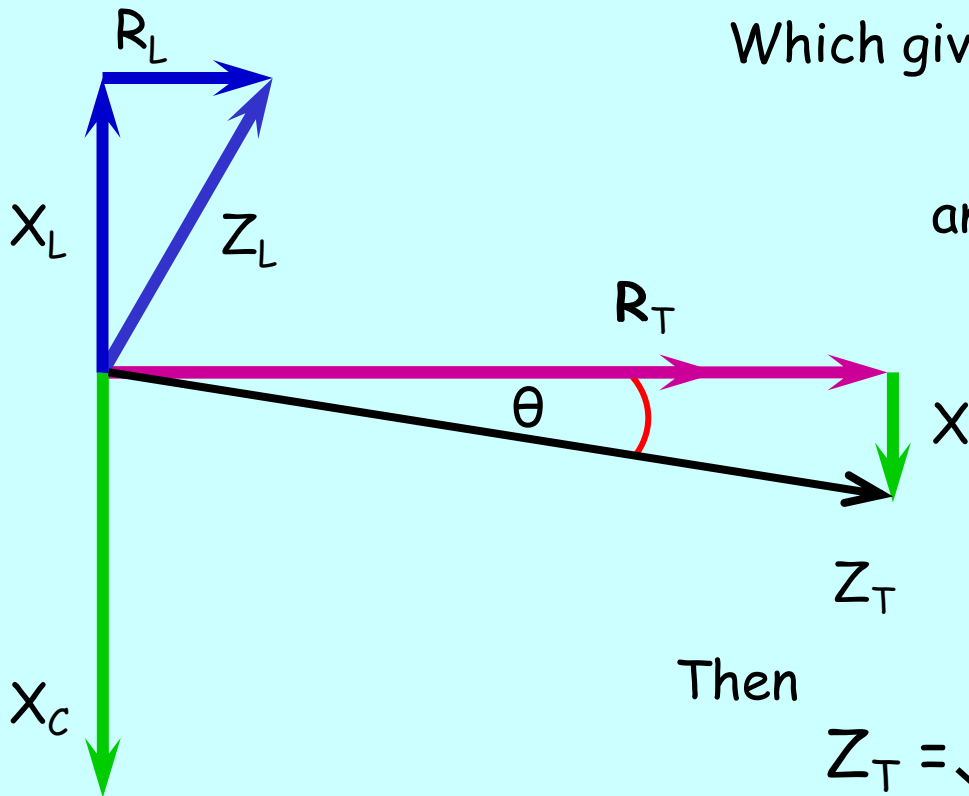
and  $V_X = V_{XL} - V_{XC}$

Then  $V_T = \sqrt{\{(V_R + V_{RL})^2 + (V_{XL} - V_{XC})^2\}}$

and  $\theta = \tan^{-1} \frac{V_X}{V_{RT}}$

The same thing happens with the Impedance Triangle.

$Z_L$  has components  $X_L$  and  $R_L$ .



Which gives us:

$$R_T = R + R_L$$

and

$$X = X_L - X_C$$

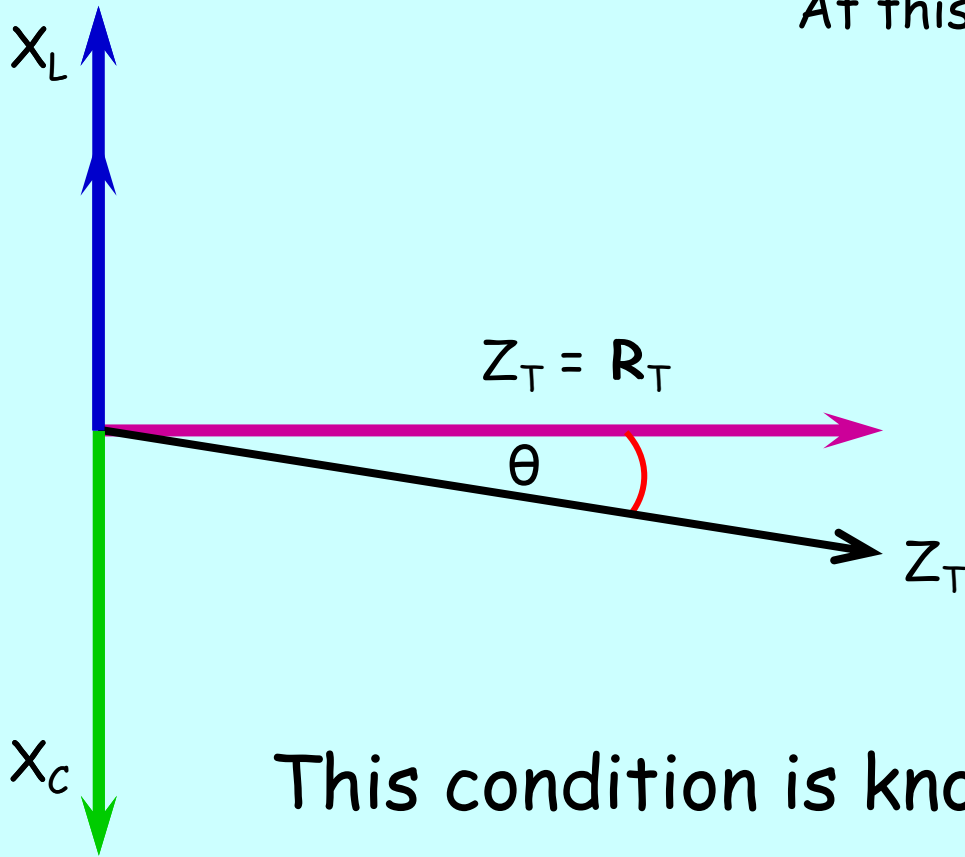
Then

$$Z_T = \sqrt{\{(R + R_L)^2 + (X_L - X_C)^2\}}$$

and

$$\theta = \tan^{-1} \frac{X}{R_T}$$

A special condition occurs when  $X_L = X_C$ .



At this point:  $X = X_L - X_C = 0$

$$R_T = R$$

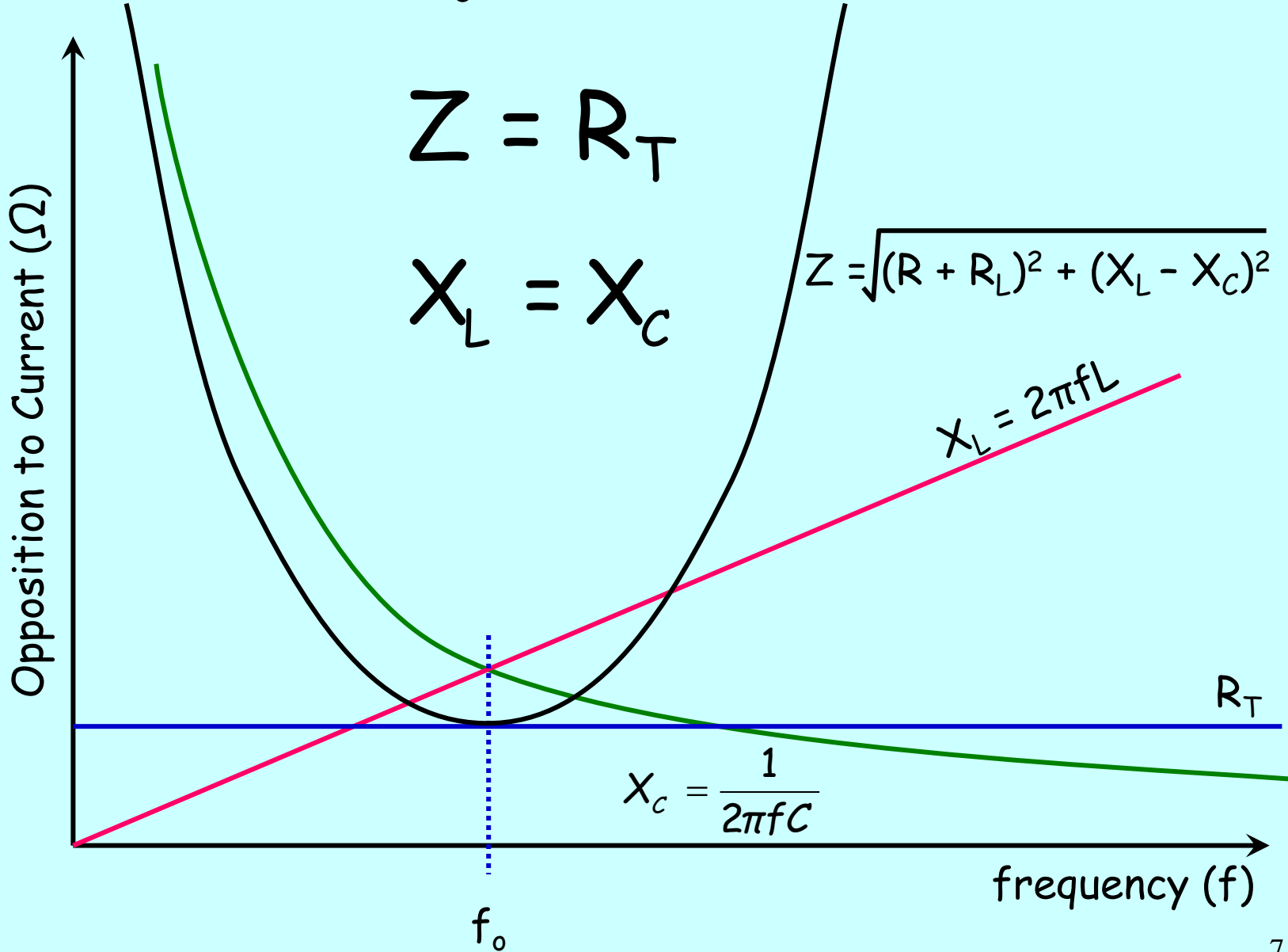
$$Z_T = R$$

$$\theta = 0$$

and  $\lambda = 1$

This condition is known as Resonance.

At Resonance ( $f_0$ ):



At Resonance ( $f_0$ ):

$$Z = R_T$$

Circuit Impedance is a MINIMUM at Resonance ( $f_0$ ).

$$X_L = X_C$$

$$2\pi f_0 L = \frac{1}{2\pi f_0 C}$$

$$f_0 = \frac{1}{2\pi\sqrt{LC}}$$

# Example Calculations

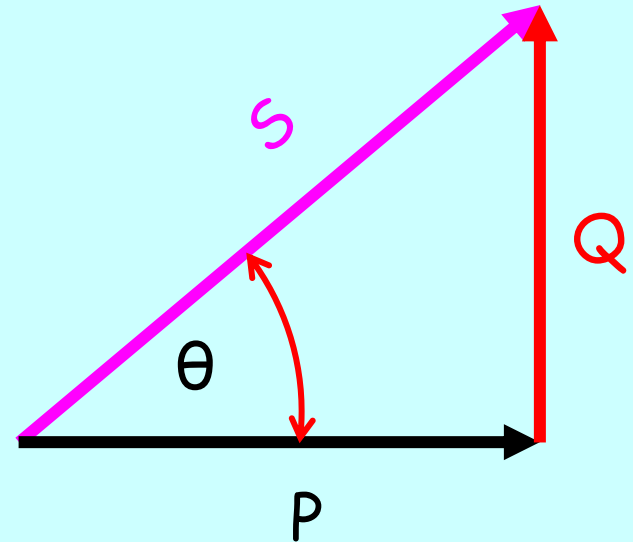
## CIVIL

$$Z = \frac{V}{I} \quad Z = \sqrt{R^2 + X^2} \quad |X_C| = \frac{1}{2\pi fC} \quad |X_L| = 2\pi fL$$

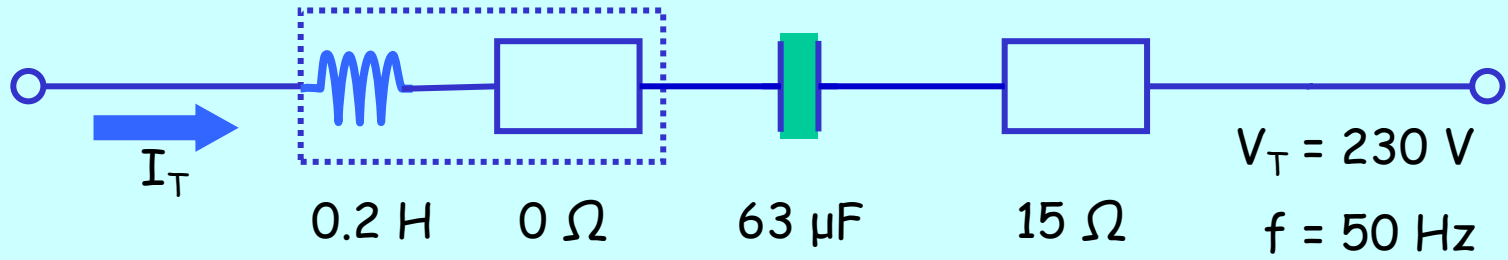
$$\sin\theta = \frac{X_L}{Z_T} = \frac{V_L}{V_T} = \frac{Q}{S} \quad f_0 = \frac{1}{2\pi\sqrt{LC}}$$

$$\cos\theta = \frac{R_T}{Z_T} = \frac{V_R}{V_T} = \frac{P}{S} \quad S = VI$$

$$\tan\theta = \frac{X_L}{R_T} = \frac{V_L}{V_R} = \frac{Q}{P} \quad P = VI \cos\theta$$
$$Q = VI \sin\theta$$







$$X_L = ?$$

$$X_C = ?$$

$$Z = ?$$

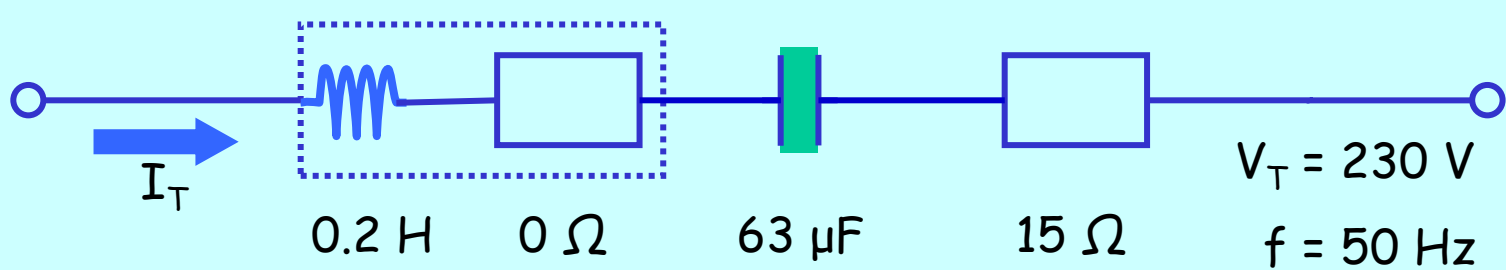
$$I = ?$$

$$\theta = ?$$

$$V = ?$$

$$V = ?$$

$$V = ?$$



$$X_L = 2\pi fL = 100\pi \times 0.2 = 62.83 \Omega$$

$$X_C = \frac{1}{2\pi fC} = \frac{1}{100\pi \times 63\mu} = 50.53 \Omega$$

$$Z = \sqrt{R^2 + X^2} = \sqrt{15^2 + 12.3^2} = 19.4 \Omega$$

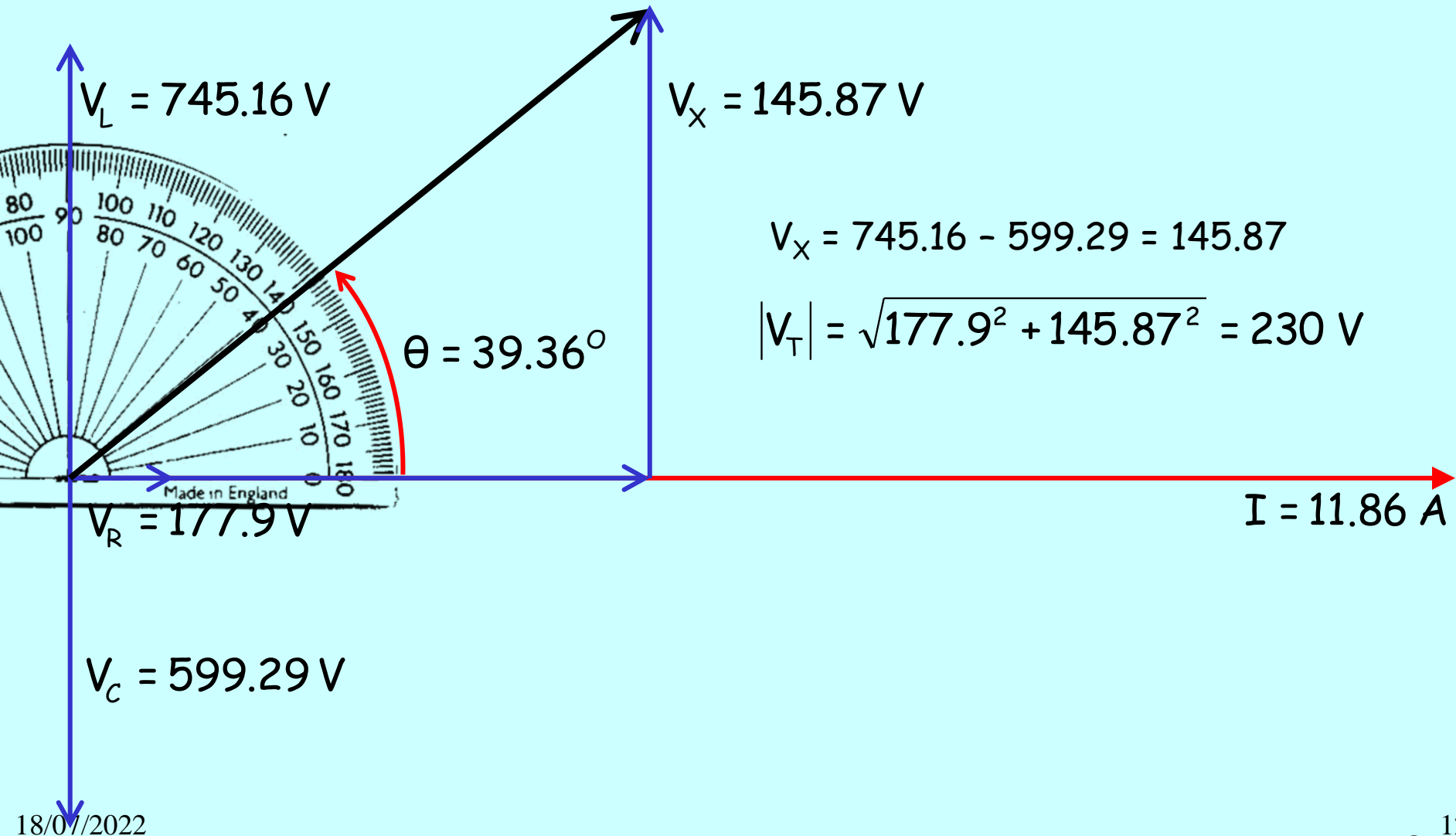
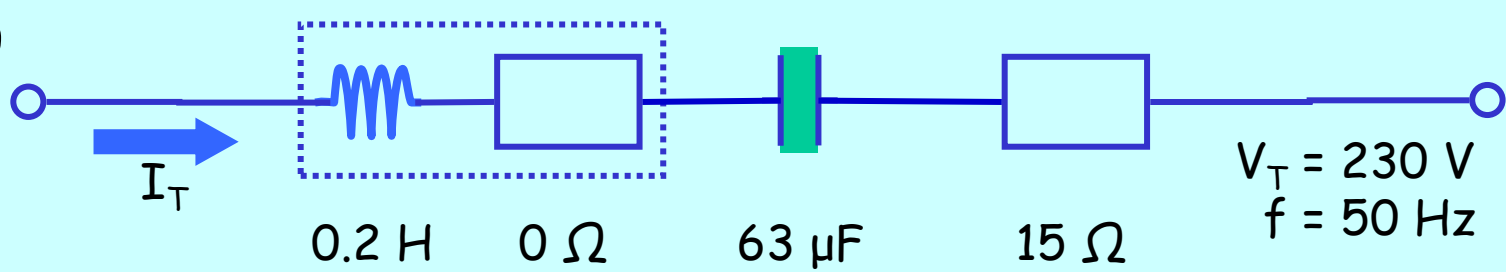
$$I = \frac{V}{Z} = \frac{230}{19.4} = 11.86 \text{ A}$$

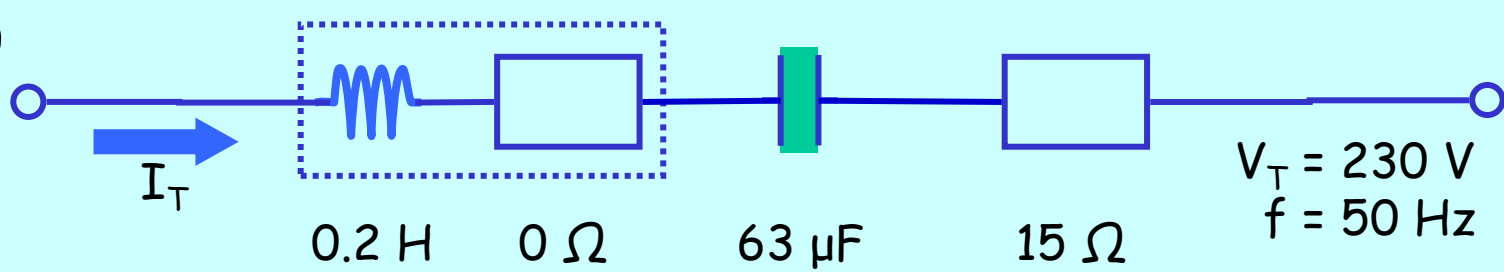
$$\theta = \cos^{-1} \frac{R}{Z} = \cos^{-1} \frac{15}{19.4} = 39.36^\circ$$

$$V = IR = 11.86 \times 15 = 177.9 \text{ V}$$

$$V = IX_L = 11.86 \times 62.83 = 745.16 \text{ V}$$

$$V = IX_C = 11.86 \times 50.53 = 599.29 \text{ V}$$





$$f_o = \frac{1}{2\pi\sqrt{LC}}$$

$$Z = 15 \Omega$$

$$f_o = \frac{1}{2\pi\sqrt{0.2 \times 63\mu}}$$

$$\theta = 0^\circ$$

$$f_o = 44.84 \text{ Hz}$$

$$\lambda = 1$$

# End of Lesson

# Practical Exercises

Series RLC Circuits.

**UEENEEG102A**

**Solve problems in  
low voltage a.c. circuits**

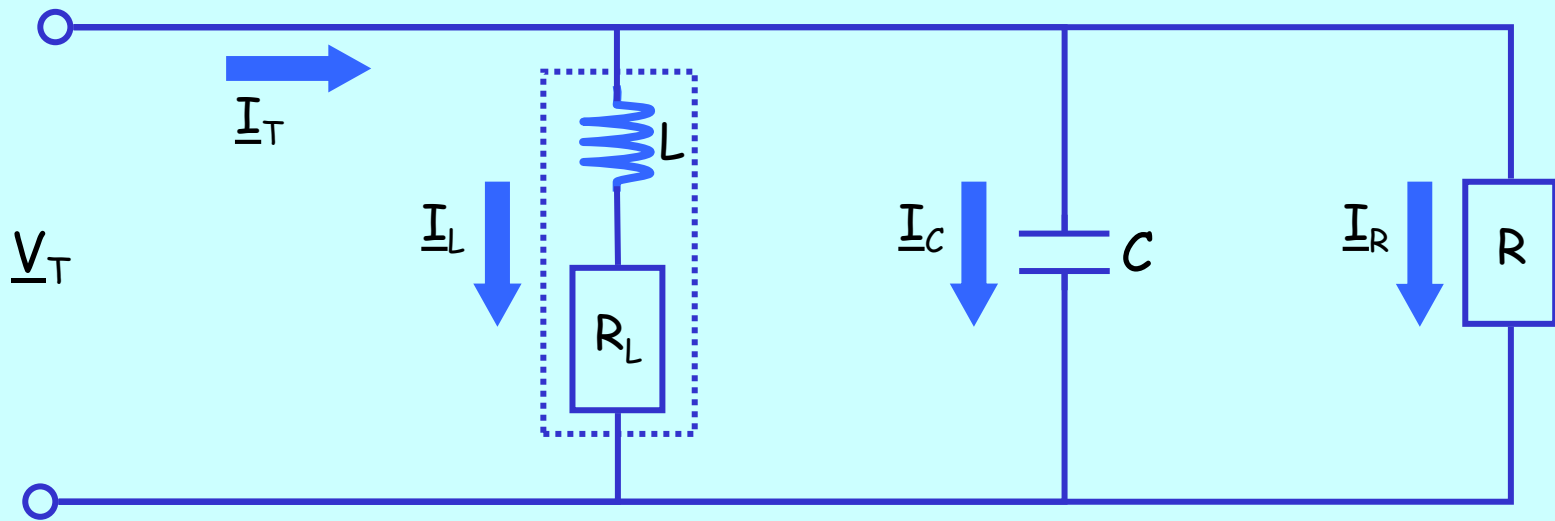
**Parallel RLC**

**AC Circuits**

# Objectives:

At the end of this lesson students should be able to:

1. Determine circuit quantities and characteristics of ac Parallel Circuits.
2. Draw and label Impedance and Power Triangles for ac Parallel Circuits.
3. Draw and label the Phasor Diagram for ac Parallel Circuits.
4. List a number of practical applications for ac Parallel Circuits.



In a parallel circuit Voltage is common.  $\underline{V}_T = \underline{V}_L = \underline{V}_C = \underline{V}_R$

## CIVIL

The current through the Inductor lags the applied voltage by some angle less than  $90^\circ$ .

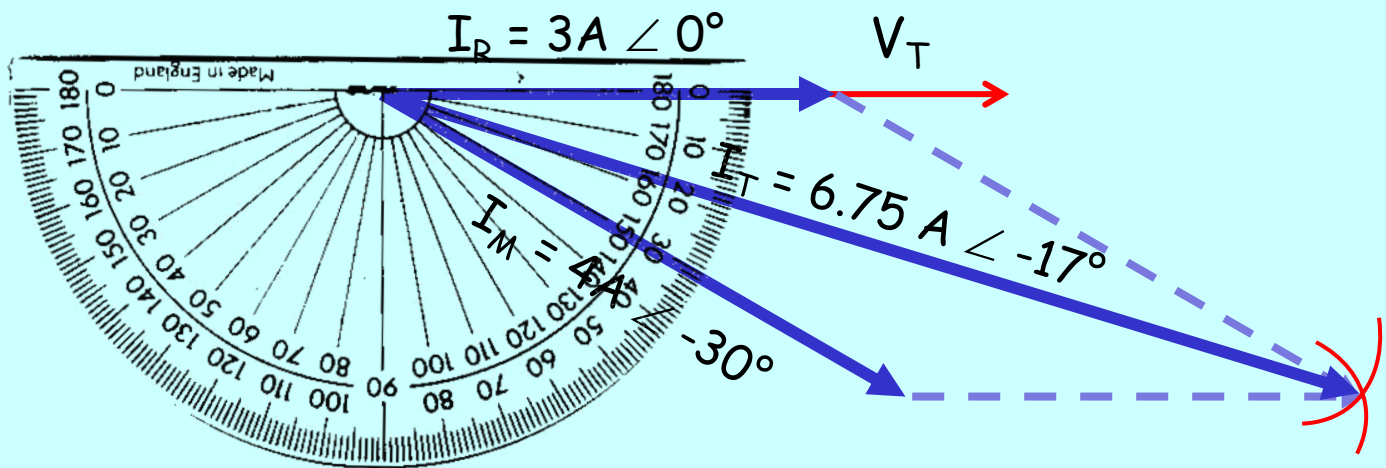
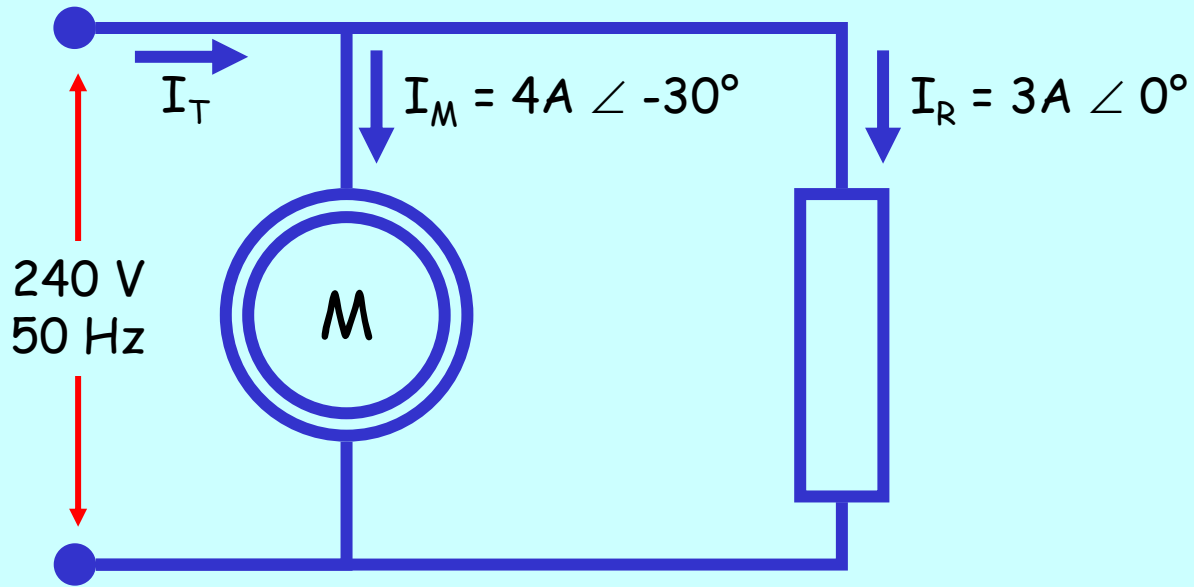
The current through the Capacitor leads the applied voltage by about  $90^\circ$ .

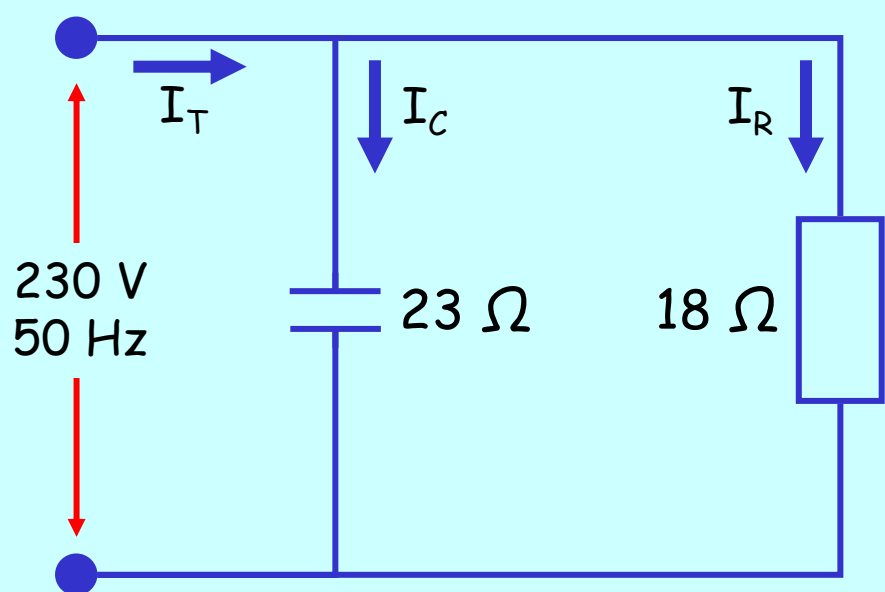
The current through the Resistor is in phase with the applied voltage.

The total current is the algebraic sum of the branch currents.

$$\underline{I}_T = \underline{I}_L + \underline{I}_C + \underline{I}_R$$





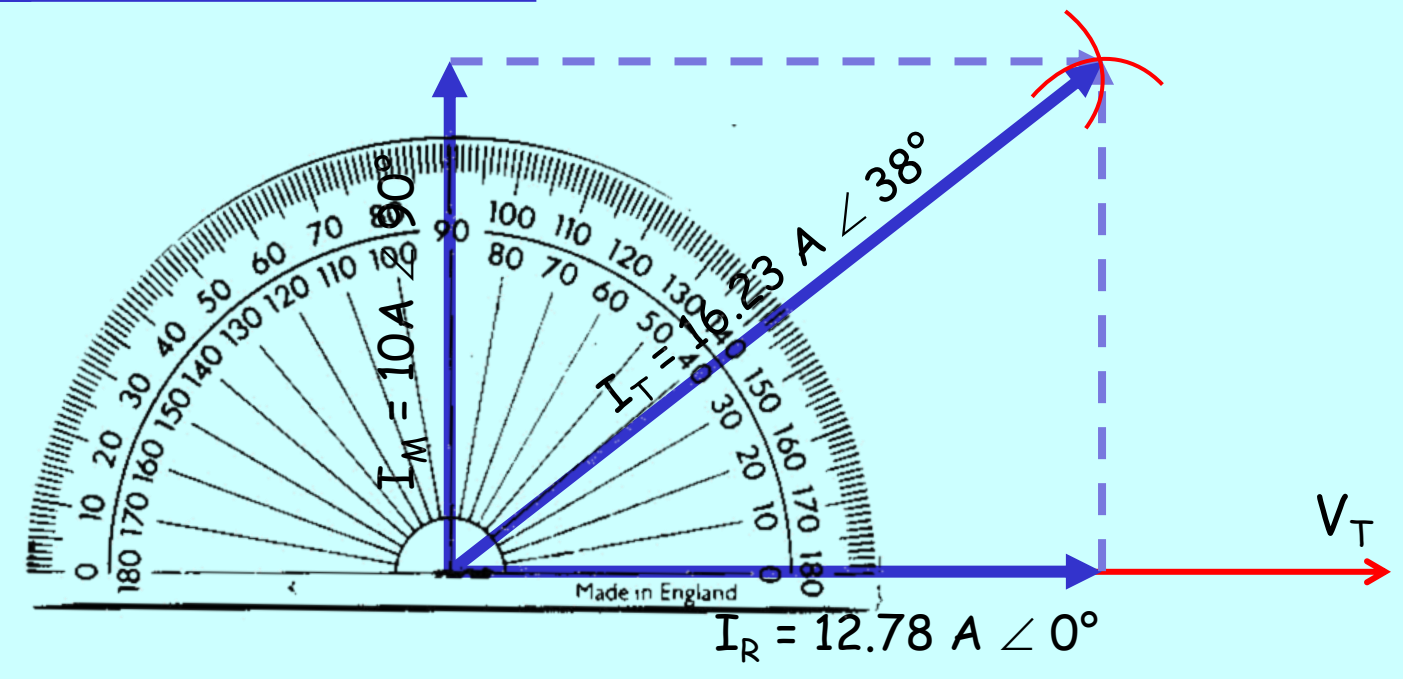


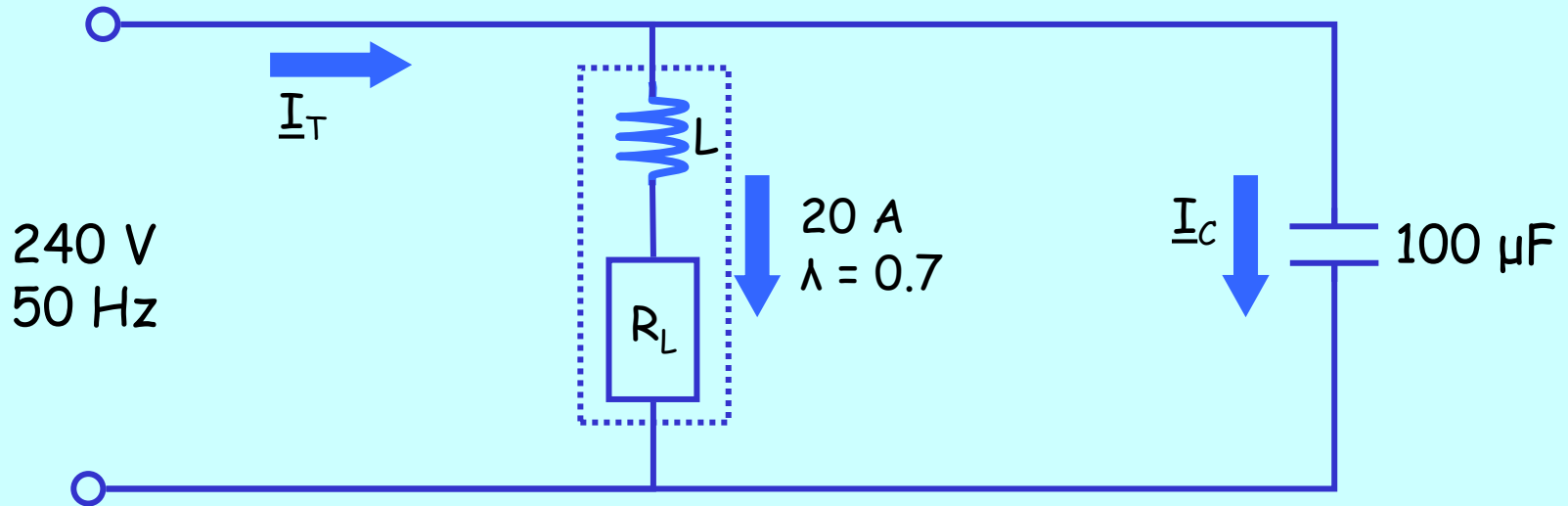
$$I_R = \frac{230}{18} = 12.78 \text{ A}$$

$$I_R = (12.78 \angle 0)$$

$$I_C = \frac{230}{23} = 10 \text{ A}$$

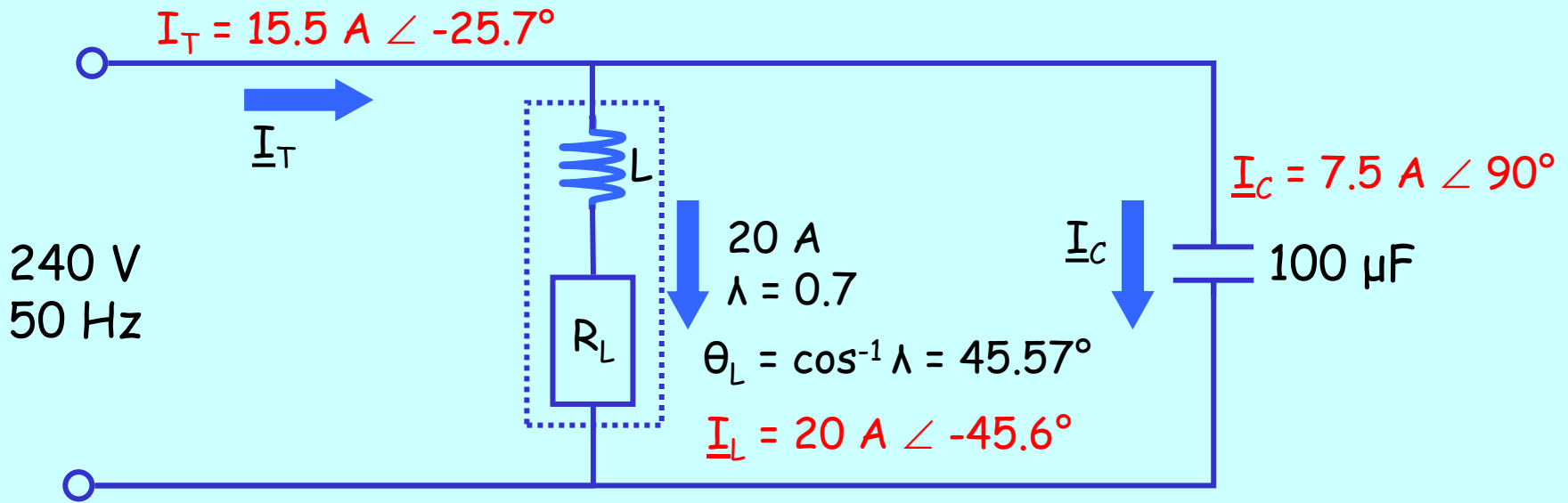
$$I_C = (10 \angle 90)$$





Find:

- (a) Total Current ( $\underline{I}_T$ )
- (b) Total Impedance ( $\underline{Z}_T$ )
- (c) Power Factor ( $\lambda$ )
- (d) Real Power ( $P$ )



(a)  $\underline{I}_T = \underline{I}_L + \underline{I}_C$

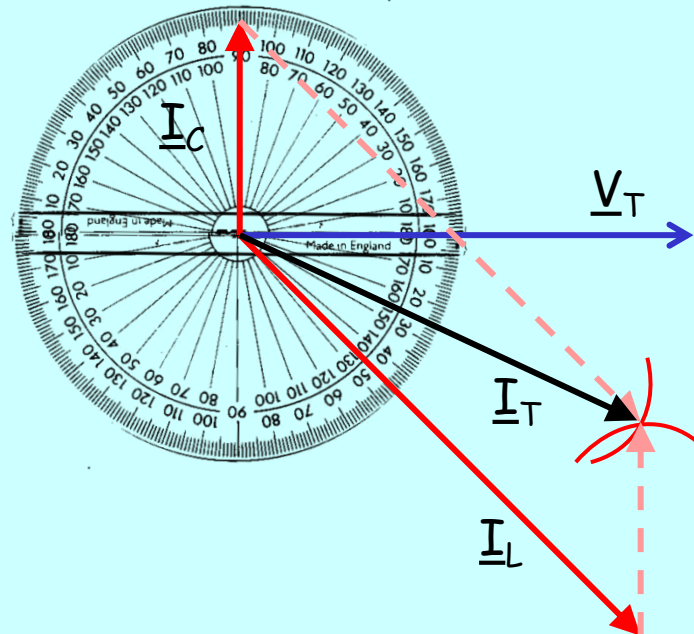
$$I_C = \frac{V}{X_C}$$

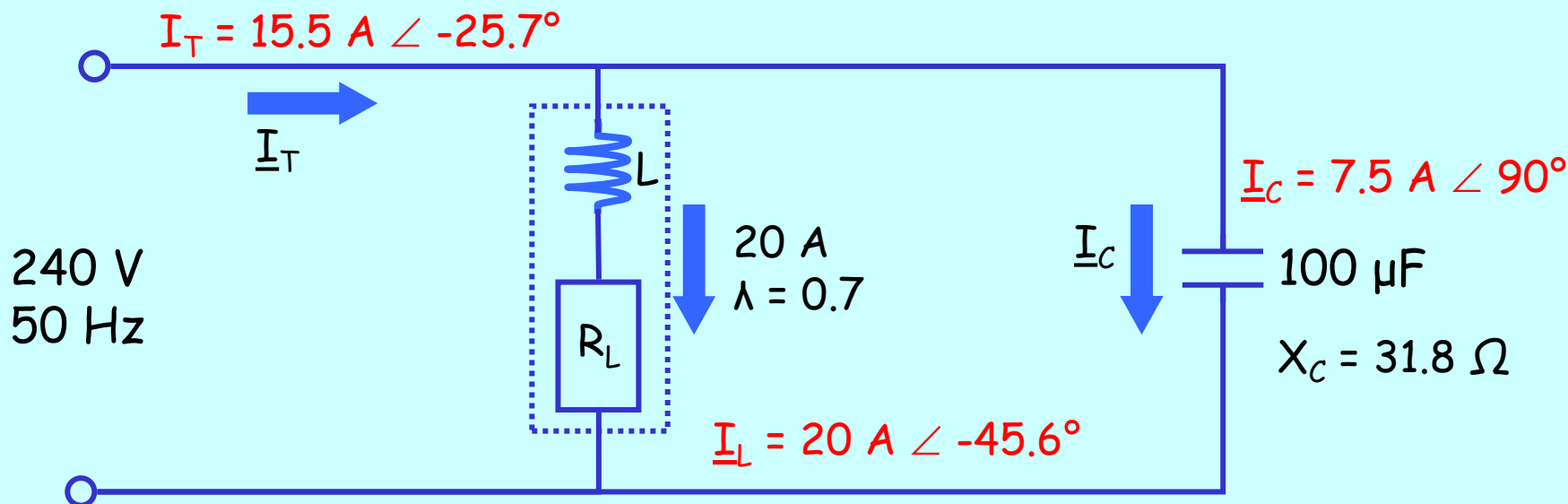
$$|X_C| = \frac{1}{2\pi f C}$$

$$|X_C| = \frac{1}{100\pi \times 100\mu}$$

$$|X_C| = 31.83 \Omega$$

$$I_C = \frac{240}{31.83} = 7.54 \text{ A}$$





(b)  $Z_T = \frac{V}{I_T}$

$$|Z_T| = \frac{240}{15.54} = 15.44 \Omega$$

$$\theta_Z = 25.7^\circ$$

$$Z_T = 15.4 \Omega \angle 25.7^\circ$$

(c)  $\lambda = \cos \theta$

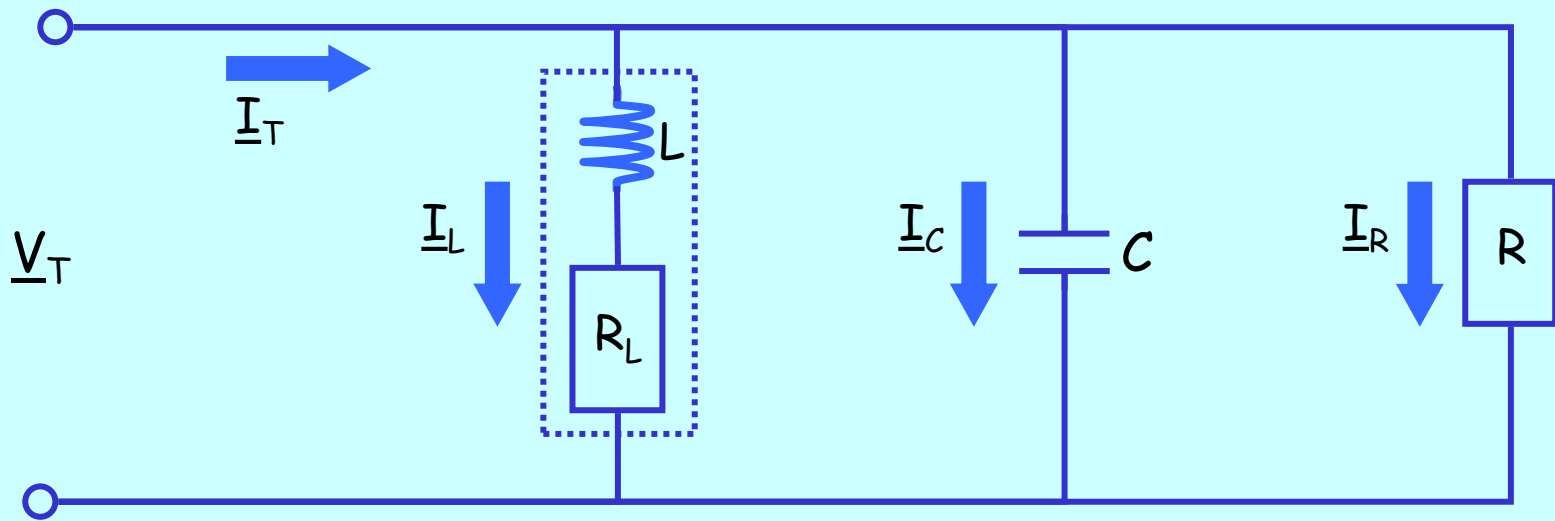
$$\lambda = \cos(-25.7)$$

$$\lambda = 0.9$$

(d)  $P = VI \cos \theta = VI \lambda$

$$P = 240 \times 15.5 \times 0.9$$

$$P = 3,348 \text{ W} = 3.35 \text{ kW}$$



Resonance occurs in a parallel circuits.

This happens when:

$$X_L = X_C$$

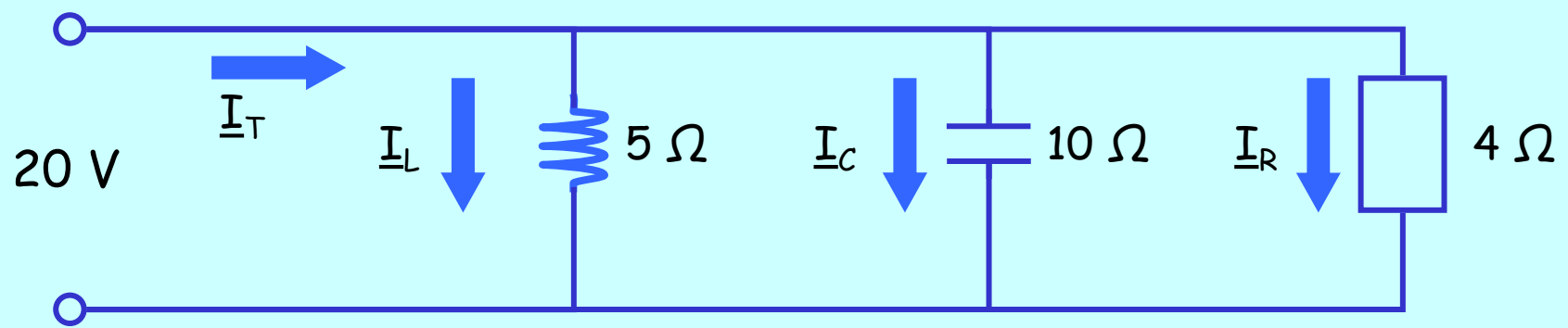
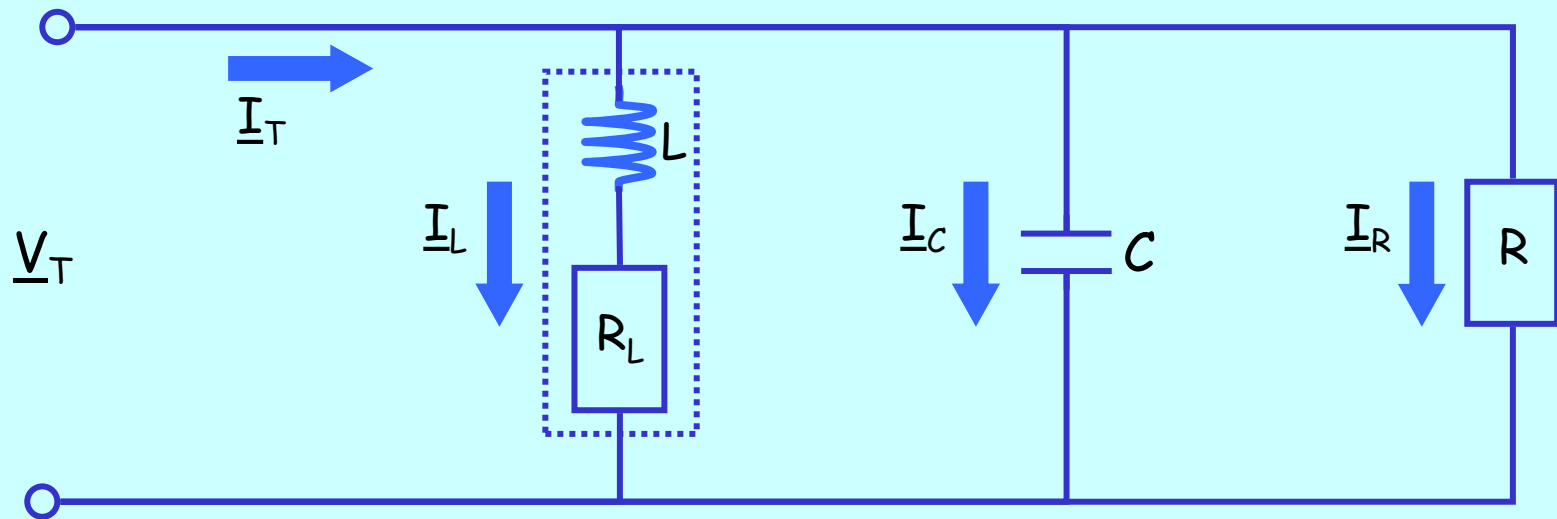
As  $X_L$  and  $X_C$  cancel each other they appear to be an open circuit to the source.

