

Q.1

pb

$\sin \pi t \rightarrow u(t)$
 FIND V_C AFTER $t=0$
 $\uparrow u(t-4) \rightarrow \sin \pi(t-4)$

Q2

pb

ASSUME THAT THE BAR IS RIGID BUT FRICTIONS ARE VERTICAL MOTION.
 ONLY PIVOT IS FRICTIONLESS
 FIND f, I ANALOGOUS ELECTRICAL CIRCUIT OF MECHANICAL SYSTEM
 f, f_2, v AND VELOCITY u_1, u_2, u_3 AS ANALOGOUS ELECTRICAL QUANTITY
 $f_1 r_1 = f_2 r_2 \rightarrow u_2 = u_1 \frac{r_2}{r_1}$

Q3

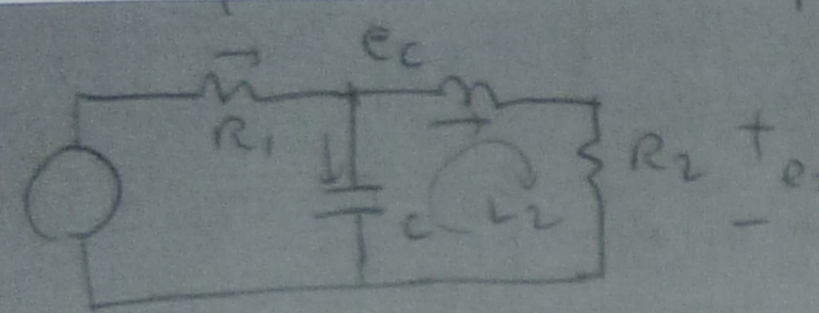
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SKETCH THE BLOCK DIAGRAM

Q4

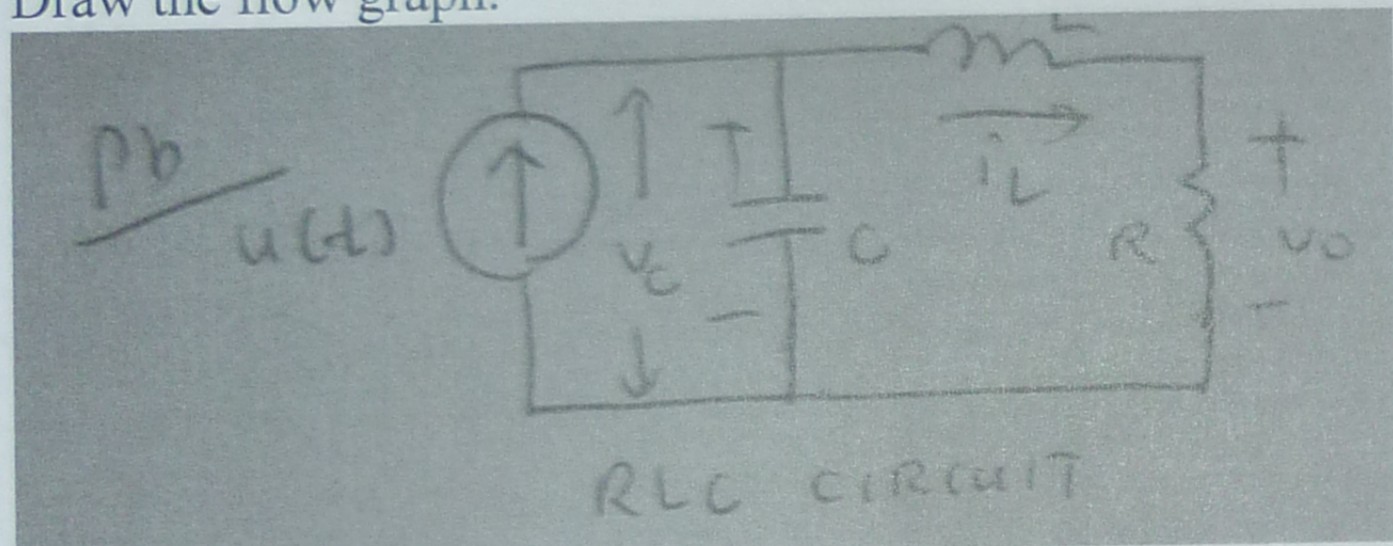
2nd ORDER SYSTEM $2 \frac{d^2 y}{dt^2} + 4 \frac{dy}{dt} + 8y = 8x$
 SIMPLIFY

Q5


 THE STATE VARIABLE WITH DESIRABLE SYSTEM ARE NOT UNIQUE SET
 SOLVE AT e_c NODE

Q6

Draw the flow graph.



Q7

GIVEN A UNITY FEED BACK SYSTEM WITH $G = \frac{k}{(s+1)(s+3)}$
 DESIGN THE SYSTEM TO SATISFY THE FOLLOWING SPECIFICATIONS:
 (i) $POE \leq 20\%$ (ii) $TP \leq 1.5 \text{ SEC}$ (iii) $MP \geq 4$ $ess \leq 0.2$

Q8

$GH = \frac{k}{(s+1)^2 \times (s)}$ FIND ROOT LOCUS AND ALL RELEVANT VALUES (14)

Q9

Write the example of steady state model for linear system

Q10

Why Routh Harwitz Criterion is applied?