

thus
$$I_{mf} = \frac{1}{2}(I_m - jI_a) \quad \dots (17-3)$$

$$I_{mb} = \frac{1}{2}(I_m + jI_a) \quad \dots (17-4)$$

Suppose that in a two-phase system, the impedances are Z_a and Z_m as shown in Figure 17-2. Then

$$V_m = I_m Z_{lm} + E_m \quad \dots (17-5)$$

$$V_a = I_a Z_{la} + E_a \quad \dots (17-6)$$

where V_m , V_a are the phasor source voltages; I_m , I_a are the phasor phase currents; Z_{lm} , Z_{la} are each the phasor sum of the external-circuit impedance and the leakage impedance of a stator phase; E_m and E_a are the counter emfs generated in the stator windings by the resultant air-gap flux.

Let N_m and N_a be the effective turns in windings m and a , respectively. Exactly as in a balanced 2-phase motor, a constant-amplitude revolving field would result if the currents in the 2 windings produced equal amplitude mmfs in time quadrature. The direction of rotation of the field would depend on the phase sequence of the currents. A constant-amplitude forward field would result if a set of phasor currents I_{mf} and I_{af} in the windings m and a , respectively, satisfied the phasor relationship

$$N_a I_{af} = j N_m I_{mf} \quad \dots (17-7)$$

or
$$I_{af} = j I_{mf} / a \quad \dots (17-8)$$

where a is the effective turns ratio N'_a/N'_m . Similarly, a constant-amplitude backward field would result if another set of phasor currents I_{mb} and I_{ab} satisfied the phasor relationship

$$I_{ab} = -j I_{mb} / a$$

If both sets of currents existed simultaneously, the actual winding currents I_m and I_a would be

$$I_m = I_{mf} + I_{mb} \quad \dots (17-9)$$

$$I_a = I_{af} + I_{ab} = j I_{mf} / a - j I_{mb} / a \quad \dots (17-10)$$

and both a forward and a backward field would be present. Solution of these equations for the component currents I_{mf} and I_{mb} in terms of the actual winding currents I_m and I_a gives

$$I_{mf} = \frac{1}{2}(I_m - j a I_a) \quad \dots (17-11)$$

$$I_{mb} = \frac{1}{2}(I_m + j a I_a) \quad \dots (17-12)$$

Note that a I_a is simply the current in winding a referred to winding m , as in static-transformer theory.

Figure 17-3. Equivalent circuits representing the reactions of (a) the forward and (b) the backward fields as viewed from the main winding.

From the viewpoint of winding m , the internal reactions of the forward and backward fields are just like those in a balanced 2-phase motor. Thus, if the rotor and magnetizing impedances are referred to winding m , the forward and backward-field impedances Z_f and Z_b as viewed from winding m , are given by the equivalent circuits in Figure 17-3 and the component counter emfs E_{mf} and E_{mb} generated in winding m by the forward and backward fields, respectively, equal the voltages across these impedances. The total counter emf E_m generated in winding m is, as a phasor,

$$E_m = E_{mf} + E_{mb} = I_{mf} Z_f + I_{mb} Z_b \quad \dots (17-13)$$

Because of the stator turns ratio, the component counter emfs generated in winding a will be a times the corresponding component voltages generated in winding m . Because of the directions in which the fields rotate, the forward-field component generated in winding a leads and the backward-field component lags the corresponding component generated in winding m . The total counter emf E_a generated in winding a by both fields therefore is