This means that:

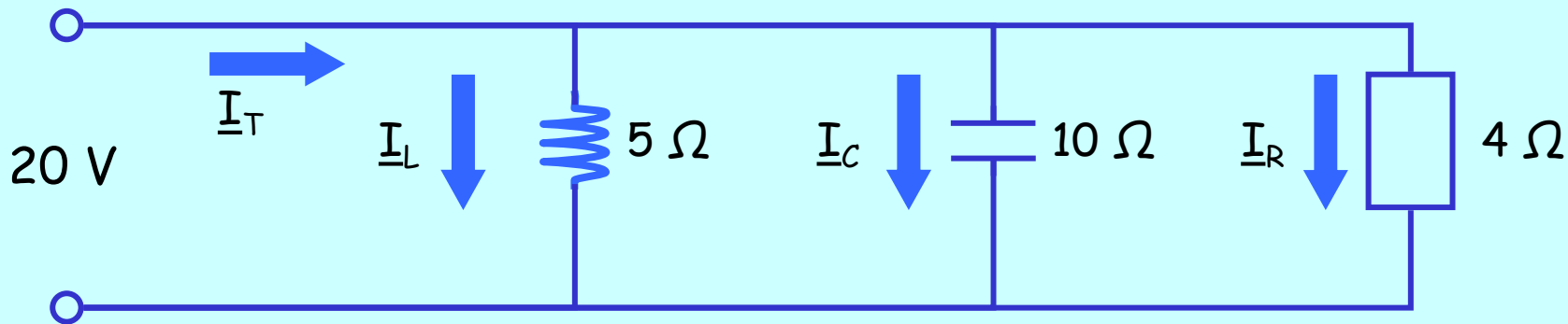
$$Z = R_T$$

Circuit Impedance is a **MAXIMUM** at Resonance ( $f_o$ ).

$$f_o = \frac{1}{2\pi\sqrt{LC}}$$



No  $R$  in series with  $L \therefore$  assume ideal components!



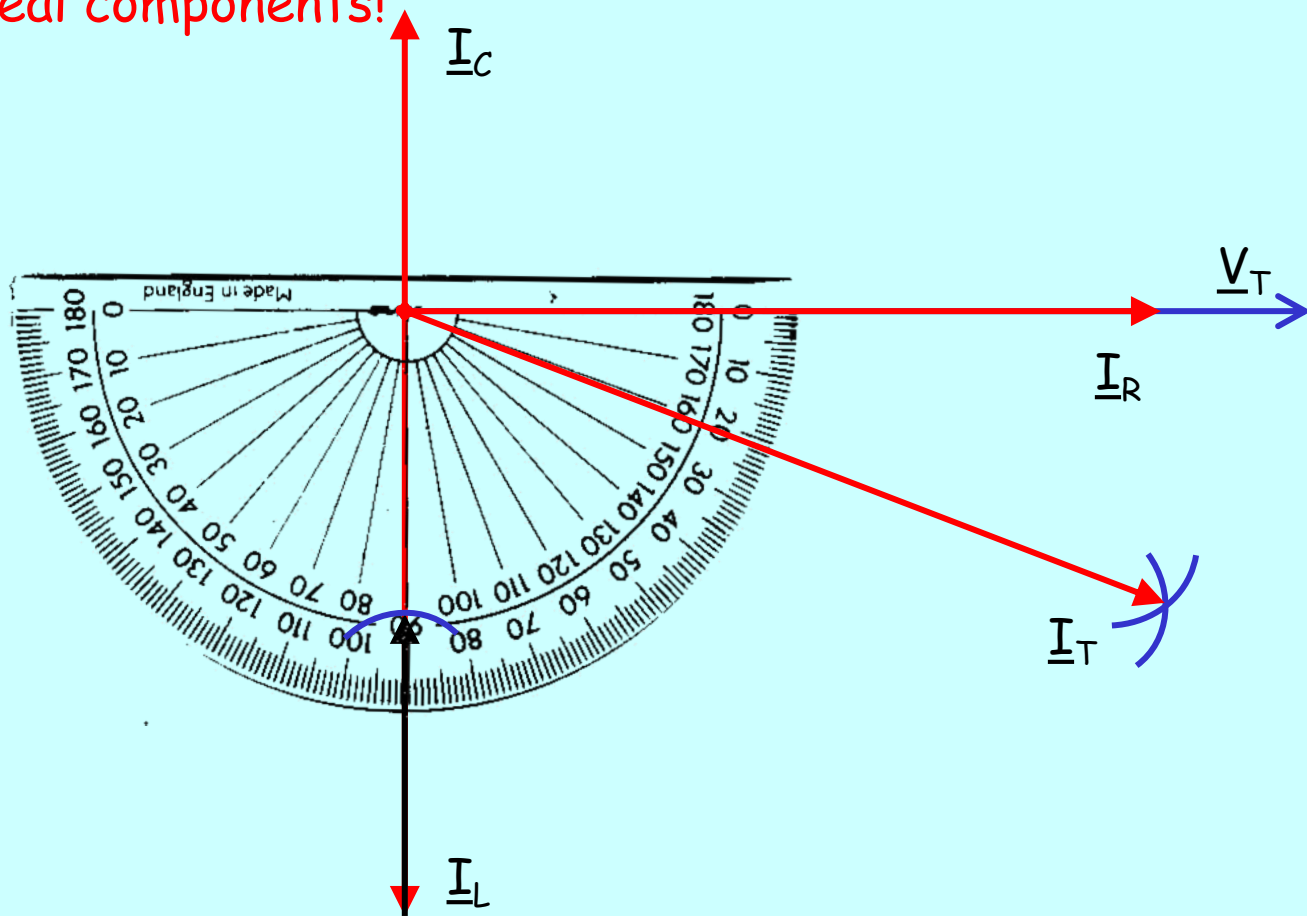
Assume ideal components!

$$|I_R| = \frac{20}{4} = 5 \text{ A}$$

$$|I_L| = \frac{20}{5} = 4 \text{ A}$$

$$|I_C| = \frac{20}{10} = 2 \text{ A}$$

$$I_T = 5.39 \angle -21.8^\circ$$





# End of Lesson

## Practical Exercises

Parallel ac Circuits

Parallel RLC ac Circuits

**UEENEEG102A**

**Solve problems in  
low voltage a.c. circuits**

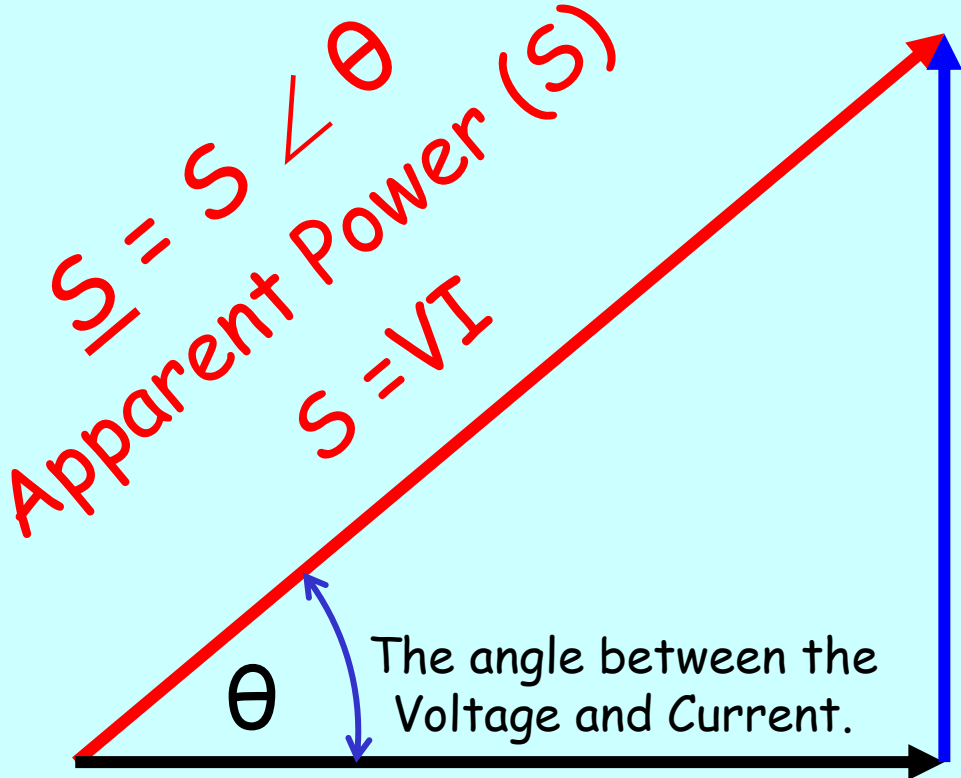
**Power in  
AC Circuits**

## Objectives:

At the end of this lesson students should be able to:

1. Calculate values of the Power Triangle.
2. Draw and label Power Triangles for AC Circuits.
3. Draw Circuit diagrams showing Wattmeter connections.
4. Measure True and Apparent power.

# Power Triangle



$S = S \angle \theta$   
Apparent Power (S)  
 $S = VI$

Reactive Power (Q)

$$Q = VI \sin \theta$$

$$Q = S \sin \theta$$

Real Power (P)

$$P = VI \cos \theta$$

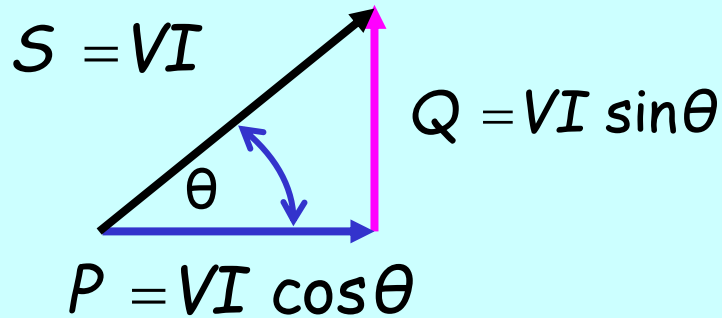
$$P = S \cos \theta$$

$$\text{Power Factor } (\lambda) \triangleq \frac{P}{S}$$

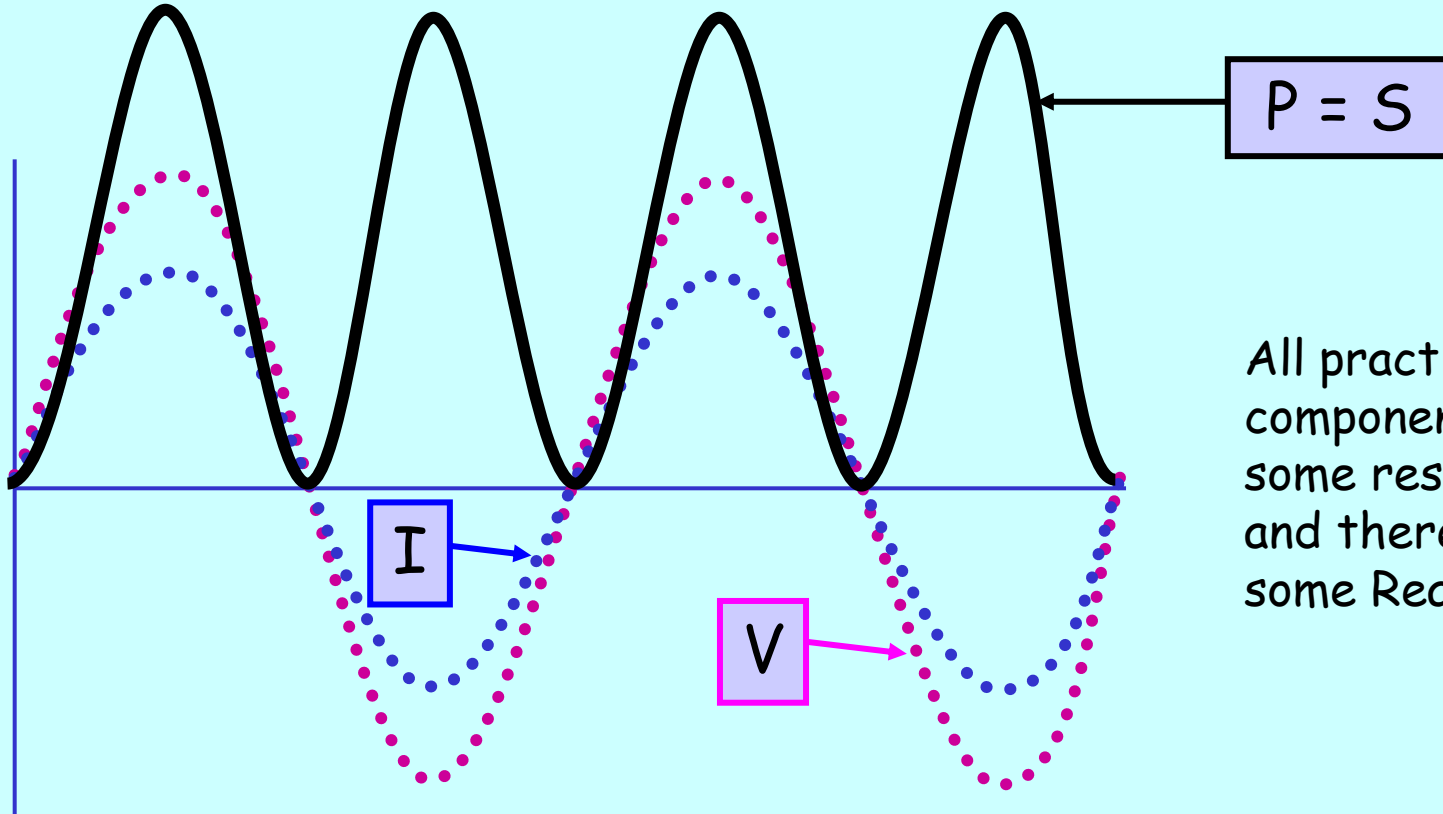
$\cos \theta$  is often called the Power Factor ( $\lambda$ ) because it relates the Real Power to the Apparent Power.

# From the Power Triangle:

In a purely resistive circuit Current is In Phase with Voltage  $\therefore \theta = 0^\circ$   
( $\cos 0 = 1$  &  $\sin 0 = 0$ )



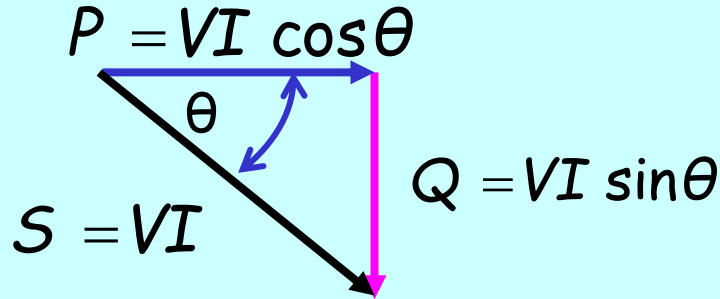
$$P = VI \quad Q = 0$$



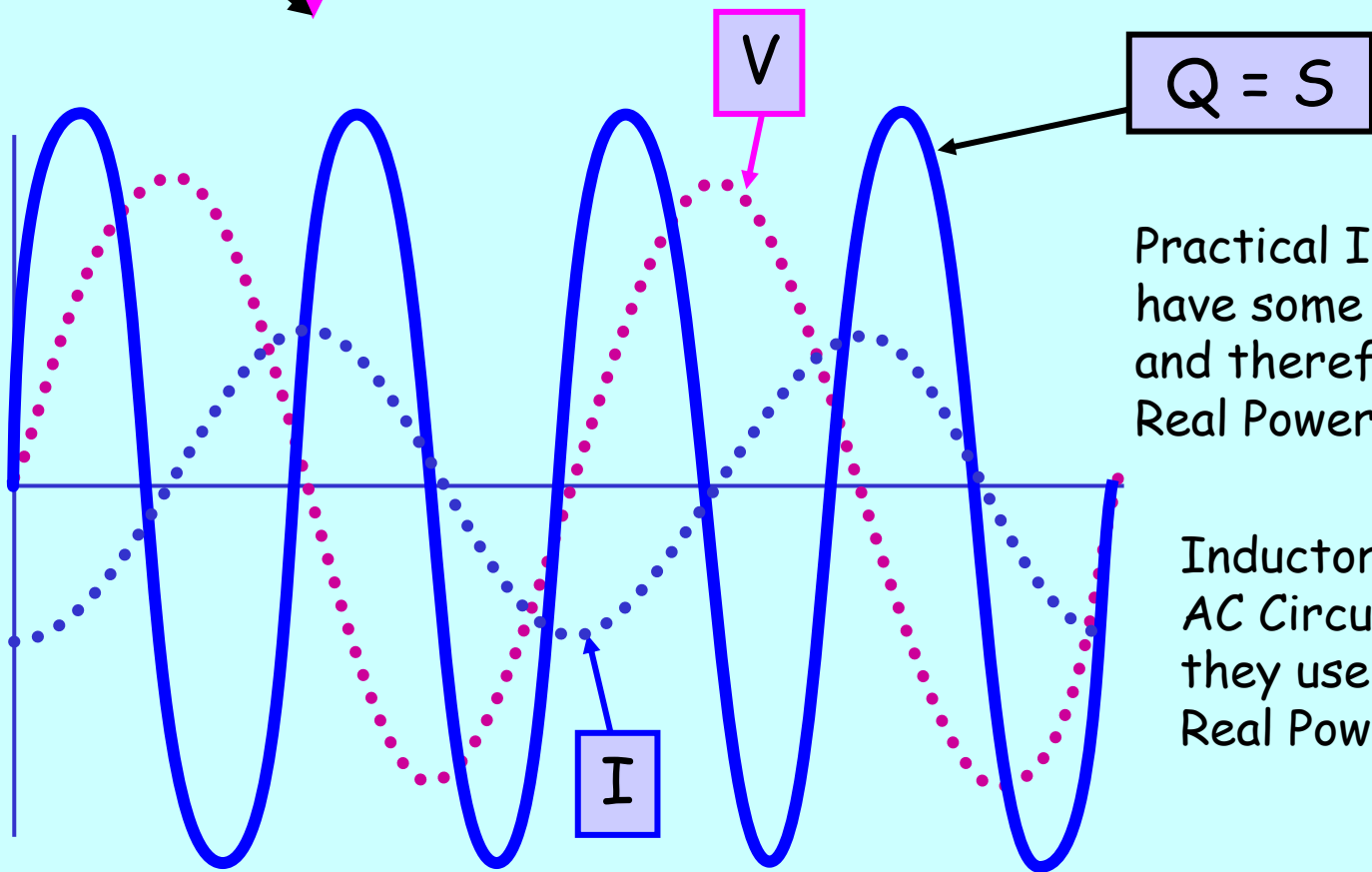
All practical components have some resistance and therefore use some Real Power.

# From the Power Triangle:

In a purely Inductive circuit Current Lags Voltage  $\therefore \theta = -90^\circ$   
( $\cos -90 = 0$  &  $\sin -90 = -1$ )



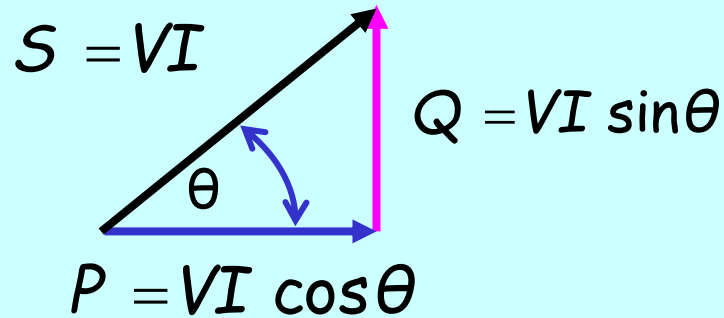
$P = 0$        $Q = -VI$



Practical Inductors have some resistance and therefore use some Real Power ( $I^2R$ ).

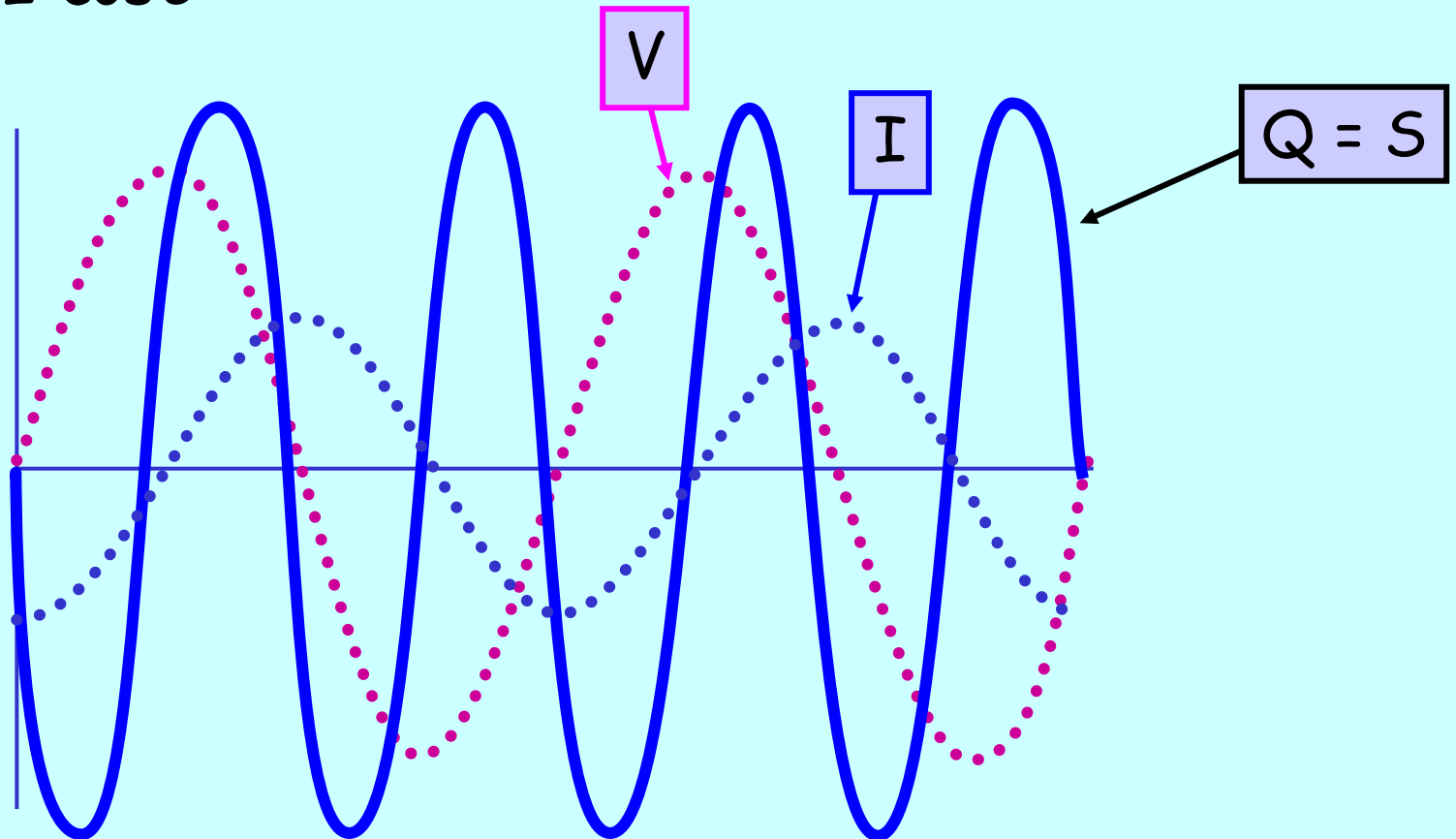
Inductors are used in AC Circuits because they use very little Real Power.

# From the Power Triangle:



In a purely Capacitive circuit Current Leads Voltage  $\therefore \theta = 90^\circ$   
( $\cos 90 = 0$  &  $\sin 90 = 1$ )

$$P = 0 \quad Q = VI$$



A single phase 20 Amp load has a Power Factor of 0.866 when connected to a 240 Volt 50 Hz supply. Determine the Circuit Phase Angle, Apparent, Real and Reactive Power of the load.

What do we know?

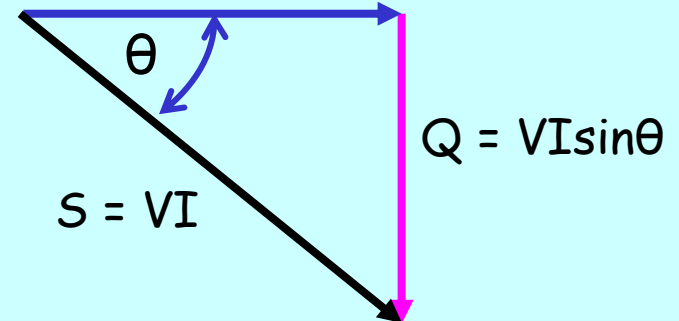
$$I = 20 \text{ A}$$

$$\lambda = 0.866 \text{ lagging}$$

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$P = VI \cos \theta$$



What do we want to know?

Find  $\theta$ ,  $S$ ,  $P$  &  $Q$

$$-\theta = \cos^{-1} \lambda$$

$$\theta = -30^\circ$$

$$Q = \sqrt{S^2 - P^2}$$

$$S = VI$$

$$P = VI \cos \theta$$

$$Q = VI \sin \theta$$

$$S = 20 \times 240$$

$$P = 4.8\text{k} \times 0.866$$

$$Q = 4.8\text{k} \times -0.5$$

$$S = 4.8 \text{ kVA}$$

$$P = 4.16 \text{ kW}$$

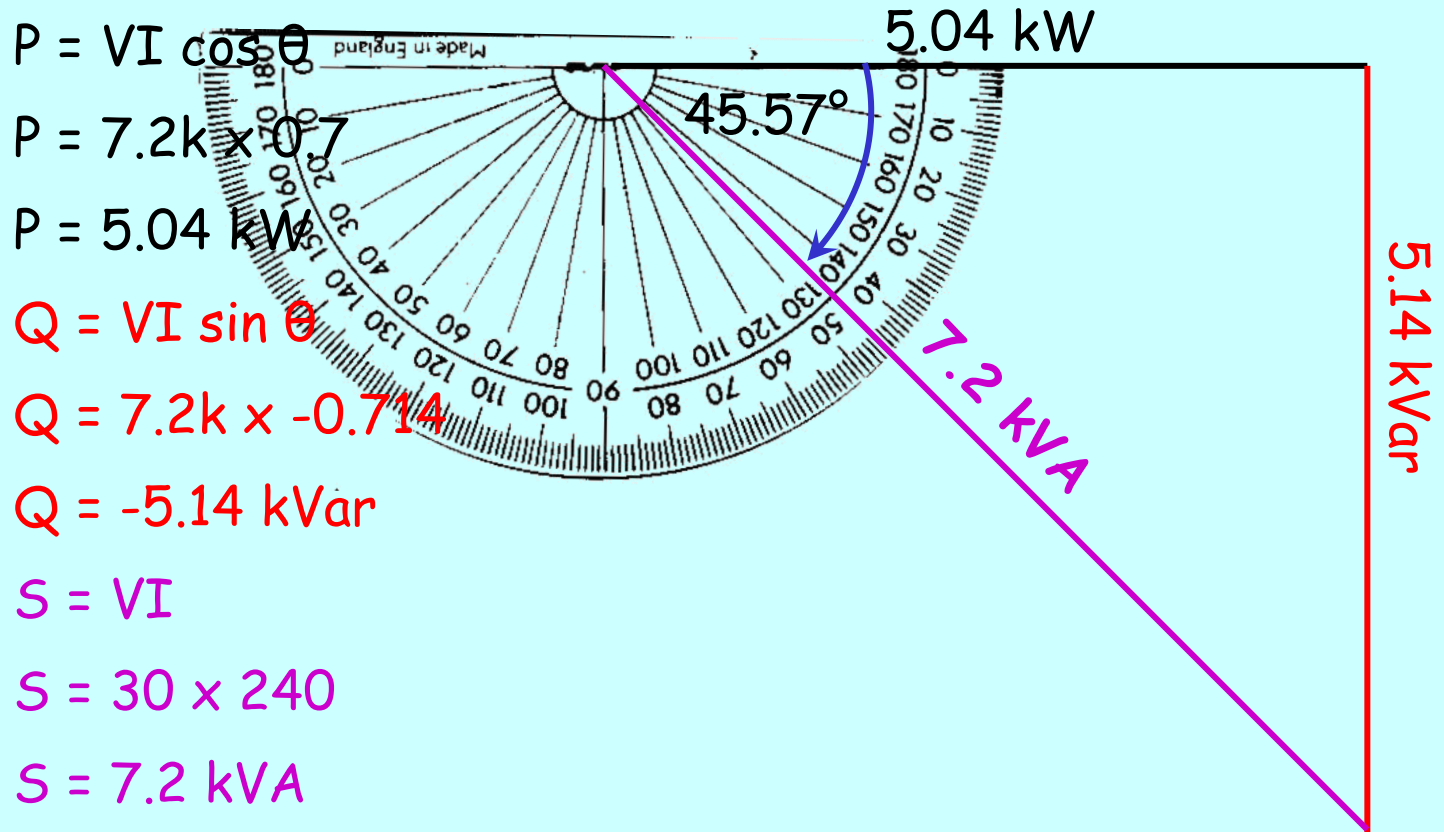
$$Q = -2.4 \text{ kVar}$$



A single phase 240 V 50 Hz supply is connected to a small factory. If the total current drawn from the supply is 30 Amps with a lagging power factor of 0.7, determine the power dissipated by the load, the reactive and apparent powers and draw the Power Triangle.

What do we know?  $I = 30 \text{ A}$   $\lambda = 0.7$  lagging  $V = 240 \text{ V}$   $f = 50 \text{ Hz}$

What do we want to know?  $-\theta = \cos^{-1} \lambda$   $\theta = -45.57^\circ$



Load #1 = 5.04 kW @ 0.7 lag

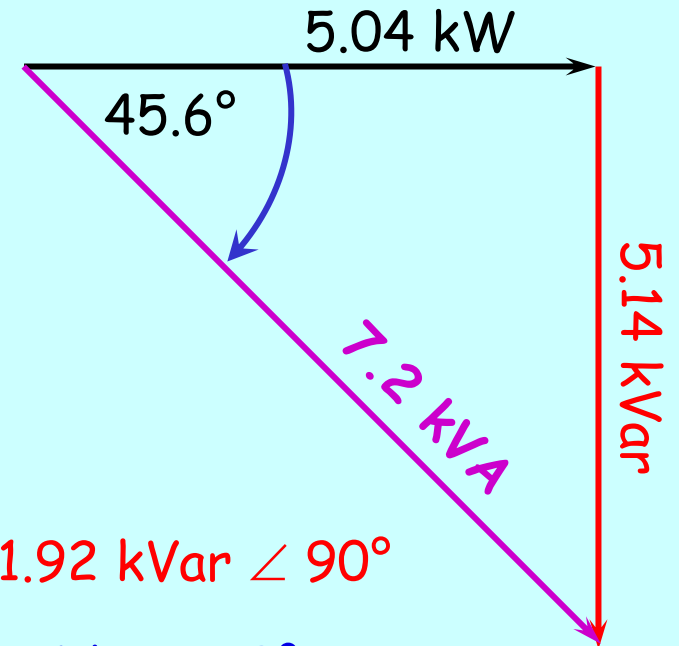
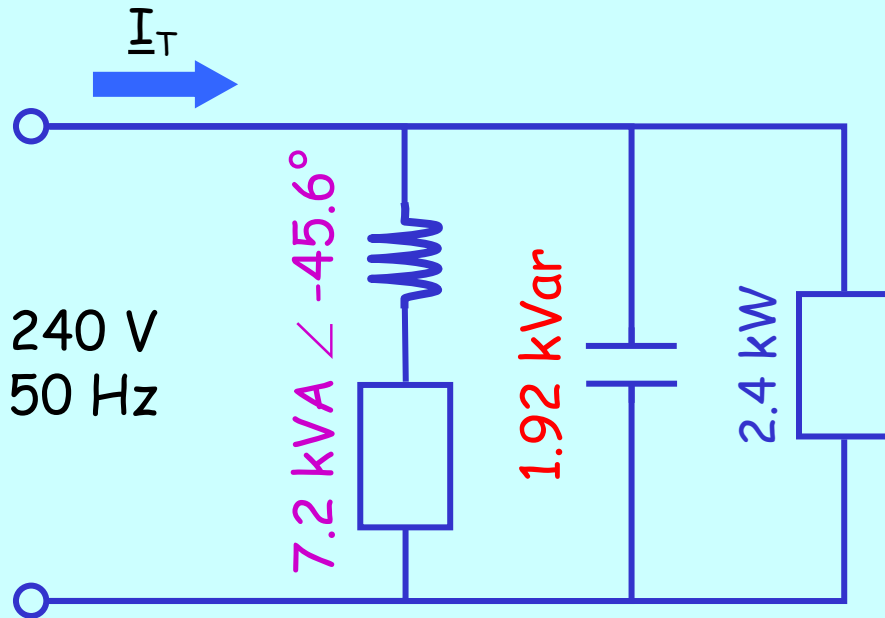
Load #2 = Capacitive @ 1.92 kVar

Load #3 = Purely resistive @ 2.4 kW

Source 240 V @ 50 Hz

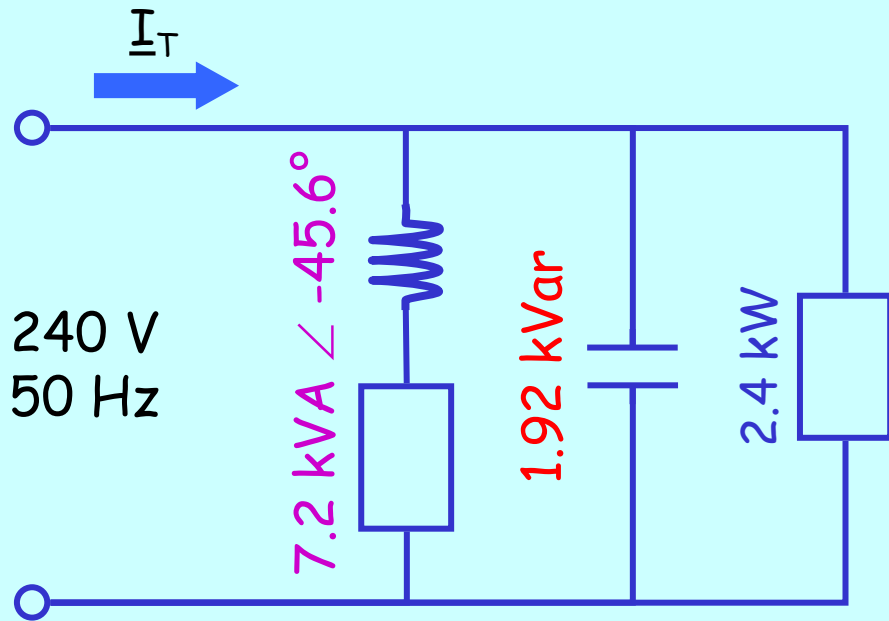
Draw the circuit Power Triangle and find  $I_T$ .

$$P_L = 5.04 \text{ kW} \quad S_L = \frac{P}{\lambda} = \frac{5.04}{0.7}$$
$$\lambda_L = 0.7 \text{ lagging} \quad S_L = 7.2 \text{ kVA}$$
$$-\theta_L = \cos^{-1} 0.7 = -45.6^\circ$$
$$\underline{S}_L = 7.2 \text{ kVA} \angle -45.6^\circ$$
$$Q_L = 7.2 \text{ k} \sin(-45.6^\circ) = 5.14 \text{ kVar}$$



$$\underline{Q}_C = 1.92 \text{ kVar} \angle 90^\circ$$

$$\underline{P}_R = 2.4 \text{ kW} \angle 0^\circ$$



$$P_T = (5.04 + 2.4) = 7.44 \text{ kW}$$

$$Q_T = (1.92 - 5.14) = -3.22 \text{ kVar}$$

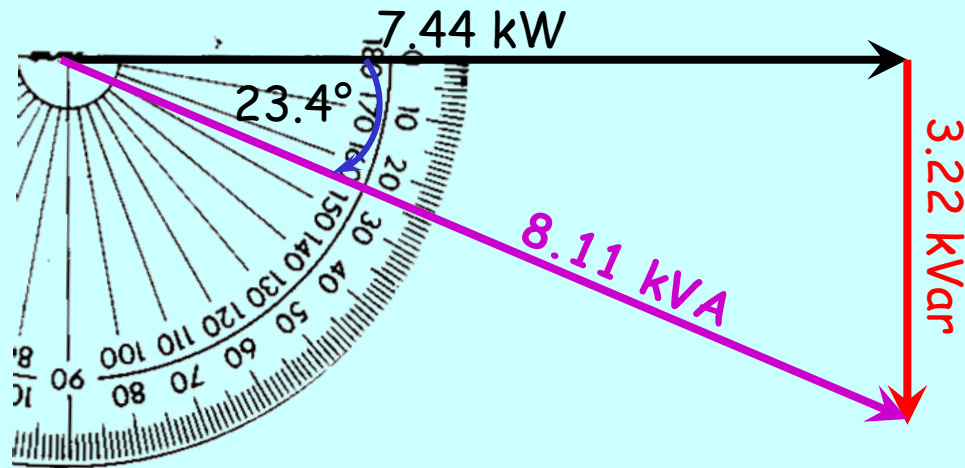
$$S_T = \sqrt{(7.44^2 + 3.22^2)} = 8.11 \text{ kVA}$$

$$\theta_T = \tan^{-1}(-3.22/7.44) = -23.4^\circ$$

$$\lambda = \cos \theta$$

$$\lambda = \cos -23.4$$

$$\lambda = 0.918$$



$$I = \frac{S}{V}$$

$$I = \frac{8.11\text{k} \angle -23.4}{240 \angle 0}$$

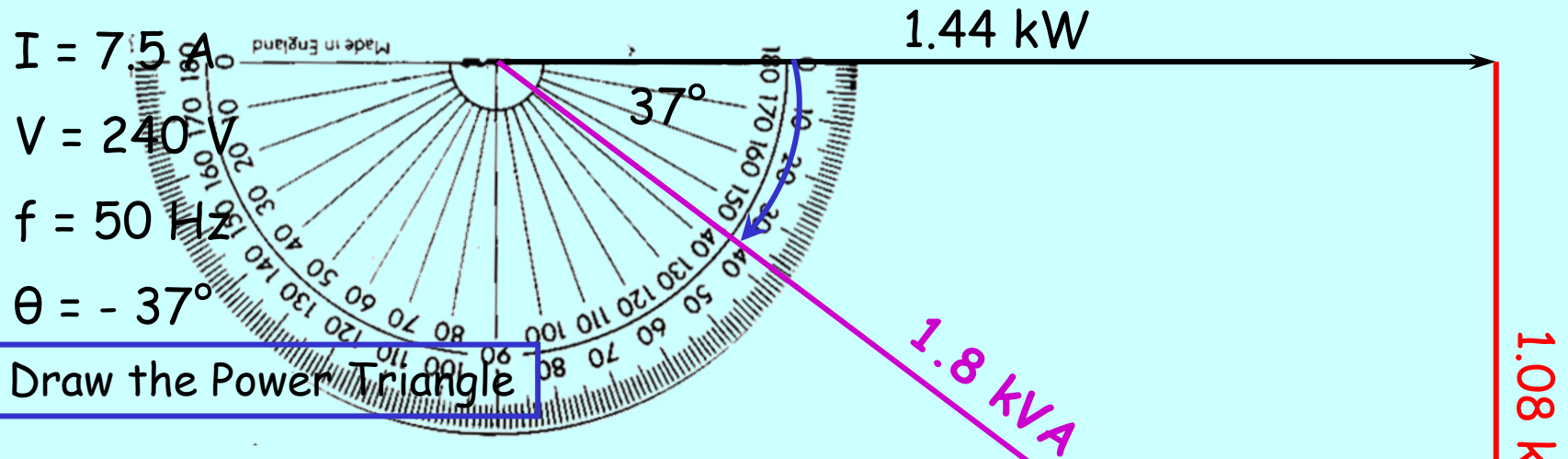
$$I = 33.8 \text{ A} \angle -23.4^\circ$$

# End of Lesson

## Practical Exercises

Single Phase Power Measurement

Need to add pix of Power Meter and how to connect it.  
Circuit diagrams as well.



$$S = VI$$

$$S = 7.5 \times 240$$

$$S = 1.8 \text{ kVA}$$

$$P = VI \cos \theta$$

$$P = 1.8\text{k} \times 0.799$$

$$P = 1.44 \text{ kW}$$

$$Q = VI \sin \theta$$

$$Q = 1.8\text{k} \times -0.602$$

$$Q = -1.08 \text{ kVar}$$

$$P = 10 \text{ kW}$$
$$V = 240 \text{ V}$$

$$(a) \quad \lambda = 1$$

$$S = 10 \text{ kVA}$$

$$I = \frac{10\text{k}}{240}$$

$$I = 41.7 \text{ A}$$

$$(b) \quad \lambda = 0.8 \text{ lag}$$

$$\underline{S} = \frac{10\text{k}}{0.8}$$

$$I = \frac{12.5\text{k}}{240}$$

$$S = 12.5 \text{ kVA}$$

$$I = 52.1 \text{ A}$$

$$(c) \quad \lambda = 0.6 \text{ lag}$$

$$\underline{S} = \frac{10\text{k}}{0.6}$$

$$I = \frac{16.7\text{k}}{240}$$

$$S = 16.7 \text{ kVA}$$

$$I = 69.6 \text{ A}$$

$$\underline{S} = \frac{P}{\lambda}$$

$$I = \frac{S}{V}$$

Note that as Power Factor decreases Current increases

Find the Apparent Power, the Reactive Power & the Power Factor

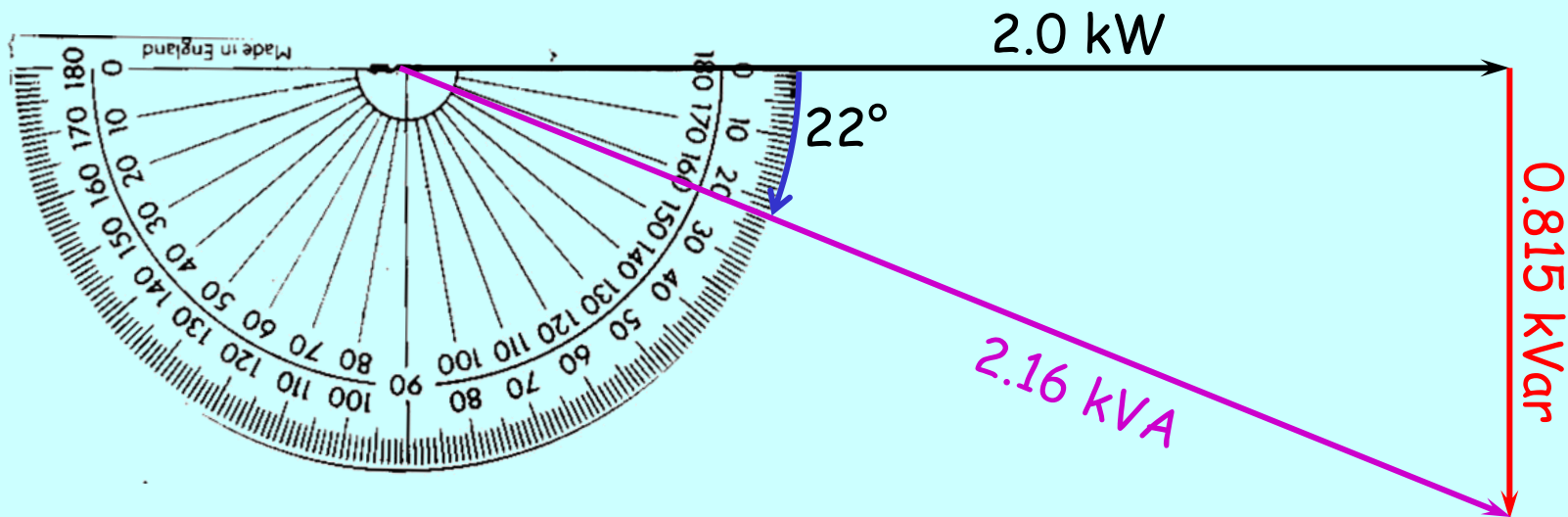
$$V = 240 \text{ V} \quad S = VI \quad \lambda = \frac{P}{S} = \frac{2\text{k}}{2.16\text{k}} \quad \theta = \cos^{-1} \lambda$$

$$I = 9 \text{ A} \quad S = 240 \times 9 \quad \theta = 22.2^\circ$$

$$P = 2 \text{ kW} \quad S = 2.16 \text{ kVA} \quad \lambda = 0.926 \quad Q = S \sin \theta$$

$$Q = \sqrt{(2.16^2 - 2^2)} \text{ kVar} \quad Q = 2.16\text{k} \sin 22.2$$

$$Q = 0.815 \text{ kVar} \quad Q = 0.816 \text{ kVar}$$





**UEENEEEG102A**

**Solve problems in  
low voltage a.c. circuits**

**Power Factor  
Improvement**

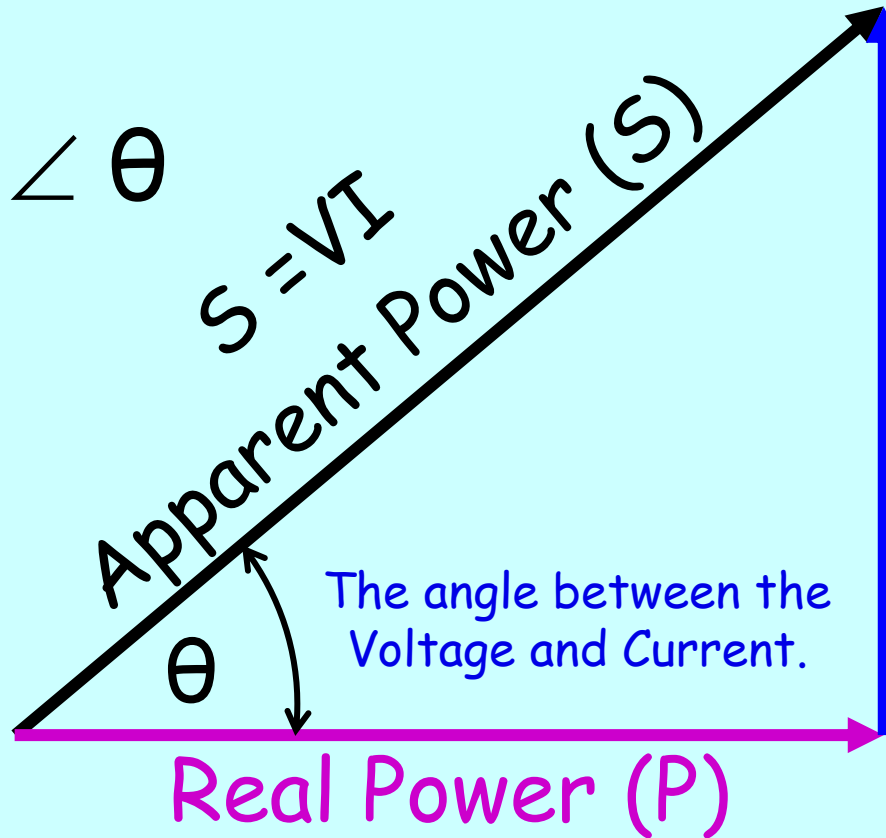
## Objectives:

At the end of this lesson students should be able to:

1. Determine the Power Factor of a Single Phase Circuit.
2. State the effects of low power factor in a single phase circuit.
3. Determine the value of capacitance or reactive power required to improve power factor.
4. State the requirements concerning installation power factor.

# Power Triangle

$$\underline{S} = S \angle \theta$$



Reactive  
Power (Q)  
 $Q = VI \sin \theta$

$$P = VI \cos \theta$$

$\cos \theta$  is called the **Power Factor ( $\lambda$ )** of the circuit because it relates the **Real Power** to the **Apparent Power**.

Power Factor ( $\lambda$ ) is a measure of an installations efficiency ( $\eta$ )

$$\lambda = \cos \theta$$

$\theta$  = The Phase angle of the circuit

Low Power Factor ( $\lambda$ ) can be caused by:

Inductive loads (lagging power factor).

Fluorescent light Ballasts.

Lightly loaded Motors and Transformers

Capacitive Loads (leading power factor).

Long cable runs.

Low Power Factor ( $\lambda$ ) causes:

Increased Losses ( $I^2R$ ).

Increased Cable Sizes.

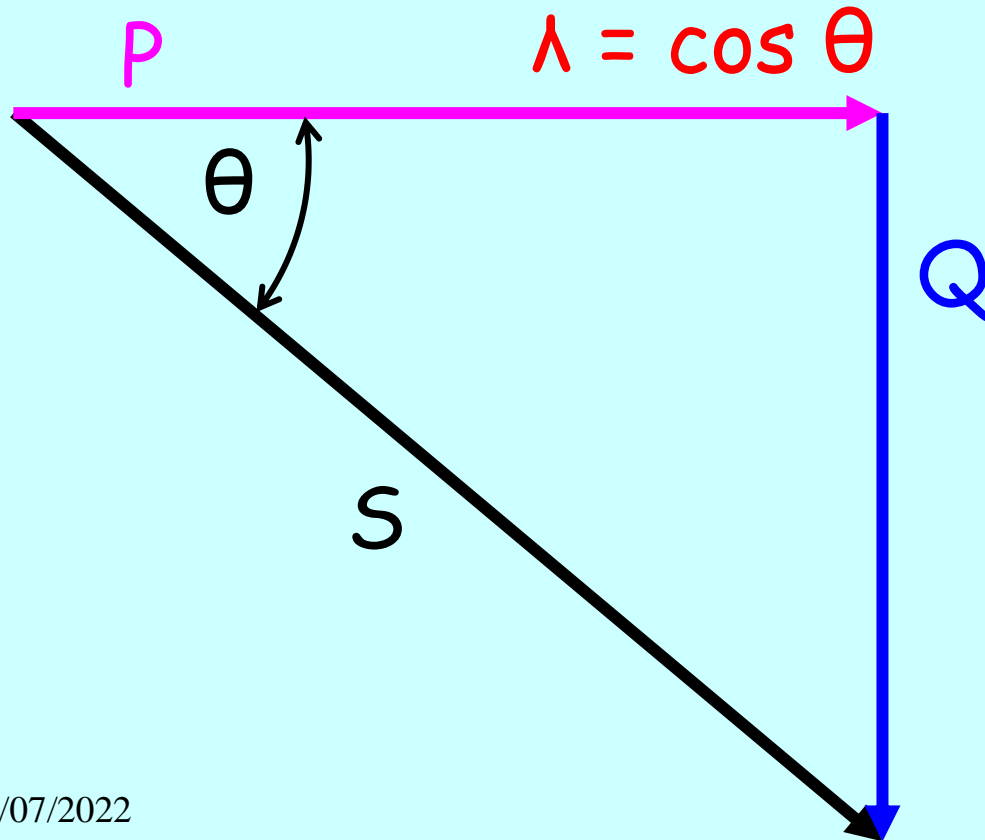
Increased Equipment Costs (require higher ratings).

Increased Generation Costs. Operational problems.

# Power Factor Improvement

The NSW Service and Installation Rules requires that a consumers installation should have a power factor of not less than 0.9 lagging and that the power factor of any installation MUST NOT become leading at any time.

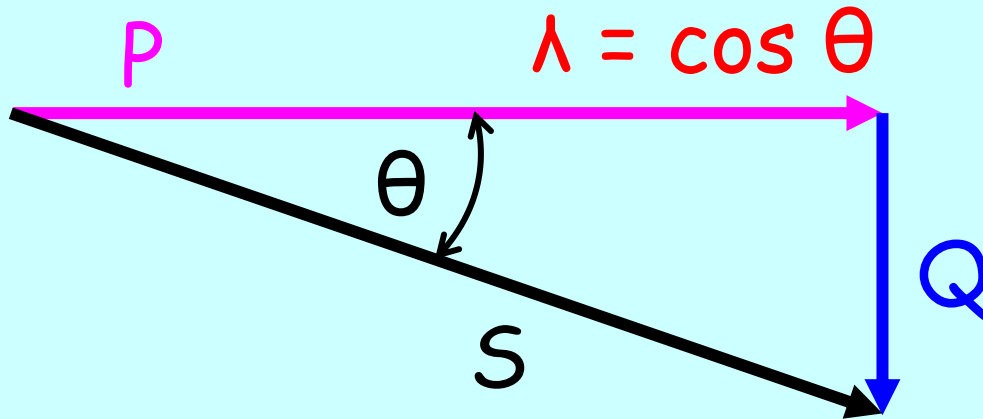
How can we improve power factor?



# Power Factor Improvement

The NSW Service and Installation Rules requires that a consumers installation should have a power factor of not less than 0.9 lagging and that the power factor of any installation MUST NOT become leading at any time.

How can we improve power factor?



## Reduce 'Q'

This reduces 'S' and  $\theta$

But does not change 'P'

Most reactive loads are Inductive and hence have a lagging power factor.

Counteract Inductive loads by placing a Capacitor in parallel.

## Tutorial pg. 51 Example:

A 240 V, 50 Hz, single phase installation draws 40 A from a supply at a power factor of 0.4 lag. Determine the Farads rating of a capacitor bank to be connected in parallel with the load to achieve an installation power factor of:

- a) 0.866 lag
- b) Unity

What do we know?

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$I = 40 \text{ A}$$

$$\lambda = 0.4 \text{ lag}$$

What do we want to know?

Capacitance

What can we calculate?

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$I = 40 \text{ A}$$

$$\lambda = 0.4 \text{ lag}$$

$$\theta = \cos^{-1} \lambda$$

$$\theta = \cos^{-1} 0.4$$

$$\theta = -66.4^\circ$$

$$S = VI$$

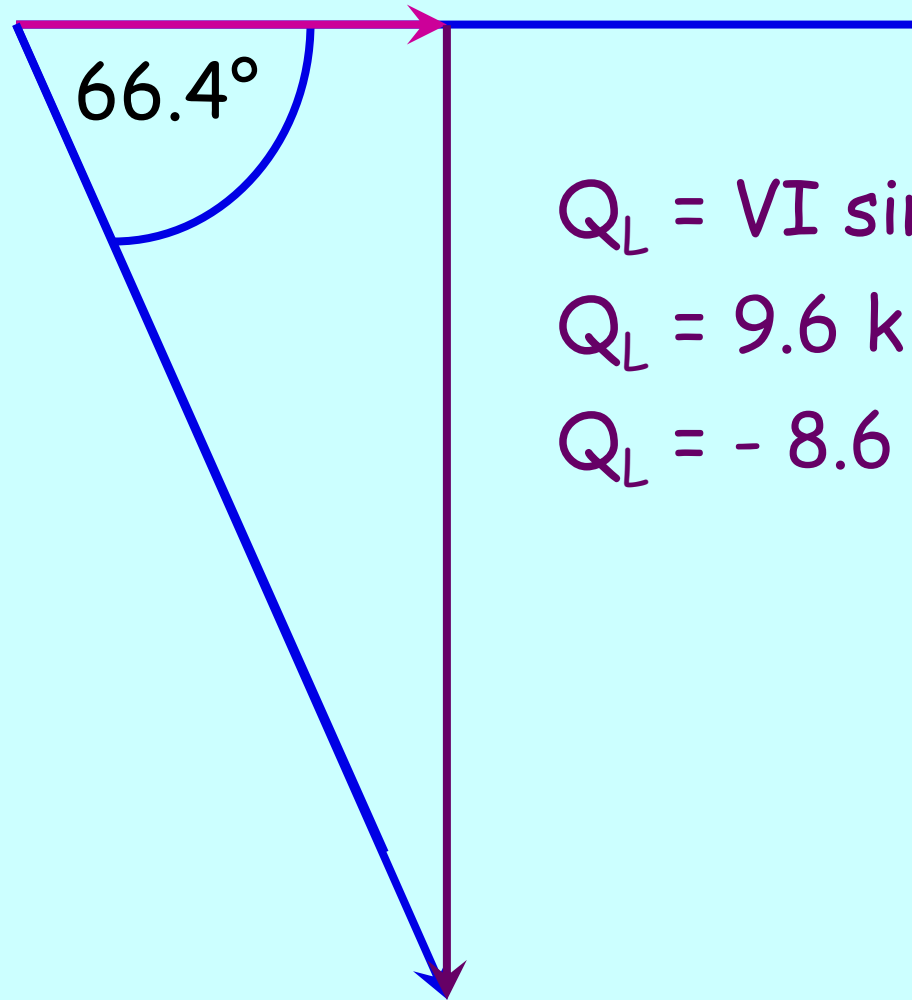
$$S = 40 \times 240$$

$$S = 9.6 \text{ kVA}$$

$$P = VI \cos \theta$$

$$P = 9.6 \text{ k} \times 0.4$$

$$P = 3.8 \text{ kW}$$



$$Q_L = VI \sin \theta$$

$$Q_L = 9.6 \text{ k} \times (-0.9)$$

$$Q_L = -8.6 \text{ kVar}$$



a)  $0.866 \text{ lag}$

$V = 240 \text{ V}$

$f = 50 \text{ Hz}$

$\lambda = 0.866 \text{ lag}$

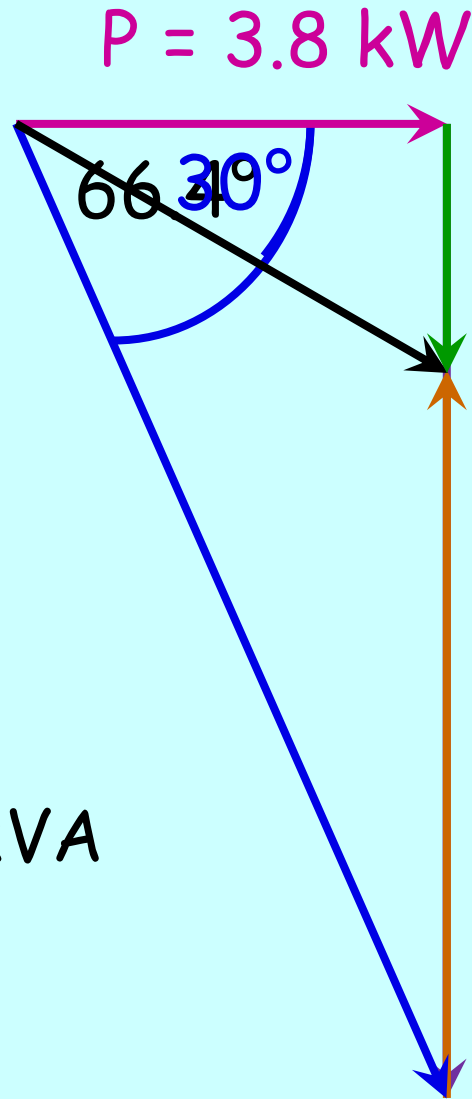
$\theta = \cos^{-1} \lambda$

$\theta_a = \cos^{-1} 0.866$

$\theta_a = -30^\circ$

$S = \frac{P}{\lambda}$

$S = \frac{3.8}{0.866} = 4.4 \text{ kVA}$



$Q_L = -8.6 \text{ kVar}$

$Q_T = S \sin \theta$

$Q_T = 4.4 \text{ k} \times (-0.5)$

$Q_T = -2.2 \text{ kVar}$

$Q_T = Q_L + Q_C$

$Q_C = Q_T - Q_L$

$Q_C = -2.2 + 8.6$

$Q_C = 6.4 \text{ kVar}$

a)  $0.866 \text{ lag}$

$$Q_C = 6.4 \text{ kVar}$$

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$Q_C = V_C I_C$$

$$I_C = \frac{V_C}{X_C}$$

$$Q_C = \frac{V_C^2}{X_C}$$

$$X_C = \frac{1}{2\pi f C}$$

$$X_C = \frac{V^2}{Q_C}$$

$$C = \frac{1}{2\pi f X_C}$$

$$X_C = \frac{240^2}{6.4\text{k}}$$

$$C = \frac{1}{2\pi \times 50 \times 9}$$

$$X_C = 9 \Omega$$

$$C = 353.7 \mu\text{F}$$

b) Unity

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$\lambda = 1.0$$

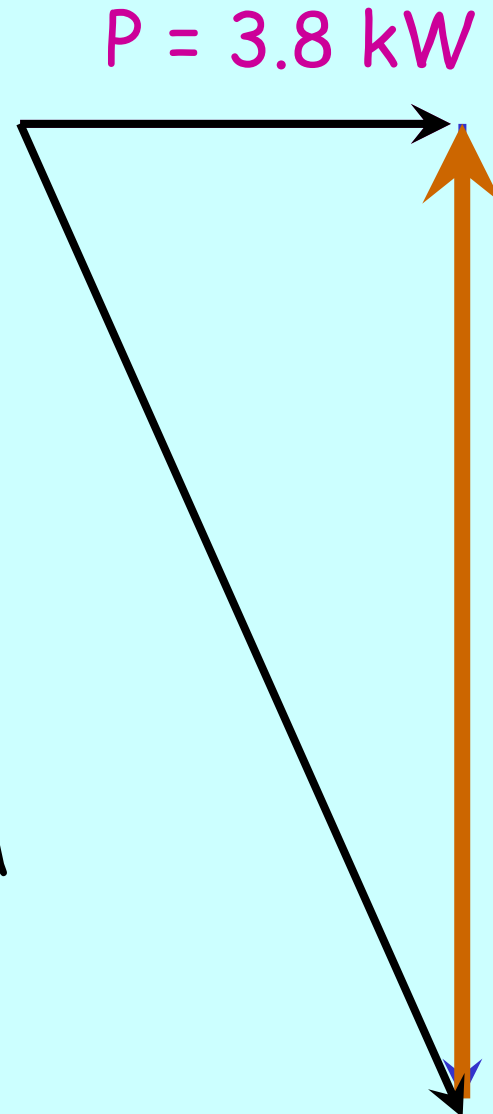
$$\theta = \cos^{-1} \lambda$$

$$\theta_a = \cos^{-1} 1.0$$

$$\theta_a = 0^\circ$$

$$S = \frac{P}{\lambda}$$

$$S = \frac{3.8}{1.0} = 3.8 \text{ kVA}$$



$$Q_L = -8.6 \text{ kVar}$$

$$Q_T = 0 \text{ kVar}$$

$$Q_C = 8.6 \text{ kVar}$$

b) Unity

$$Q_C = 8.6 \text{ kVar}$$

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$Q_C = V_C I_C$$

$$I_C = \frac{V_C}{X_C}$$

$$Q_C = \frac{V_C^2}{X_C}$$

$$X_C = \frac{1}{2\pi f C}$$

$$X_C = \frac{V^2}{Q_C}$$

$$C = \frac{1}{2\pi f X_C}$$

$$X_C = \frac{240^2}{8.6\text{k}}$$

$$C = \frac{1}{2\pi \times 50 \times 6.7}$$

$$X_C = 6.7 \Omega$$

$$C = 475.3 \mu\text{F}$$

A 240 V, 50 Hz, single phase installation draws 10 A from a supply at a power factor of 0.6 lag. Determine the Farads rating of a capacitor bank to be connected in parallel with the load to make it comply with the requirements of the NSW Service and Installation Rules.

What do we know?

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$I = 10 \text{ A}$$

$$\lambda = 0.6 \text{ lag}$$

What do we want?

$$\lambda = 0.9 \text{ lag}$$

What do we need to know?

Capacitance

What can we calculate?

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$I = 10 \text{ A}$$

$$\lambda = 0.6 \text{ lag}$$

$$\theta = \cos^{-1} \lambda$$

$$\theta = \cos^{-1} 0.6$$

$$\theta = -53.1^\circ$$

$$S = VI$$

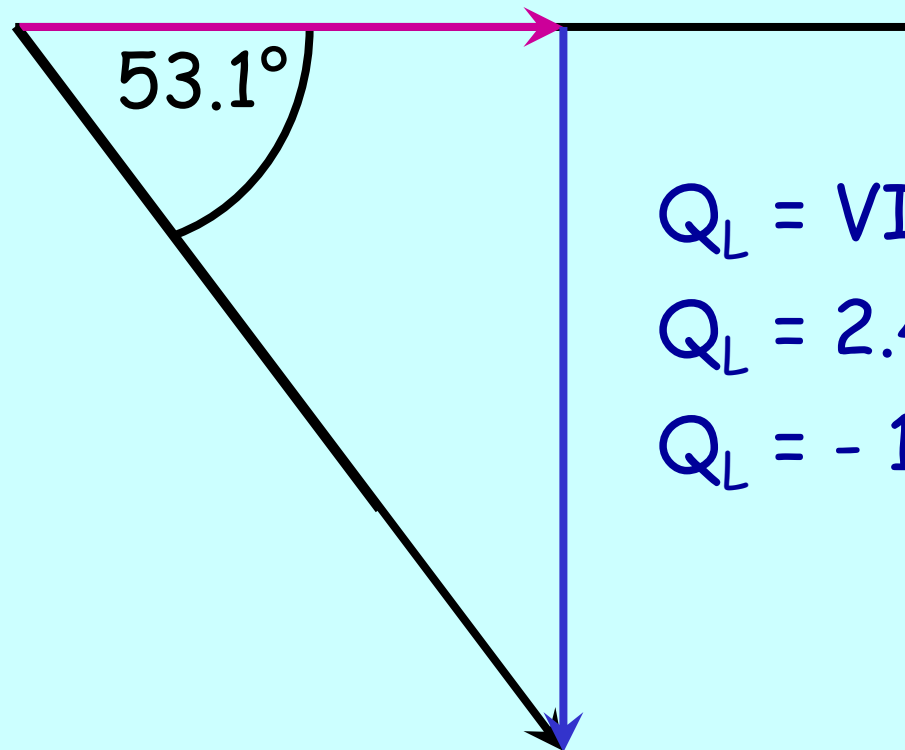
$$S = 10 \times 240$$

$$S = 2.4 \text{ kVA}$$

$$P = VI \cos \theta$$

$$P = 2.4 \text{ k} \times 0.6$$

$$P = 1.44 \text{ kW}$$



$$Q_L = VI \sin \theta$$

$$Q_L = 2.4 \text{ k} \times (-0.8)$$

$$Q_L = -1.92 \text{ kVar}$$

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$I = 10 \text{ A}$$

$$\lambda = 0.9 \text{ lag}$$

$$\theta = \cos^{-1} \lambda$$

$$\theta_a = \cos^{-1} 0.9$$

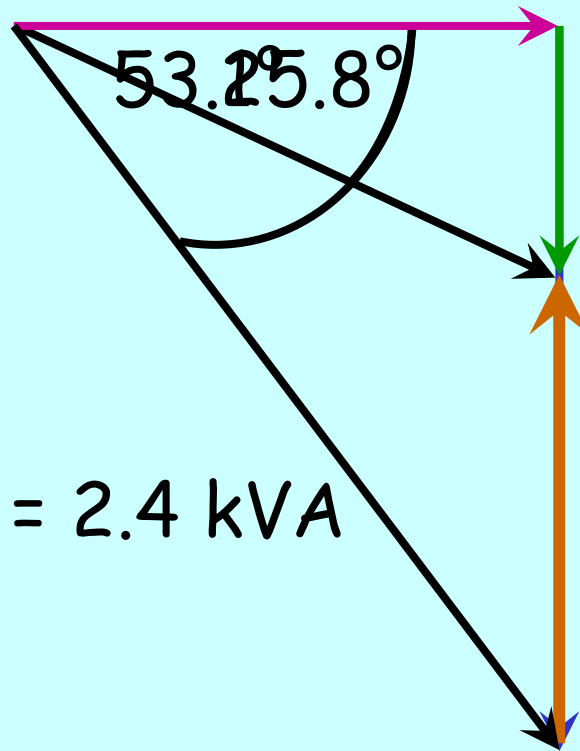
$$\theta_a = -25.8^\circ$$

$$S = \frac{P}{\lambda}$$

$$S = \frac{1.44 \text{ k}}{0.9} = 1.6 \text{ kVA}$$

$$S = 2.4 \text{ kVA}$$

$$P = 1.44 \text{ kW}$$



$$Q_L = -1.92 \text{ kVar}$$

$$Q_T = S \sin \theta$$

$$Q_T = 1.6 \text{ k} \times (-0.44)$$

$$Q_T = -0.7 \text{ kVar}$$

$$Q_T = Q_L + Q_C$$

$$Q_C = Q_T - Q_L$$

$$Q_C = -0.7 + 1.92$$

$$Q_C = 1.22 \text{ kVar}$$

$$Q_C = 1.22 \text{ kVar}$$

$$V = 240 \text{ V}$$

$$f = 50 \text{ Hz}$$

$$Q_C = V_C I_C$$

$$I_C = \frac{V_C}{X_C}$$

$$Q_C = \frac{V_C^2}{X_C}$$

$$X_C = \frac{1}{2\pi f C}$$

$$X_C = \frac{V^2}{Q_C}$$

$$C = \frac{1}{2\pi f X_C}$$

$$X_C = \frac{240^2}{1.22\text{k}}$$

$$C = \frac{1}{2\pi \times 50 \times 47.2}$$

$$X_C = 47.2 \Omega$$

$$C = 67.4 \mu\text{F}$$



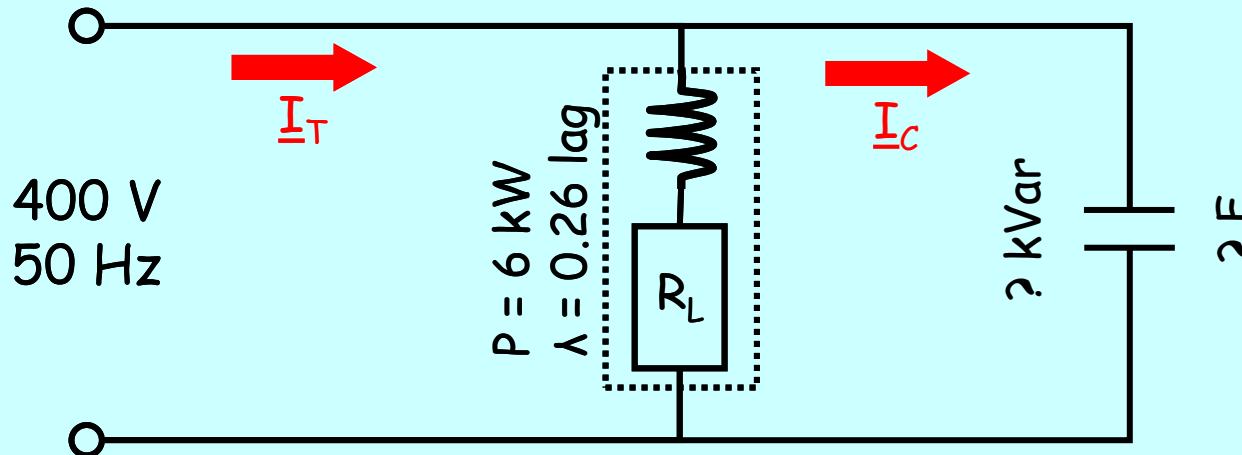
## Tutorial pg. 52 Exercise 1

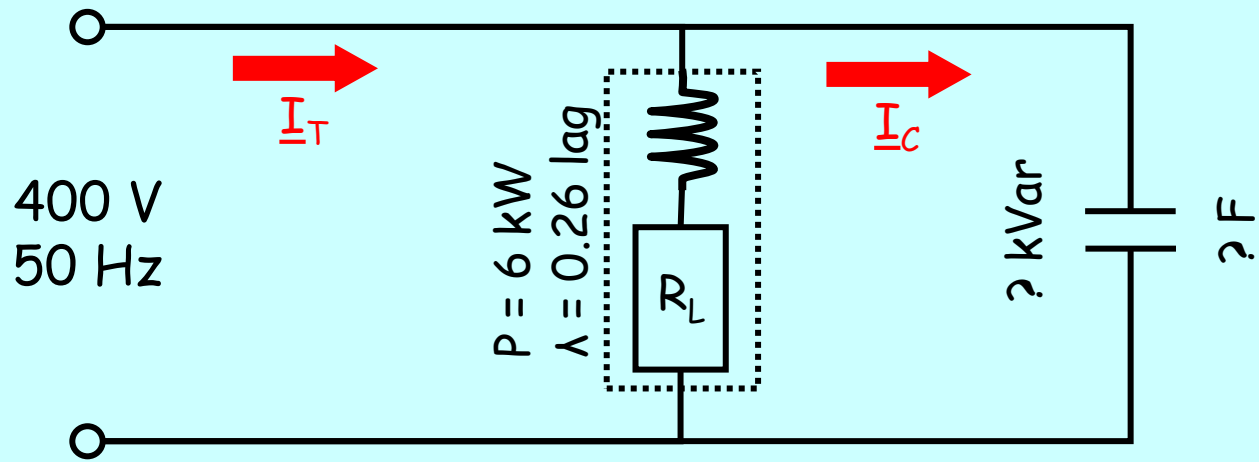
A 400V 50Hz, fluorescent lighting load in a shopping centre is measured at 6000 Watts at a power factor of 0.26 lagging.

Determine:

- The KVar Rating of a Capacitor Bank to improve the power factor to 0.8. Use both the Measurement & Calculation methods.
- Determine the current through the capacitor bank
- Determine the capacitance value of the capacitor required.

Where could we start?

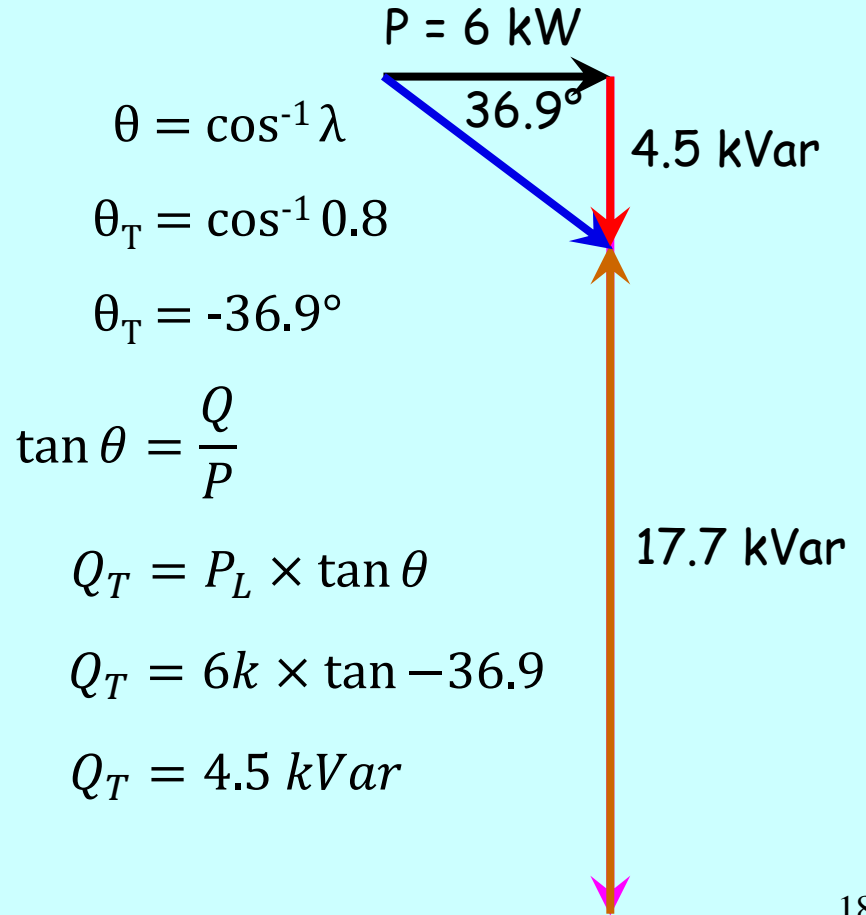
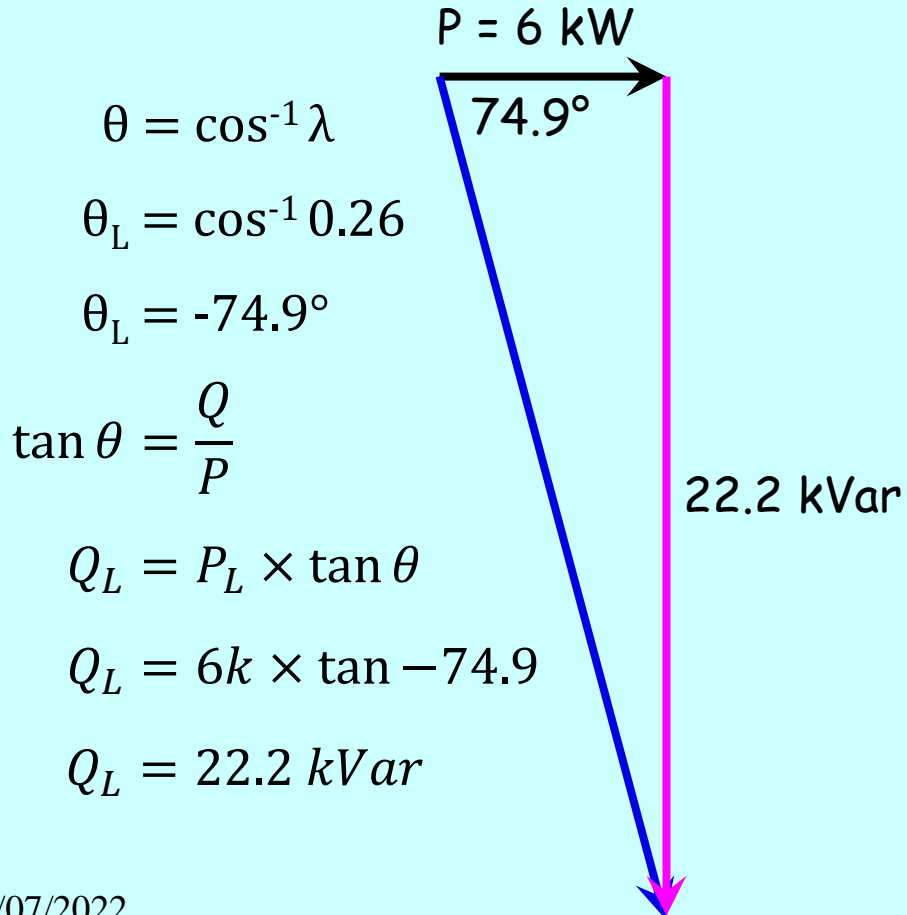


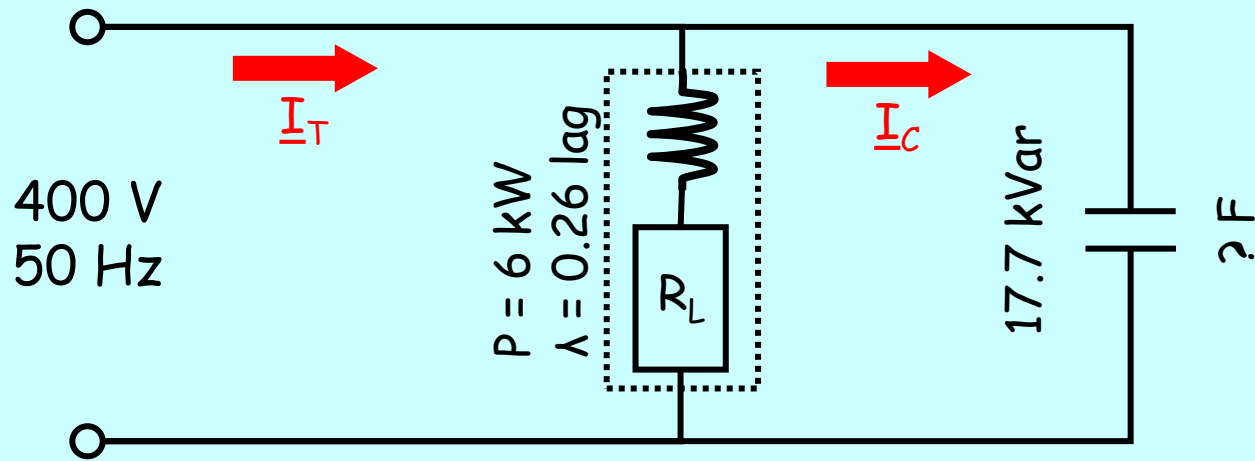


$$Q_C = Q_T - Q_L$$

$$Q_C = -4.5 + 22.2$$

$$Q_C = 17.7 \text{ kVar}$$





$$Q_C = V_C I_C \qquad X_C = \frac{V_C}{I_C} \qquad X_C = \frac{1}{2\pi f C}$$

$$I_C = \frac{Q_C}{V_C} \qquad X_C = \frac{400}{44.25} \qquad C = \frac{1}{2\pi f X_C}$$

$$I_C = \frac{17.7k}{400} \qquad X_C = 9 \Omega \qquad C = \frac{1}{2\pi \times 50 \times 9}$$

$$I_C = 44.25 \text{ A} \qquad C = 353.7 \mu\text{F}$$

## Tutorial pg. 52 Exercise 4

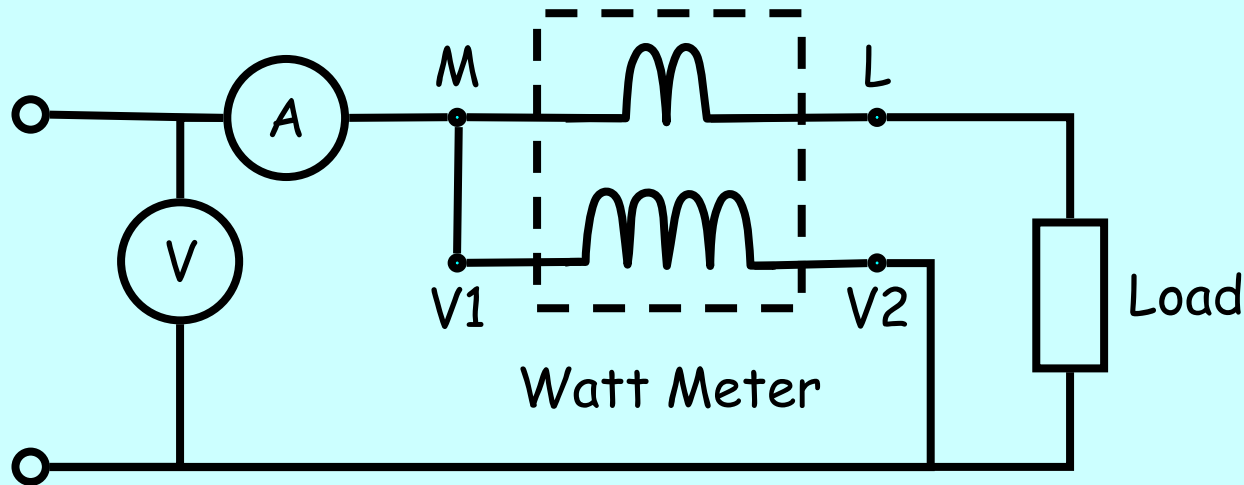
The following meter readings were taken on a single-phase circuit. Use these to determine the power factor and the phase angle of the circuit.

Voltmeter = 240V

Ammeter = 20A

Wattmeter = 4.2kW

What do we know?



## Tutorial pg. 52 Exercise 4

The following meter readings were taken on a single-phase circuit. Use these to determine the power factor and the phase angle of the circuit.

Voltmeter = 240V

Ammeter = 20A

Wattmeter = 4.2kW

What do we know?

$$V = 240 \text{ V}$$

$$I = 20 \text{ A}$$

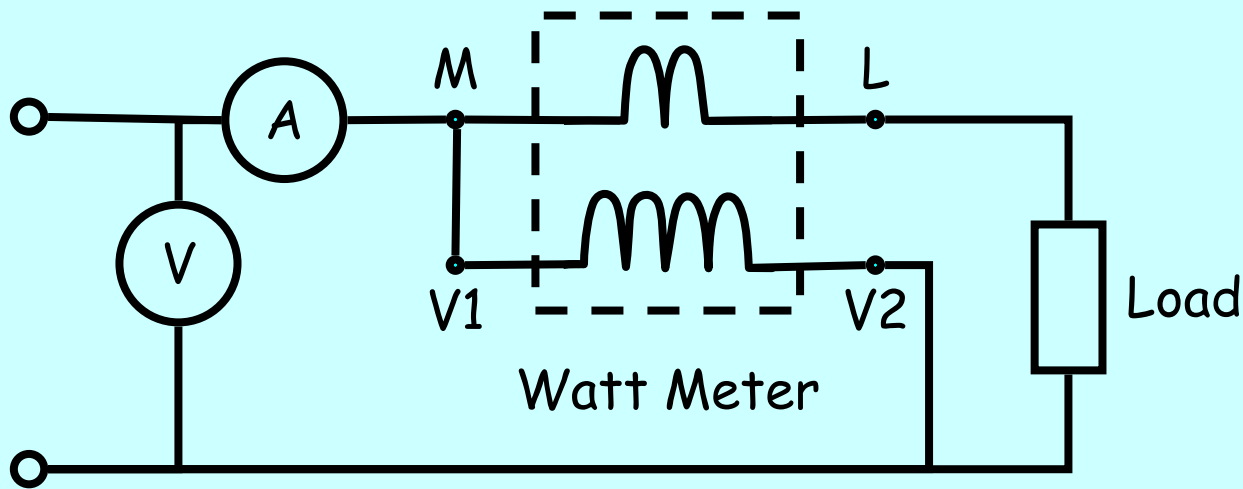
$$P = 4.2 \text{ kW}$$

What do we want to know?

$\lambda$  &  $\theta$

How can we calculate?

$$\lambda = \frac{P}{S} \quad \text{and} \quad \theta = \cos^{-1} \lambda$$



$$V = 240 \text{ V}$$

$$I = 20 \text{ A}$$

$$P = 4.2 \text{ kW}$$

### Apparent Power

$$S = VI$$

$$S = 240 \times 20$$

$$S = 4,800 \text{ VA}$$

### Power Factor

$$\lambda = \frac{P}{S}$$

$$\lambda = \frac{4.2k}{4.8k} = 0.875$$

### Phase Angle

$$\theta = \cos^{-1} \lambda$$

$$\theta = \cos^{-1} 0.875$$

$$\theta = 29.0^\circ$$

# **End of Lesson**

## **Practical Exercise**

### **Power Factor Improvement**

**UEENEEEG102A**  
**Solve problems in**  
**low voltage a.c. circuits**

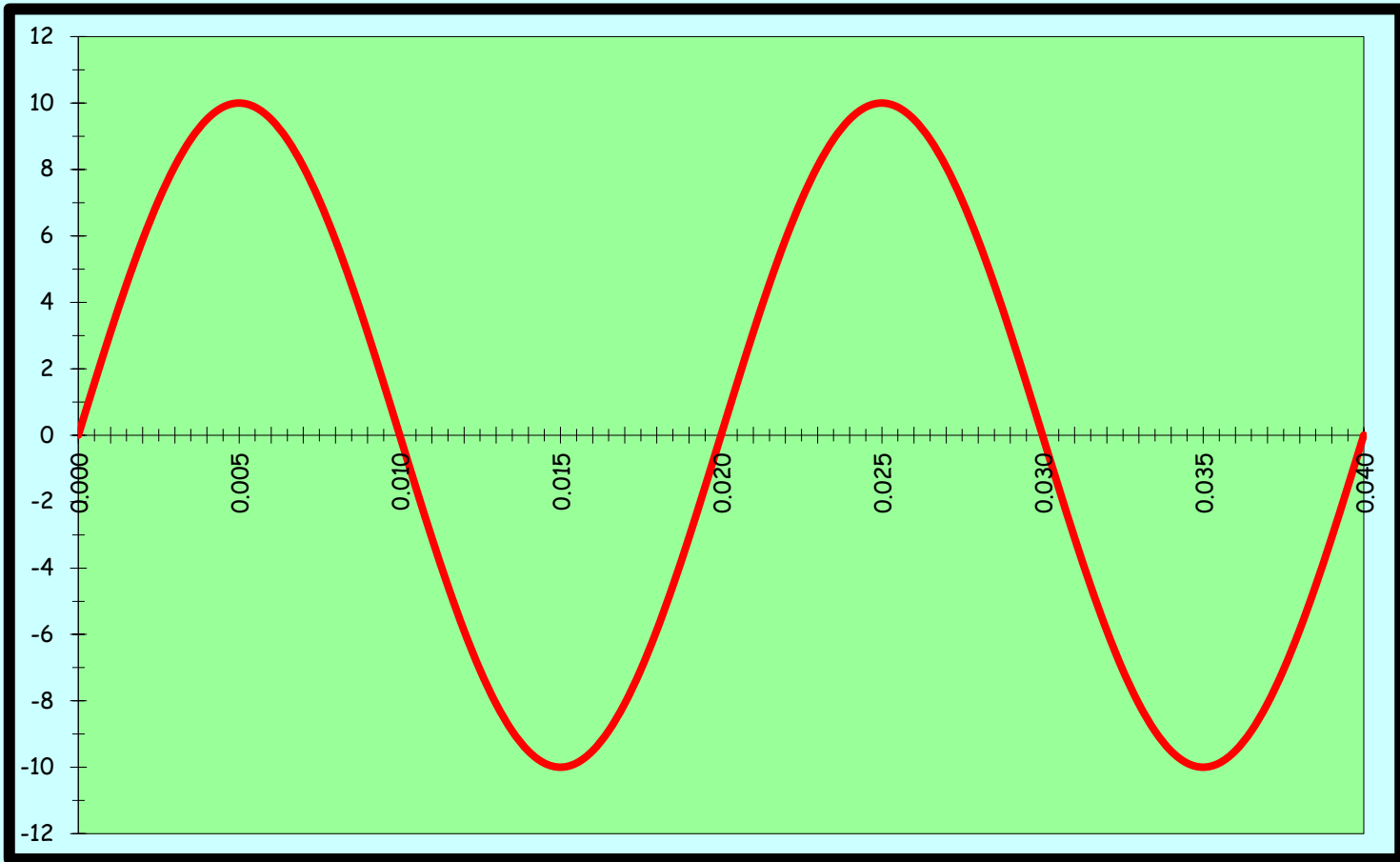
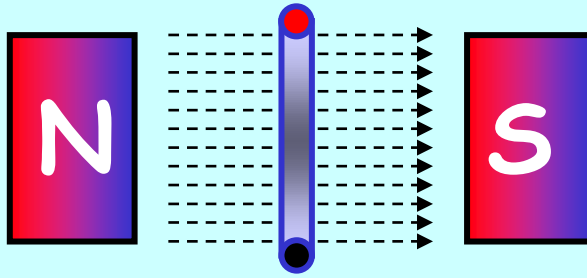
**Three Phase Systems**  
**& Harmonics**

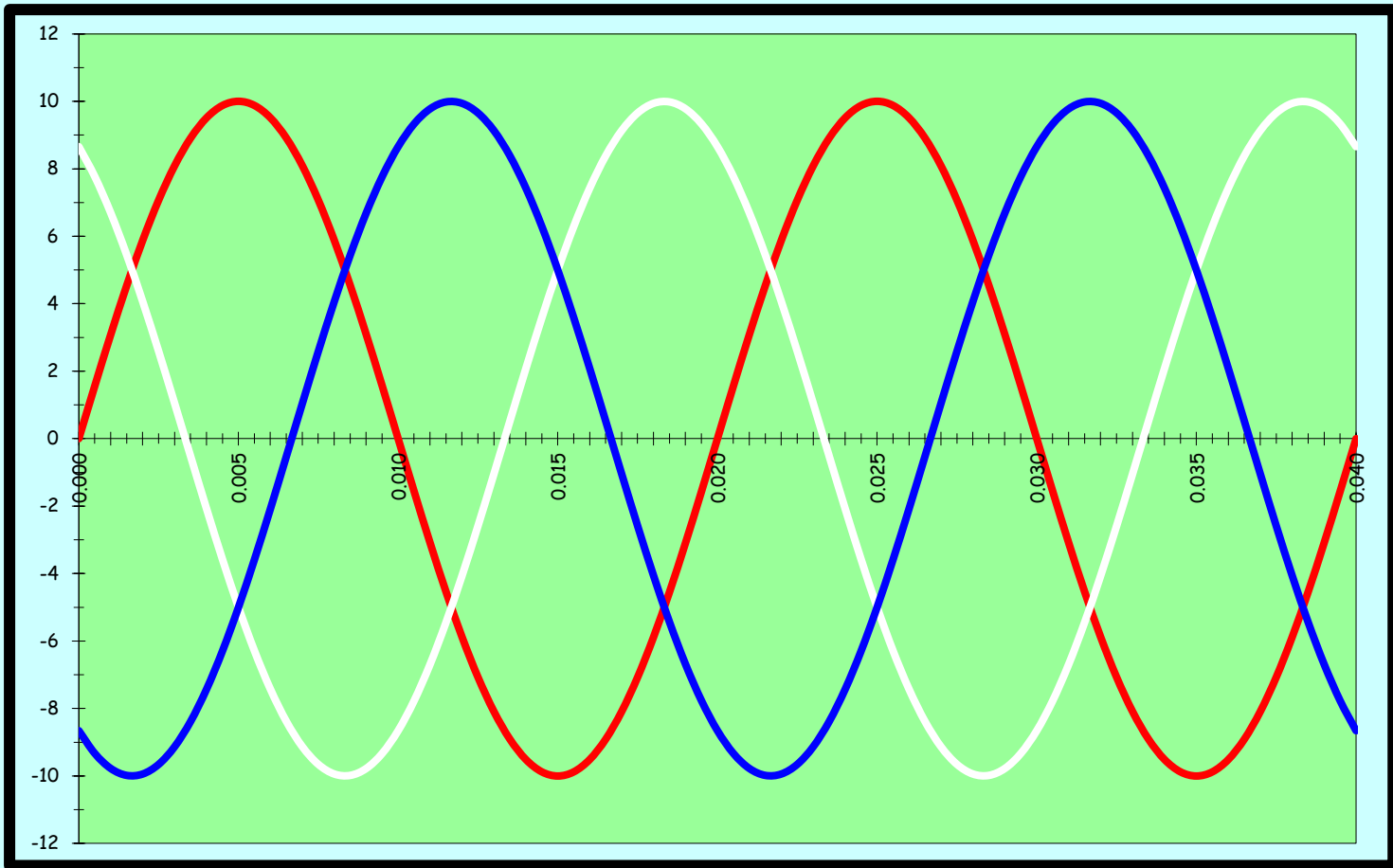
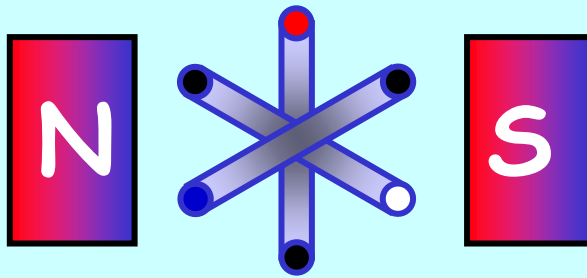


## Objectives:

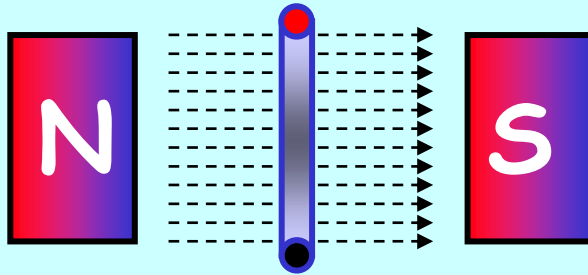
At the end of this lesson students should be able to:

1. Draw the voltage waveforms and Phasor diagram for a three phase system.
2. Briefly describe the principle of three phase generation.
3. State at least four advantages of three phase systems.
4. Determine the phase sequence of a three phase supply.

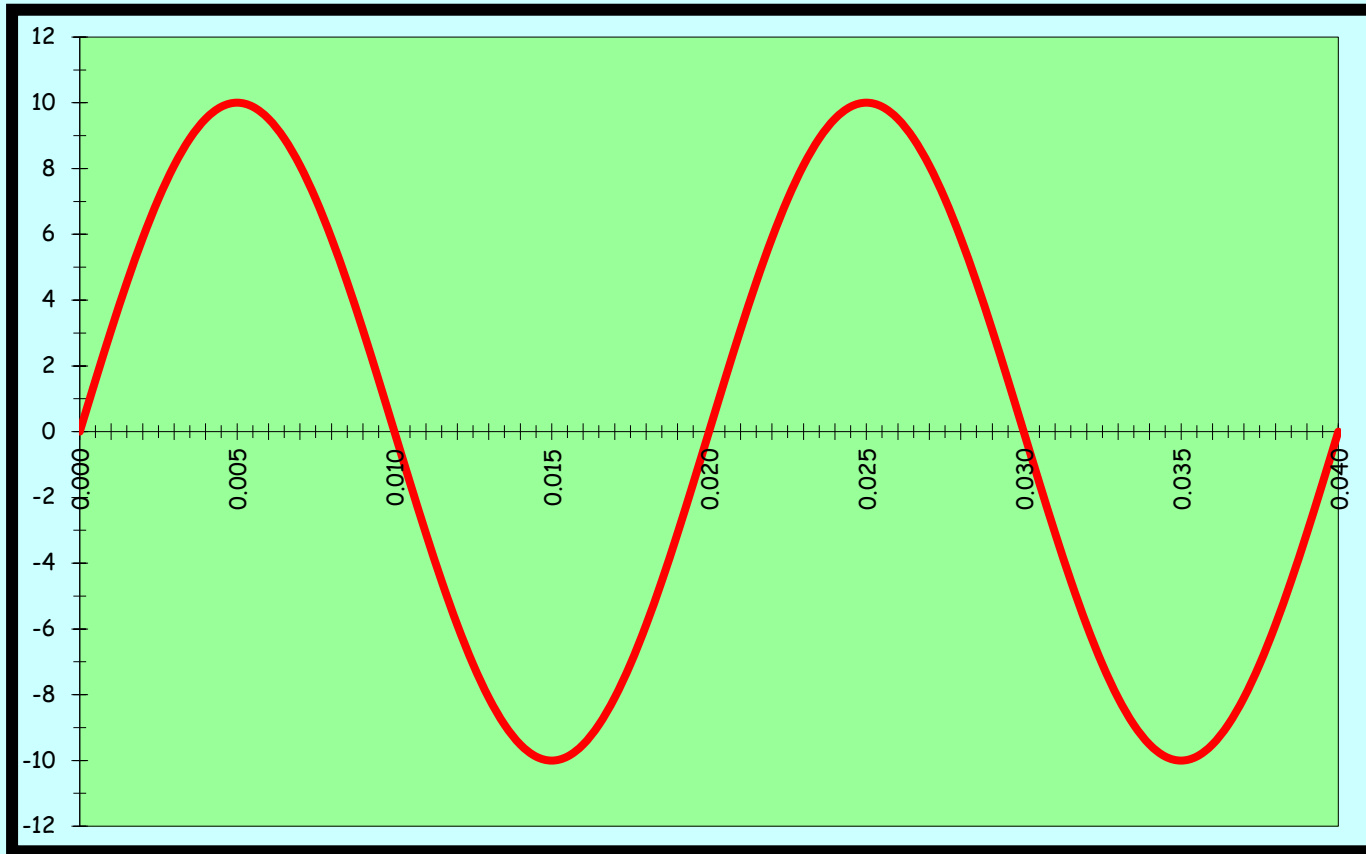




# Generation Principles



$$f = \frac{N}{60} \times \frac{P}{2} = \frac{NP}{120}$$



$$f = \frac{N}{60} \times \frac{P}{2} = \frac{NP}{120}$$

$$P = 2$$

$$N = 3,000 \text{ rpm}$$

$$f = \frac{2 \times 3000}{120}$$

$$f = 50 \text{ hz}$$

$$P = 6$$

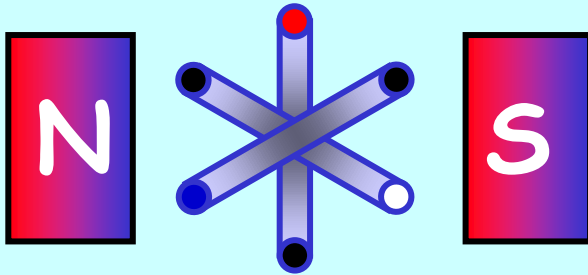
$$f = 50 \text{ Hz}$$

$$N = \frac{120f}{P}$$

$$N = \frac{120 \times 50}{6}$$

$$N = 1,000 \text{ rpm}$$

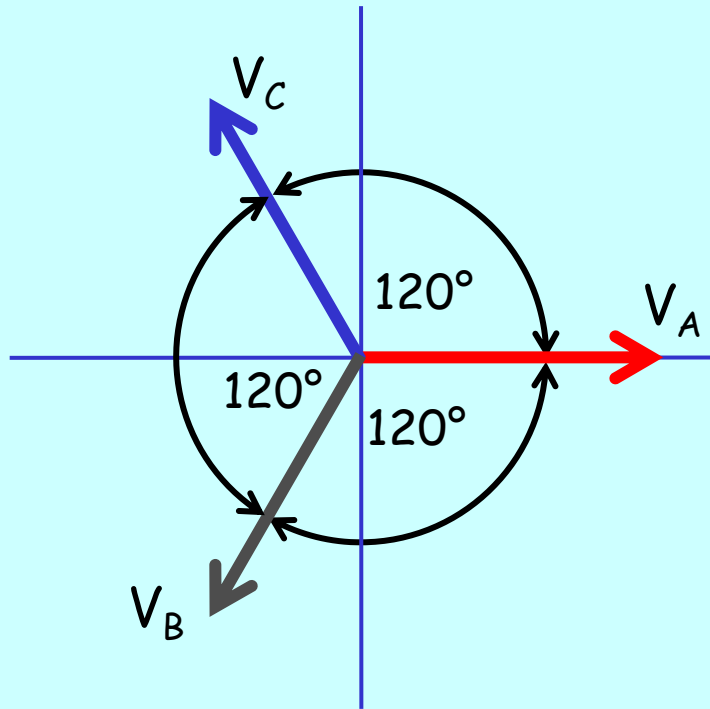
# Three Phase Phasors



$$V_A = V_M \sin \theta$$

$$V_B = V_M \sin (\theta - 120)$$

$$V_C = V_M \sin (\theta + 120)$$



## Advantages

- \* More Available Power
- \* Smoother Power delivery
- \* Varying Voltages  
Phase to Phase (400) and  
Phase to Neutral (230)
- \* Lower Current per phase
- \* Smaller Conductors

Find the line voltages of a three phase ac system at  $\theta = 60^\circ$  if the maximum voltage in the system is 110 V.

What do we know?

$$V_M = 110 \text{ V}$$

$$\theta = 60^\circ$$

What do we want to know?

$$V_A = V_M \sin \theta$$

$$V_A = V_M \sin 60^\circ$$

$$V_A = 95.3 \text{ V}$$

$$V_B = V_M \sin (\theta - 120)$$

$$V_B = V_M \sin (60 - 120)$$

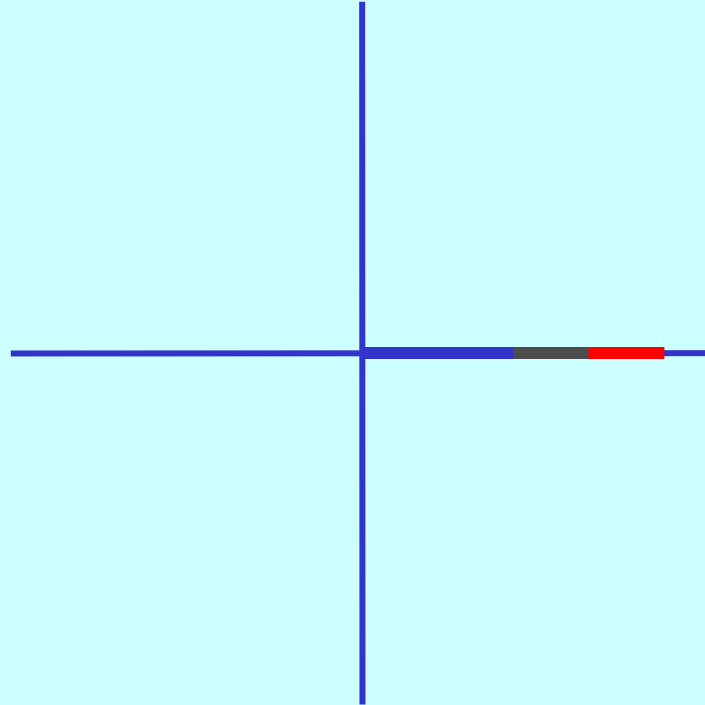
$$V_B = -95.3 \text{ V}$$

$$V_C = V_M \sin (\theta - 240)$$

$$V_C = V_M \sin (60 - 240)$$

$$V_C = 0 \text{ V}$$

# Harmonics





# Objectives:

At the end of this lesson students should be able to:

1. Define what a Harmonic Waveform is.
2. Define the term selective resonance.
3. List the types and classifications of harmonic waveforms.
4. Explain the effects of harmonics.
5. Describe how harmonics are generated, produced, found and reduced.

# Harmonics are whole number multiples of a Fundamental Frequency (1<sup>st</sup> Harmonic)

Eg. Fundamental frequency = 50 Hz

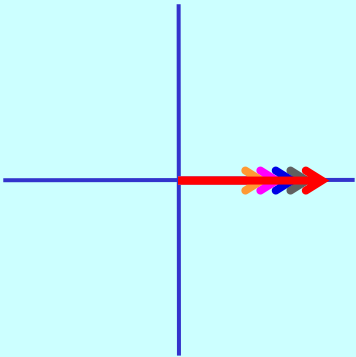
$$1^{\text{st}} \text{ Harmonic} = (50 \times 1) = 50 \text{ Hz}$$

$$2^{\text{nd}} \text{ Harmonic} = (50 \times 2) = 100 \text{ Hz}$$

$$3^{\text{rd}} \text{ Harmonic} = (50 \times 3) = 150 \text{ Hz}$$

$$4^{\text{th}} \text{ Harmonic} = (50 \times 4) = 200 \text{ Hz}$$

$$5^{\text{th}} \text{ Harmonic} = (50 \times 5) = 250 \text{ Hz}$$



# Harmonics are whole number multiples of a Fundamental Frequency (1<sup>st</sup> Harmonic)

Eg. Fundamental frequency = 50 Hz

$$\text{1st Harmonic} = (50 \times 1) = 50 \text{ Hz}$$

$$\text{2nd Harmonic} = (50 \times 2) = 100 \text{ Hz}$$

$$\text{3rd Harmonic} = (50 \times 3) = 150 \text{ Hz}$$

$$\text{4th Harmonic} = (50 \times 4) = 200 \text{ Hz}$$

$$\text{5th Harmonic} = (50 \times 5) = 250 \text{ Hz}$$

**ODD Harmonics = Fundamental frequency x ODD Number**

# Harmonics are whole number multiples of a Fundamental Frequency (1<sup>st</sup> Harmonic)

Eg. Fundamental frequency = 50 Hz

$$1\text{st Harmonic} = (50 \times 1) = 50 \text{ Hz}$$

$$2\text{nd Harmonic} = (50 \times 2) = 100 \text{ Hz}$$

$$3\text{rd Harmonic} = (50 \times 3) = 150 \text{ Hz}$$

$$4\text{th Harmonic} = (50 \times 4) = 200 \text{ Hz}$$

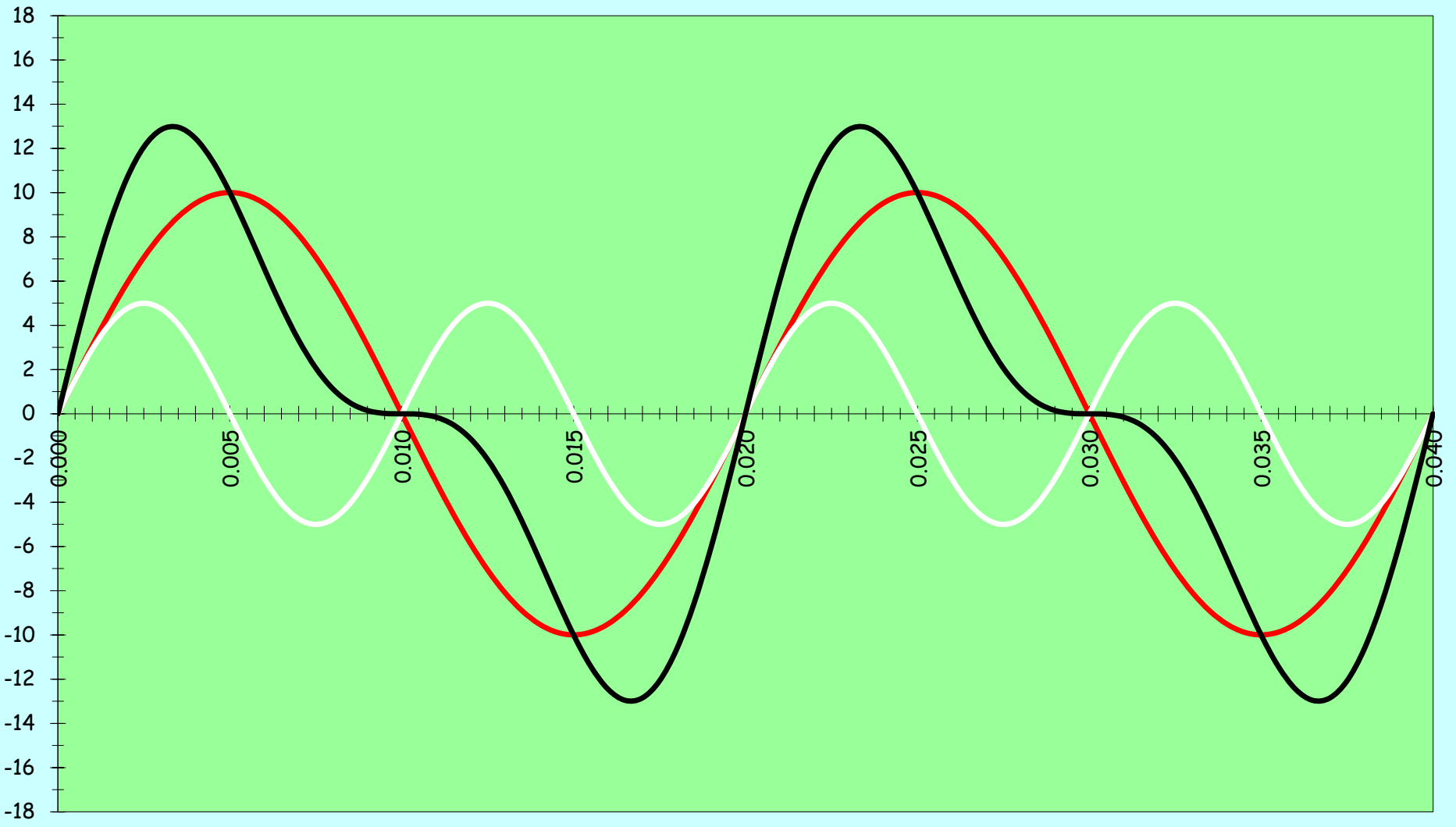
$$5\text{th Harmonic} = (50 \times 5) = 250 \text{ Hz}$$

ODD Harmonics = Fundamental frequency  $\times$  ODD Number

EVEN Harmonics = Fundamental frequency  $\times$  EVEN Number

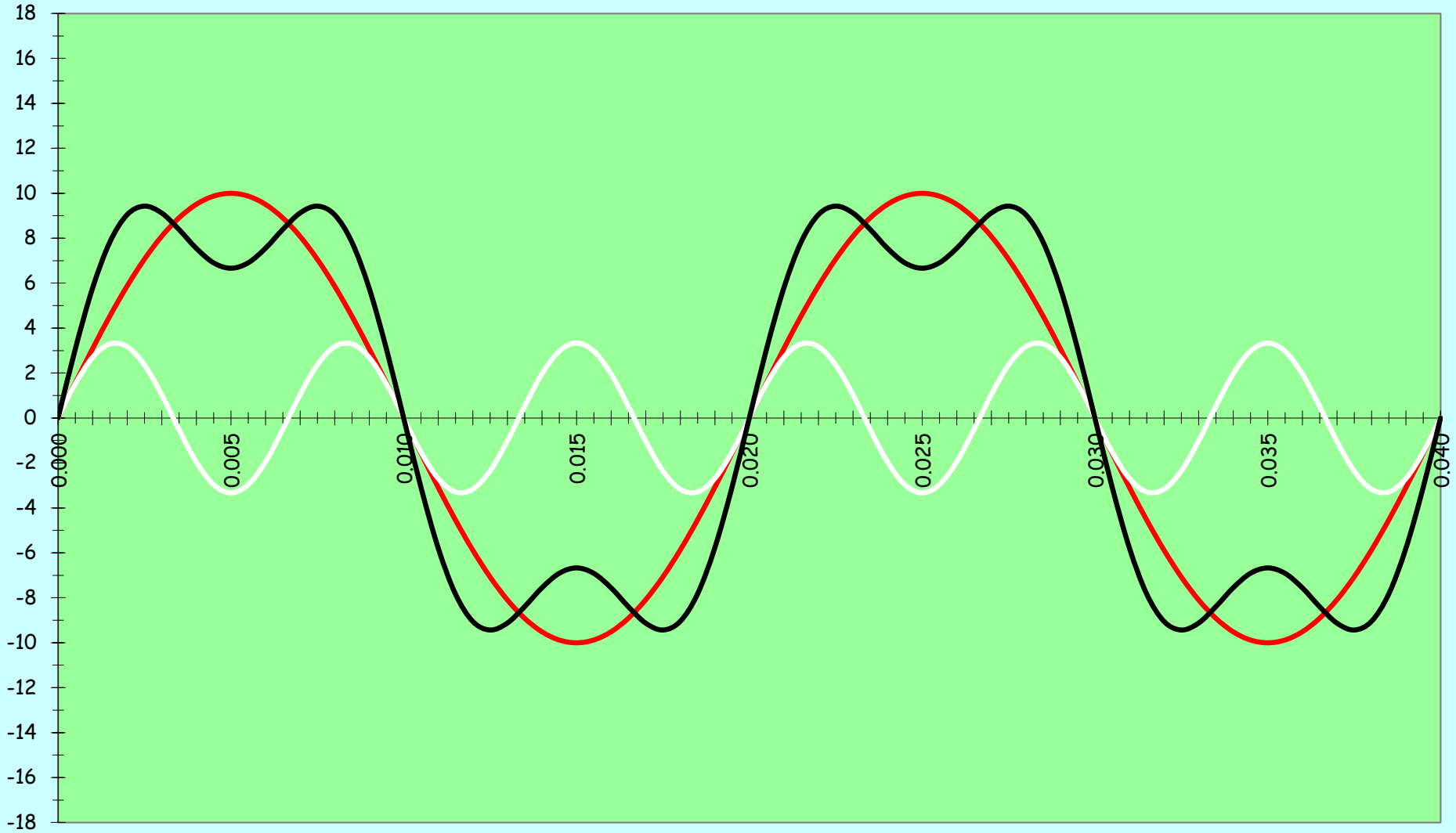
$$10(\sin\{360ft\} + 0.5\sin\{720ft\})$$

H1 + H2

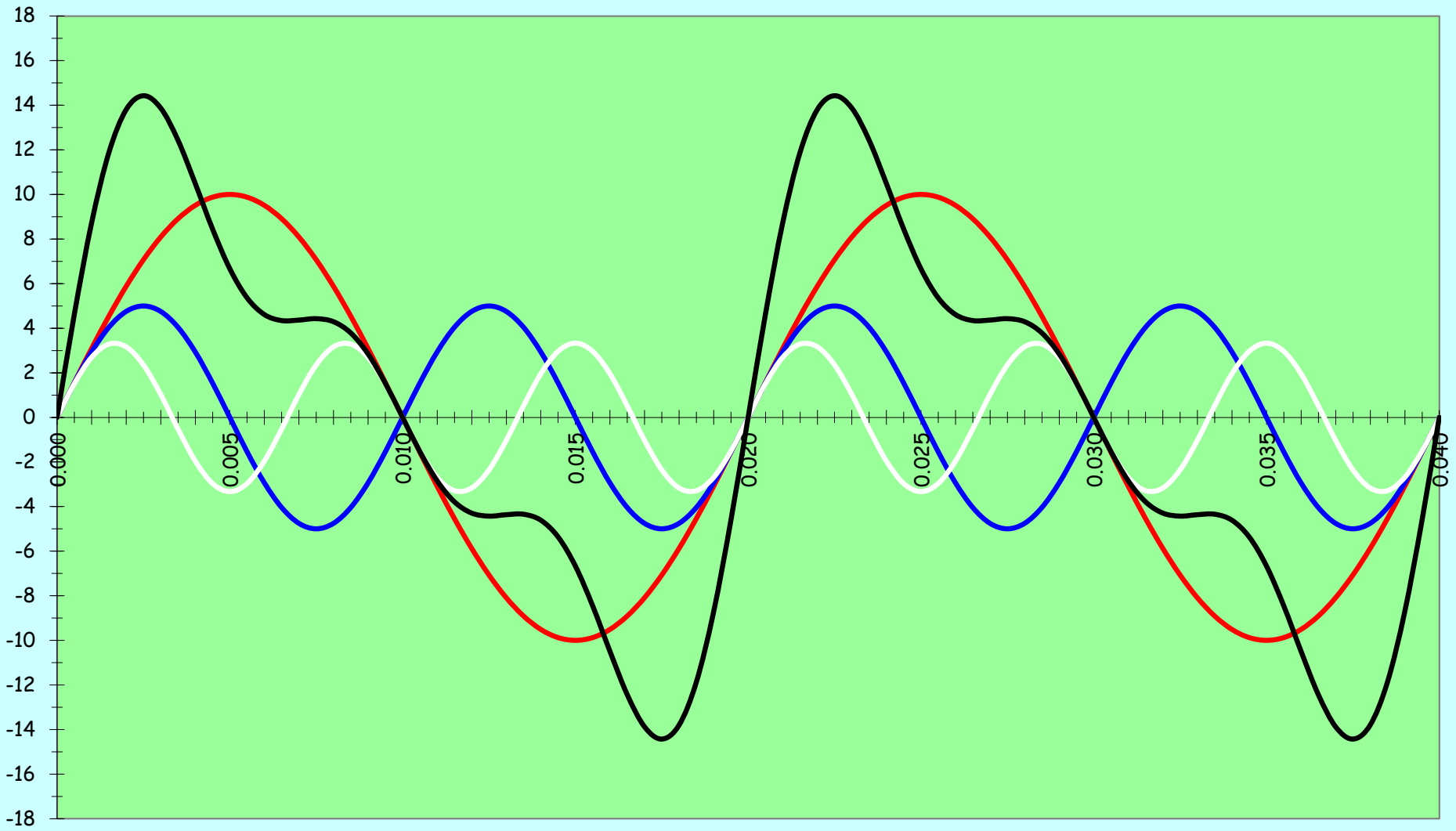


$$10(\sin(360ft) + 0.3\sin(1080ft))$$

H1 + H3



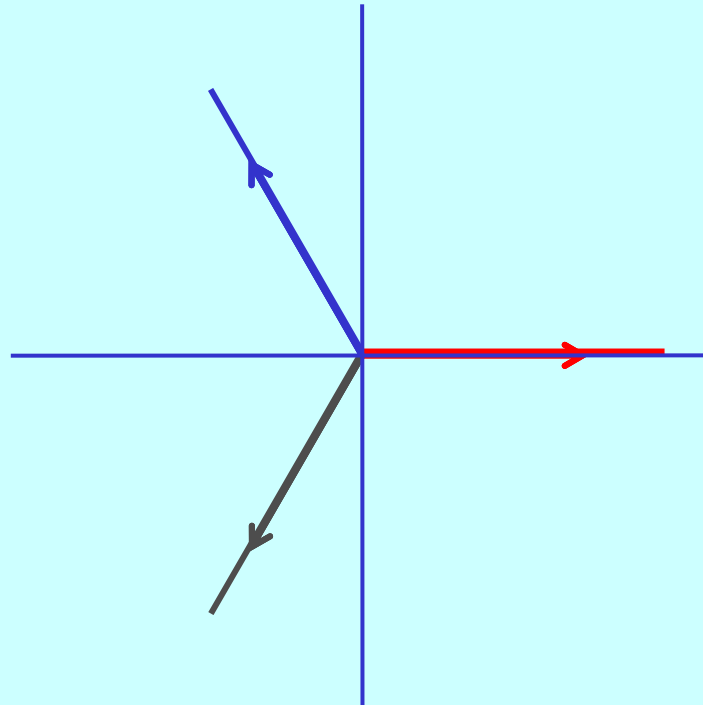
H1 + H2 + H3



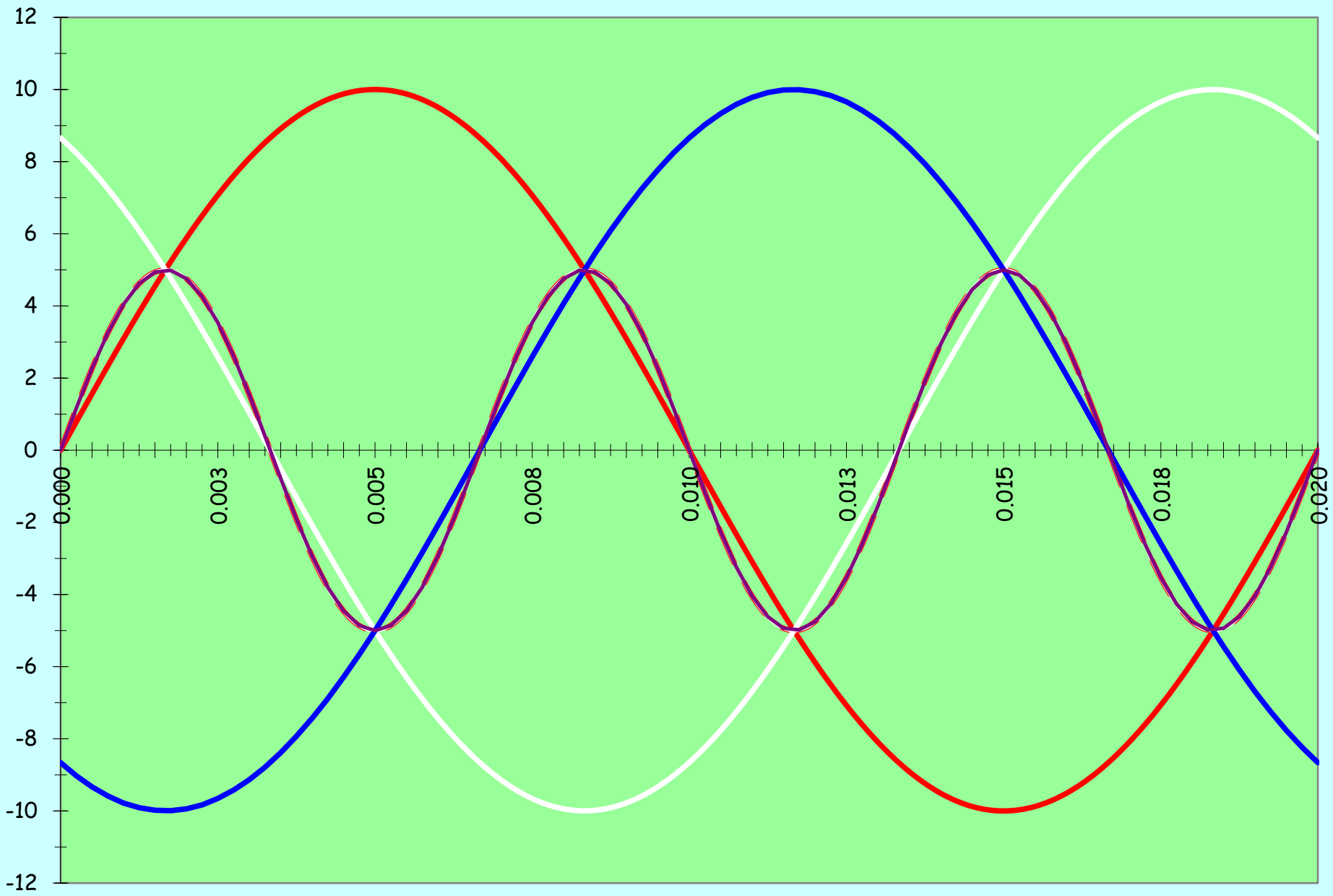
Harmonics which "rotate" with the same sequence as the fundamental are called *positive sequence*, eg. 7<sup>th</sup> Harmonic.

Harmonics which "rotate" in the opposite sequence to the fundamental are called *negative sequence*, eg. 5<sup>th</sup> Harmonic.

Harmonics which don't "rotate" at all because they're in phase with each other are called *zero sequence*, Eg. 3<sup>rd</sup> Harmonic.







# Effects for Harmonics

Sequence	Effects on a Motor	Effects on a Distribution System
Positive	Forward rotating magnetic field  Assists Torque	Heating
Negative	Reverse rotating magnetic field  Reduces Torque	Heating and Motor Problems
Zero	Little or None	Heating and Excessive Neutral Currents

# Testing for Harmonics

## Display the waveform

Use a CRO to look at the shape of the waveform.

## Measure the frequency components

Use a Spectrum Analyser to look at the frequency components of the waveform.

## Measure the current components

Use a True RMS or Average Responding Ammeter to measure the currents.

## Other Indicators

Abnormally Hot Transformers and other components

Abnormal vibrations

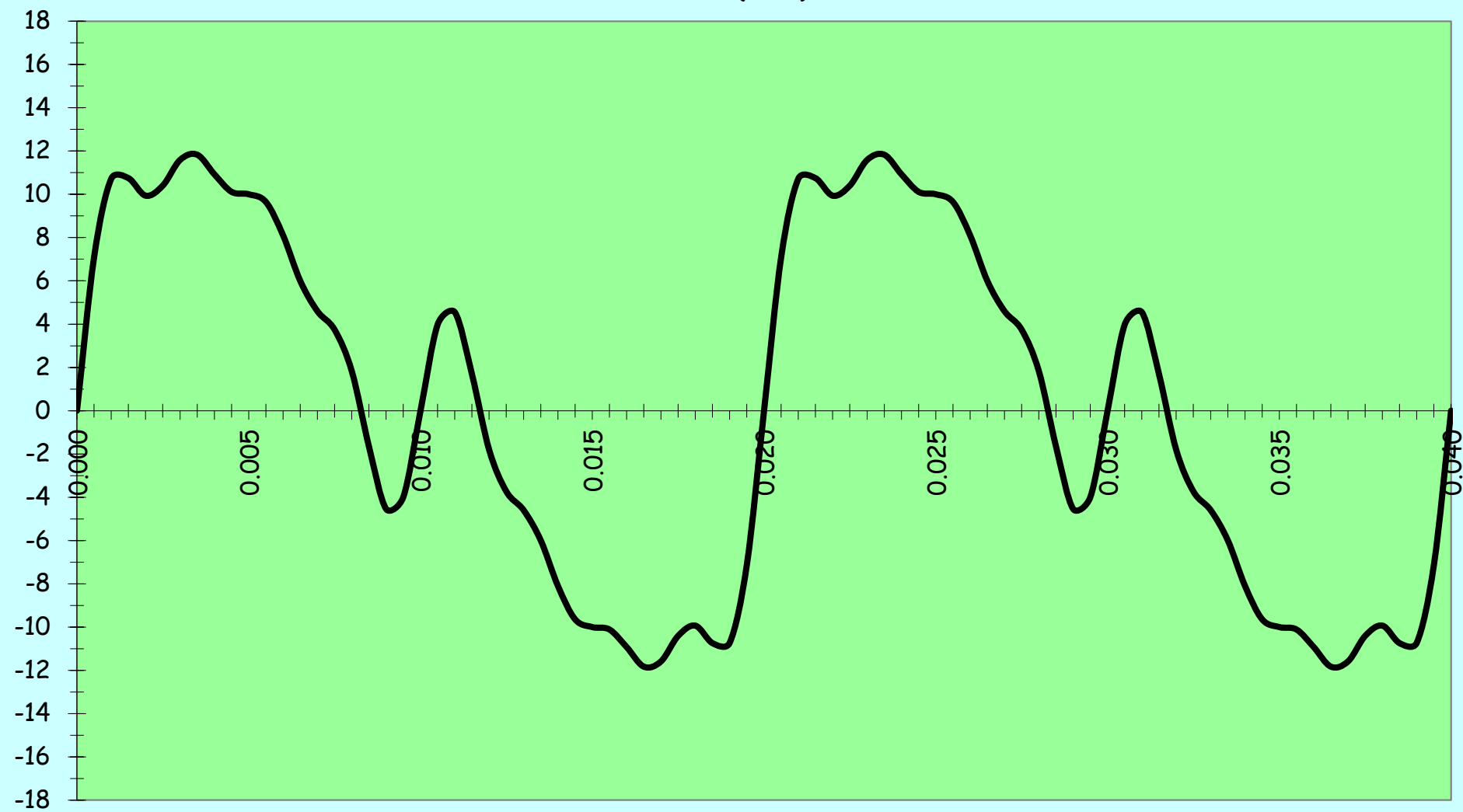
Erratic motor behaviour

## Methods of overcoming Harmonic effects

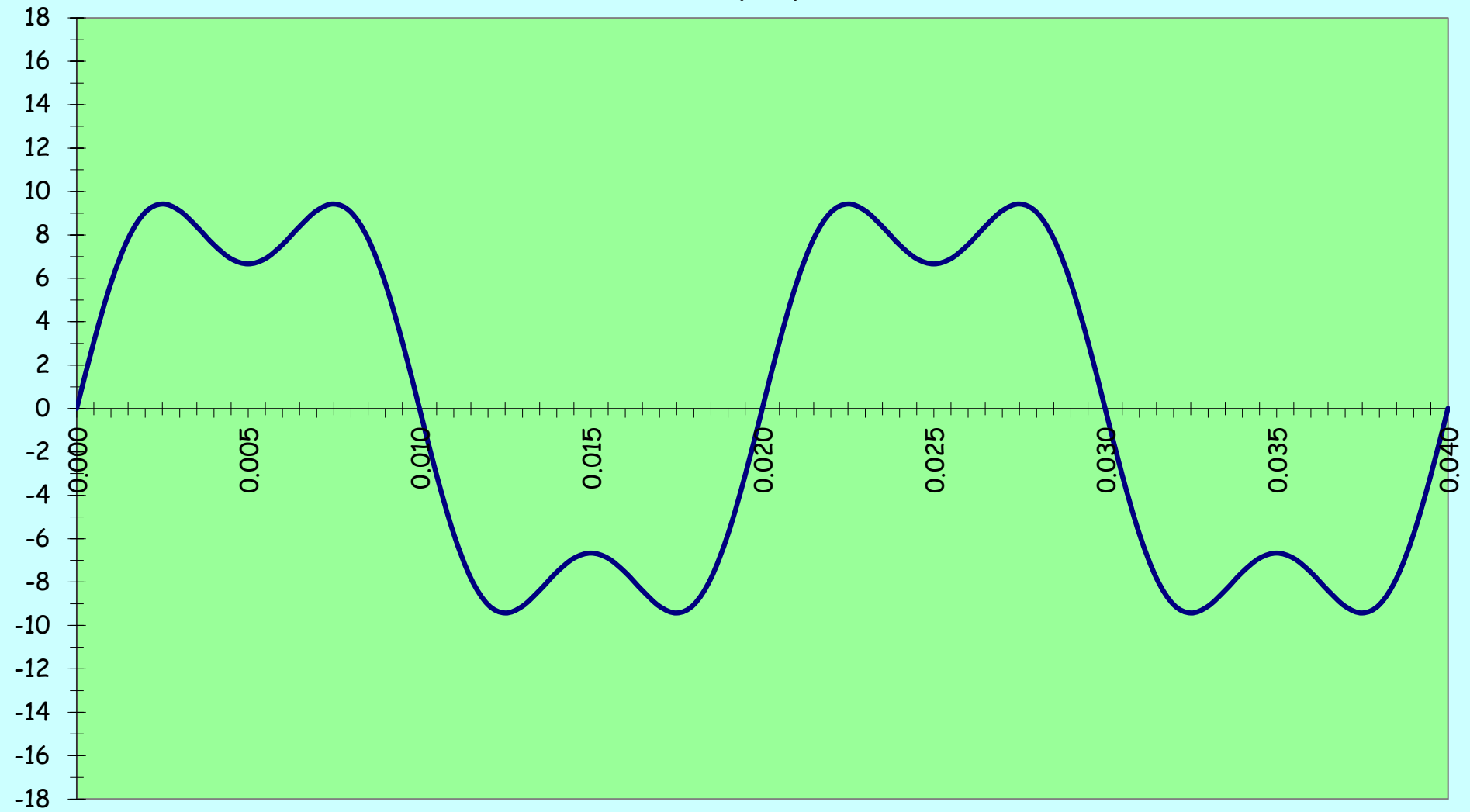
Good design practices

Filters

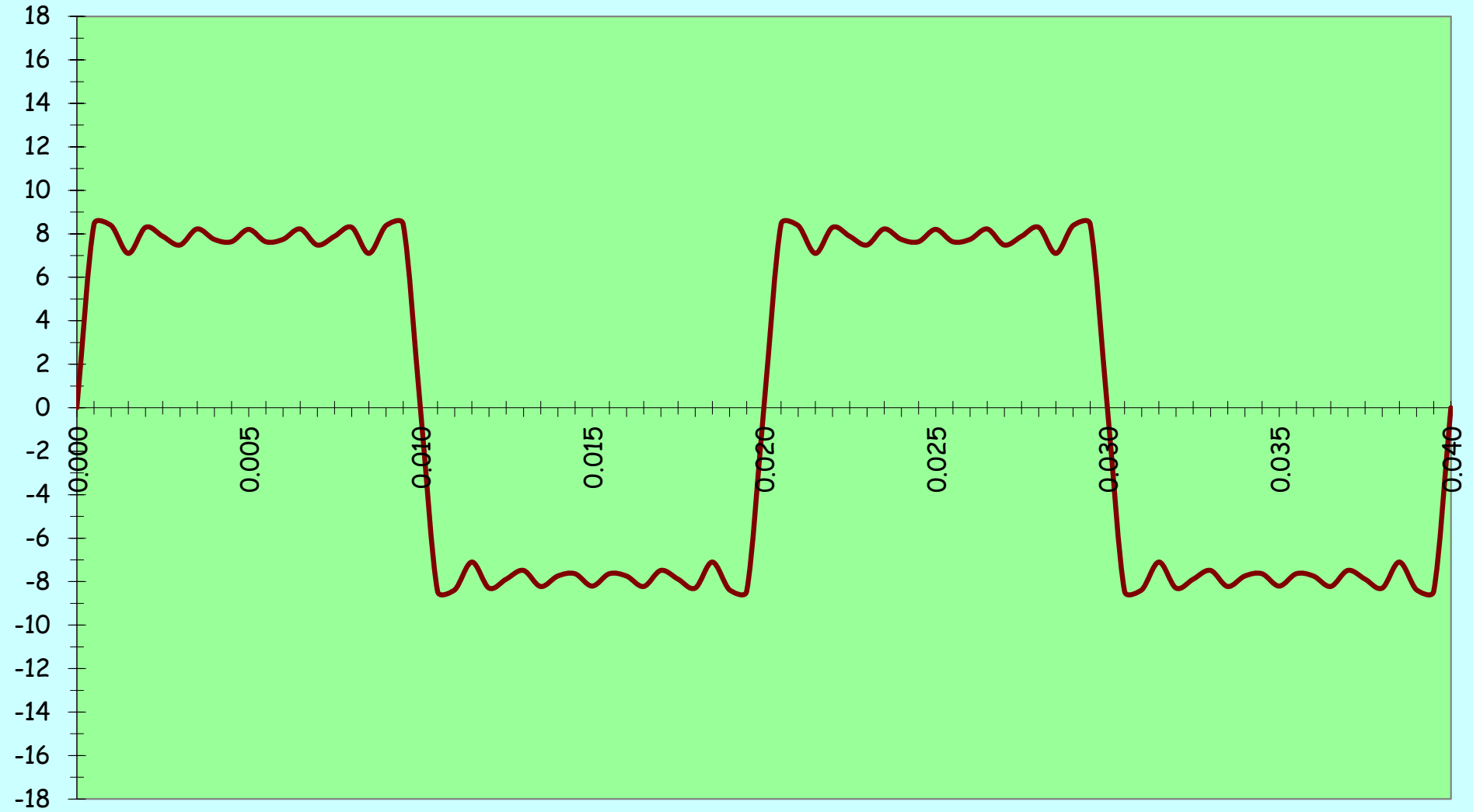
H1 + H2 + H4 + H6 + H8  
Sum(Even)



H1 + H3  
Sum(Odd)



H1 + H3 + H5 + H7 + H9 + H11 + H13  
Sum(Odd)



# End of Lesson

## Practical Exercises

### Three Phase Waveforms

**UEENEEEG102A**

**Solve problems in  
low voltage a.c. circuits**

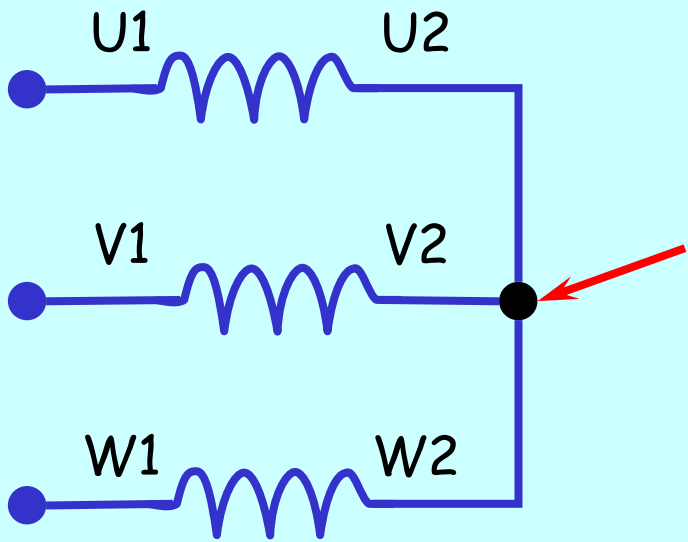
**Three Phase  
Four Wire Systems**



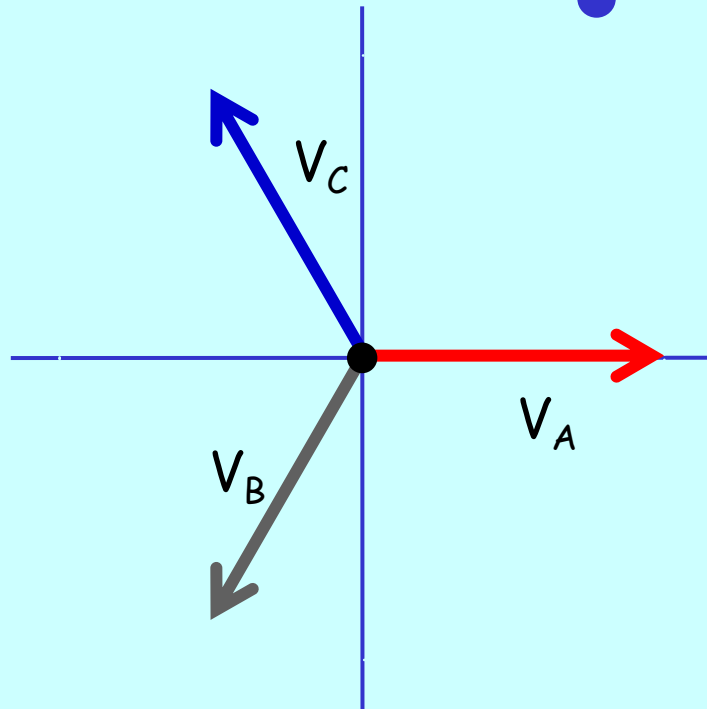
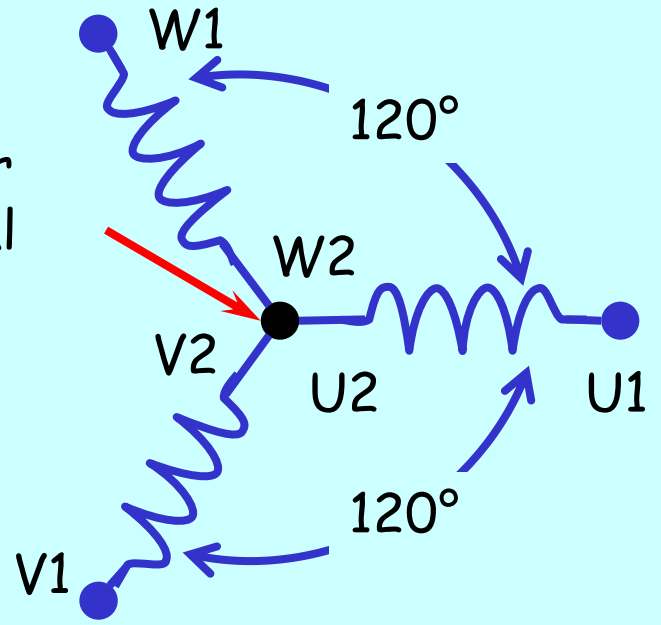
# Objectives:

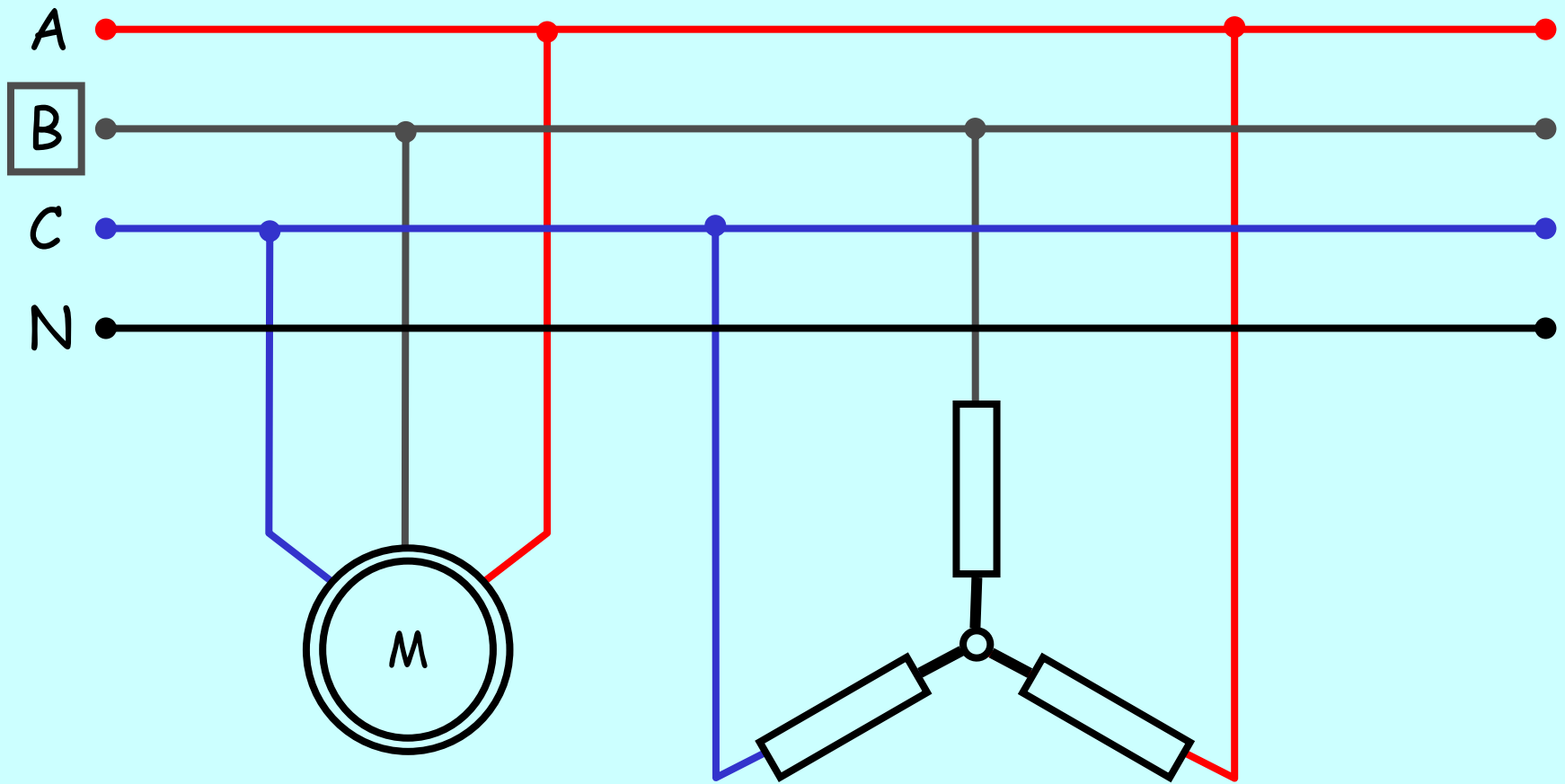
At the end of this lesson students should be able to:

1. Draw the circuit connections for a Star Connected System.
2. Calculate Line & Phase Voltages and Currents for a three phase star connected system.
3. Develop Phasor Diagrams for a star connected system.
4. Connect a load in star.



Star or  
Neutral  
Point



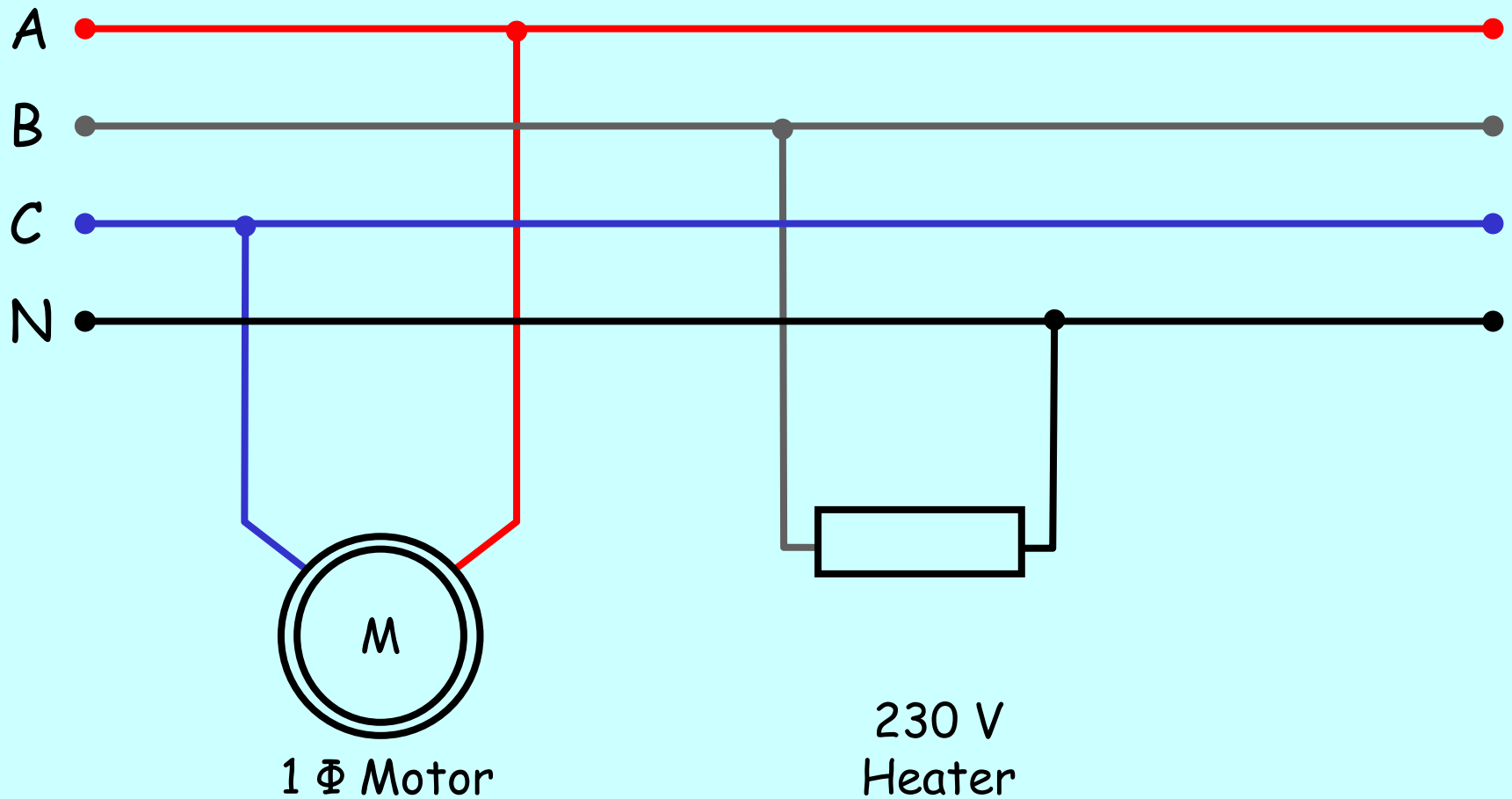


3  $\Phi$  Motor

3  $\Phi$  Heater

3  $\Phi$  Balanced Loads

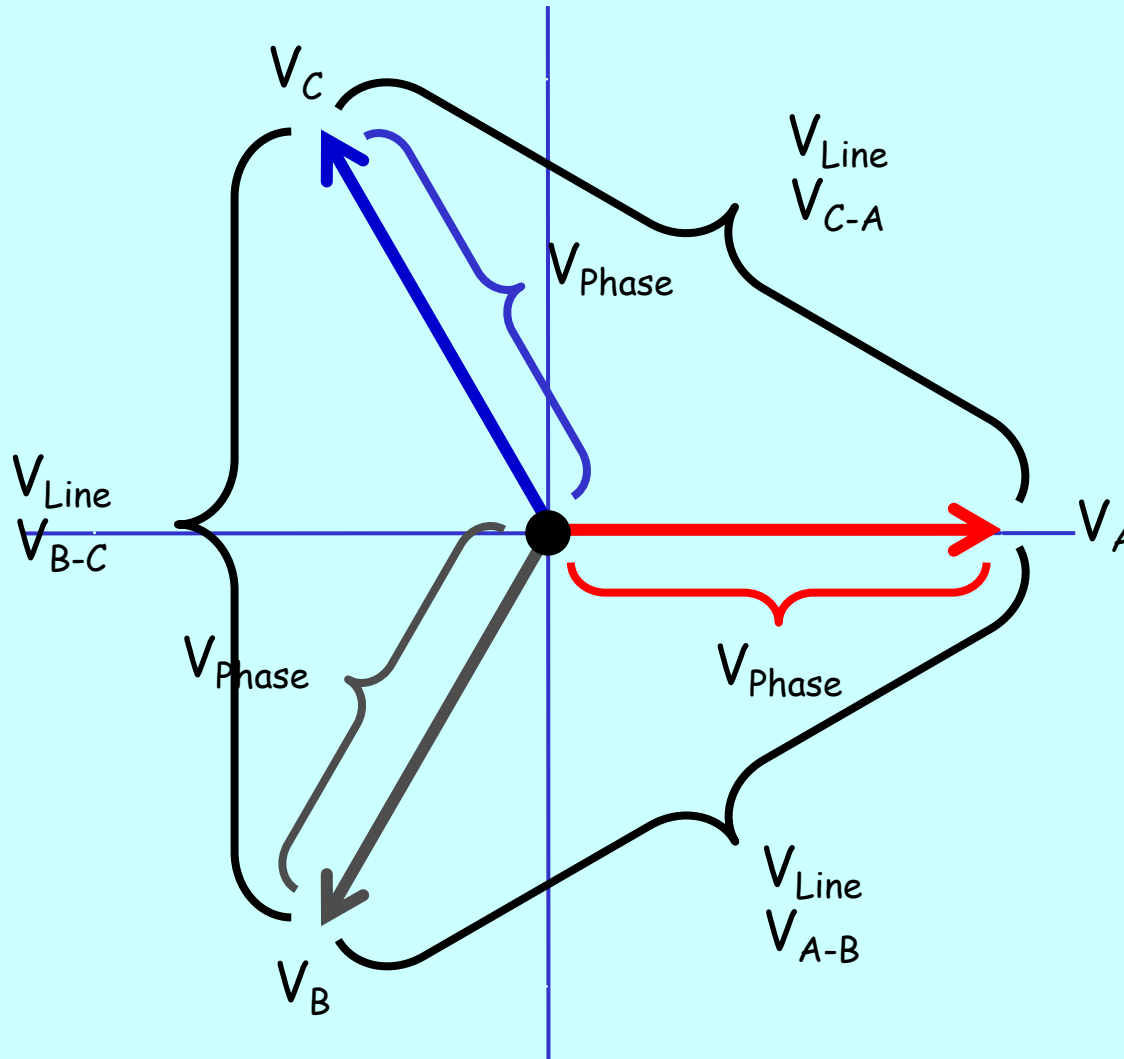
3  $\Phi$  Unbalanced Loads

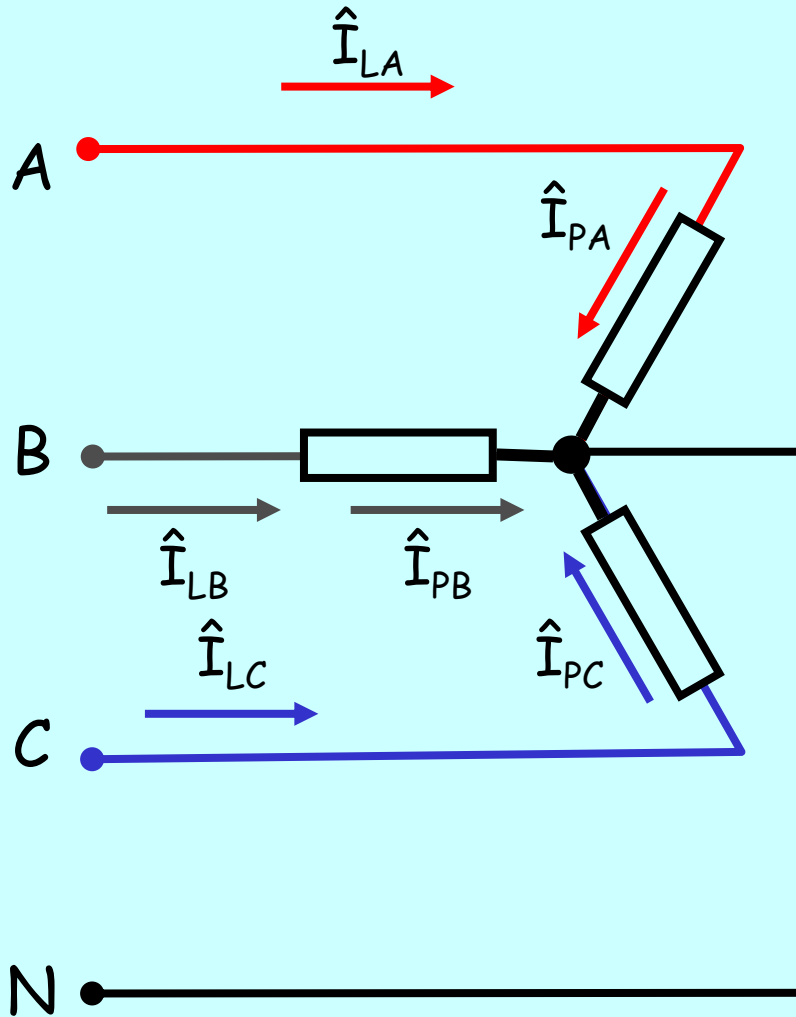


Single  $\Phi$  Loads  
Always Unbalanced

but we try to share the load evenly between phases

# Phase & Line Voltages

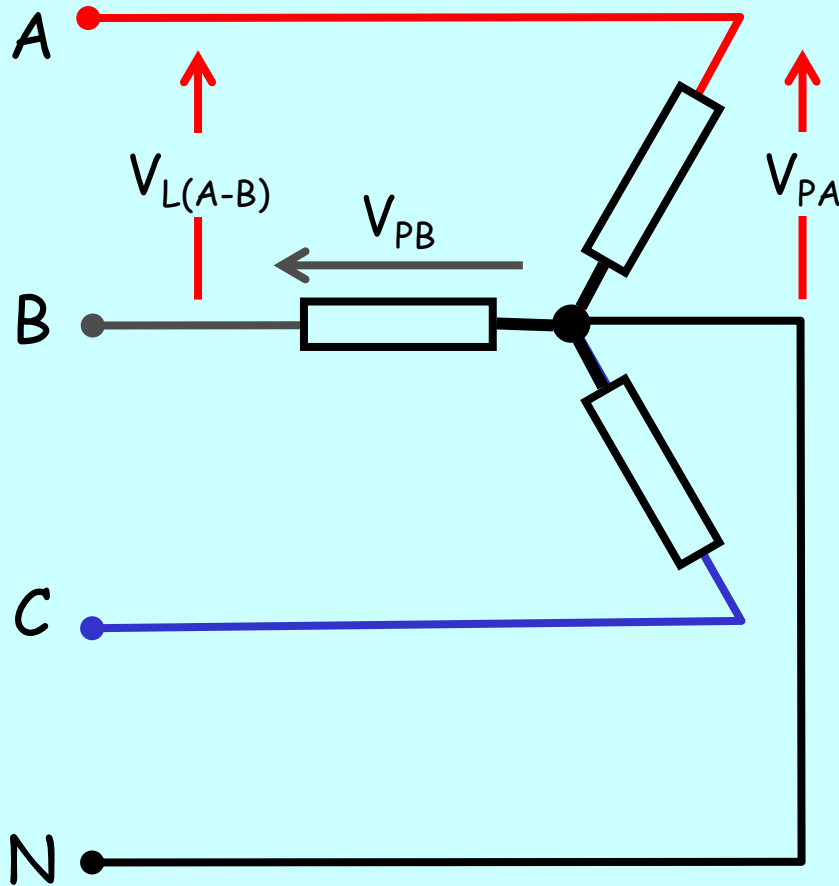




## Voltage & Current Relationships

Line Current      Phase Current

$$\hat{I}_L = \hat{I}_P$$



## Voltage & Current Relationships

Line Current	Phase Current
-----------------	------------------

$$\hat{I}_L = \hat{I}_P$$

Line Voltage	Difference of two Phase Voltages
-----------------	-------------------------------------

$$\underline{V}_L = \underline{V}_{PA} - \underline{V}_{PB}$$

# Phase Voltages

$$\underline{V}_A = V_M \sin \theta$$

$$\underline{V}_B = V_M \sin (\theta - 120)$$

# Line Voltage

$$\underline{V}_{AB} = \underline{V}_A - \underline{V}_B$$

$$V_{AB}^2 = V_A^2 + V_B^2 - 2V_A V_B \cos(120)$$

$$V_{AB}^2 = 2(1 - \cos(120))$$

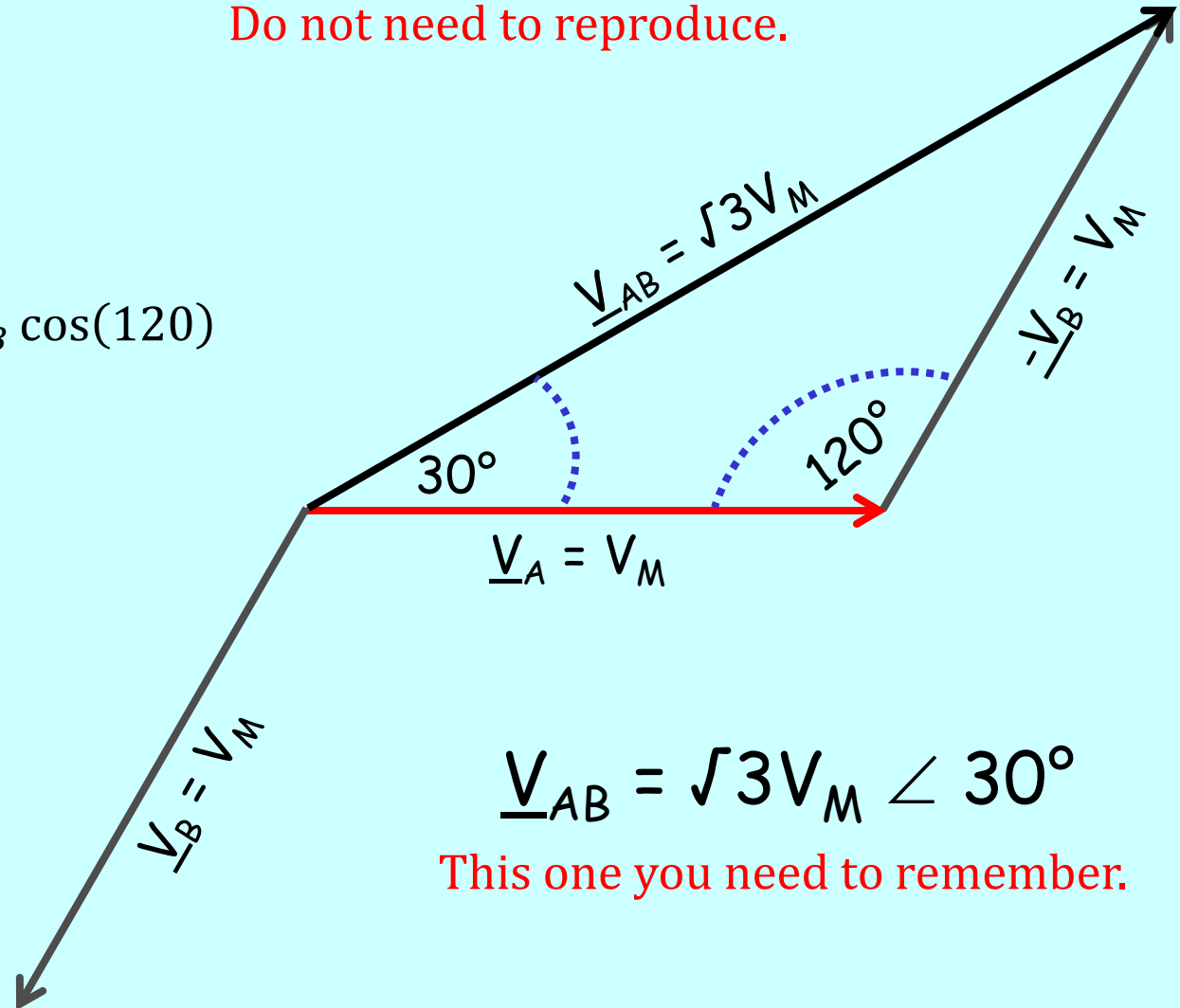
$$V_{AB}^2 = 3$$

## Cosine Rule

$$a^2 = b^2 + c^2 - 2bc \cos \theta$$

For proof only!!!

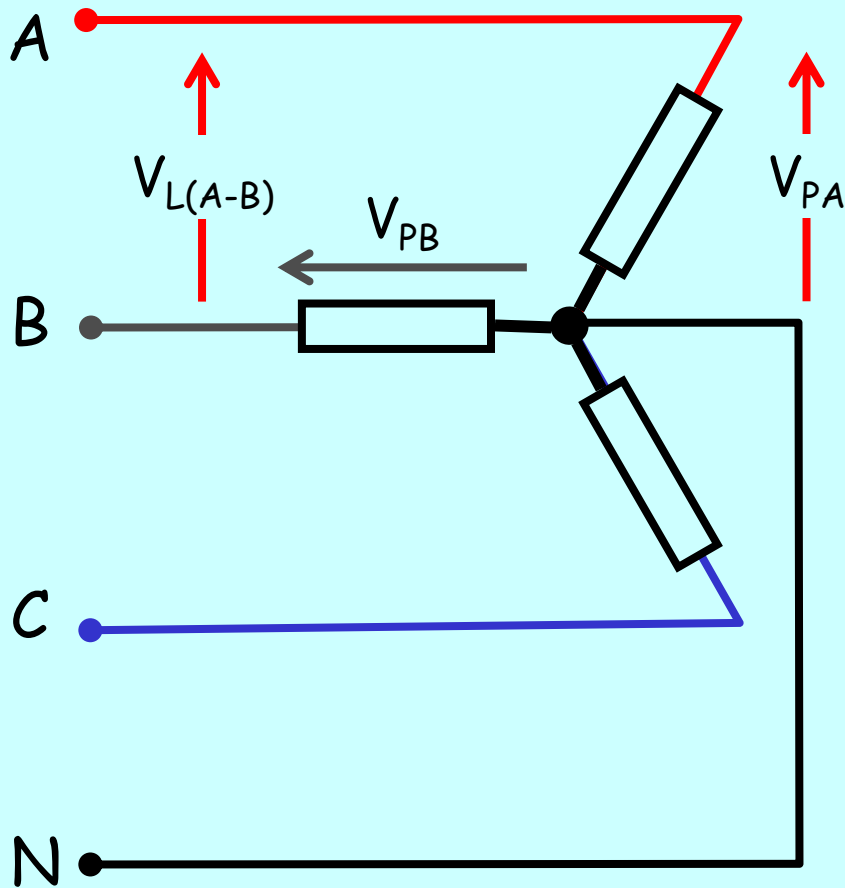
Do not need to reproduce.



$$\underline{V}_{AB} = \sqrt{3}V_M \angle 30^\circ$$

This one you need to remember.





## Voltage & Current Relationships

Line Current	Phase Current
-----------------	------------------

$$\hat{I}_L = \hat{I}_P$$

Line Voltage	Difference of two Phase Voltages
-----------------	-------------------------------------

$$\underline{V}_L = \underline{V}_{PA} - \underline{V}_{PB}$$

$$|V_L| = \sqrt{3} |V_P|$$

A Star connected alternator produces 6.35 kV in each phase winding.  
What is the Line Voltage?

What do we know?

$$V_p = 6.35 \text{ kV}$$

What do we want to know?

$$V_L = \sqrt{3} \times V_p$$

$$V_L = \sqrt{3} \times 6.35 \text{ kV}$$

$$V_L = 11 \text{ kV}$$

A Star connected transformer has a line voltage of 400 V.  
What is the Phase Voltage?

What do we know?

$$V_L = 400 \text{ V}$$

What do we want to know?

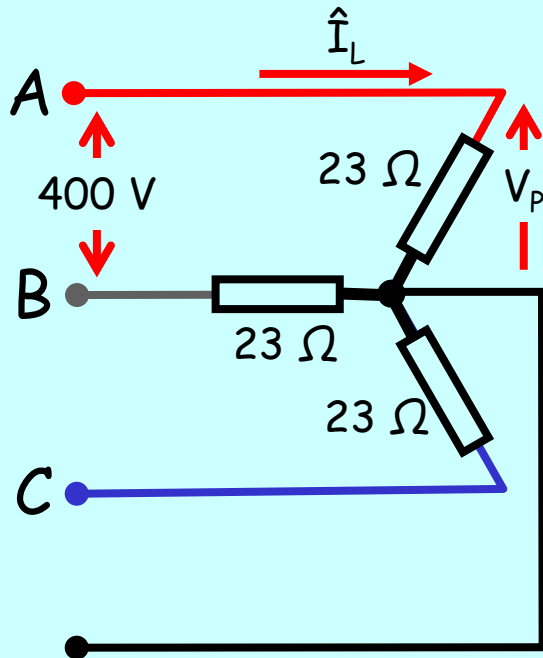
$$V_P = \frac{V_L}{\sqrt{3}}$$

$$V_P = \frac{400}{\sqrt{3}}$$

$$V_P = 230.9 \text{ V}$$

A 3 Phase Star connected heater has a line voltage of 400 V.  
 Determine the Line Current if each element has an impedance of  $23 \Omega$ .

What do we know?



$$I_L = I_P$$

What do we want to know?

$$V_P = \frac{V_L}{\sqrt{3}}$$

$$V_P = \frac{400}{\sqrt{3}} = 230 \text{ V}$$

$$I_P = \frac{V_P}{Z_P} = \frac{230}{23} = 10 \text{ A}$$

$$I_L = I_P = 10 \text{ A}$$

A three phase star connected four wire supply has a phase voltage of 220 V.  
What is the Line Voltage?

What do we know?

$$V_P = 220 \text{ V}$$

What do we want to know?

$$V_L = \sqrt{3} \times V_P$$

$$V_L = \sqrt{3} \times 220$$

$$V_L = 381 \text{ V}$$

A star connected induction motor draws 48 A from a system with a line voltage of 400 V. What is the Impedance of the Phase Windings?

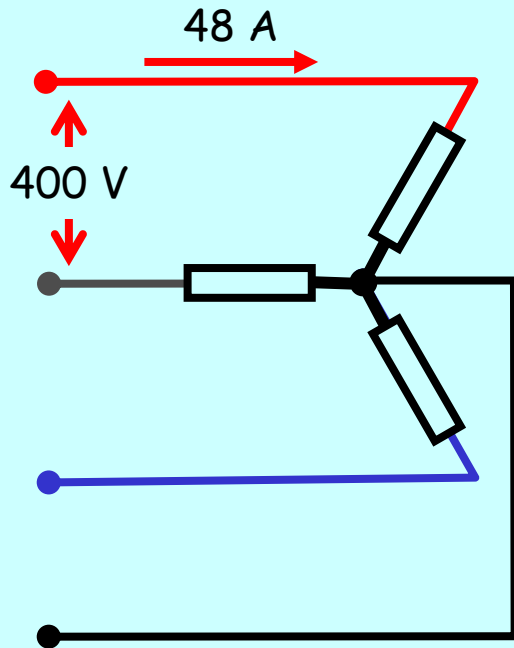
What do we know?

$$V_L = 400 \text{ V}$$

$$I_L = I_p = 48 \text{ A}$$

$$Z = \frac{V}{I}$$

What do we want to know?



$$V_p = \frac{400}{\sqrt{3}}$$

$$Z = \frac{230}{48}$$

$$V_p = 230 \text{ V}$$

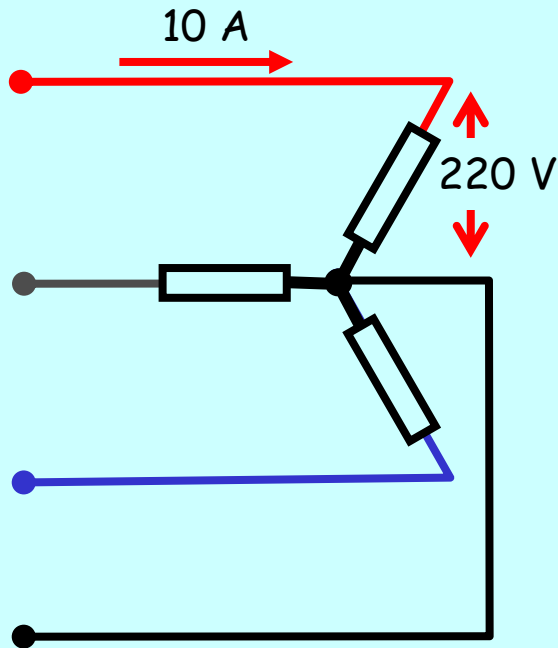
$$Z = 4.79 \Omega$$

A star connected symmetrical load draws 10 A from a system with a phase voltage of 220 V. What is the Impedance of each load and the Line Voltage?

What do we know?

$$V_p = 220 \text{ V}$$

$$I_L = I_p = 10 \text{ A}$$



What do we want to know?

$$Z = \frac{V}{I}$$

$$Z = \frac{220}{10}$$

$$Z = 22 \Omega$$

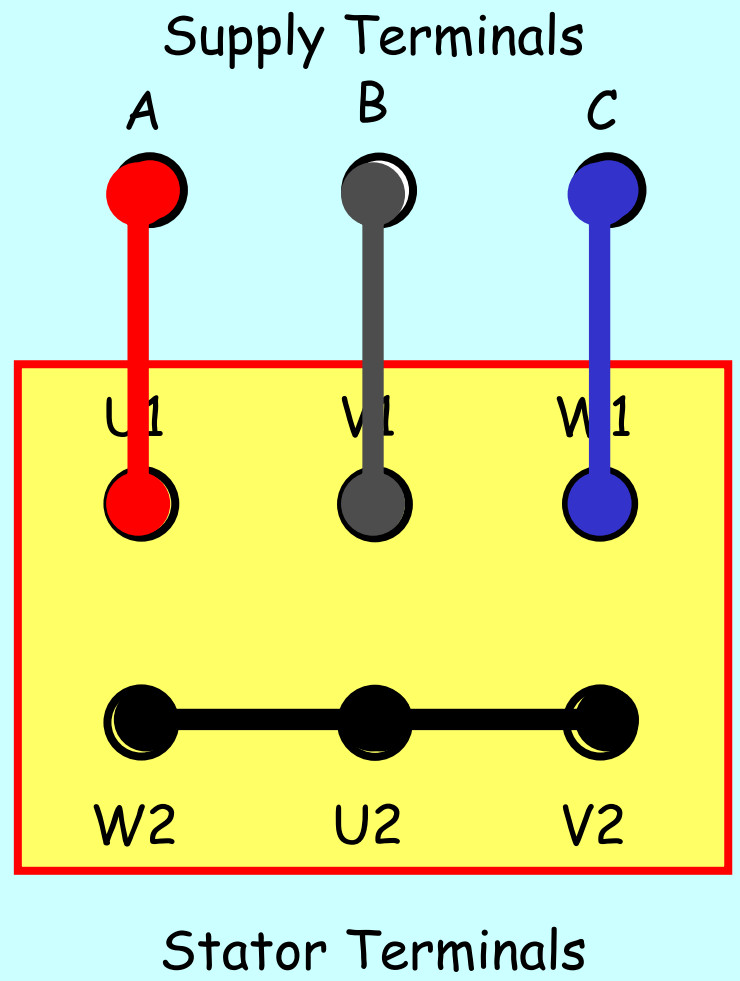
$$V_L = \sqrt{3} \times V_p$$

$$V_L = \sqrt{3} \times 220$$

$$V_L = 381 \text{ V}$$

The adjacent diagram represents the terminal connections for a 3 Phase Motor (U, V & W) and the terminals for a 3 Phase Supply (A, B & C).

What connections could be made to have the motor to operate in STAR configuration?

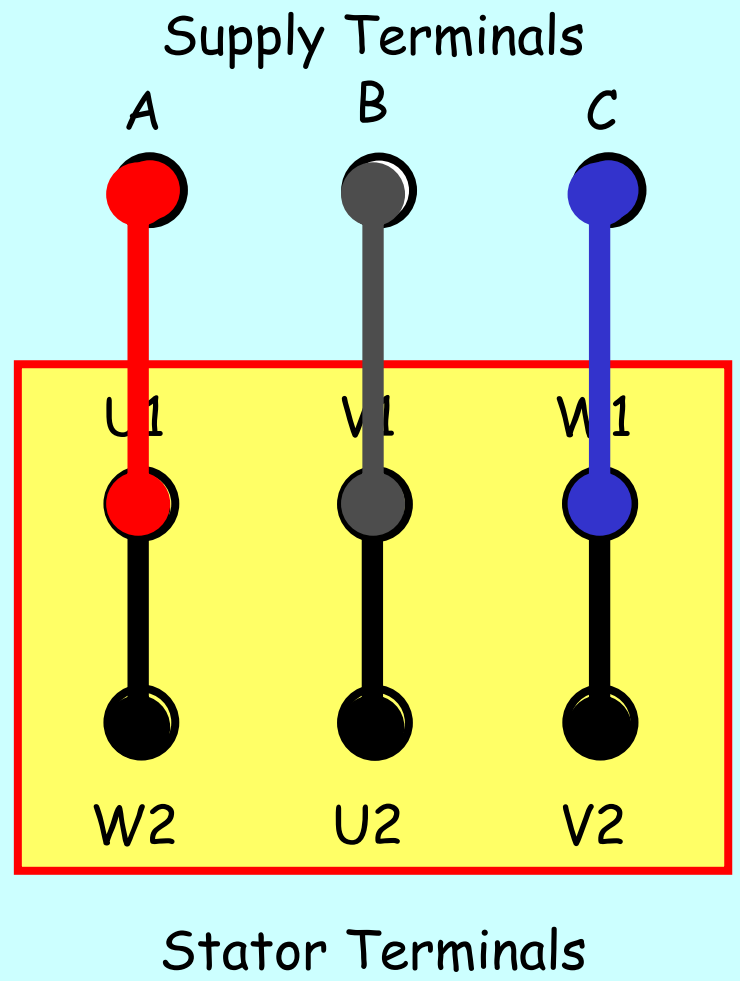


# Star Connection



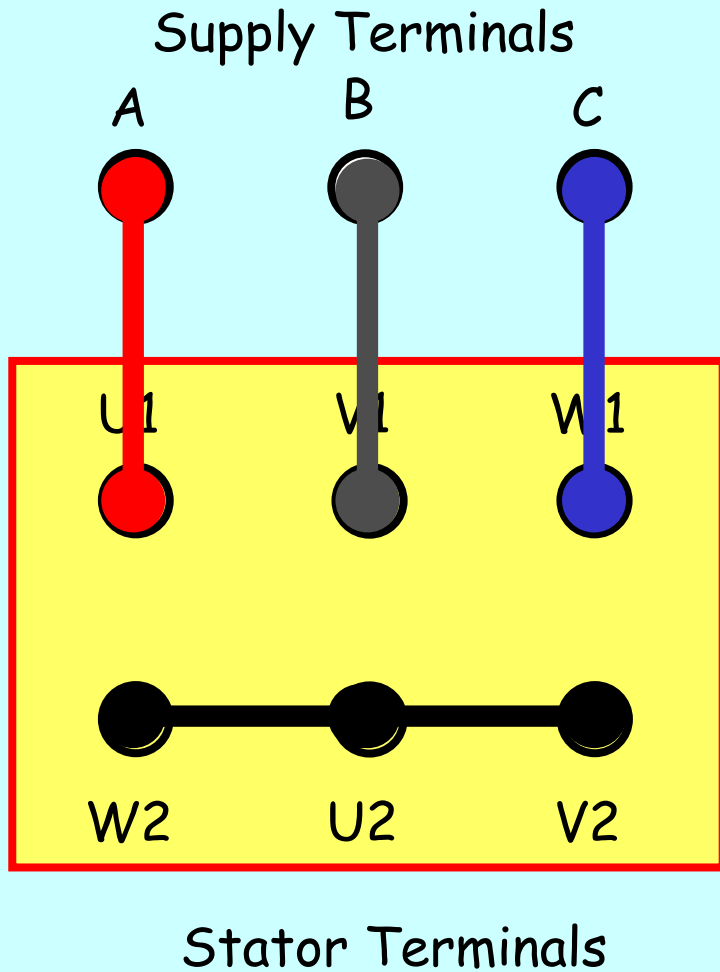
The adjacent diagram represents the terminal connections for a 3 Phase Motor (U, V & W) and the terminals for a 3 Phase Supply (A, B & C).

What connections could be made to have the motor to operate in Delta configuration?

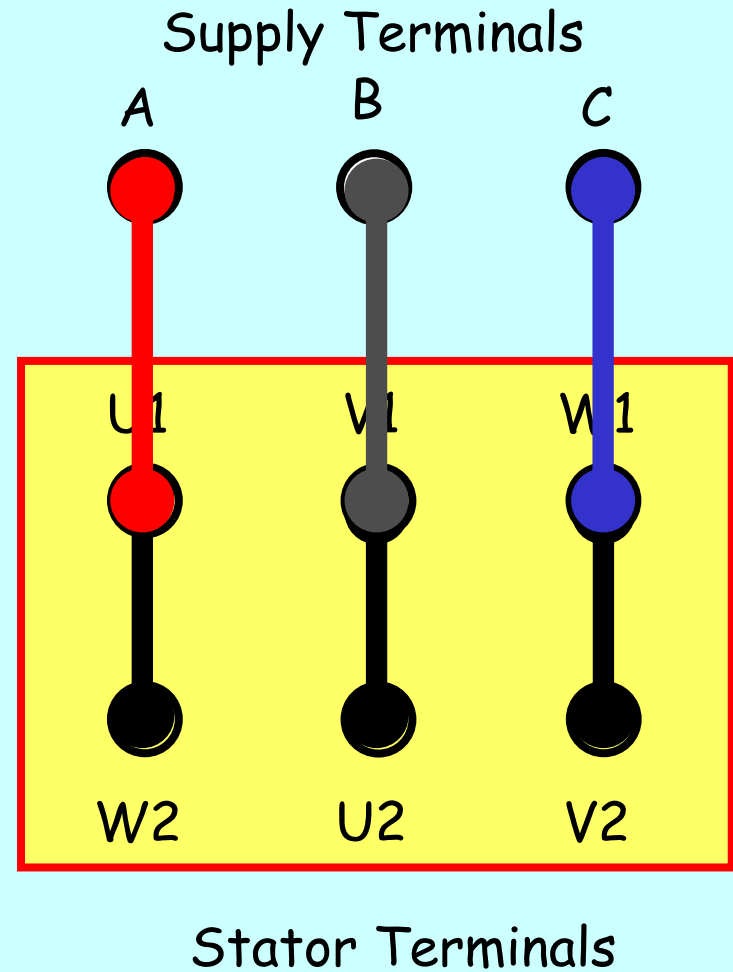


# Delta Connection

# Star Connection



# Delta Connection



**UEENEEEG102A**

**Solve problems in  
low voltage a.c. circuits**

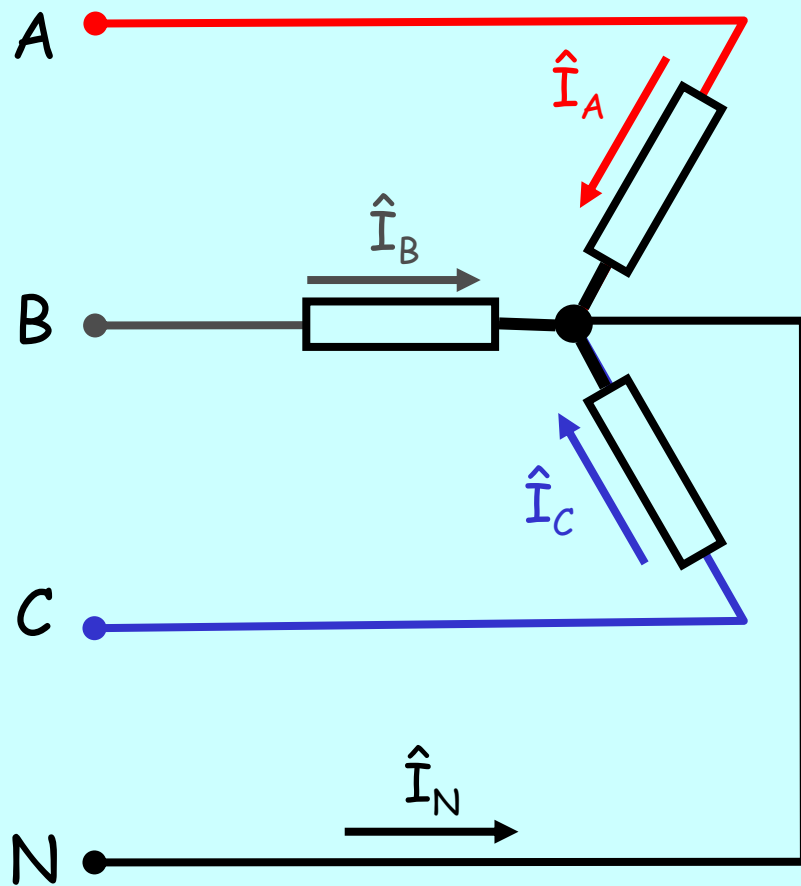
**Three Phase  
Four Wire Systems**

# Objectives:

At the end of this lesson students should be able to:

1. Determine Phase and Neutral Currents for Balanced and Unbalanced four wire systems.
2. State the purpose of the Neutral conductor in a three phase system.
3. Develop Phasor Diagrams for a star connected system.
4. State the requirements regarding the size of Neutral Conductors.

# Neutral Current



By Kirchoff's Current Law (KCL):

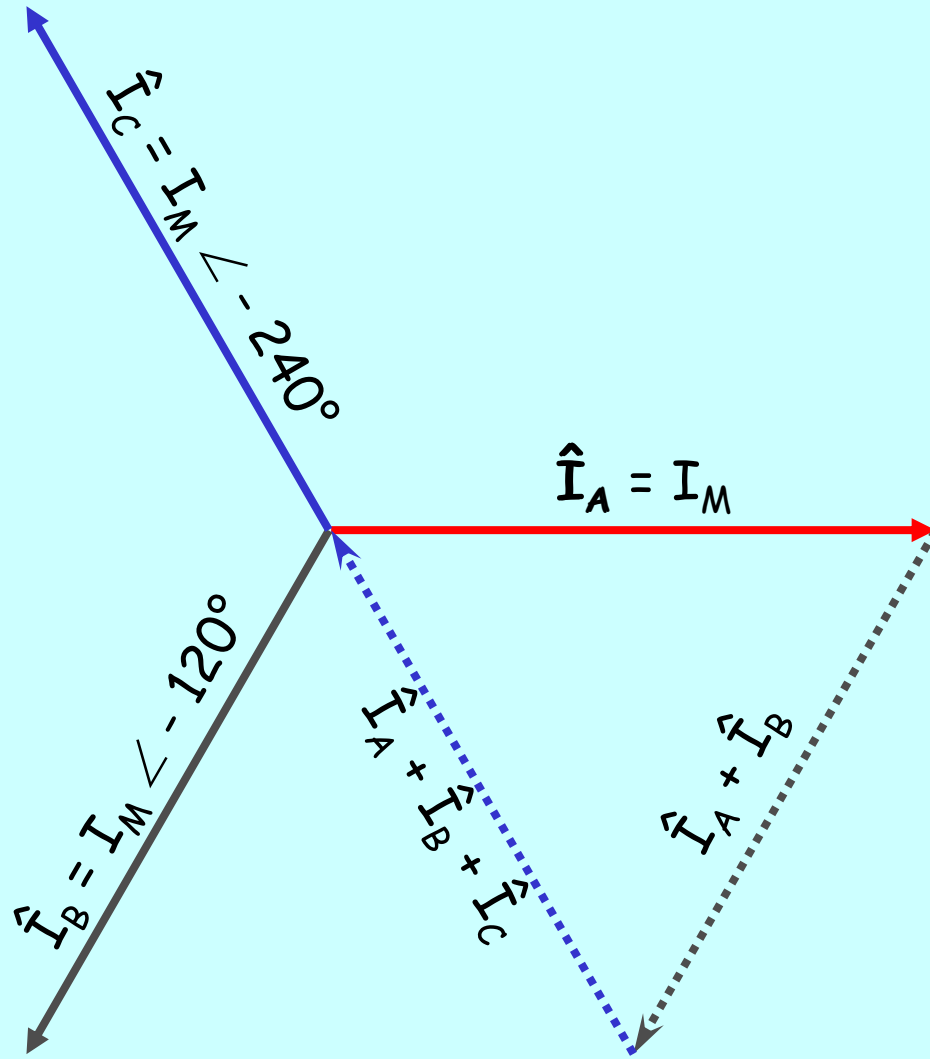
$$\hat{I}_N + \hat{I}_A + \hat{I}_B + \hat{I}_C = 0$$

For a balanced load

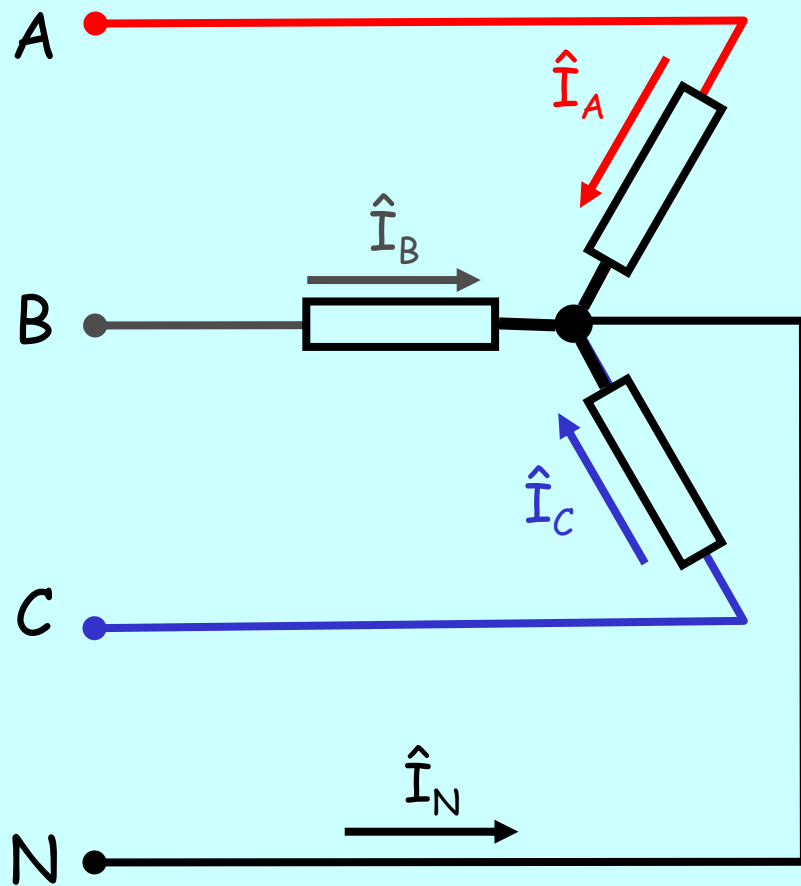
$$I_A = I_M \angle 0^\circ$$

$$I_B = I_M \angle -120^\circ$$

$$I_C = I_M \angle -240^\circ$$



# Neutral Current



By Kirchoff's Current Law (KCL):

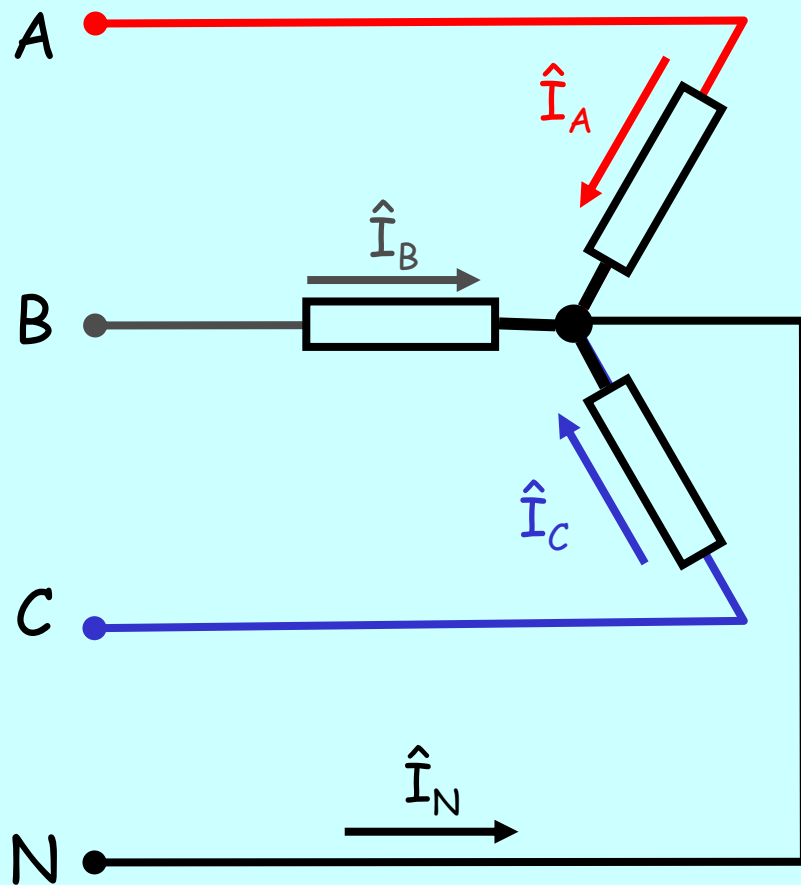
$$\hat{I}_N + \hat{I}_A + \hat{I}_B + \hat{I}_C = 0$$

$$\hat{I}_N = -(\hat{I}_A + \hat{I}_B + \hat{I}_C)$$

$$\hat{I}_N = 0 \text{ A}$$

What would happen if the loads are NOT Balanced?

# Neutral Current



By Kirchoff's Current Law (KCL):

$$\hat{I}_N + \hat{I}_A + \hat{I}_B + \hat{I}_C = 0$$

$$\hat{I}_N = -(\hat{I}_A + \hat{I}_B + \hat{I}_C)$$

$$\hat{I}_N = ? \text{ A}$$

$$\hat{I}_A = 25 \text{ A @ } \lambda = 0.707 \text{ lag}$$

$$\hat{I}_A = 25 \angle -45^\circ$$

$$\hat{I}_B = 10 \text{ A @ } \lambda = 0.866 \text{ lag}$$

$$\hat{I}_B = 10 \angle -30^\circ$$

$$\hat{I}_C = 15 \text{ A @ } \lambda = 1.0$$

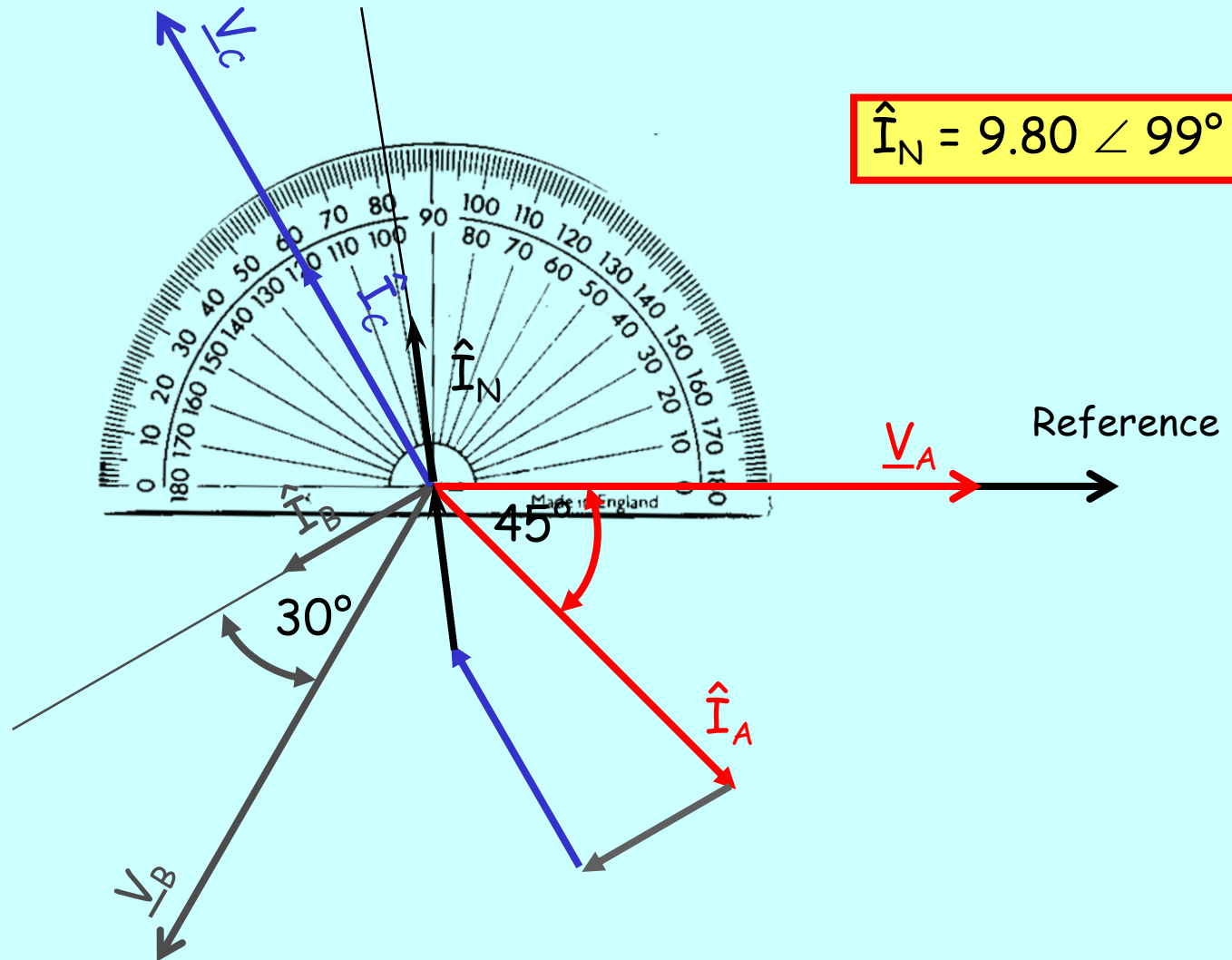
$$\hat{I}_C = 15 \angle 0^\circ$$



$$\hat{I}_A = 25 \angle -45^\circ$$

$$\hat{I}_B = 10 \angle -30^\circ$$

$$\hat{I}_C = 15 \angle 0^\circ$$



Three single phase 240 V loads are connected to different phases of a 415 V 3-Phase 4-Wire Supply. Determine the Neutral Current if the loads are:

- Phase A      A Capacitor Run Motor drawing 10 A @ a power factor of 0.9 lead  
Phase B      A Split Phase A/C Motor taking 15 A at a power factor of 0.65 lag  
Phase C      A 2.4 kW Radiator.

What do we know?

$$\hat{I}_A = 10 \text{ A @ } \lambda = 0.9 \text{ lead} \quad \longrightarrow \quad \hat{I}_A = 10 \angle 25.8^\circ$$

$$\hat{I}_B = 15 \text{ A @ } \lambda = 0.65 \text{ lag} \quad \longrightarrow \quad \hat{I}_B = 15 \angle -49.5^\circ$$

Radiators are Purely Resistive  $\therefore$  power factor is 1

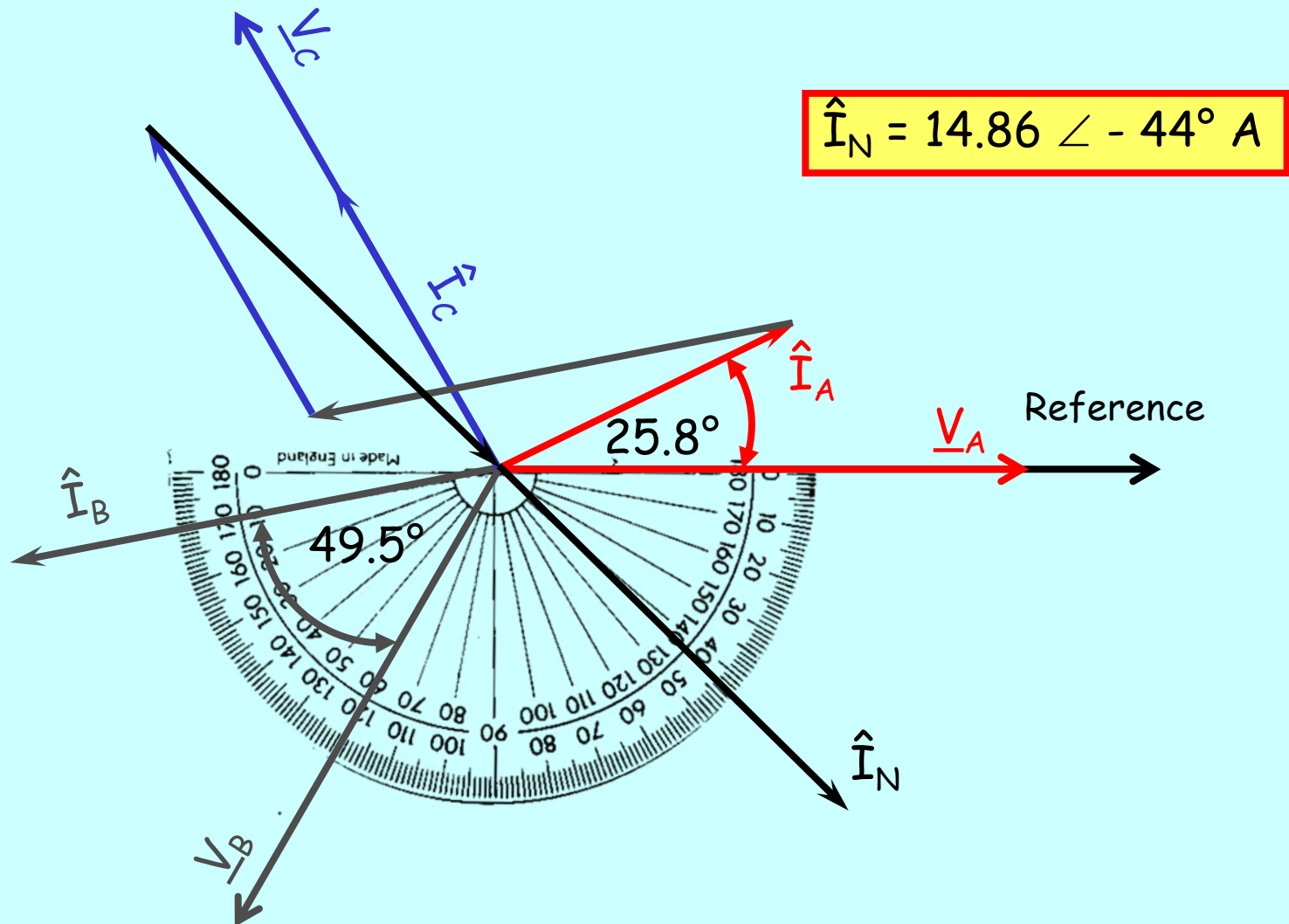
$$I = \frac{P}{V \cos \theta} = \frac{2400}{240 \times 1} = 10 \text{ A}$$

$$\hat{I}_C = 10 \text{ A @ } \lambda = 1.0 \quad \longrightarrow \quad \hat{I}_C = 10 \angle 0^\circ$$

$$\hat{I}_A = 10 \angle 25.8^\circ$$

$$\hat{I}_B = 15 \angle -49.5^\circ$$

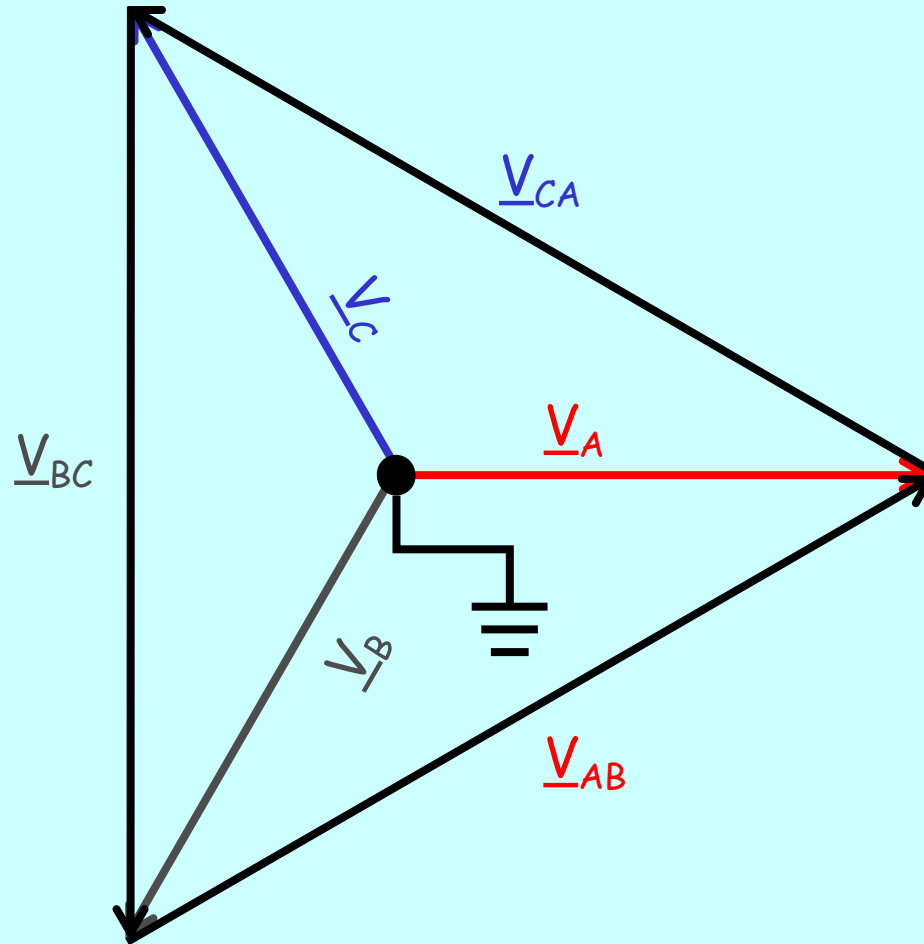
$$\hat{I}_C = 10 \angle 0^\circ$$



# Neutral Conductor Functions

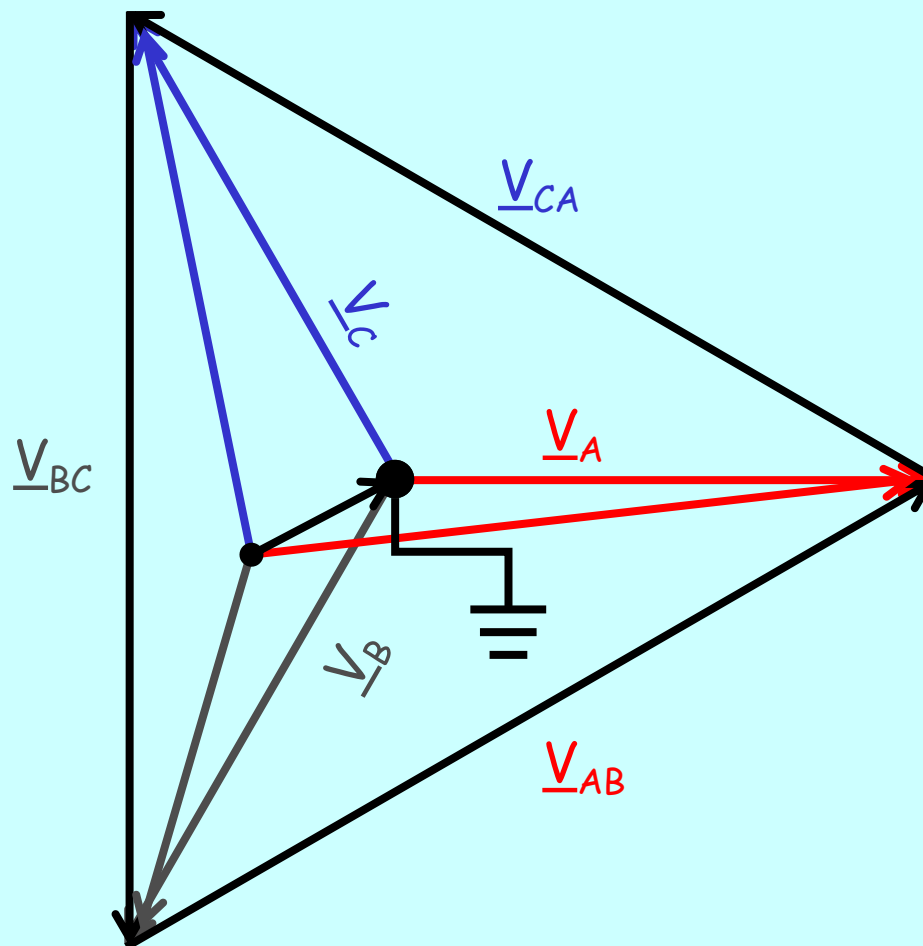
- Allow Single Phase Loads
- Maintain Phase Voltage equality
- Ensure correct operation of Protective Devices
- Carry out of balance currents
- Carry 3<sup>rd</sup> Harmonic Currents

The Neutral point forces the Line and Phase Voltages to remain even.



If the Neutral point becomes Open Circuit the Line Voltages remain the same, but the Phase Voltages change.

And now there is a Potential Difference from the common point to Earth.



# Neutral Conductor Size

Check this reference

IAW AS3000 Clause 3.5.2

## Factors

- Current Carrying Capacity
- Active Conductor Size
- Presence of Harmonics
- Detection Devices

A three phase star connected load is supplied by a 400 V three phase four wire supply. If each element of the heater has a resistance of  $12 \Omega$ , determine the magnitude of the Neutral Current.

What do we know?

This is a **BALANCED** Load!!!!

$$\hat{I}_N = 0 \text{ A}$$



A 3-Phase 4-Wire Supply has the phase currents:

Phase A      3 A in a purely resistive load

Phase B      2 A lagging by  $60^\circ$

Phase C      2 A leading by  $50^\circ$

Determine the current in the Neutral Conductor

What do we know?

This is an unbalanced load

Purely Resistive loads have a power factor of 1 and  $\angle 0^\circ$

$$\hat{I}_A = 3 \angle 0^\circ$$

$$\hat{I}_B = 2 \angle -60^\circ$$

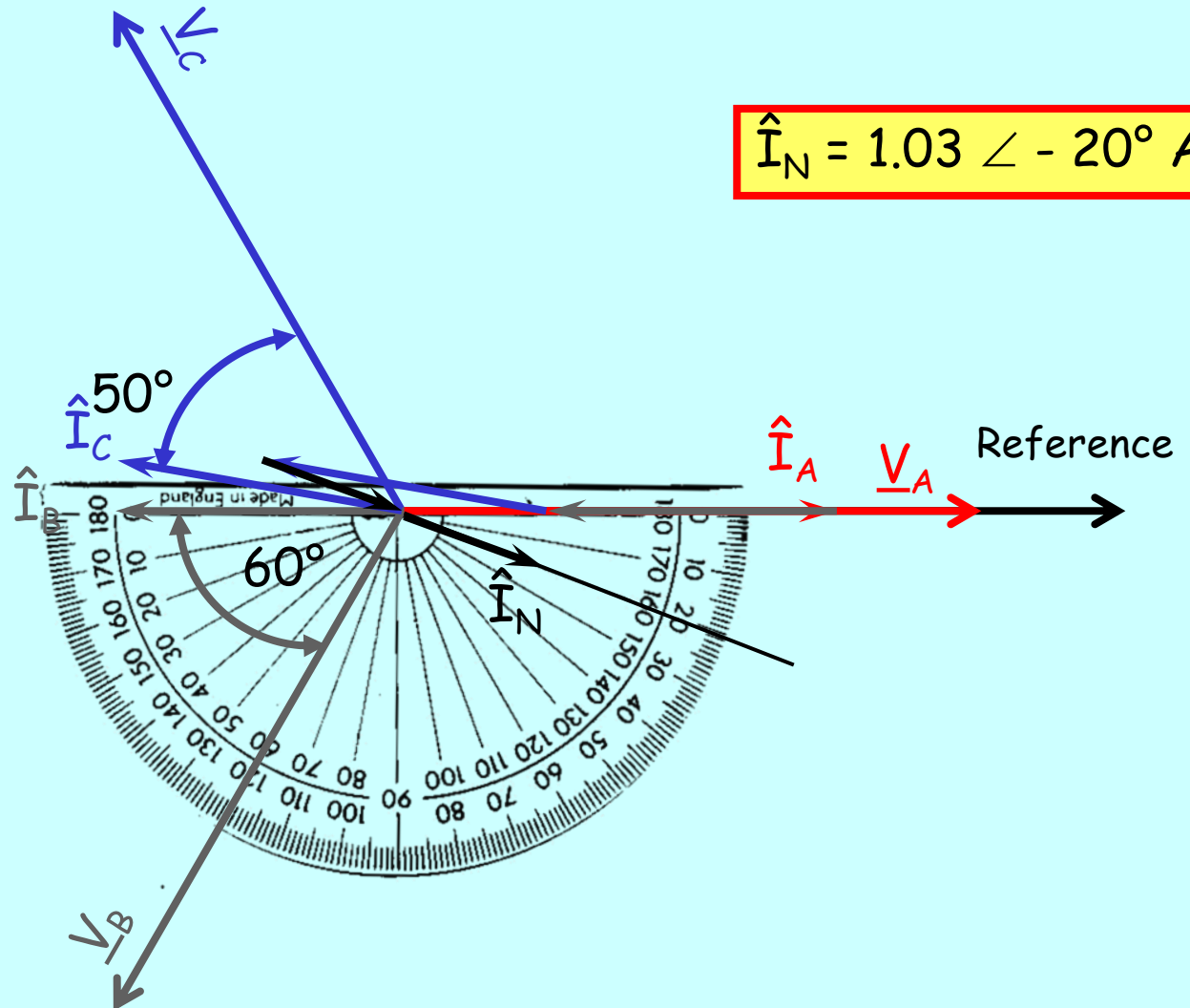
$$\hat{I}_C = 2 \angle +50^\circ$$

Do this on the board

$$\hat{I}_A = 3 \angle 0^\circ$$

$$\hat{I}_B = 2 \angle -60^\circ$$

$$\hat{I}_C = 2 \angle 50^\circ$$



$$\hat{I}_N = 1.03 \angle -20^\circ \text{ A}$$

Determine the Phase C to Star Point and Star Point to Earth Voltages of a 3\_Phase, 4-Wire, 400 Volt system is the Phase A to Star Point voltage is measured at 270 V and the Phase B to Star Point voltage is 180 V.

What do we know?

$$V_{AB} = V_{BC} = V_{CA} = 400 \text{ V}$$

$$V_{AN} = 270 \text{ V}$$

$$V_{BN} = 180 \text{ V}$$

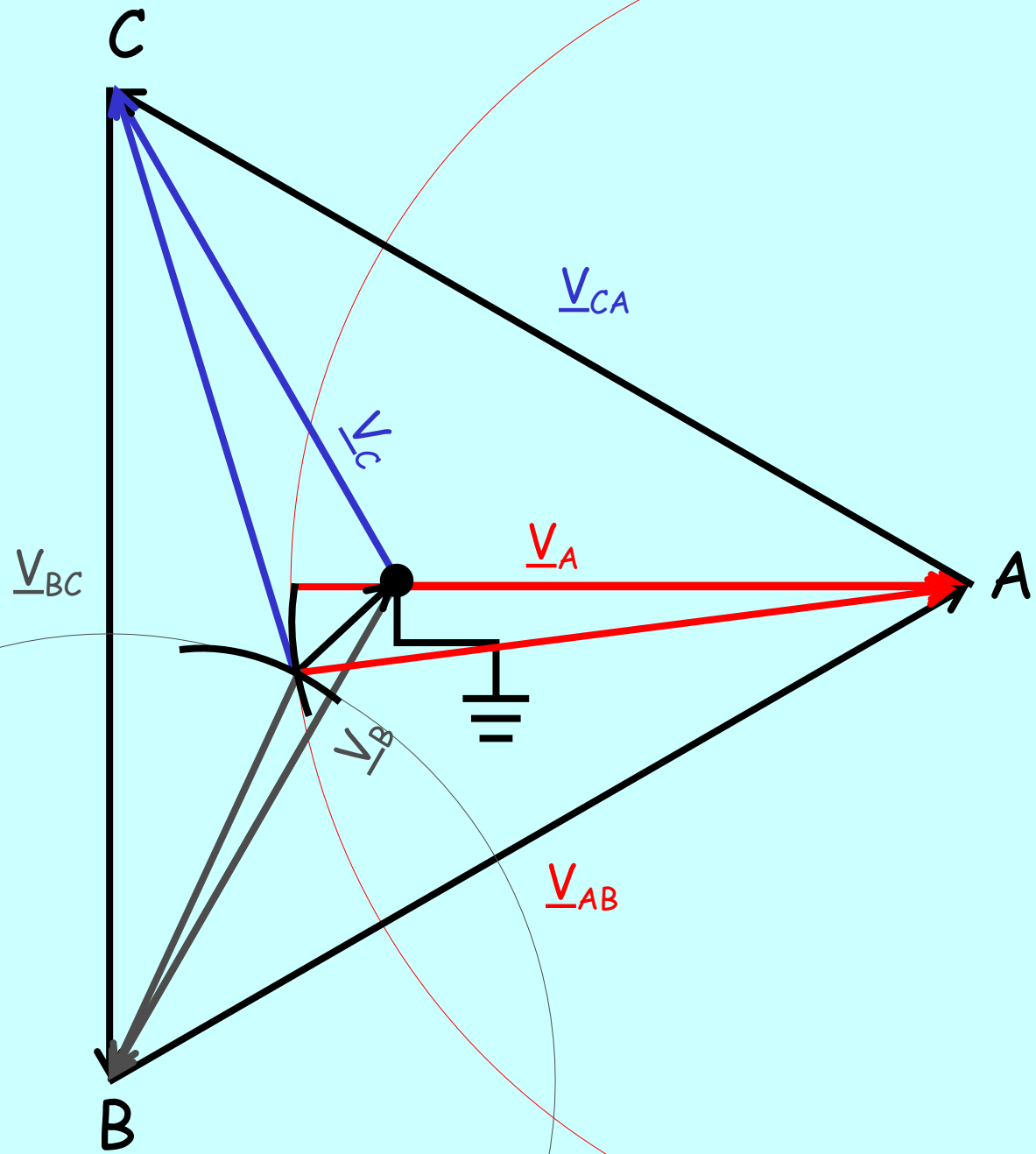
Do this on the board

$V_{AN} = 270 \text{ V}$

$V_{BN} = 180 \text{ V}$

$V_{CN} = 248 \text{ V}$

$V_{NO} = 54.7 \text{ V}$



# End of Lesson

## Practical Exercises

Three Phase Star Connected Systems.

Neutral Conductor Current.

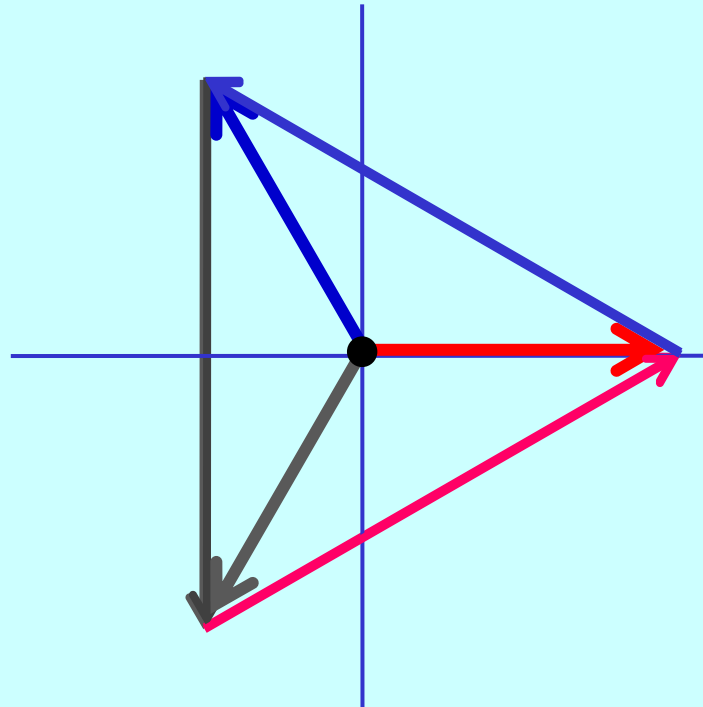
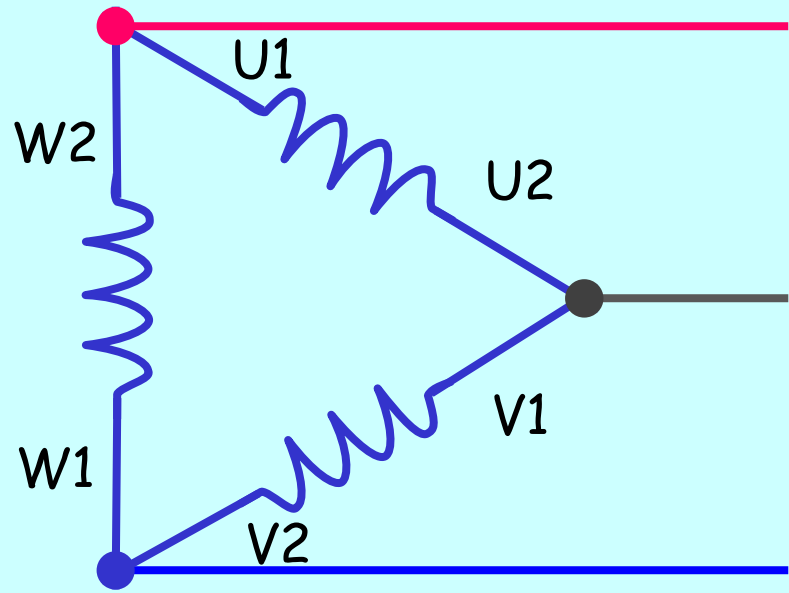
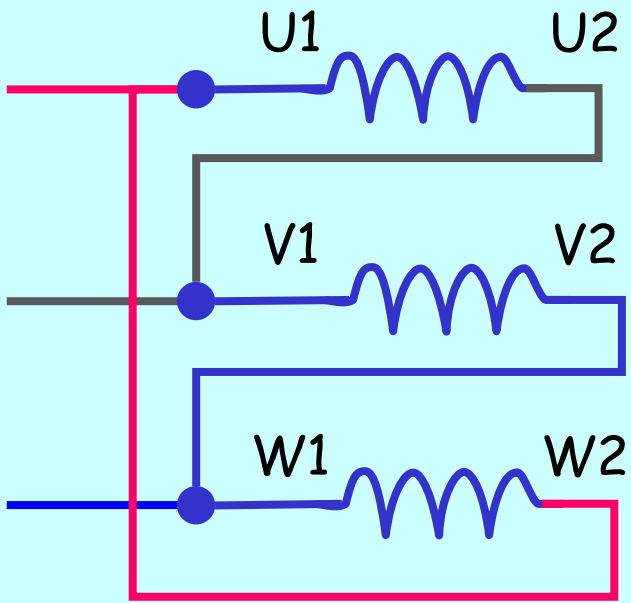
**UEENEEEG102A**  
**Solve problems in**  
**low voltage a.c. circuits**

**Three Phase Delta**

## Objectives:

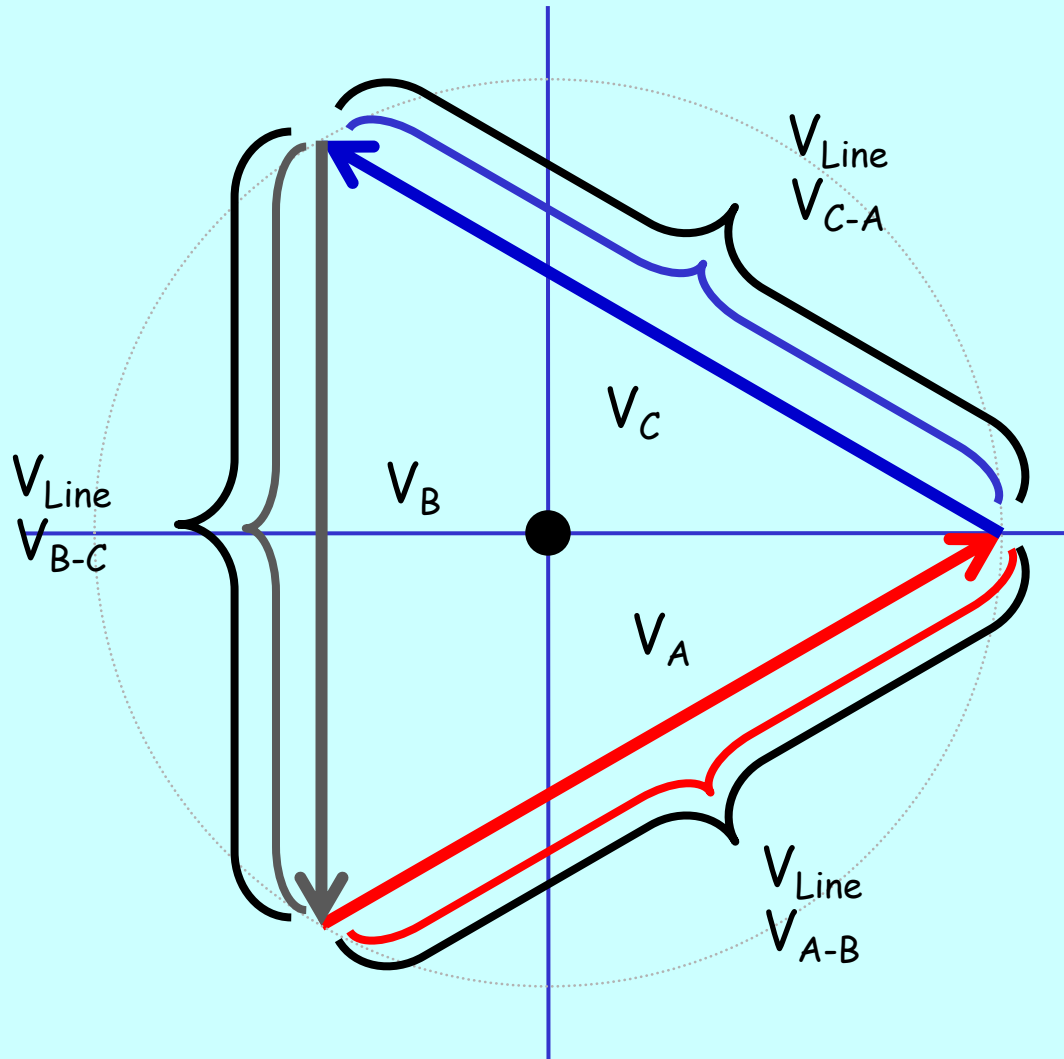
At the end of this lesson students should be able to:

1. Draw the circuit for a three phase Delta Connection.
2. Determine Line & Phase Voltages for a Delta Connected System.
3. Determine Line & Phase Currents for a Delta Connected System.
4. Draw and label the Phasor Diagrams for a Delta connected system.
5. State the limitations of Delta connected systems.
6. Connect a Delta connected load.





# Phase & Line Voltages



# Delta

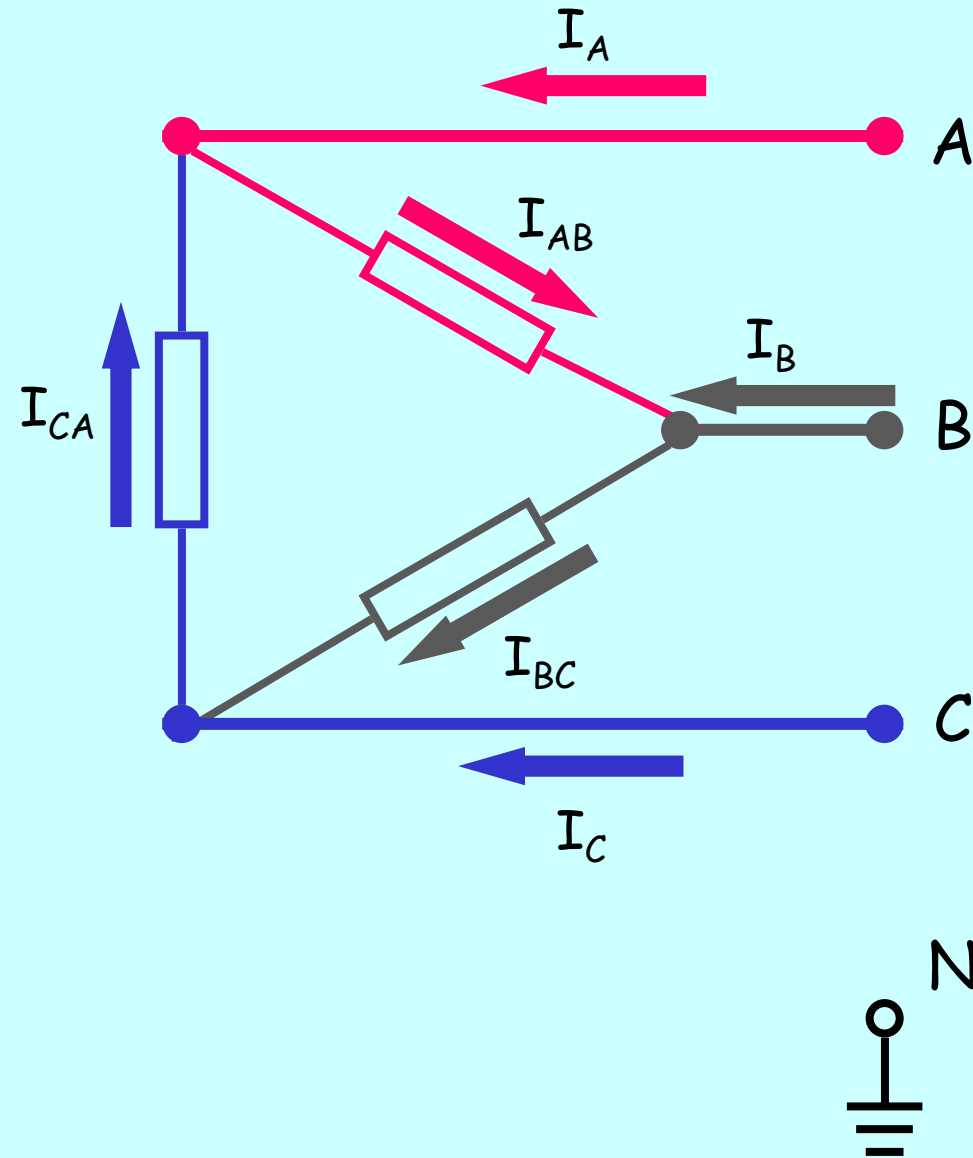
## Voltage & Current Relationships

Line Voltage      Phase Voltage

$$\underline{V}_L = \underline{V}_P$$

Line Current      Difference of two Phase Currents

$$\hat{I}_A = \hat{I}_{AB} - \hat{I}_{CA}$$



# Phase Currents

$$\underline{I}_{AB} = I_M \sin \theta$$

$$\underline{I}_{BC} = I_M \sin (\theta - 120)$$

$$\underline{I}_{CA} = I_M \sin (\theta - 240)$$

$$\underline{I}_{AB} = I_M \angle 0^\circ$$

$$\underline{I}_{BC} = I_M \angle -120^\circ$$

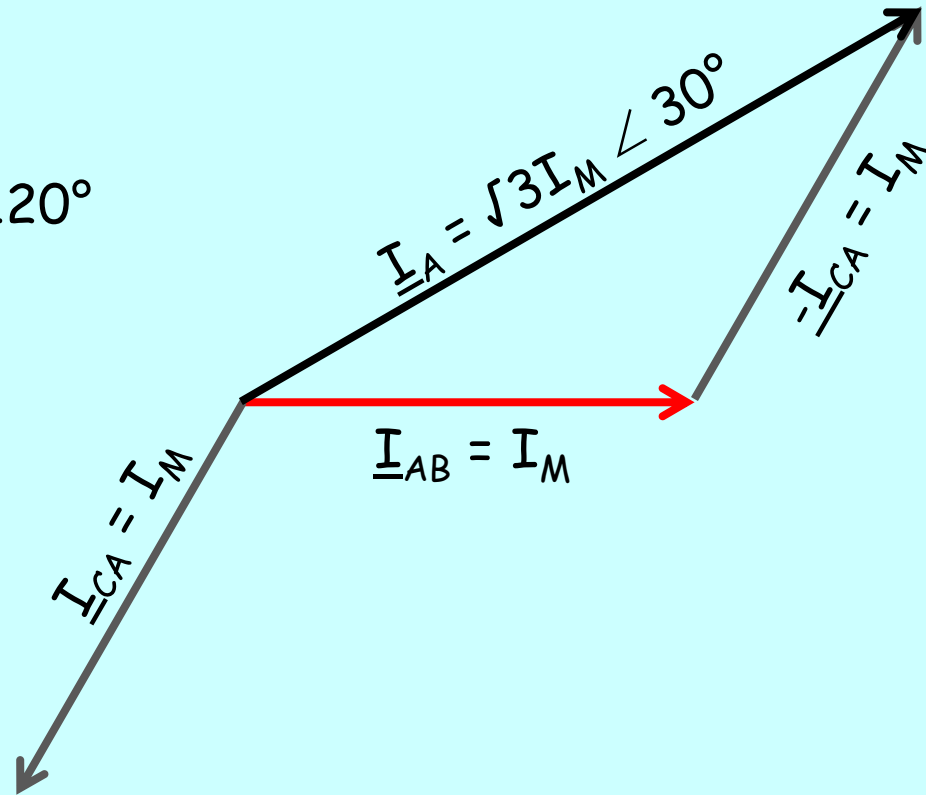
$$\underline{I}_{CA} = I_M \angle -240^\circ$$

# Line Currents

$$\underline{I}_A = \underline{I}_{AB} - \underline{I}_{CA}$$

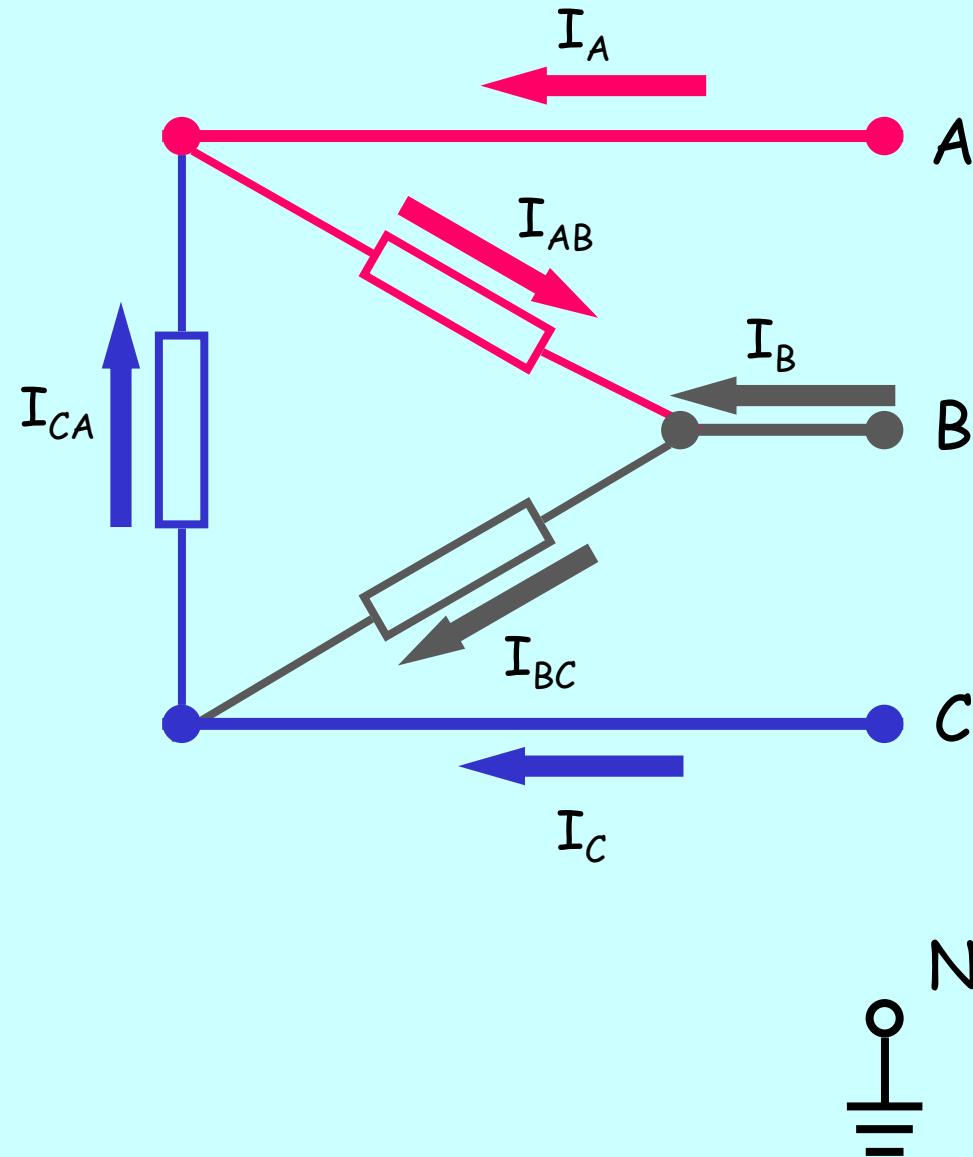
$$\underline{I}_A = I_M - I_M \angle -120^\circ$$

$$\underline{I}_A = \sqrt{3}I_M \angle 30^\circ$$



# Delta

## Voltage & Current Relationships



Line Voltage      Phase Voltage

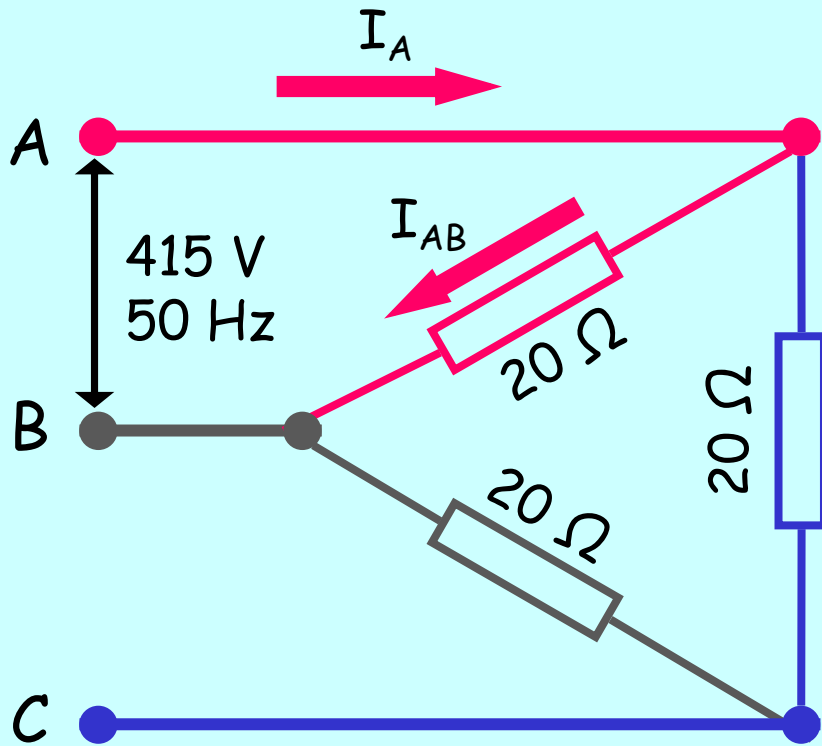
$$\underline{V}_L = \underline{V}_P$$

Line Current      Difference of two Phase Currents

$$\hat{I}_L = \hat{I}_{P1} - \hat{I}_{P2}$$

$$I_L = \sqrt{3}I_P$$

Determine the line current for a 3-phase motor stator winding which has an impedance of  $20 \Omega$  per phase when it is connected to a 415 V 50 Hz supply.



$$V_p = V_L = 415 \text{ V}$$

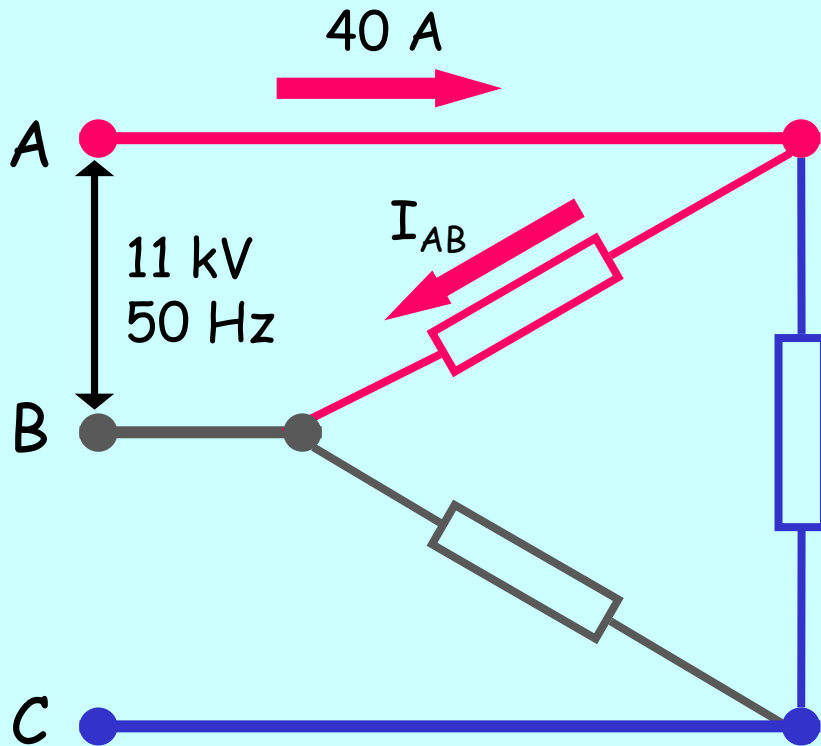
$$I_p = \frac{V_p}{Z_p}$$

$$I_p = \frac{415}{20} = 20.75 \text{ A}$$

$$I_L = \sqrt{3} I_p = \sqrt{3} \times 20.75$$

$$I_L = 35.94 \text{ A}$$

Determine the phase current for a 3-phase Delta connected transformer which delivers 40 A when it is connected to an 11 kV 50 Hz supply.

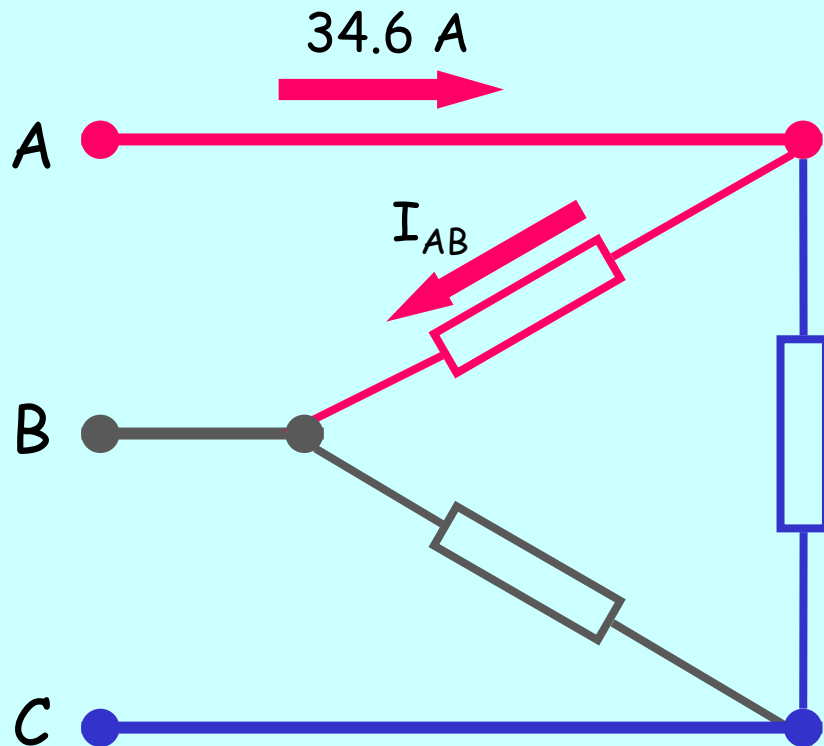


$$I_p = \frac{I_L}{\sqrt{3}}$$

$$I_p = \frac{40}{\sqrt{3}}$$

$$I_p = 23.1 \text{ A}$$

Determine the phase current for a 3-phase Delta connected resistive load which has a line current of 34.6 Amps.

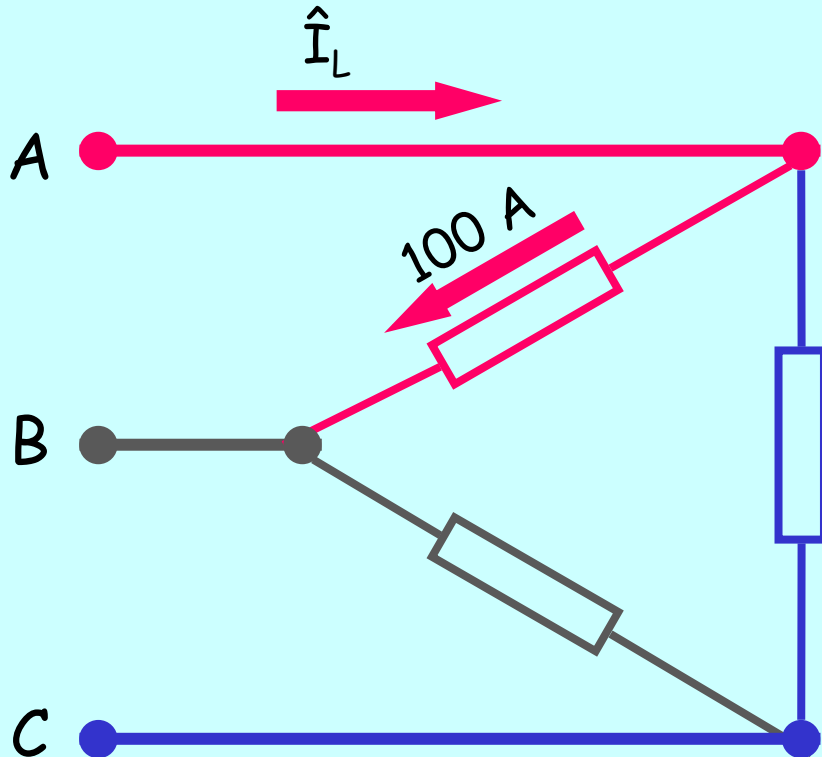


$$I_p = \frac{I_L}{\sqrt{3}}$$

$$I_p = \frac{34.6}{\sqrt{3}}$$

$$I_p = 19.98 \text{ A}$$

Determine the line current for a 3-phase Delta connected resistive load which has a phase current of 100 Amps.



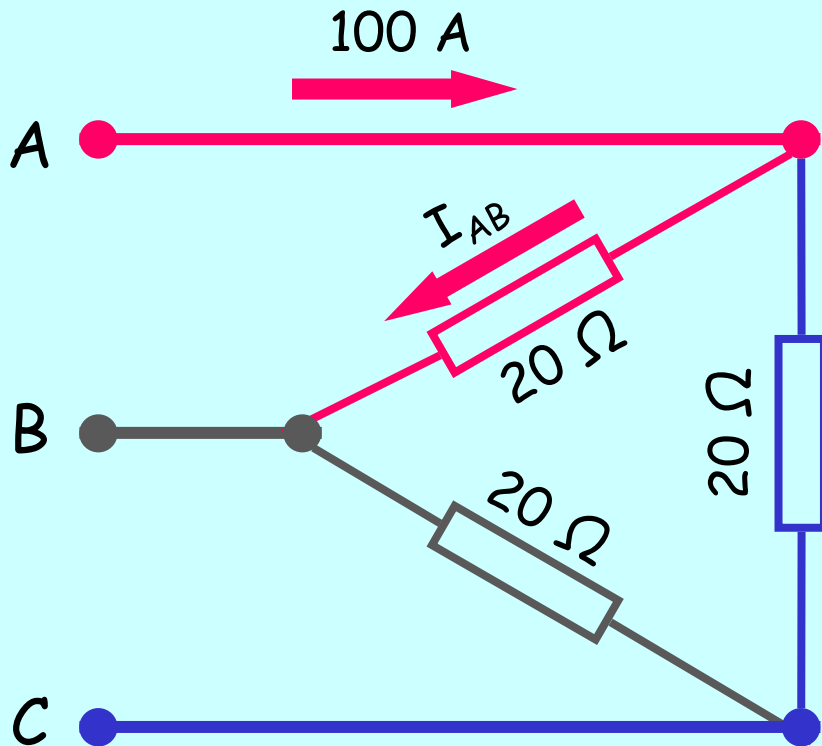
$$I_L = \sqrt{3}I_p$$

$$I_L = 100 \times \sqrt{3}$$

$$I_L = 173.2 \text{ A}$$



Determine the phase voltages and currents for a balanced 3-phase Delta connected resistive load which has a line current of 100 Amps and phase impedance of  $20 \Omega$ .



$$I_p = \frac{I_L}{\sqrt{3}}$$

$$I_p = \frac{100}{\sqrt{3}}$$

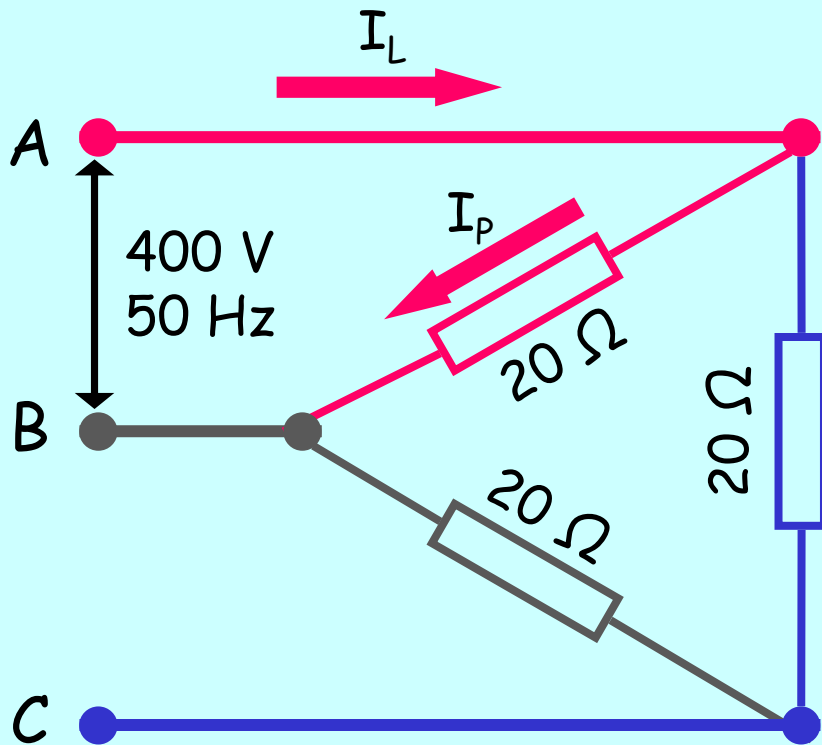
$$I_p = 57.74 \text{ A}$$

$$V_L = V_p = I_p Z$$

$$V_L = 57.74 \times 20$$

$$V_L = 1,154.8 \text{ V}$$

Determine the line current for a 3-phase motor which has a balanced impedance of  $20 \Omega$  per phase when it is connected to a three wire 400V 50Hz supply.



$$V_p = V_L = 400 \text{ V}$$

$$I_p = \frac{V_p}{Z_p}$$

$$I_p = \frac{400}{20} = 20 \text{ A}$$

$$I_L = \sqrt{3} I_p = \sqrt{3} \times 20$$

$$I_L = 34.64 \text{ A}$$

**UEENEEG102A**

**Solve problems in  
low voltage a.c. circuits**

**Star-Delta Systems**

# Objectives:

At the end of this lesson students should be able to:

1. Identify interconnected Star - Delta Systems.
2. Show the relationships between Line & Phase Voltages and Currents for a three phase Systems.
3. State the effect of reversing a phase winding in a three phase system.
4. Connect Star and Delta Systems.

# Star

## Voltage & Current Relationships

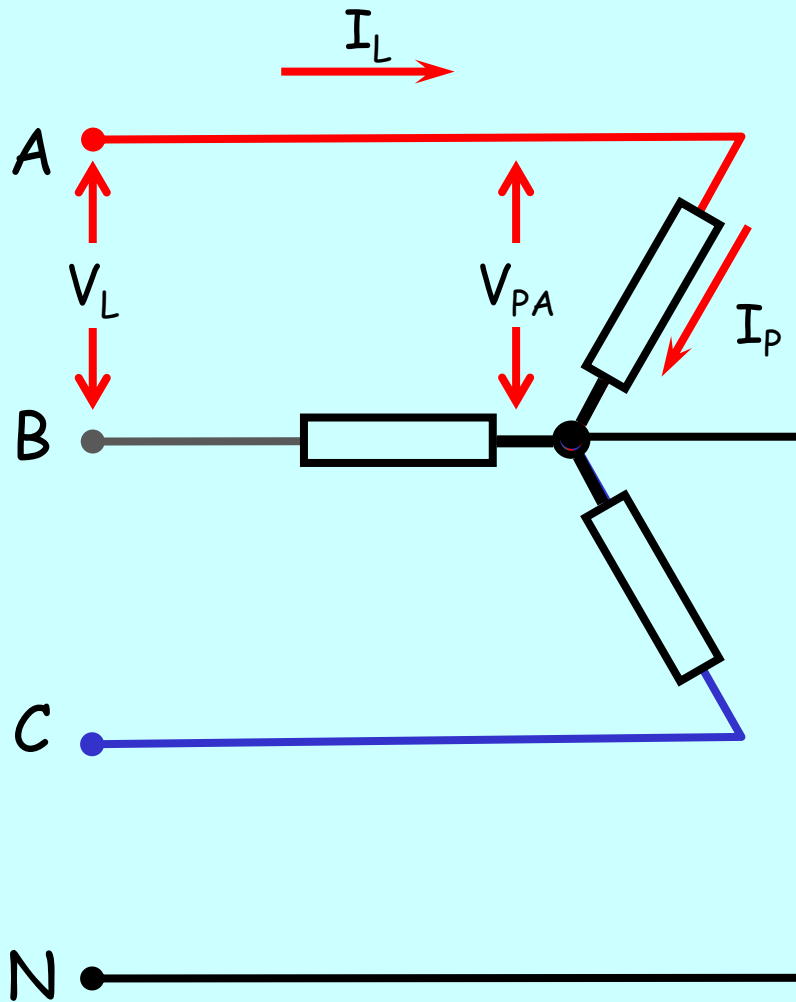
Line Current = Phase Current

$$I_L = I_P$$

$$I_N + I_A + I_B + I_C = 0$$

Line Voltage = Difference of two Phase Voltages

$$V_L = \sqrt{3}V_P$$



# Delta

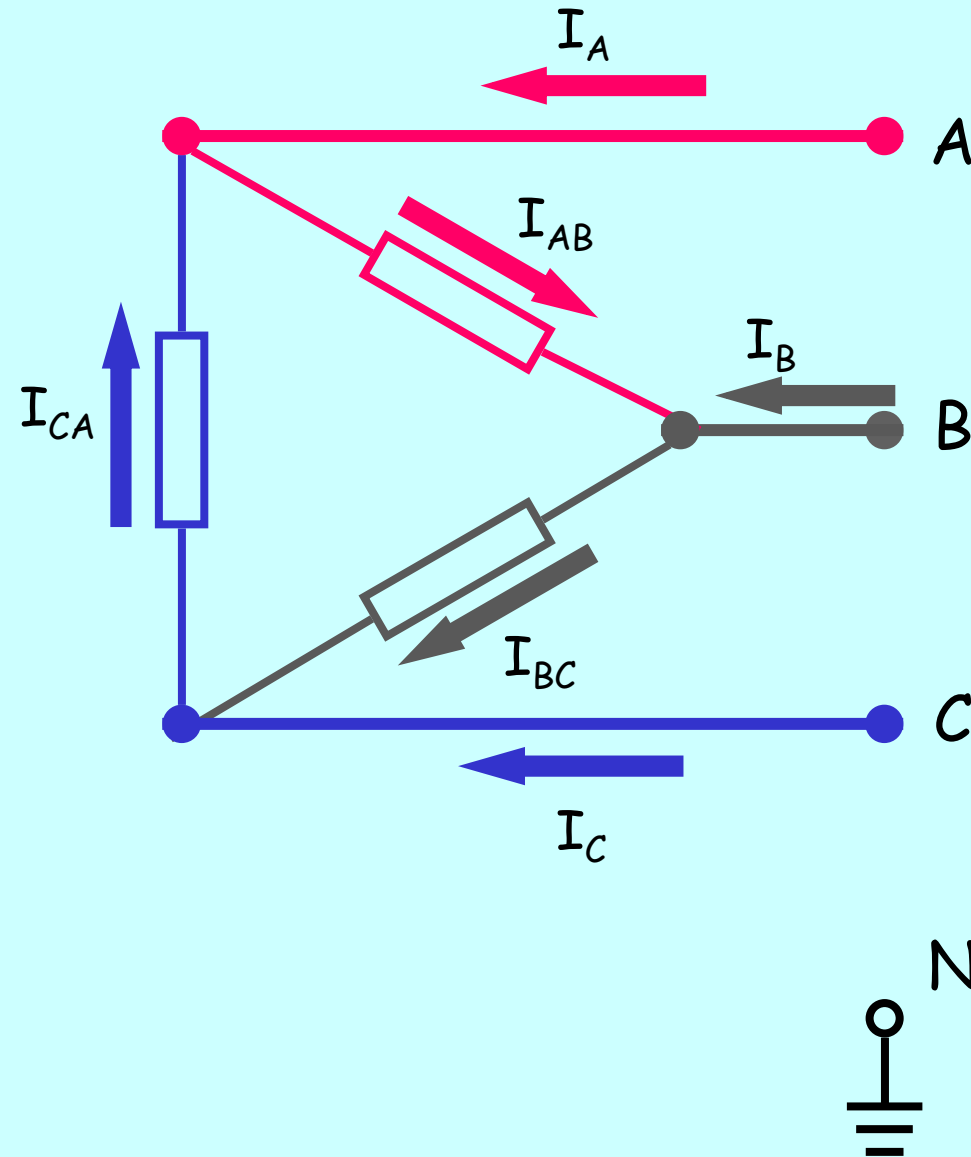
## Voltage & Current Relationships

Line Voltage = Phase Voltage

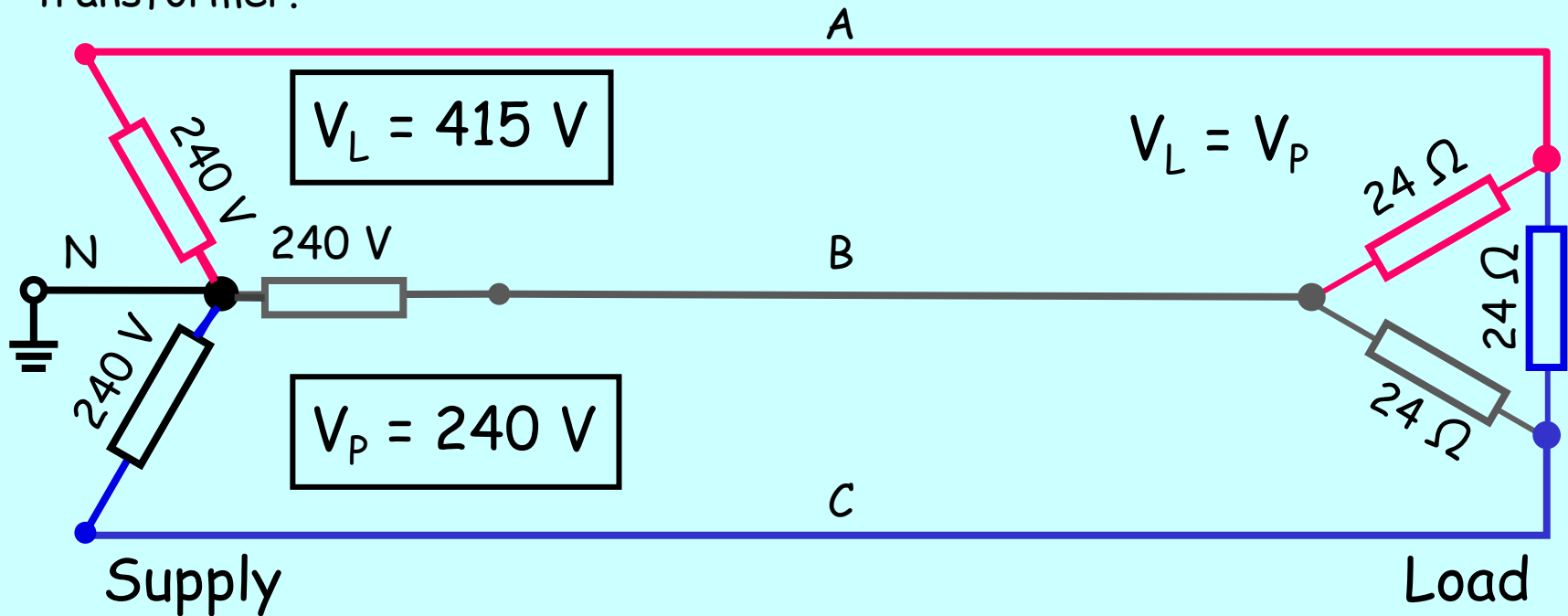
$$V_L = V_P$$

Line Current = Difference of two Phase Currents

$$I_L = \sqrt{3}I_P$$



Determine the line current of a 3 phase Delta connected motor which has an impedance of  $24 \Omega$  per phase when it is connected to a 240V Star connected transformer.



$$V_L = \sqrt{3}V_p$$

$$I_L = \sqrt{3}I_p$$

$$I_p = \frac{V_p}{Z_p}$$

$$V_L = \sqrt{3} \times 240$$

$$I_L = \sqrt{3} \times 17.32$$

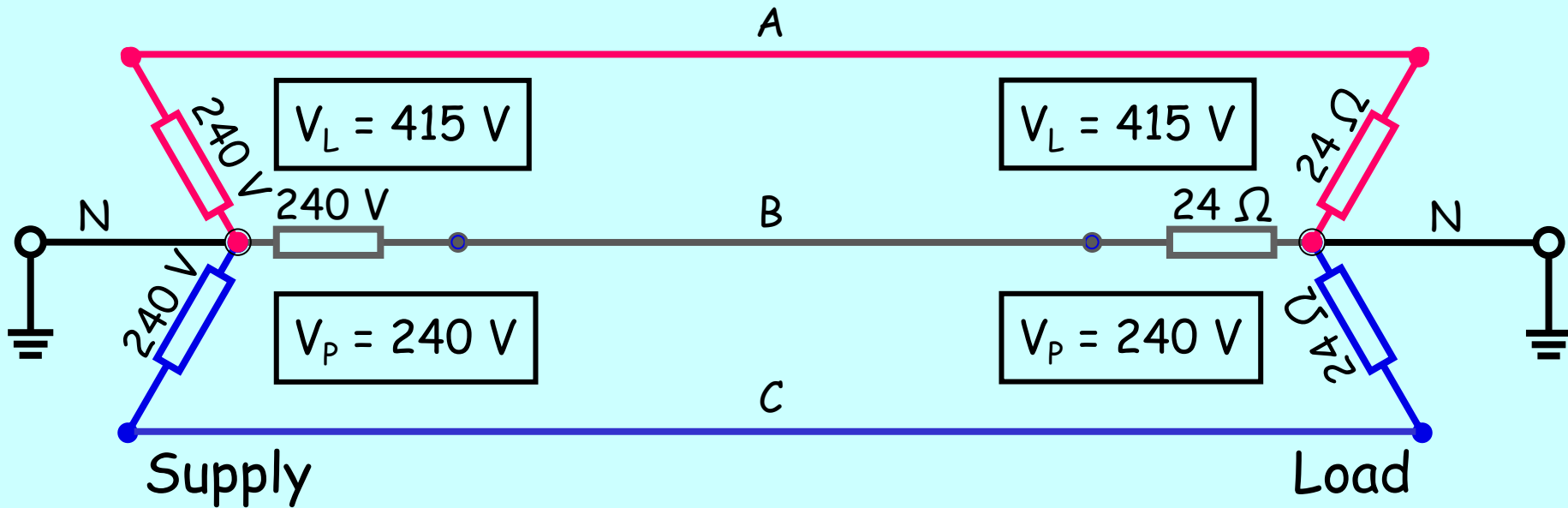
$$I_p = \frac{415}{24}$$

$$V_L = 415 \text{ V}$$

$$I_L = 30 \text{ A}$$

$$I_p = 17.32 \text{ A}$$

Determine the line current of a 3 phase Star connected motor which has an impedance of  $24 \Omega$  per phase when it is connected to a 240V Star connected transformer.



$$V_L = \sqrt{3}V_P$$

$$I_L = I_P$$

$$I_P = \frac{V_P}{Z_P} \quad V_P = \frac{V_L}{\sqrt{3}}$$

Delta

$$I_L = 30 \text{ A}$$

STAR

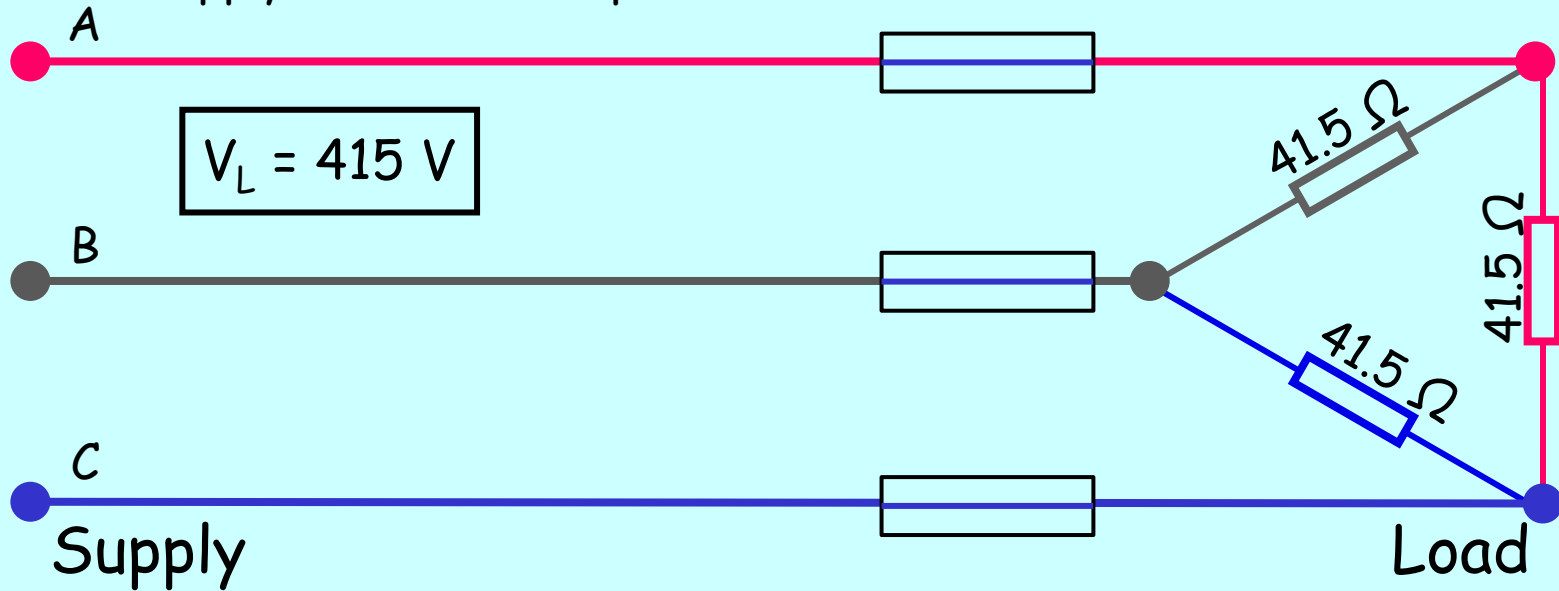
$$I_L = 10 \text{ A}$$

$$I_P = \frac{240}{24}$$

$$I_P = 10 \text{ A}$$



Determine the current in the elements of a 3 phase Delta connected heater which has an impedance of  $41.5 \Omega$  per phase when it is connected to a 415 V three wire supply if the fuse in phase C has blown.



Normal  
Operation

$$I_p = \frac{V_p}{Z_p}$$

$$I_L = \sqrt{3}I_p$$

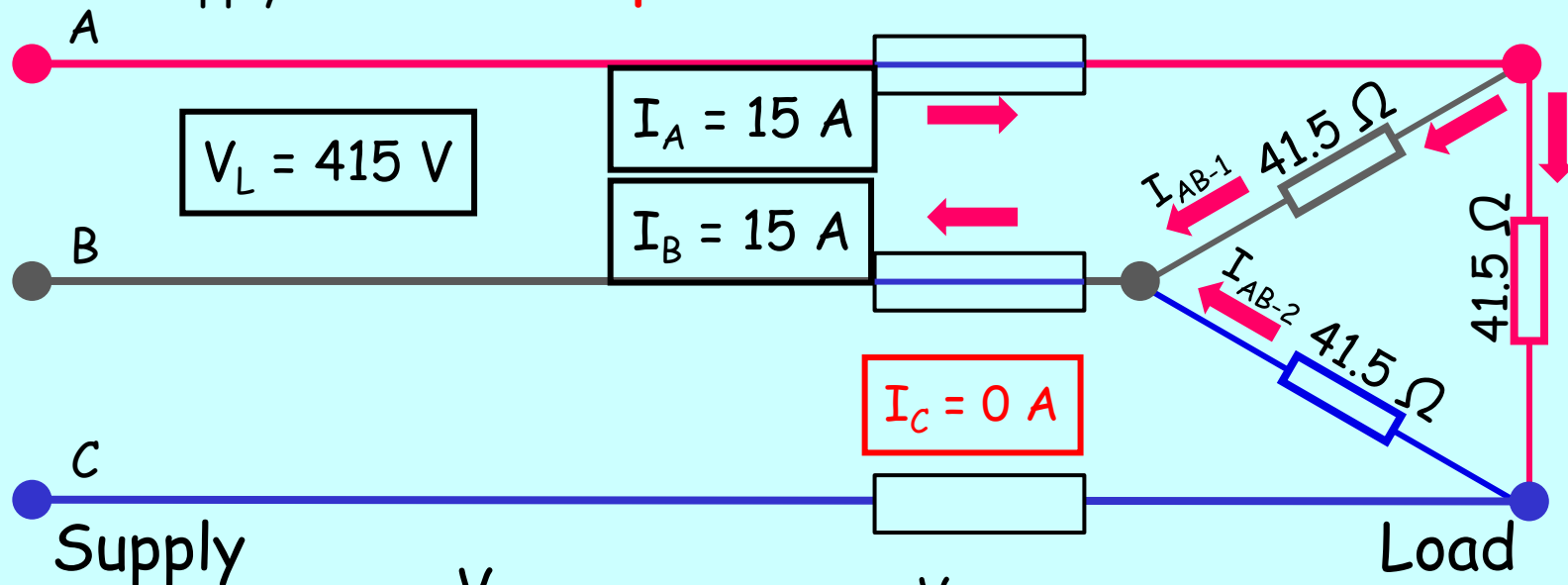
$$I_p = \frac{415}{41.5}$$

$$I_L = \sqrt{3} \times 10$$

$$I_p = 10 \text{ A}$$

$$I_L = 17.32 \text{ A}$$

Determine the current in the elements of a 3 phase Delta connected heater which has an impedance of  $41.5 \Omega$  per phase when it is connected to a 415 V three wire supply **if the fuse in phase C has blown.**



**Fuse blown  
Operation**

$$I_P = \frac{V_P}{Z_P}$$

$$I_{AB-2} = \frac{V_{AB}}{Z_{AB-2}}$$

$$I_A = I_B = I_{AB-1} + I_{AB-2}$$

$$I_{AB-1} = \frac{V_{AB}}{Z_{AB-1}}$$

$$I_{AB-2} = \frac{415}{41.5 + 41.5}$$

$$I_A = 10 + 5$$

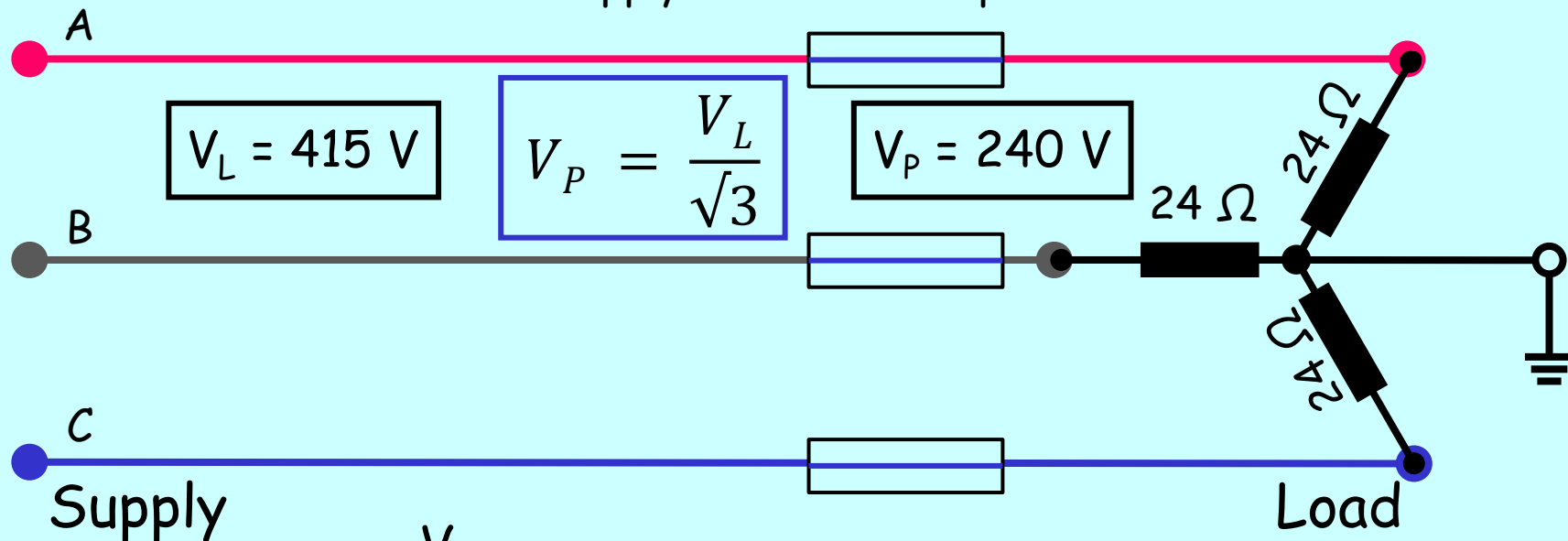
$$I_{AB-1} = \frac{415}{41.5}$$

$$I_{AB-1} = 10 \text{ A}$$

$$I_{AB-2} = 5 \text{ A}$$

$$I_A = I_B = 15 \text{ A}$$

Determine the phase voltages and line currents for the elements of a 3 phase Star connected heater which has an impedance of  $24 \Omega$  per phase when it is connected to a 415 V **four wire** supply if the fuse in phase C has blown.



Normal  
Operation

$$I_P = \frac{V_P}{Z_P}$$

$$I_P = \frac{240}{24}$$

$$I_L = I_P$$

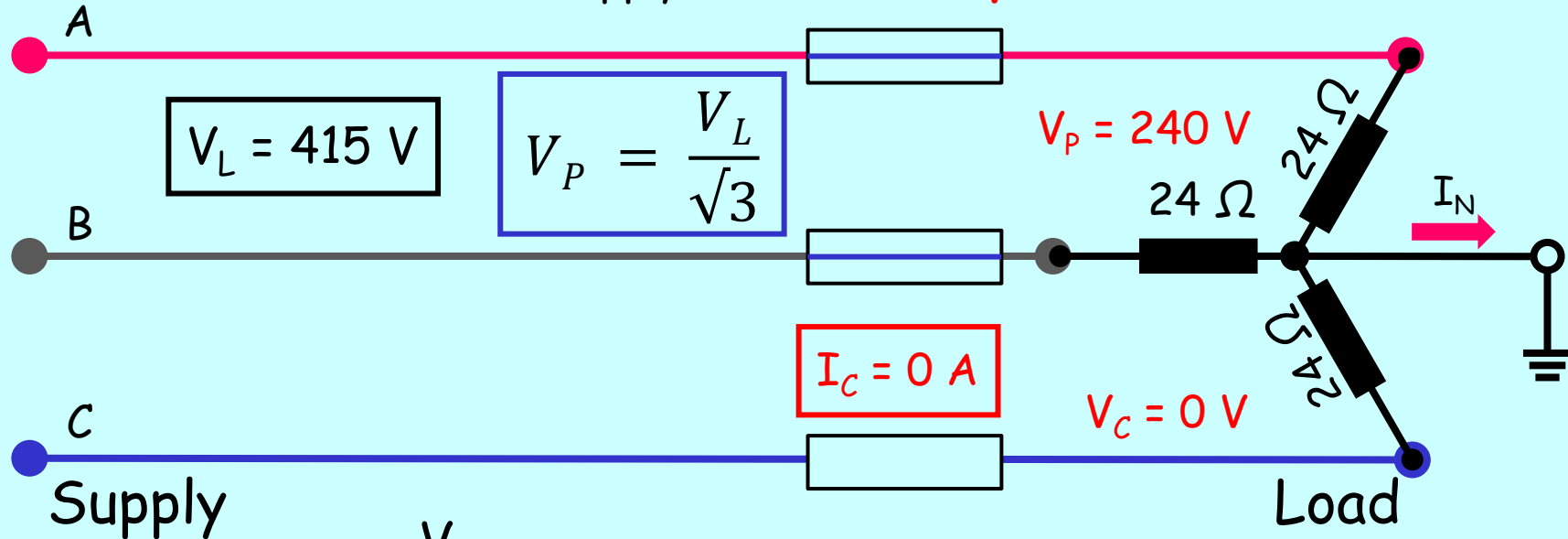
$$\hat{I}_N + \hat{I}_A + \hat{I}_B + \hat{I}_C = 0$$

$$I_P = 10 \text{ A}$$

$$I_L = 10 \text{ A}$$

$$I_N = 0 \text{ A}$$

Determine the phase voltages and line currents for the elements of a 3 phase Star connected heater which has an impedance of  $24 \Omega$  per phase when it is connected to a 415 V four wire supply if the fuse in phase C has blown.



Fuse blown  
Operation

$$I_p = \frac{V_p}{Z_p}$$

$$I_p = \frac{240}{24}$$

$$I_L = I_p$$

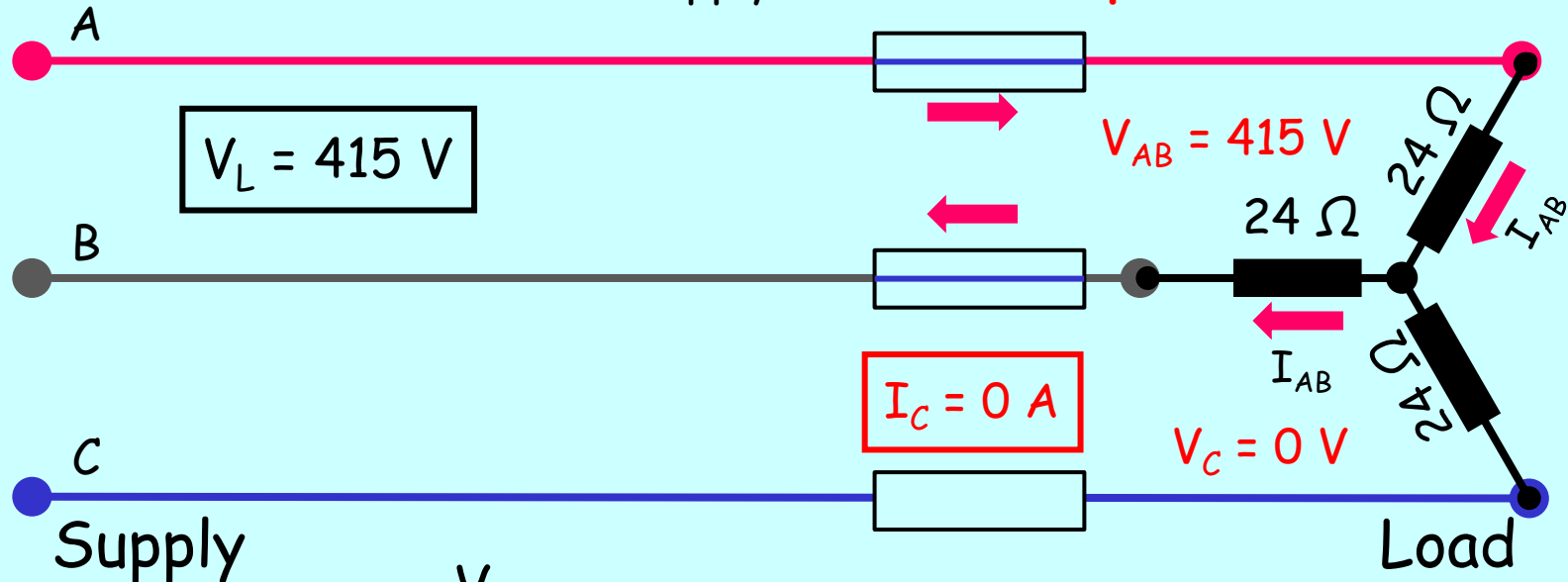
$$\hat{I}_N + \hat{I}_A + \hat{I}_B + \hat{I}_C = 0$$

$$I_p = 10 \text{ A}$$

$$I_L = 10 \text{ A}$$

$$I_N = I_L = 10 \text{ A}$$

Determine the phase voltages and line currents for the elements of a 3 phase Star connected heater which has an impedance of  $24 \Omega$  per phase when it is connected to a 415 V **three wire** supply if the **fuse in phase C has blown**.



Fuse blown  
Operation

$$I_p = \frac{V_p}{Z_p}$$

$$I_A = -I_B$$

$$I_p = \frac{415}{24 + 24}$$

$$I_p = 8.65 A$$

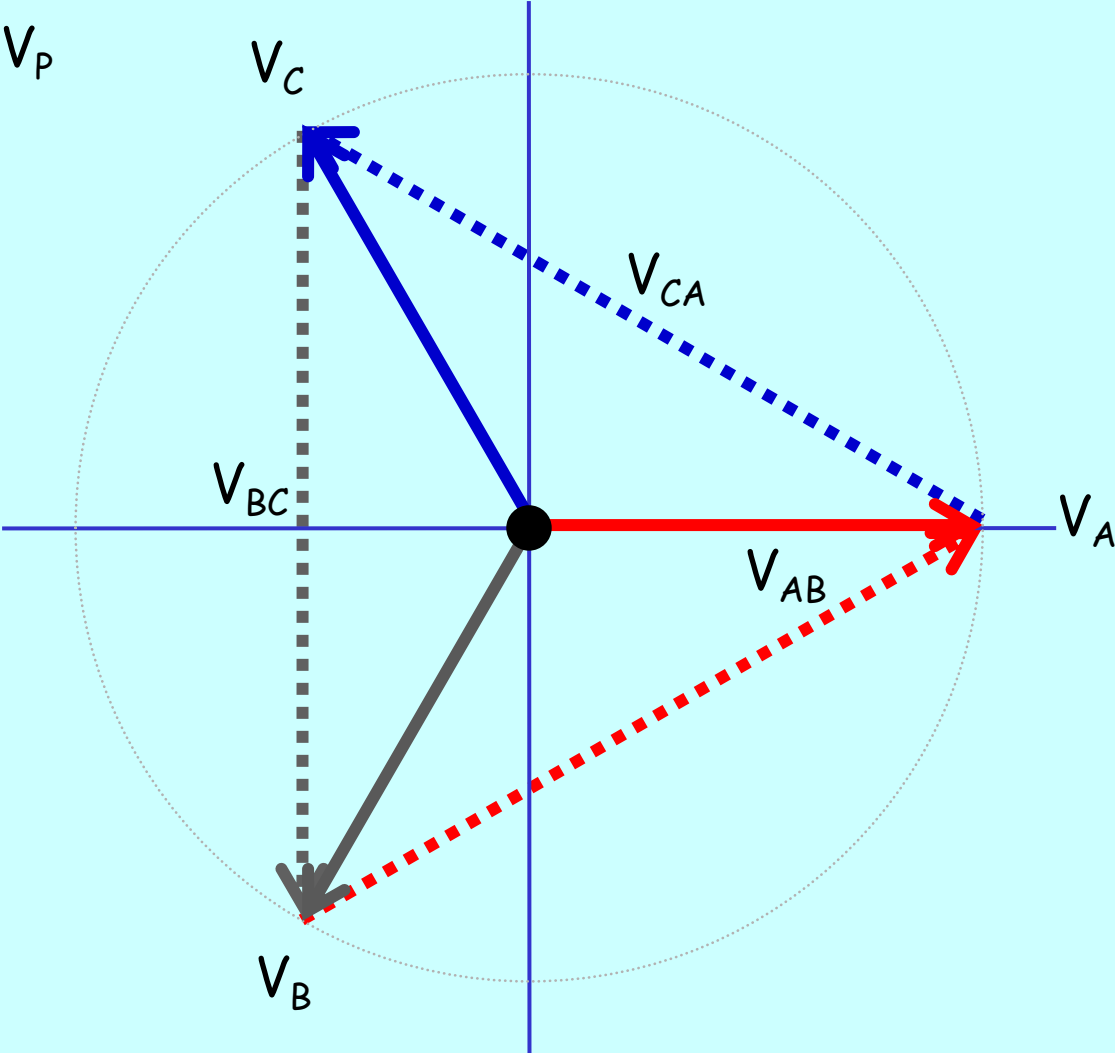
# Star Voltages

$$V_A = V_B = V_C = V_P$$

$$V_{AB} = \sqrt{3}V_P$$

$$V_{BC} = \sqrt{3}V_P$$

$$V_{CA} = \sqrt{3}V_P$$



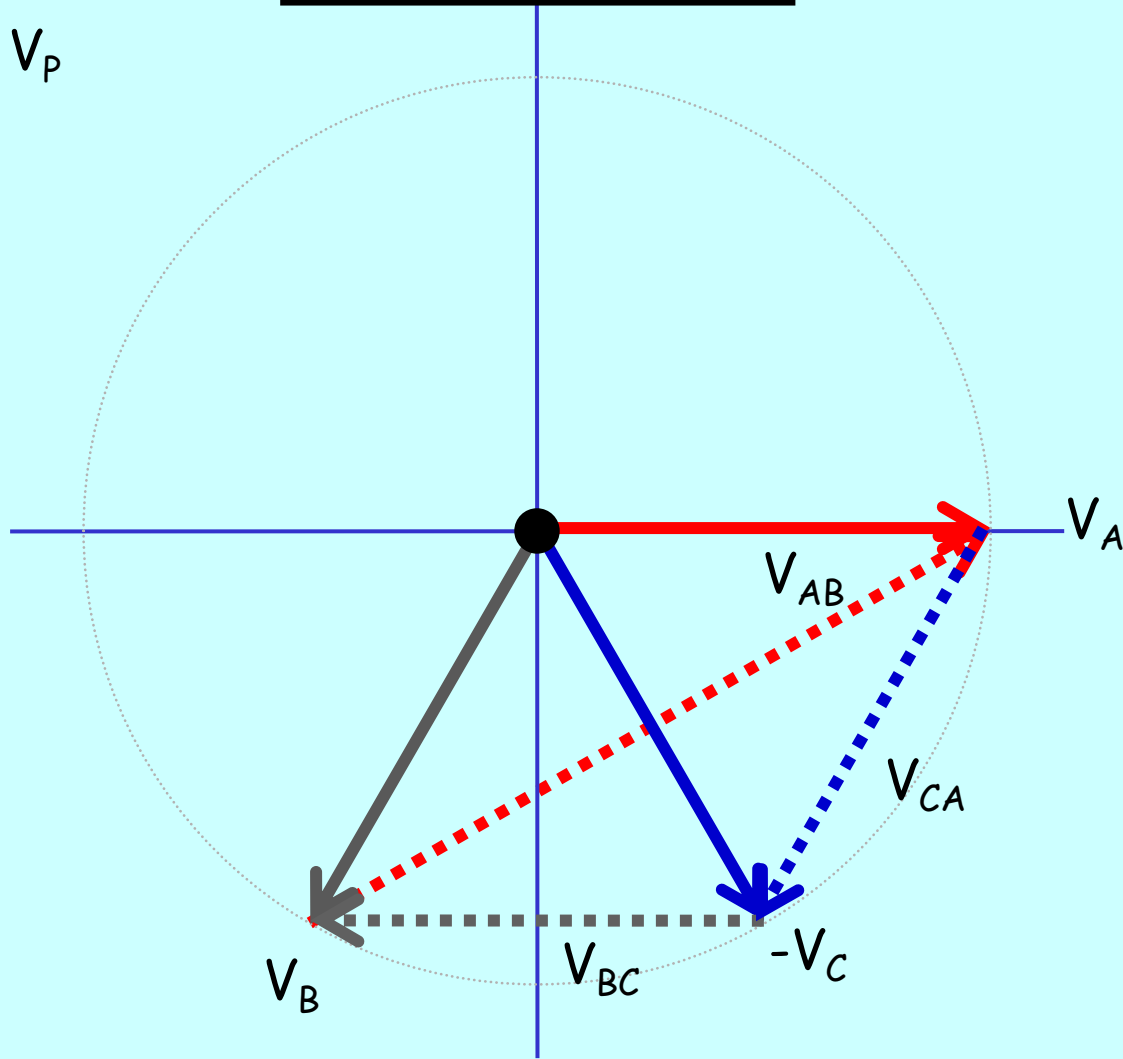
# Star Voltages Phase Reversal

$$V_A = V_B = V_C = V_P$$

$$V_{AB} = \sqrt{3}V_P$$

$$V_{BC} \neq \sqrt{3}V_P$$

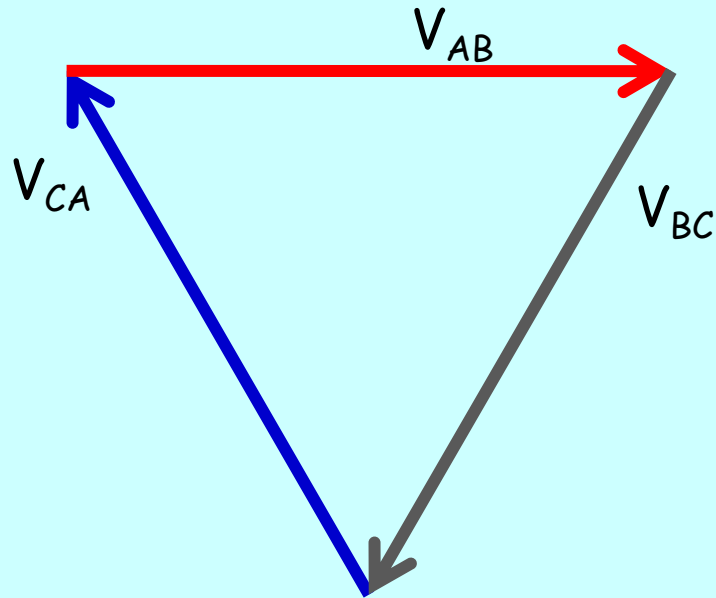
$$V_{CA} \neq \sqrt{3}V_P$$



# Delta Voltages

$$V_{AB} = V_{BC} = V_{CA} = V_P$$

$$V_{AB} + V_{BC} + V_{CA} = 0$$



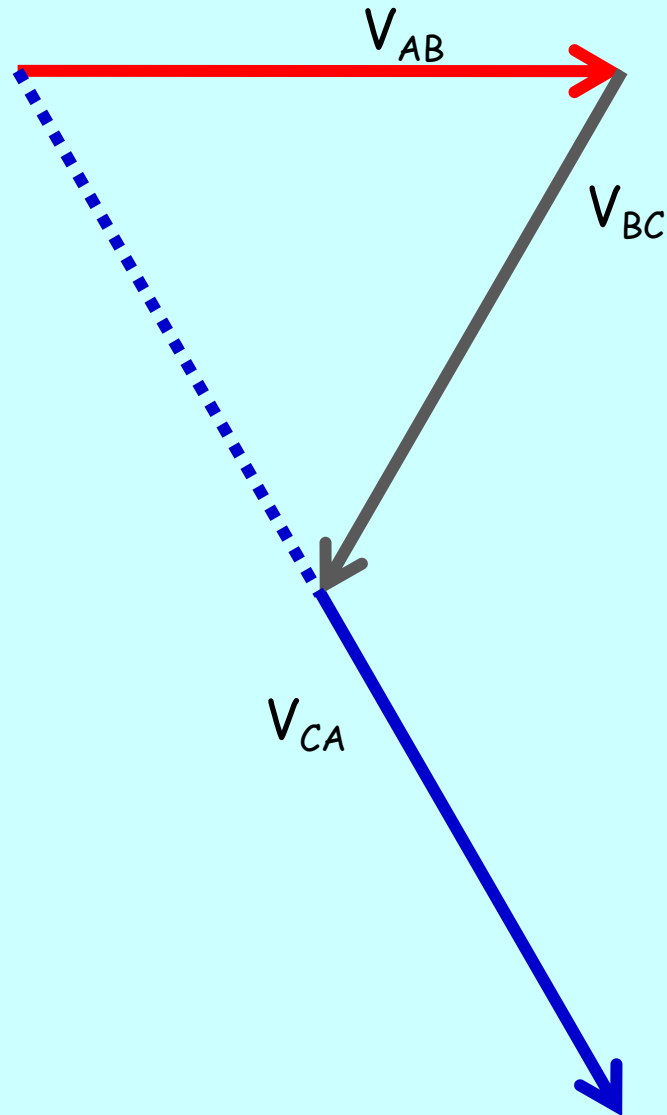


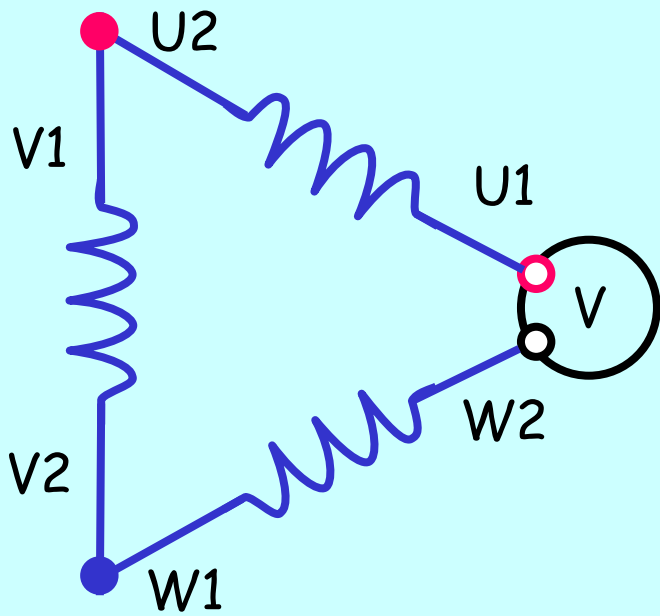
# Delta Voltages Phase Reversal

$$V_{AB} + V_{BC} + V_{AC} \neq 0$$

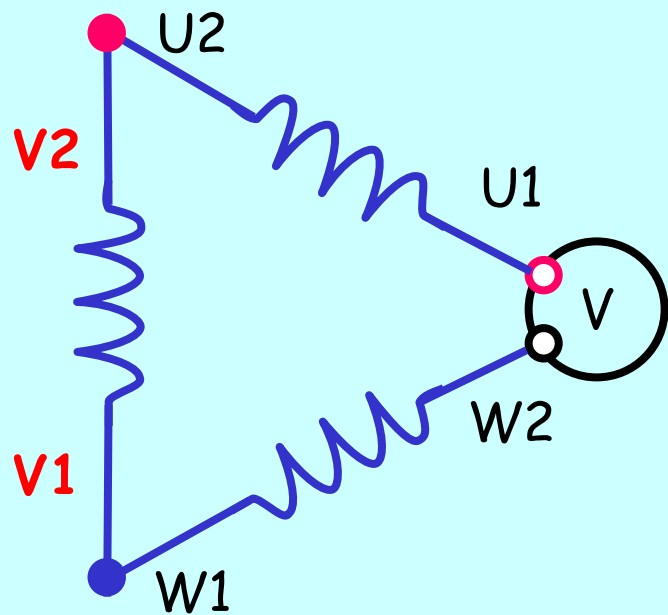
$$V_{AB} = V_{BC}$$

$$V_{CA} = 2V_{AB}$$



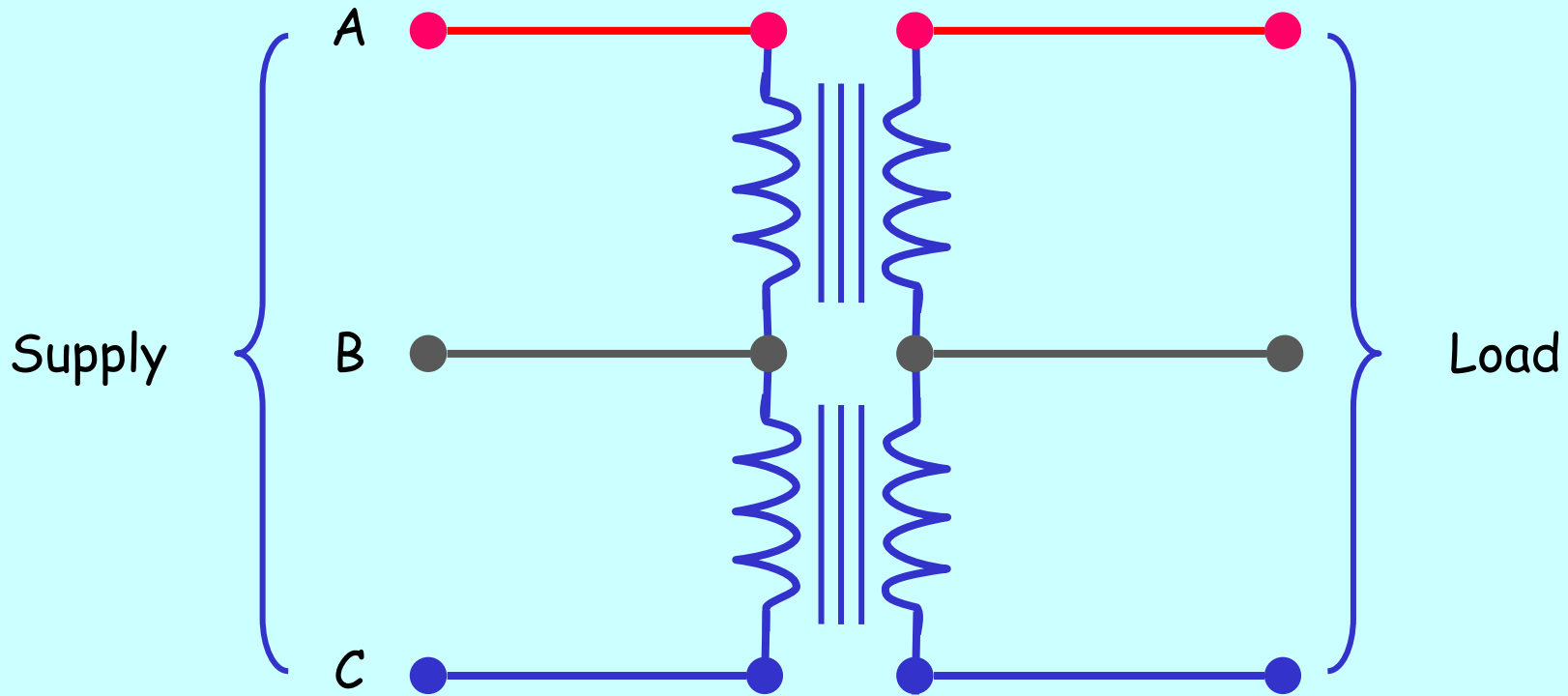


If rotation is correct  
Voltage reading is Zero



If any phase is reversed  
Voltage reading is  $2V_p$

# Open Delta Connected System



Three Phase Input

Two Single Phase  
Transformers

Three Phase Output

Simple and Easy to construct  
Produces same Voltages

$$I_L = I_p$$

Does NOT have the same  
POWER Capabilities  
Only 57.7%

# End of Lesson

## Practical Exercises

Three Phase Delta Connected System.

Star - Delta Connected System.

# UEENEEEG102A

## Solve problems in low voltage a.c. circuits

### Energy & Power in 3 Phase Systems

# Objectives:

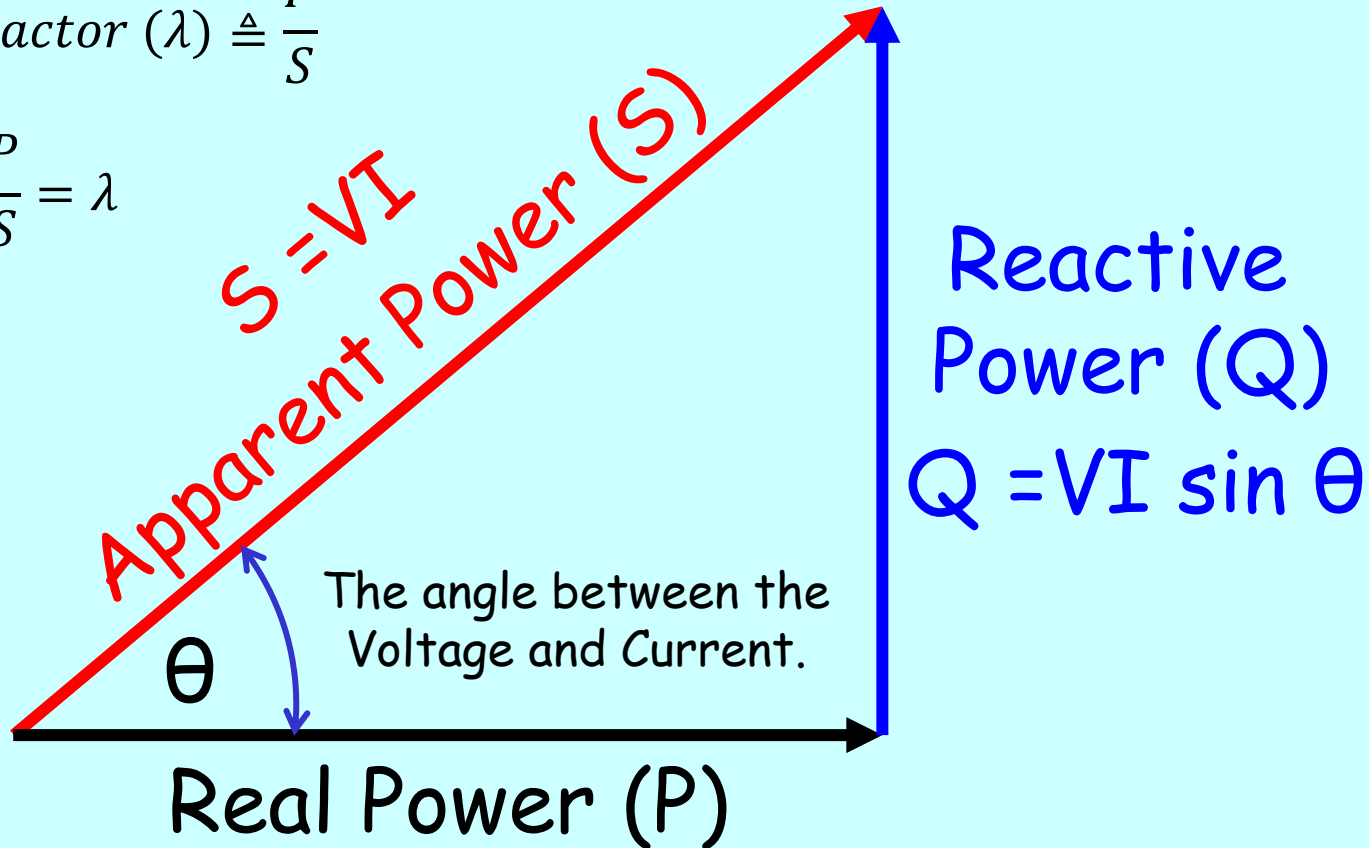
At the end of this lesson students should be able to:

1. Calculate True, Apparent and Reactive Power in a Three Phase System.
2. Measure True Power in a Three Phase System.

# Power Triangle

$$\text{Power Factor } (\lambda) \triangleq \frac{P}{S}$$

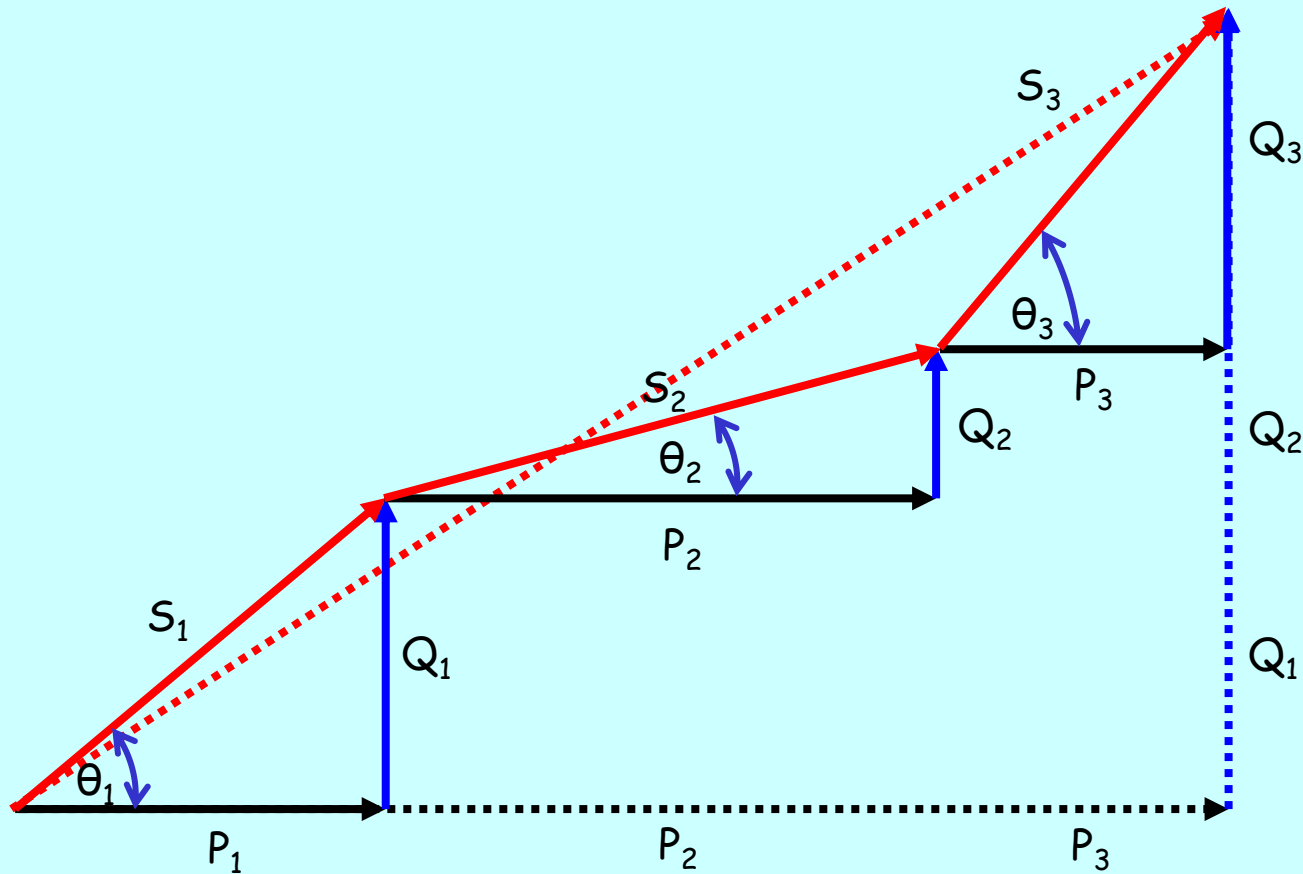
$$\cos \theta = \frac{P}{S} = \lambda$$



$$P = VI \cos \theta$$

The Power Factor ( $\lambda$ ) of the circuit relates the Real Power to the Apparent Power.

# In an Unbalanced Three Phase System

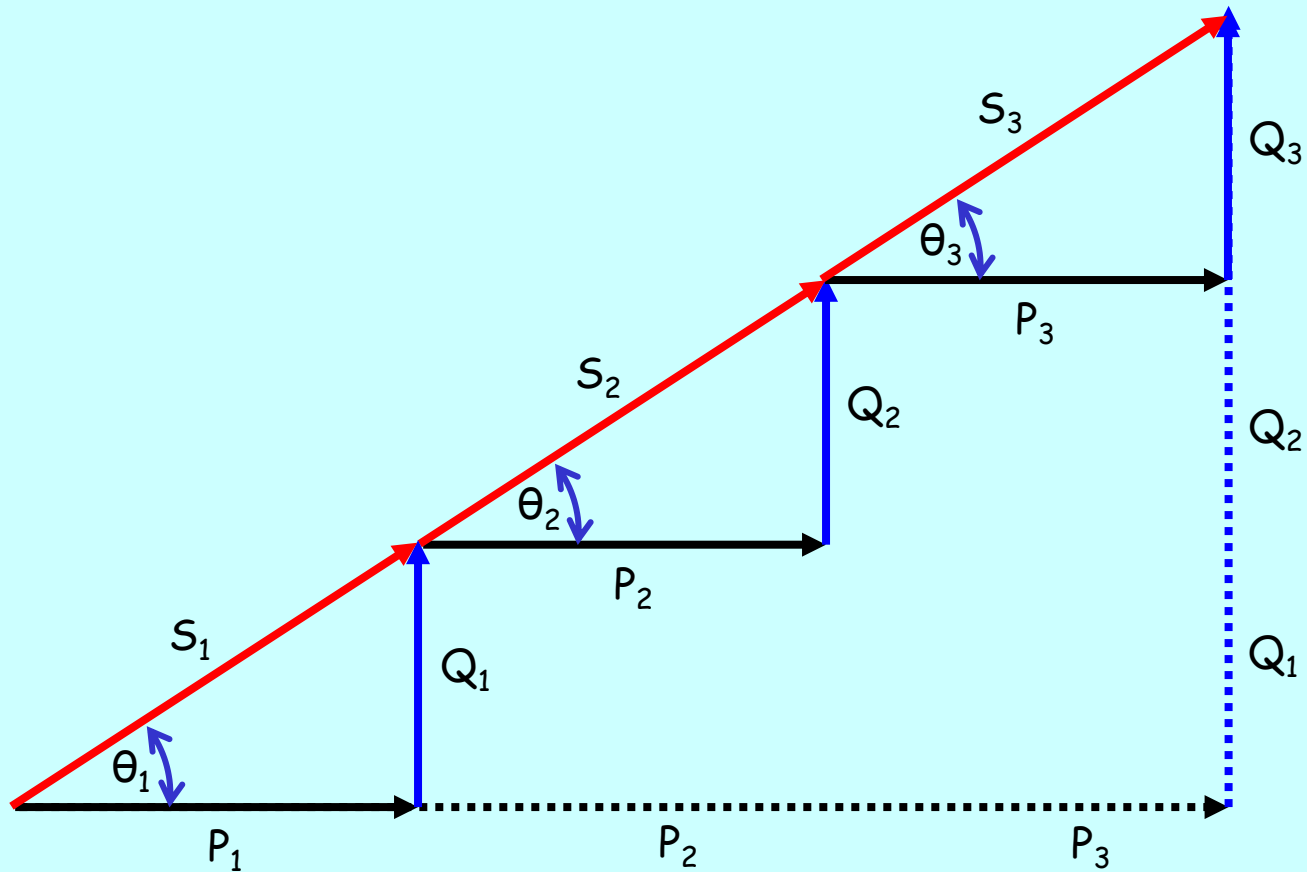


## Real Power in the Three Phase System

$$\underline{P}_T = \underline{P}_A + \underline{P}_B + \underline{P}_C$$



# In a Balanced Three Phase System



## Real Power in the Three Phase System

$$\underline{P}_T = \underline{P}_A + \underline{P}_B + \underline{P}_C$$

## Real Power in any Three Phase System

$$\underline{P}_T = \underline{P}_A + \underline{P}_B + \underline{P}_C$$

## In a Balanced Three Phase System

$$P_T = 3P_p = 3V_p I_p \cos \theta$$

### In a Star Connected System

$$V_p \times I_p = I_L \times \frac{V_L}{\sqrt{3}}$$

$$P_T = 3 \times \frac{V_L I_L}{\sqrt{3}} \times \cos \theta$$

$$P_T = 3 \times V_p I_p \times \cos \theta$$

### In a Delta Connected System

$$V_p \times I_p = V_L \times \frac{I_L}{\sqrt{3}}$$

$$P_T = \sqrt{3} \times V_L I_L \times \cos \theta$$

Determine the true power delivered to a 3-phase Delta connected induction motor which draws a balanced **line** current of 20 Amps at a lagging power factor of 0.866 from a 415 V, 50 Hz supply.

$$V_L = 415 \text{ V}$$

$$I_L = 20 \text{ A}$$

$$\lambda = 0.866$$

$$P_T = \sqrt{3} V_L I_L \cos \theta$$

$$P_T = \sqrt{3} \times 415 \times 20 \times 0.866$$

$$P_T = 12,449 \text{ W}$$

$$P_T = 12.5 \text{ kW}$$

Determine the line current delivered by an 11 kV transformer to a 3-phase balanced load which uses 300 kW at a lagging power factor of 0.9.

$$V_L = 11 \text{ kV}$$

$$I_L = \frac{P_T}{\sqrt{3}V_L \cos\theta}$$

$$P_T = 300 \text{ kW}$$

$$I_L = \frac{300\text{k}}{\sqrt{3} \times 11\text{k} \times 0.9}$$

$$\lambda = 0.9$$

$$I_L = 17.5 \text{ A}$$

Determine the true and reactive power that can be delivered by a 3-phase transformer rated at 50 kVA if the load has a 0.5 lagging power factor.

$$S_T = 50 \text{ kVA}$$

$$\lambda = 0.5 \text{ lag}$$

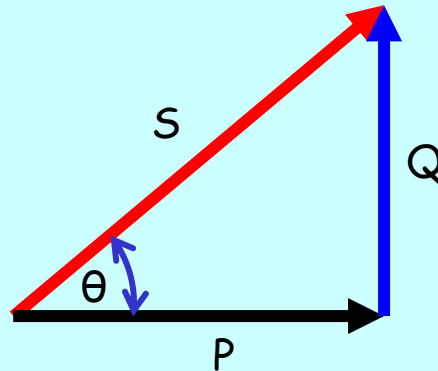
$$\lambda = \cos \theta$$

$$P_T = S \cos \theta$$

$$P_T = S \lambda$$

$$P_T = 50 \text{ k} \times 0.5$$

$$P_T = 25 \text{ kW}$$



$$\theta = \cos^{-1} \lambda$$

$$\theta = \cos^{-1} 0.5$$

$$\theta = 60^\circ$$

$$Q_T = \sqrt{S^2 - P^2}$$

$$Q_T = \sqrt{50^2 - 25^2}$$

$$Q_T = 43.3 \text{ kVar}$$

$$Q_T = S \sin \theta$$

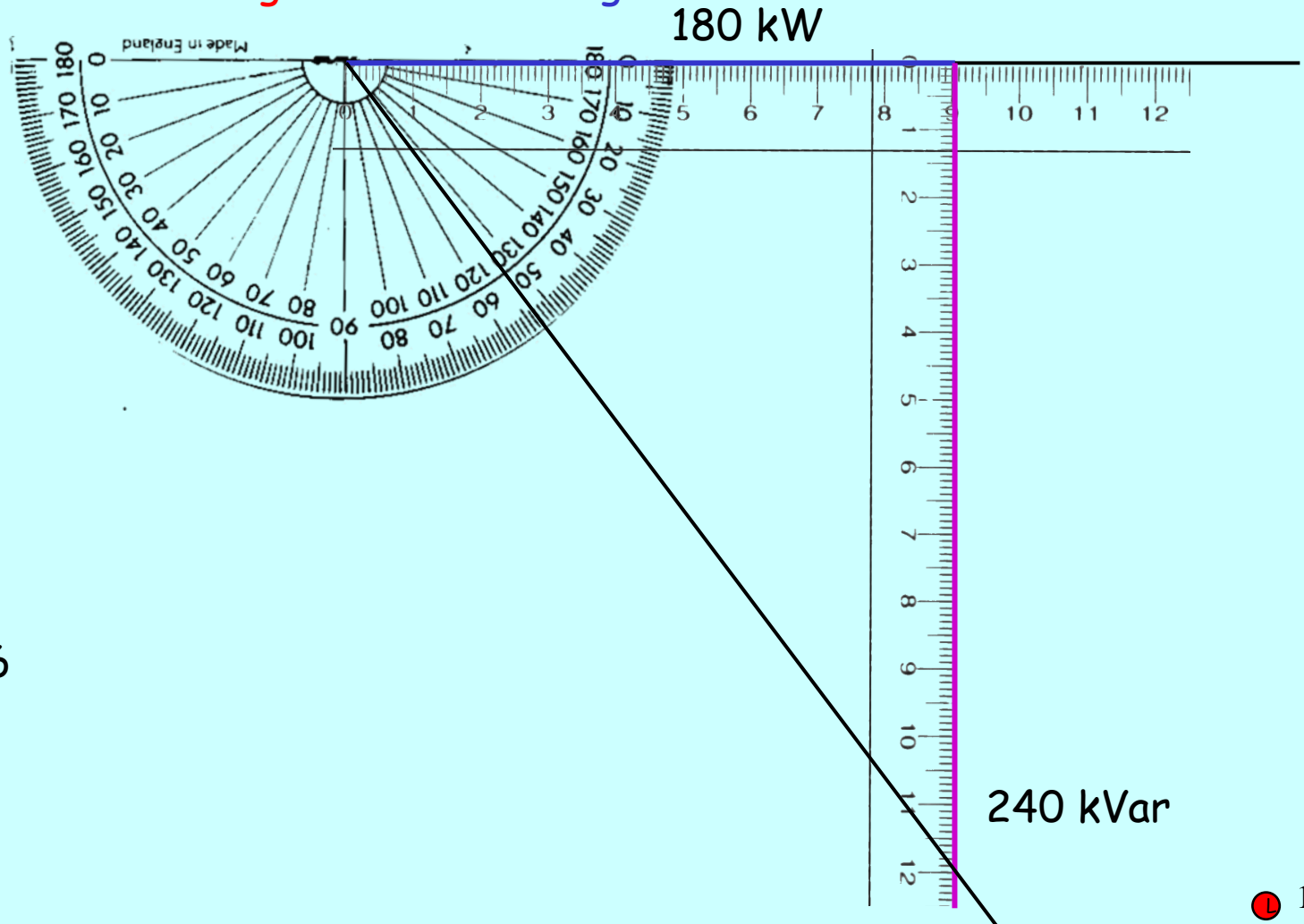
$$Q_T = 50 \text{ k} \times 0.866$$

$$Q_T = 43.3 \text{ kVar}$$

A 3-phase balanced load requires 180kW of power when operating at 0.6 lag pf. and connected to a 415V 50Hz 3-phase supply. Determine the kvar rating and capacitance of a star connected capacitor bank that would improve the pf. to 0.9 lag.

Step 1: Construct the **original** Power Triangle

Scale: 1 cm = 20 k



$$P_T = 180 \text{ kW}$$

$$\lambda_1 = 0.6$$

$$\theta_1 = \cos^{-1} \lambda$$

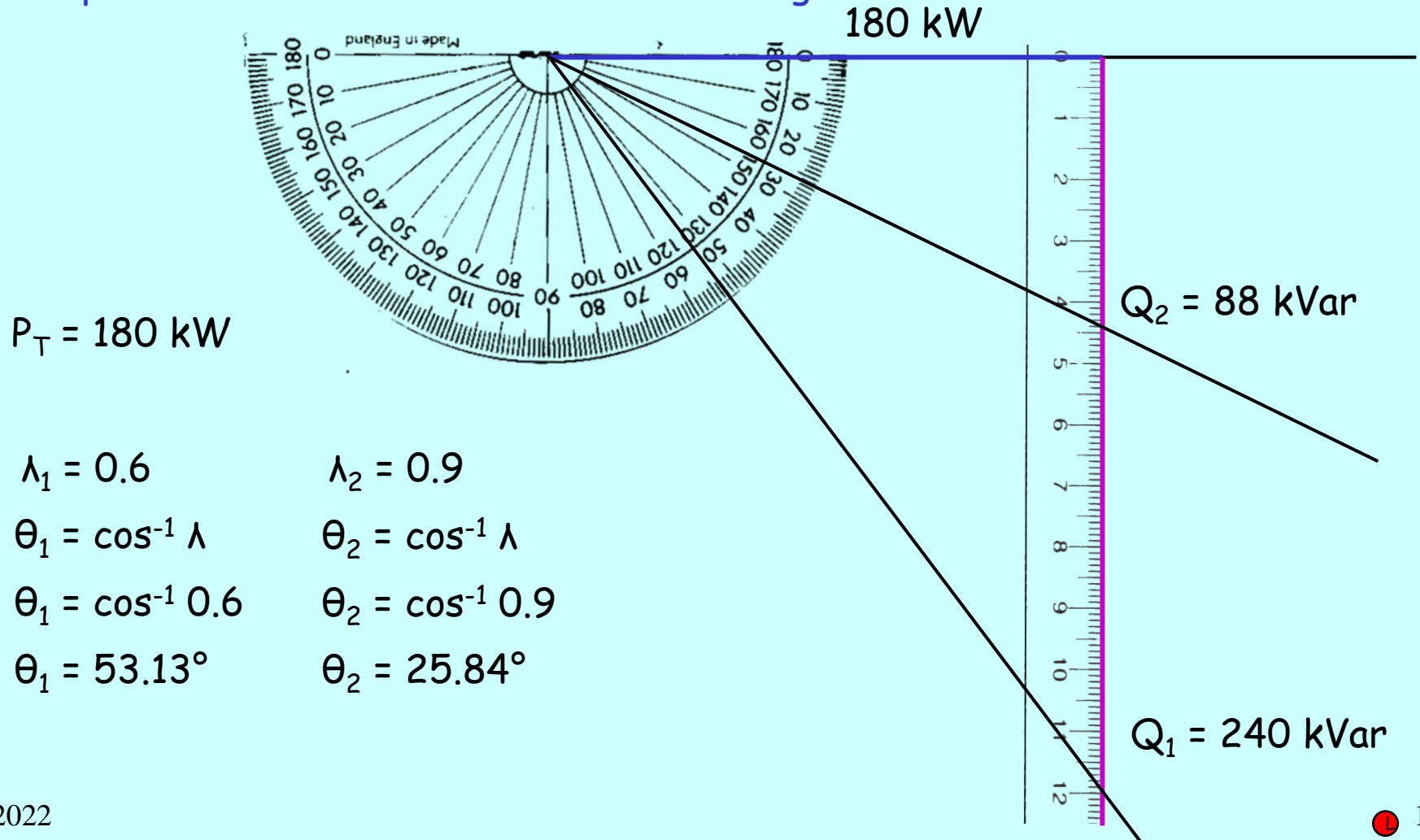
$$\theta_1 = \cos^{-1} 0.6$$

$$\theta_1 = 53.13^\circ$$

A 3-phase balanced load requires 180kW of power when operating at 0.6 lag pf. and connected to a 415V 50Hz 3-phase supply. Determine the kvar rating and capacitance of a star connected capacitor bank that would improve the pf. to 0.9 lag.

Step 2: Construct the **desired** Power Triangle

Scale: 1 cm = 20 k



A 3-phase balanced load requires 180kW of power when operating at 0.6 lag pf. and connected to a 415V 50Hz 3-phase supply. Determine the kvar rating and capacitance of a star connected capacitor bank that would improve the pf. to 0.9 lag.

Step 3: Measure the **kVar rating** of the Cap bank

Scale: 1 cm = 20 k

180 kW

$$P_T = 180 \text{ kW}$$

$$\lambda_1 = 0.6$$

$$\lambda_2 = 0.9$$

$$\theta_1 = \cos^{-1} \lambda$$

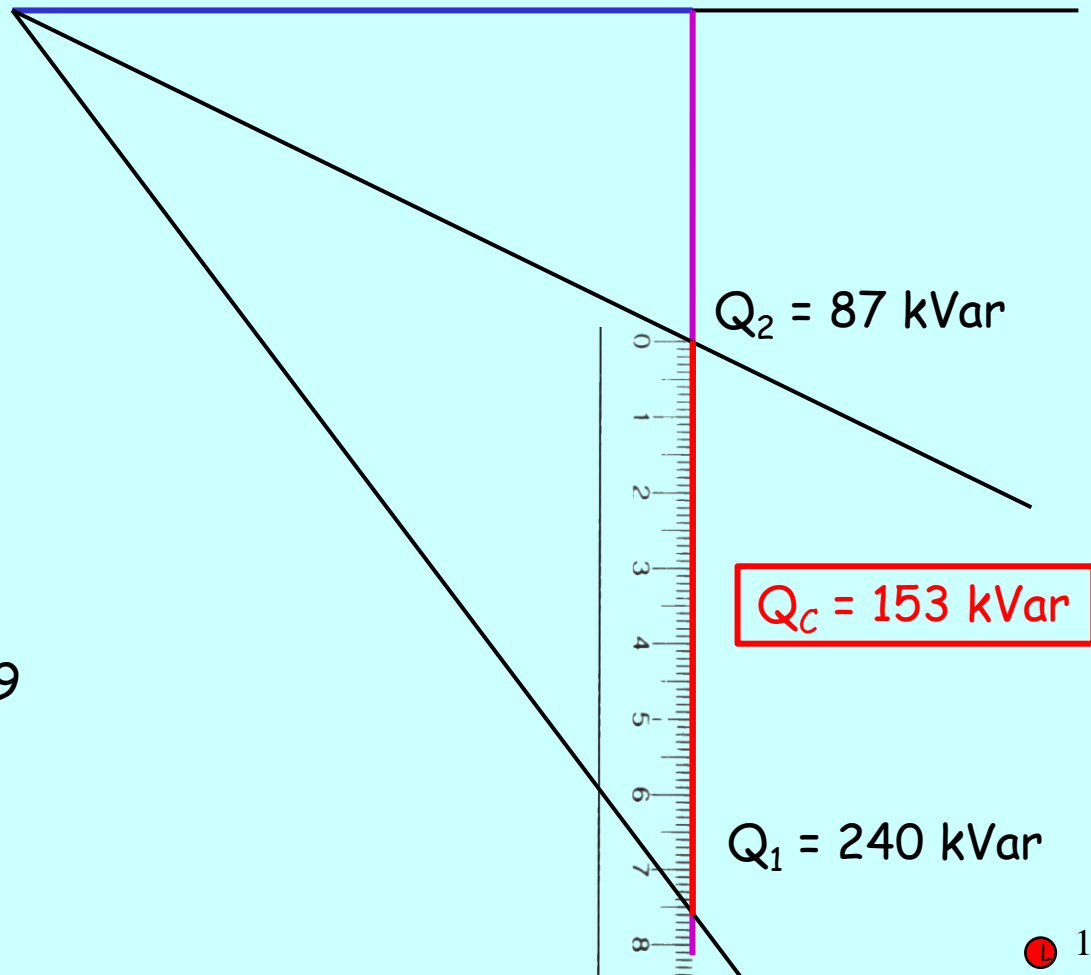
$$\theta_2 = \cos^{-1} \lambda$$

$$\theta_1 = \cos^{-1} 0.6$$

$$\theta_2 = \cos^{-1} 0.9$$

$$\theta_1 = 53.13^\circ$$

$$\theta_2 = 25.84^\circ$$





A 3-phase balanced load requires 180kW of power when operating at 0.6 lag pf. and connected to a 415V 50Hz 3-phase supply. Determine the kvar rating and capacitance of a star connected capacitor bank that would improve the pf. to 0.9 lag.

Step 4: Calculate the CAPACITANCE of the Cap bank

$$Q_C = 153 \text{ kVar}$$

$$Q_P = \frac{Q_C}{3}$$

$$Q_P = \frac{153}{3}$$

$$Q_P = 51 \text{ kVar}$$

$$X_P = \frac{V_P^2}{Q_P}$$

$$V_P = \frac{V_L}{\sqrt{3}}$$

$$X_P = \frac{240^2}{51\,000}$$

$$X_P = 1.13 \, \Omega$$

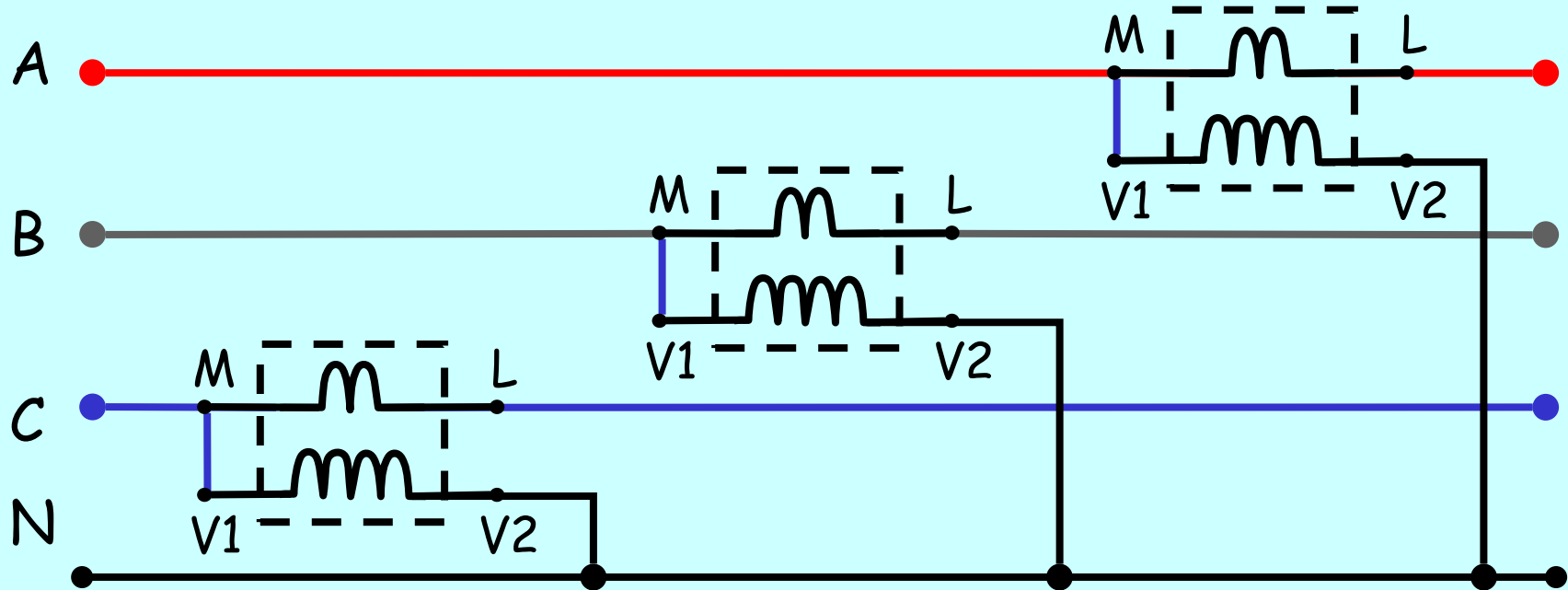
$$X_P = \frac{1}{2\pi f C}$$

$$C = \frac{1}{2\pi f X_P}$$

$$C = \frac{1}{2\pi \times 50 \times 1.13}$$

$$C = 2.82 \text{ mF}$$

# Power Measurement in 3 $\Phi$ Systems



Three Watt Meters - Four Wire method

## Advantages

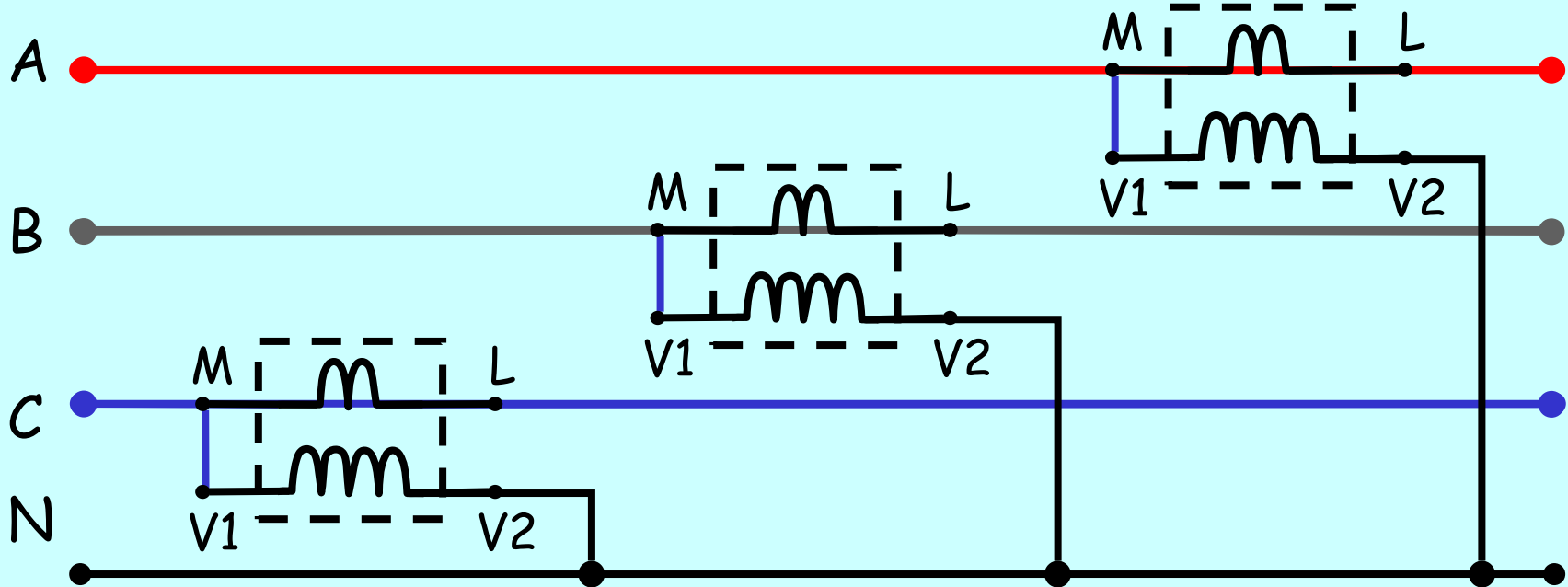
- Can be used on Balanced OR Unbalanced Loads
- Total Power easily monitored
- Reasonably accurate

$$\underline{P}_T = \underline{P}_A + \underline{P}_B + \underline{P}_C$$

## Disadvantages

- Three Wattmeters required
- Requires a Neutral (Star System)

# Power Measurement in 3 $\Phi$ Systems



One Watt Meter (move from phase to get each reading)

## Advantages

Only ONE Meter used

Simple & cheap

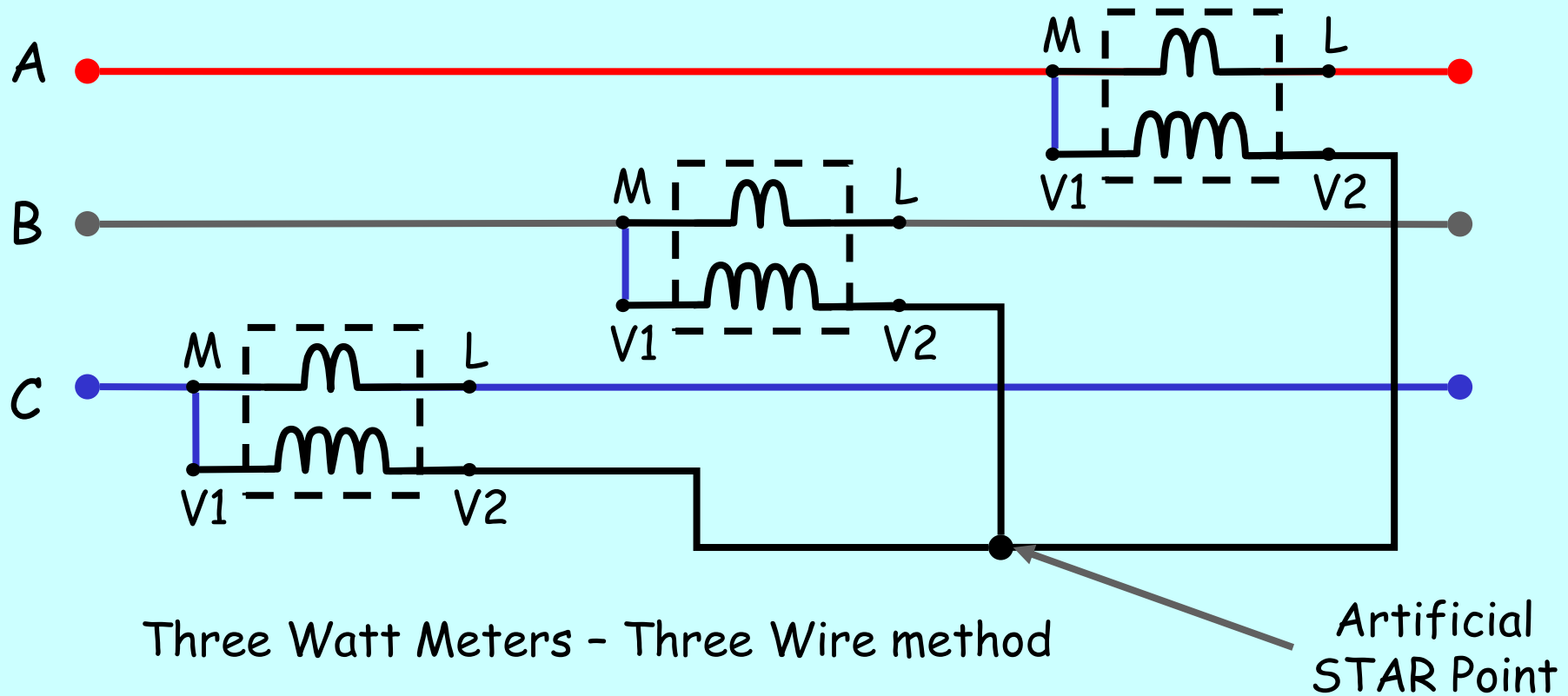
Can be used on Balanced  
OR Unbalanced Loads

$$\underline{P}_T = \underline{P}_A + \underline{P}_B + \underline{P}_C$$

## Disadvantages

Not very accurate on  
Unbalanced Loads

# Power Measurement in 3 $\Phi$ Systems



Three Watt Meters - Three Wire method

Artificial  
STAR Point

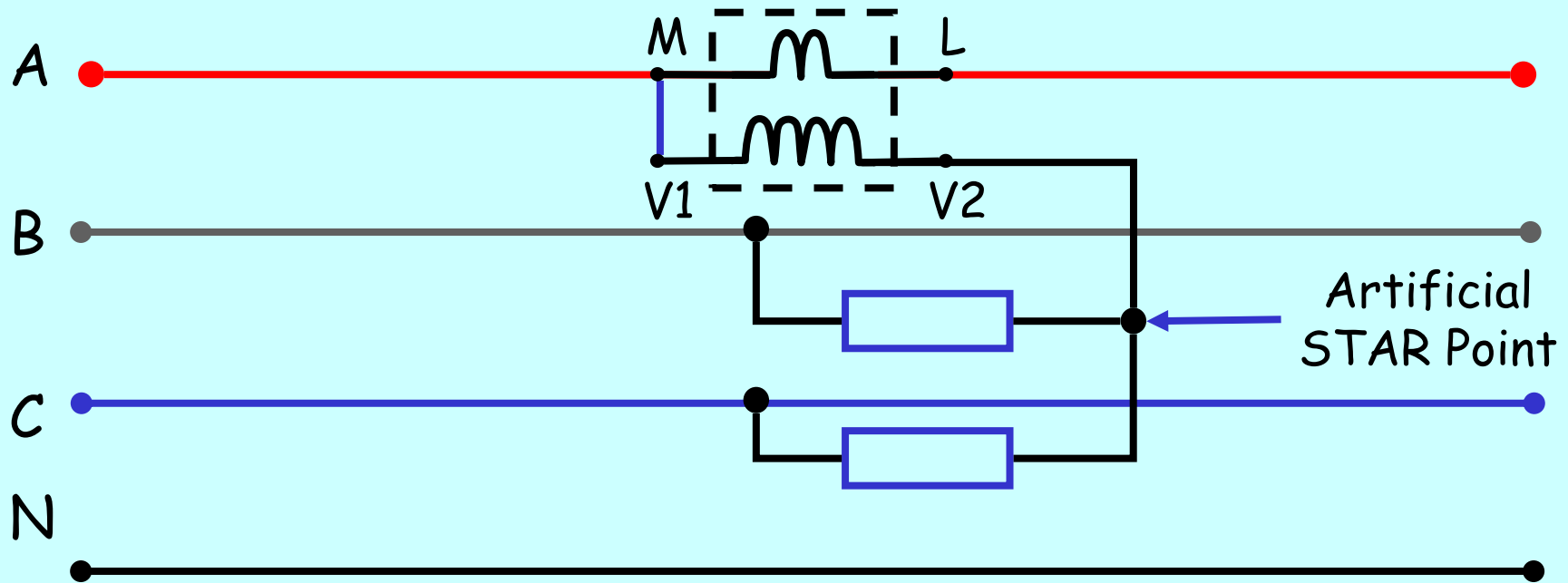
## Advantages

- Can be used on Balanced OR Unbalanced Loads
- Total Power easily monitored
- Reasonably accurate

## Disadvantages

- Requires Three identical Wattmeters

# Power Measurement in 3 $\Phi$ Systems



## One Watt Meter - Three Wire Method

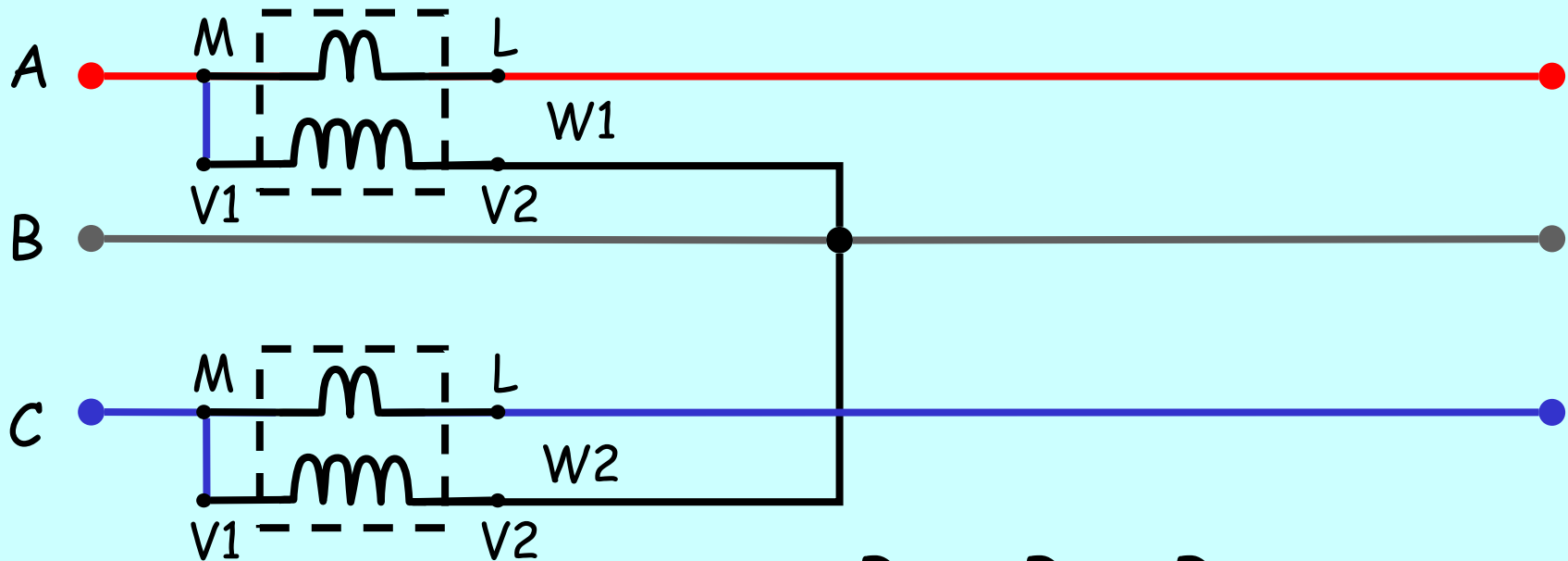
### Advantages

- Only ONE Meter used
- Simple & cheap
- Can be used on Balanced OR Unbalanced Loads

### Disadvantages

- Must construct the Artificial STAR Point
- Not accurate on varying Unbalanced Loads
- Need to reconnect to each phase for Unbalanced Loads

# Power Measurement in 3 $\Phi$ Systems



Two Watt Meters

## Advantages

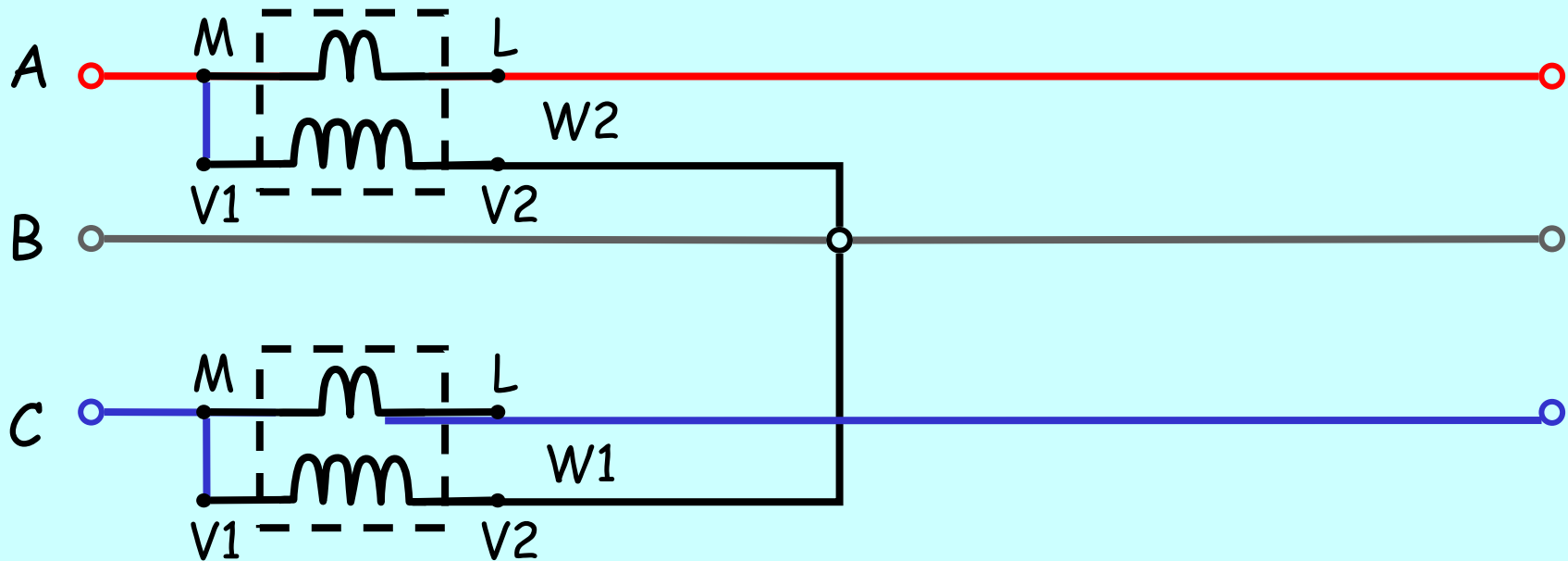
- Can be used on Balanced OR Unbalanced Loads
- Total Power easily monitored
- Only two Wattmeters required

$$\underline{P}_T = \underline{P}_1 + \underline{P}_2$$

## Disadvantages

- Can be used with Three Wire systems only
- Not accurate for loads with low power factor

# Power Measurement in 3 $\Phi$ Systems



Two Watt Meter Procedure

$$\underline{P}_T = \underline{P}_1 + \underline{P}_2$$

For balanced loads

Locate  $W_2$  in the phase immediately following  $W_1$  in the phase sequence.

$$\tan \theta = \sqrt{3} \left( \frac{W_2 - W_1}{W_2 + W_1} \right)$$

Two Element Watt meters

# Exercises

Page 73



1. A star connected A.C. generator develops 11000 volts per phase. Determine the MVA rating of the machine if the current per phase is 50 amperes. (1.65 MVA)

$$V_p = 11 \text{ kV}$$

$$I_p = 50 \text{ A}$$

$$S_T = 3V_p I_p$$

$$S_T = 3 \times 11 \text{ k} \times 50$$

$$S_T = 1.65 \text{ MVA}$$

2. A 3 phase alternator delivers a full load of 140 amperes at a power factor of 0.9 lagging. If the terminal voltage is 400 volts, calculate the:
- Kilovolt ampere rating, (97 kVA)
  - Kilowatt output.(87.3 kW).

$$V_L = 400 \text{ V}$$

$$I_L = 140 \text{ A}$$

$$\lambda = 0.9$$

$$S_T = \sqrt{3} V_L I_L$$

$$S_T = \sqrt{3} \times 400 \times 140$$

$$S_T = 96.99 \text{ kVA}$$

$$P_T = S_L \times \lambda$$

$$P_T = 97 \text{ k} \times 0.9$$

$$P_T = 87.3 \text{ kW}$$

3. The power in a 3 phase 400 volt system is measured by the two wattmeter method where W1 indicates 30 kW and W2 indicates 20 kW. Calculate the:

a. Total power (50 kW),

b. Power factor (0.94),

$$\tan \theta = \sqrt{3} \left( \frac{W_2 - W_1}{W_2 + W_1} \right)$$

c. Line current (76.78 A).

$$V_L = 400 \text{ V}$$

$$W_1 = 30 \text{ kW}$$

$$W_2 = 20 \text{ kW}$$

$$\theta = \tan^{-1} \left\{ \sqrt{3} \left( \frac{W_2 - W_1}{W_2 + W_1} \right) \right\}$$

$$\theta = \tan^{-1} \left\{ \sqrt{3} \left( \frac{20 - 30}{20 + 30} \right) \right\}$$

$$\theta = -19.1^\circ$$

$$\lambda = \cos \theta$$

$$\lambda = \cos -19.1$$

$$P_T = W_1 + W_2$$

$$P_T = (30 + 20) \text{ kW}$$

$$P_T = 50 \text{ kW}$$

$$\lambda = 0.94$$

$$P_T = \sqrt{3} V_L I_L \cos \theta$$

$$I_L = \frac{P_T}{\sqrt{3} V_L \cos \theta}$$

$$I_L = \frac{50k}{\sqrt{3} \times 400 \times 0.94}$$

$$I_L = 76.78 \text{ A}$$

4. The power input to a 3 phase, 400 volt induction motor is measured by the two wattmeter method where W1 indicates 10 kW and W2 indicates -6 kW (note the minus sign). Calculate the:

a. power input (4 kW),

b. power factor of the motor (0.14),

$$\tan \theta = \sqrt{3} \left( \frac{W_2 - W_1}{W_2 + W_1} \right)$$

$$V_L = 400 \text{ V}$$

$$W_1 = 10 \text{ kW}$$

$$W_2 = -6 \text{ kW}$$

$$P_T = W_1 + W_2$$

$$P_T = (10 - 6) \text{ kW}$$

$$P_T = 4 \text{ kW}$$

$$\theta = \tan^{-1} \left\{ \sqrt{3} \left( \frac{W_2 - W_1}{W_2 + W_1} \right) \right\}$$

$$\theta = \tan^{-1} \left\{ \sqrt{3} \left( \frac{-6 - 10}{-6 + 10} \right) \right\}$$

$$\theta = -81.79^\circ$$

$$\lambda = \cos \theta$$

$$\lambda = \cos -81.79$$

$$\lambda = 0.14$$

End of Theory

Next Lesson

Final Theory Test